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20. ABSTRACT (Continued).

methods used in the computer programs is also included in the report. COM62 solves laterally loaded pile problems using an iterative scheme that considers nonlinear soil resistance versus pile movement curves. PX4C3 is a computer program written for the analysis of an axially loaded pile accounting for nonlinear soil properties. MAKE is a program that generates lateral soil resistance-pile movement curves from laboratory soil testing data based on predefined criteria. BENTL analyzes group pile problems, again accounting for nonlinear soil behavior under both axial and lateral loads. BMCOL51 is a computer program based on the discrete element theory. Some of the uses of BMCOL51 can be in obtaining general solutions for linear beam-columns, moving load problems, beam on elastic foundation problems, variable beam-size problems, and buckling problems. Each of the five computer programs has been documented completely with a general introduction, listing of program, flow charts, guide for data input, and example problems with input-output data. Programs COM62, PX4C3, MAKE, and BENT1 run on the time-sharing mode while program BMCOL51 runs on the batch/card-in mode on the WES G-635 computer system.

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PREFACE

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The report presented herein documents five soil-structure interaction finite difference computer programs obtained from the University of Texas (UT), Austin, Texas. The computer programs are designed to analyze a wide variety of problems involving laterally and axially loaded single piles, group pile foundations, and complex beam-column structural members.

Professors L. C. Reese and H. Matlock, Civil Engineering Department, UT, are gratefully acknowledged for giving permission to use these computer programs developed under their guidance. Special thanks also go to the Center for Highway Research at UT for permission to use their reports referred to extensively in this documentation.

Funds for this work were authorized by the Lower Mississippi Valley Division (LMVD), Corps of Engineers, as part of the analysis support provided by the U. S. Army Engineer Waterways Experiment Station (WES) Automatic Data Processing Center (ADPC). Mr. D. R. Dressler, Technical Engineering Branch, LMVD, was the contact engineer and also reviewed the content and format of this report.

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The assistance given by several people in the Computer Analysis Branch (CAB), ADPC, is greatly appreciated. These include: Mr. D. W. Walters for converting the programs from the CDC 6600 computer to the G-440 system; Messrs. H. W. Jones and R. L. Hall for their help in documenting the codes; and Miss A. M. Wade for her help in converting the programs from the G-440 to the G-635 system.

The work was accomplished during the period July 1972 through April 1974 under the immediate supervision of Messrs. J. B. Cheek, Jr., Chief of CAB, and H. H. Ulery, Chief of the Pavement Design Division, Soils and Pavements Laboratory (S&PL). General supervision was provided by Messrs. D. L. Neumann, Chief of ADPC, and J. P. Sale, Chief, S&PL. The report was prepared by Drs. N. Radhakrishnan, CAB, and F. Parker, Jr., Pavement Design Division, S&PL.

BG E. D. Peixotto, CE, and COL G. H. Hilt, CE, were Directors of WES during the course of the work and the preparation of this report. Mr. F. R. Brown was Technical Director.

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CONVERSION FACTORS, U. S. CUSTOMARY TO METRIC (SI) UNITS OF MEASUREMENT

U. S. customary units of measurement used in this report can be converted to metric (SI) units as follows:

Multiply	Ву	To Obtain
inches	2.54	centimeters
feet	0.3048	meters
kips (mass)	453.5924	kilograms
pounds per cubic inch	27,679.90	kilograms per cubic meter
pounds (force)	4.448222	newtons
pounds per inch	175.1268	newtons per meter
pounds per square inch	6894.757	pascals
pounds per square foot	47.88026	pascals
inch-pounds	0.1129848	newton-meters
inch-kips	112.9848	newton-meters
inch-pounds/inch	4.448222	newton-meters/meter
degrees	0.01745329	radians

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BACKGROUND THEORY AND DOCUMENTATION OF FIVE UNIVERSITY OF TEXAS SOIL-STRUCTURE INTERACTION COMPUTER PROGRAMS

PART I: INTRODUCTION

Need for Pile Analysis

1. Pile foundations are frequently used for structures when the soil immediately below the base will not provide adequate bearing capacity. The purpose of the piles is to transfer the load from the structure to soil strata which can sustain the applied loads. The Lower Mississippi Valley Division is interested in the analysis and design of pile foundations for a variety of structures.

Group Pile Behavior

2. If the structure is supported on vertical piles and if all loads from the structure are also vertical, then the loads transmitted to the piles will all be principally axial. If some horizontal component of load is present, a lateral force will also be transmitted to the piles. If some of the piles are battered, an axial and lateral force will be transmitted to the piles regardless of the direction of the applied load. For most structures both horizontal and vertical components of load are present. In some instances, the horizontal component may be small and can be neglected. However, for many structures, such as offshore drilling platforms, tall bridge bents, or hydraulic structures, wind and wave action will produce significant horizontal forces. Therefore, for a complete analysis of a pile foundation, the behavior of the piles must be analyzed for both lateral and axial loads.

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3. When a pile is subjected to any load, deformation will occur. For small loads, the deformation may be proportional to the load; however, the load-deformation relationship becomes increasingly nonlinear as the load increases. This nonlinear load-deformation relationship is

principally due to the nonlinear load-deformation characteristics of the soil.

Methods of Group File Analysis

Hrennikoff's method

4. One of the most popular methods of analysis of a group pile foundation is due to Hrennikoff.¹ Implicit in this method of analysis is the assumption that the load-deformation relationships for soil are linear. In other words, the soil is represented by a series of linear springs in the analysis. Since the soil behavior under load is generally nonlinear, this method of analysis poses some limitations. An excellent review and comparison of various methods of analyses of group pile foundations is given by Robertson.²

University of Texas (UT) method

5. In the UT method of group pile analysis, nonlinear deflectionreaction curves are used to depict soil behavior. The axial pile-soil interaction is obtained from a nonlinear load-deformation curve. The lateral interaction is specified by a set of nonlinear deflectionreaction curves. These curves, referred to as p-y curves, establish the relationship between the deflection of the pile and the reaction exerted by the soil. The equilibrium position for the pile-supported structure is found by an iterative process that ensures the compatibility between the behavior of soil and the piles and between the piles and the structure.

Advantages of the UT method

6. The method of Hrennikoff and the UT method are somewhat similar in their approach. However, the UT method introduces two major improvements. Probably the most important of these is the use of nonlinear pile movement-soil resistance relationships. The second major improvement is that it permits the rotational stiffness of the structure or the pile-head restraint to be included in the analysis (Hrennikoff's method allows only for completely fixed or hinged conditions).

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Nonlinear Interaction Curves

7. If families of curves that will simulate the nonlinear interaction between the pile and surrounding soil are available, existing procedures for numerical computation can be used to predict the response of individual piles. The response of individual piles may then be combined to predict the behavior of a foundation supported by these piles. This is the basis of the UT method of analysis. A detailed knowledge of the behavior of the foundation and of the individual piles will allow a superior design, which will usually be more economical than is possible with a less rational procedure.

8. The family of curves describing the behavior of the soil around an axially loaded pile will give axial soil reaction versus axial pile movement for a number of locations along the pile. For a given location, a curve would show the axial force per unit area transferred to the soil for a given axial movement of the pile.

9. Similarly, the family of curves describing the behavior of the soil around a laterally loaded pile will give lateral soil reaction versus lateral pile movement for a number of locations along the pile. For a given location, a curve would show the lateral force per unit length transferred to the soil for a given lateral movement.

10. Unless procedures are available to develop soil interaction curves based on available data, the UT method of analysis loses one of its principal advantages. There are semi-empirical procedures available for predicting the interaction curves for both axial and lateral behavior of piles. However, these procedures must be used with caution; the applicability of these techniques for the problem in hand must be fully examined before use. Some of the procedures used in the computer programs documented in this report are summarized in Part V.

Beam-Column Programs

11. A series of computer programs, developed under the guidance of Prof. H. Matlock, are available at UT at Austin to solve structural

and soil-structure interaction problems. These programs are very versatile and can be used for analysis of a variety of problems. One of the earlier beam-column programs, BMCOL51, developed by Matlock and Taylor,³ is documented in this report. BMCOL51 is a discrete element program and can be used for obtaining general solutions for linear beam-columns, movable load problems, beam on elastic foundation problems, variable beam size problems, buckling problems, etc.

Purpose and Scope

12. The primary purpose of this report is to document four pile analysis-related finite difference computer programs (PX4C3, COM62, BENT1, and MAKE) and a structural beam-column program (BMCOL51), all developed at UT under the guidance of Professors L. C. Reese and H. Matlock. The subject area covered is rich in technical literature, and no attempt is made here to discuss the details of the methods of analyses. However, enough theory to explain the basis of the methods used in the computer programs is presented.

13. Finite difference approximations for laterally loaded piles (basis for program COM62) are presented in Part II and for axially loaded piles (basis for program PX4C3) in Part III. The UT pile group theory (basis for program BENT1) is discussed in Part IV. Some criteria for mathematically describing soil-structure interaction (basis for program MAKE) is presented in Part V. Part VI explains the discrete element theory used in BMCOL51 program. All five computer programs described in the report are documented with a general introduction, listing of program, flow charts, input data guide, and example problems with input-output data in Appendixes B, C, D, E, and F.

14. Most of the material presented herein has been covered in a number of earlier reports from the Center of Highway Research as well as other departments at UT. This report brings together the material needed to appreciate the power and limitations of the five computer programs selected. Liberal use of subject matter from References 2, 3, 15, 16, 22, and 31 and lecture notes on "Soil-Structure Interaction Courses" of Professors H. Matlock and L. C. Reese is gratefully acknowledged.

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PART II: FINITE DIFFERENCE APPROXIMATIONS FOR LATERALLY LOADED PILES

15. The computer code COM62 utilizes central difference approximations for describing the load-deformation response of laterally loaded piles. In addition, the code BENT1 (that predicts the load-deformation response of a pile-supported foundation) has COM62 as a subroutine for predicting the lateral load-deformation response of the individual piles in the foundation. In this part, central difference approximations for describing the elastic curve of a laterally loaded pile will be derived and used in formulating a set of simultaneous equations for describing the load-deformation response of a laterally loaded pile.

Formulation of Finite Difference Approximations

16. The finite difference approach to the solution of laterally loaded piles was first suggested by Gleser.⁴ This idea was further extended by a number of investigators including Reese and Matlock.^{5,6}

17. The first step in the formulation is the derivation of the central difference approximations for the elastic curve (Figure 1). It can be seen from this figure that the slope of the curve at sta i may be approximated by the secant drawn through the points on the curve of the two adjacent stations. Mathematically this step is expressed as

$$\left(\frac{\mathrm{d}y}{\mathrm{d}x}\right)_{i} \approx \frac{y_{i+1} - y_{i-1}}{2\mathrm{h}} \tag{1}$$

where h* denotes the increment length. For higher derivatives, the process could be repeated by taking simple differences and dividing by 2h each time. However, to keep the system more compact, temporary sta j and k are considered and the slopes at these points computed on the basis of the deflection of the station on either side. The second

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^{*} For convenience, symbols and unusual abbreviations are listed and defined in the Notation (Appendix A).



Figure 1. Geometric basis for central-difference approximations

derivative for each permanent station is then written as the difference between these slopes divided by one increment length in the following equation:

$$\left(\frac{\mathrm{d}^{2}y}{\mathrm{dx}^{2}}\right)_{i} = \frac{\left(\frac{\mathrm{d}y}{\mathrm{dx}}\right)_{k} - \left(\frac{\mathrm{d}y}{\mathrm{dx}}\right)_{j}}{h}$$

$$=\frac{y_{i+1} - 2y_i + y_{i-1}}{h^2}$$
(2)

Proceeding in a similar way, the third derivative is expressed as

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$$\begin{pmatrix} \frac{d^{3}y}{dx^{3}} \end{pmatrix} = \frac{\begin{pmatrix} \frac{d^{2}y}{dx^{2}} \\ \frac{d^{2}y}{dx^{2$$

and the fourth derivative as

$$\left(\frac{d^{4}y}{dx^{4}}\right)_{i} = \frac{\left(\frac{d^{3}y}{dx^{3}}\right)_{k} - \left(\frac{d^{3}y}{dx^{3}}\right)_{j}}{h}$$

$$=\frac{y_{i+2} - 4y_{i+1} + 6y_i - 4y_{i-1} + y_{i-2}}{h^4}$$
(4)

Development of Equations of Bending for Laterally Loaded Pile

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18. The second step in the formulation is the derivation of the differential equations for bending of a laterally loaded pile, and the substitution of the central difference approximations for the exact derivatives in the resulting differential equations. The differential equations are derived by considering an element of the pile (Figure 2). The sign of all forces, deflections, and slopes shown are positive. It should also be noted that the axial load is constant over the length of the pile. For piles this assumption is not consistent with observed behavior, since it is known that some of the applied axial load is transferred to the soil by skin friction along the shaft. The validity of this assumption is based on the fact that the errors introduced will be insignificant. Considering the problem from a physical standpoint,



Figure 2. Generalized beam-column element

it is known that for most cases the axial load transferred to the soil increases with depth. This, plus the fact that any lateral movement will cause a decrease in axial load transfer, leads to the conclusion that the axial load removed by the skin friction in the upper portion of the pile is small. Since the maximum deflection and moment occur in the top portion of the pile, and since it is the deflection of the pile top which is of interest, the assumption of constant axial load will not significantly affect the results of interest. 19. The reason for making the assumption of axial load being constant on the top of the pile is one of convenience. The addition of a variable axial load could have been handled analytically, but the effort required to obtain a solution would not be warranted because of uncertainties involved in obtaining the nature of the variation.

20. Referring to Figure 2, the equilibrium equations for the element may be written as

$$\frac{dM}{dx} - V + Q_c \frac{dy}{dx} = 0$$
(5)

and

$$\frac{\mathrm{d}\mathbf{V}}{\mathrm{d}\mathbf{x}} = -\mathbf{p} = -\mathbf{E}_{\mathbf{s}}\mathbf{y} \tag{6}$$

where

M = bending moment x = distance along axis of pile V = shear Q_c = in pile axial load constant y = lateral deflection p = lateral soil reaction per unit length E_s = soil modulus; lateral soil reaction (p) divided by lateral deflection (y)

By combining Equations 5 and 6 and differentiating, the following equation is obtained:

$$\frac{d^2 M}{dx^2} + E_s y + Q_c \frac{d^2 y}{dx^2} = 0$$
(7)

The equation for shear is written as

$$V = \frac{dM}{dx} + Q_c \frac{dy}{dx}$$
(8)

Consider that the deformation of the pile is caused only by the bending

moment. The following expression for moment can then be written:

$$M = EI \frac{d^2 y}{dx^2} = R \frac{d^2 y}{dx^2}$$
(9)

where

I = moment of inertia of pile section

R = EI (flexural rigidity)

Equation 9 is the basic expression for bending which states that the bending moment in the pile is equal to the product of the curvature of the elastic curve and the stiffness of the section.

21. At this point, the mechanics of the transfer of lateral load from a pile to the surrounding soil will be considered before proceeding further with the development of the finite difference equations of bending for a pile. In Equation 6 this load transfer is represented by the expression $p = E_y$.

22. When a lateral load is applied to the top of a pile, the load is transferred to the soil surrounding the pile as illustrated in Figure 3. A thin slice through the pile and surrounding soil is shown at a depth of x_1 below the ground surface. Before any lateral load is applied to the pile, the pressure distribution on the pile will be similar to Figure 3b. For this condition, the resultant force on the pile, obtained by integrating the pressure around the segment, will be zero. If, however, the pile is given a lateral deflection of y_1 at depth x_1 , the pressure distribution will be similar to Figure 3c. The integration of the pressure around the segment, for this condition, will yield a resultant force P_1 per unit length of pile, as shown in the above figure. The same procedure may be applied for a series of deflections, resulting in a corresponding series of forces which may be combined into a p-y curve. In a similar manner, p-y curves for any depth may be defined, resulting in a set of curves (Figure 4).

23. Implicit in the development thus far are the assumptions that the soil pressure is a linear function of deflection, the relationship being defined by the constant $E_{\rm g}$, and that the pressure at a

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a. REPRESENTATION OF PILE SEGMENT



c. PRESSURE DISTRIBUTION AFTER LOADING

Figure 3. Illustration of lateral load transfer

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Figure 4. Family of p-y curves

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particular point is independent of the deflections at all other points on the pile. Nonlinear soil behavior can be handled by relying on repeated applications of elastic theory where the constant coefficient of soil reaction is replaced by a secant modulus value. Figure 5 illustrates the secant modulus concept.

24. The second assumption leads to the representation of the soil by a set of independent springs as proposed by Winkler⁷ in 1867. If the effects of the soil pressure is considered to be concentrated at a finite number of points along the pile then, the pile-soil system can be represented by the model shown in Figure 6. This model is compatible with the finite difference equations which will be developed.



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Figure 5. Definition of secant modulus

Figure 6. Model of a laterally loaded pile

Formulation of Finite Difference Approximations for Equations of Bending of Laterally Loaded Piles

25. Equations 7, 8, and 9 may be written in finite difference by using the central-difference approximations for the first and second of the elastic curve. The equations will be written for a general point referred to as sta i. Station numbering increases from top to bottom of piles. The equations obtained for sta i are as follows:

$$y_{i+2}(R_{i+1}) + y_{i+1}(-2R_{i+1} - 2R_{i} + Q_{c}h^{2}) + y_{i}(R_{i+1} + 4R_{i})$$

+ $R_{i-1} - 2Q_{c}h^{2} + E_{si}h^{4} + y_{i-1}(-2R_{i} - 2R_{i-1} + Q_{c}h^{2})$
+ $y_{1-2}(R_{i-1}) = 0$ (10)

$$V_{i} = \frac{1}{2h^{3}} \left[y_{i+2}(R_{i+1}) + y_{i+1} \left(-2R_{i+1} + Q_{c}h^{2} \right) + y_{i}(R_{i+1} - R_{i-1}) + y_{i-1} \left(-Q_{c}h^{2} \right) + y_{i-2} \left(-R_{i-1} \right) \right]$$
(11)

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 $M_{i} = R_{i} \frac{y_{i+1} - 2y_{i} + y_{i-1}}{h^{2}}$ (12)

26. In the development of the equations, no consideration was given to the assumptions regarding the variation in pile bending stiffness (EI = R). For the case of pure bending and constant bending stiffness, the second derivative of moment is usually written as

$$\frac{d^2 M}{dx^2} = EI \frac{d^4 y}{dx^4}$$
(13)

For the case of pure bending and a variable bending stiffness, the second derivative of moment is expressed as

$$\frac{d^{2}M}{dx^{2}} = EI \frac{d^{4}y}{dx^{4}} + \frac{2d(EI)}{dx} \frac{d^{3}y}{dx^{3}} + \frac{d^{2}(EI)}{dx^{2}} \frac{d^{2}y}{dx^{2}}$$
(14)

However, in formulating the difference equations, the assumption was made that the moment was a smooth continuous function of x and that the second derivative of moment could be approximated by the expression

$$\frac{d^{2}M}{dx^{2}} \approx \frac{M_{i+1} - 2M_{i} + M_{i-1}}{2h}$$
(15)

where M_{i+1} , M_i , and M_{i-1} are the moment at joints i+1, i, and i-1, respectively. The use of Equation 15 gives the same expression as does Equation 13 but, for a variable stiffness, is a somewhat cruder approximation than Equation 14. However, it permits the bending stiffness to vary from station to station since Equation 12 can be substituted directly into Equation 15.

Solution of the Difference Equations

27. The final step is the formulation of a set of simultaneous equations which when solved yield the deflected shape of the pile. The solution requires the application of four boundary conditions since Equation 7 is actually a fourth order differential equation in terms of the dependent variable y. With values of deflection known, moment, shear, and soil reaction may be obtained for any location along the pile by back substitution of appropriate values of deflection into appropriate equations.

28. The pile is divided into n increments of length h (Figure 7). In addition, two fictitious increments are added to the top and bottom of the pile. The four fictitious stations are added for formulating the set of equations, but they will not appear in the solution or influence the results. The coordinate system and numbering system used is illustrated in the same figure.

29. The procedure used is to write Equations 10, 11, and 12 about sta n+3. This results in three equations involving five unknown

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Figure 7. Finite difference representative of pile

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deflections $(y_{n+5}, y_{n+4}, y_{n+3}, y_{n+2}, y_{n+1})$. Two boundary conditions, $V_{n+3} = 0$ and $M_{n+3} = 0$, are applied at sta n+3. The deflections for the fictitious sta n+4 and n+5 are eliminated from the three equations, and the deflection for sta n+3 is found in terms of the deflection at sta n+2 and n+3. The equation obtained may be written as

$$y_{n+3} = a_{n+3}y_{n+2} - b_{n+3}y_{n+1}$$
 (16)

where

$$a_{n+3} = \frac{4R_{n+2} - 2Q_{c}h^{2}}{2R_{n+2} - 2Q_{c}h^{2} + E_{s(n+3)}h^{4}}$$
(17)

and

$$b_{n+3} = \frac{2R_{n+2}}{2R_{n+2} - 2Q_ch^2 + E_s(n+3)^h}$$
(18)

Equation 10, written for sta n+2, can be combined with Equations 11 and 12 for sta n+3 and with Equation 16 to determine the deflection for sta n+2. The deflection y_{n+2} is found in terms of the deflection of sta n+1 and n. The equation obtained is as follows:

$$y_{n+2} = a_{n+2}y_{n+1} - b_{n+2}y_n$$
(19)

where

$$a_{n+2} = \frac{2R_{n+1} + (2R_{n+2} - Q_{c}h^{2})(i - b_{n+3})}{R_{n+1} + (2R_{n+2} - Q_{c}h^{2})(2 - a_{n+3}) + E_{s(n+2)}h^{4}}$$
(20)

and

$$b_{n+2} = \frac{R_{n+1}}{R_{n+1} + (2R_{n+2} - Q_{c}h^{2})(2 - a_{n+3}) + E_{s(n+2)}h^{\frac{1}{4}}}$$
(21)

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The deflection for sta n+1 may be found in a similar manner. From sta n+1 to the top of the pile the expressions for the deflection have the same form. The general form of the equation is as follows:

$$y_{i} = a_{i}y_{i-1} - b_{i}y_{i-2}$$
 (22)

where

$$\mathbf{a}_{i} = \frac{2R_{i-1} + R_{i}(2 - 2b_{i+1}) + R_{i+1}(a_{1+2}b_{1+1} - 2b_{i+1}) - Q_{c}h^{2}(1 - b_{i+1})}{c_{i}}$$
(23)

$$b_{i} = \frac{R_{i-1}}{c_{i}}$$
(24)

and

$$c_{i} = R_{i-1} + R_{i}(4 - 2a_{i+1}) + R_{i+1}(a_{i+1}a_{i+2} - b_{i+2} - 2b_{i+1} + 1) - Q_{c}h^{2}(2 - a_{i+1}) + E_{si}h^{4}$$
(25)

The terms, a_i , b_i , and c_i , are recursive coefficients and are defined for all stations along the pile during the solution procedure.

30. With the general expression, the deflection of each station may be expressed as a function of the deflection of the two stations immediately above it. If the deflections for sta 3, 4, and 5 are written, a set of three equations involving five unknown deflections will be obtained. If two boundary conditions are introduced, the deflections for the fictitious stations may be eliminated and the equations solved for the deflections. Once the deflections for sta 3 and 4 are found, the deflections for the remainder of the pile may be obtained by back substitution into the equations derived for the deflection of a station in terms of the deflection of the two stations directly above it.

31. The expressions obtained for y_3 and y_4 will depend on the boundary conditions applied to the top of the pile. Three sets of

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boundary conditions are used resulting in three sets of equations.

32. For the first case, the following boundary conditions are applied:

$$M_3 = M_t$$
(26)

$$V_3 = P_t$$
 (27)

where M_t and P_t are the moment and lateral load, respectively, applied to the top of the pile. The application of these boundary conditions results in the following expressions for y_3 and y_4 :

$$\mathbf{y}_{3} = \left\{ \lambda_{1} \left[R_{4} (2a_{5}b_{4} - 4b_{4}) + R_{3} (2 - 2b_{4}) + 2Q_{c}h^{2}b_{4} \right] + \lambda_{2}v_{2} \right\}$$

$$\left\{ v_{1} \left[R_{3} (2b_{4} - 2) + R_{4} (4b_{4} - 2a_{5}b_{4}) - 2Q_{c}h^{2}b_{4} \right] + v_{2} \left[R_{3} (4 - 2a_{4}) + R_{4} (2a_{4}a_{5} - 2b_{5} - 4a_{4} + 2) + Q_{c}h^{2} (-2 + 2a_{4}) + E_{s(3)}h^{4} \right] \right\}$$

$$(28)$$

and the second s

$$y_{l_{4}} = y_{l_{4}} \left(a_{l_{4}} - \frac{B_{l_{4}}v_{l}}{v_{2}}\right) - \frac{b_{l_{4}}\lambda_{l}}{v_{2}}$$
 (29)

where the boundary condition coefficients are defined as follows:

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$$\lambda_{1} = \frac{M_{t}h^{2}}{R_{3}}$$
(30)

$$\lambda_2 = 2P_t h^3 \tag{31}$$

$$v_1 = 2 - a_4$$
 (32)

$$v_2 = 1 - b_4$$
 (33)

33. The second set of boundary conditions applied is as follows:

$$V_3 = P_t$$
 (27 bis)

$$\left(\frac{\mathrm{d}y}{\mathrm{d}x}\right)_{3} = \frac{y_{4} - y_{2}}{2\mathrm{h}} = \Omega_{\mathrm{t}}$$
(34)

where Ω_t is the slope of the pile top. These boundary conditions result in the following expressions for y₃ and y₄:

$$y_{3} = \left\{ \lambda_{2} (1 + b_{4}) + \lambda_{3} \left[2R_{4} (2b_{4} - a_{5}b_{4}) + 2R_{3} (b_{4} - 1) - 2Q_{c}h^{2}b_{4} \right] \right\} / \left\{ 2R_{4} \left[a_{4}a_{5} - b_{5} - b_{4}b_{5} - 2a_{4} + 1 + b_{4} \right] + 4R_{3} (1 - a_{4} + b_{4}) + 2Q_{c}h^{2}(a_{4} - b_{4} - 1) + E_{s(3)}h^{4} \right\}$$
(35)

$$y_{l_{4}} = y_{3} \left(\frac{a_{l_{4}}}{1 + b_{l_{4}}} \right) + \frac{b_{l_{4}}\lambda_{3}}{1 + b_{l_{4}}}$$
(36)

where

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$$\lambda_3 = 2\Omega_t h \tag{37}$$

34. The third set of boundary conditions applied is as follows:

$$V_3 = P_t$$
 (27 bis)

$$\frac{M_3}{\Omega_3} = \frac{M_t}{\Omega_t}$$
(38)

These boundary conditions result in the following expressions for $\ensuremath{\,\,y_3}$ and $\ensuremath{\,y_4}$:

$$y_{3} = \lambda_{2} \left[1 - b_{\mu} + \lambda_{\mu} (1 + b_{\mu}) \right] / \left\{ 2\lambda_{\mu} (2R_{3} + 2R_{3}b_{\mu} - 2R_{3}a_{\mu} + R_{\mu}a_{\mu}a_{5} - R_{\mu}b_{\mu}b_{5} - 2R_{\mu}a_{\mu} + R_{\mu} + R_{\mu}b_{\mu} \right) + 2R_{\mu} (a_{\mu}a_{5} - 2a_{5}b_{\mu} - b_{5} + b_{\mu}b_{5} - 2a_{\mu} + 3b_{\mu} + 1) + 2Q_{c}h^{2}(a_{\mu} - b_{\mu} - 1 + a_{\mu}\lambda_{\mu} - \lambda_{\mu} - b_{\mu}\lambda_{\mu}) + E_{s3}h^{\mu} \left[1 - b_{\mu} + \lambda_{\mu} (1 + b_{\mu}) \right] \right\}$$
(39)
$$Y_{\mu} = \left[a_{\mu} - \frac{b_{\mu}(2 - a_{\mu} + a_{\mu}\lambda_{\mu})}{(1 + \lambda_{\mu} - b_{\mu} + b_{\mu}\lambda_{\mu})} \right] y_{3}$$
(40)

where

$$\lambda_{\downarrow} = \frac{M_{t}}{\Omega_{t}} \left(\frac{h}{2R_{3}}\right)$$
(41)

35. The values of y_3 and y_4 are used to begin the back substitution procedure to calculate deflections for the remainder of the stations along the pile. With the values of deflection thus established, values of moment, shear, and soil reaction may be computed for any station along the pile.

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PART III: FINITE DIFFERENCE APPROXIMATIONS FOR AXIALLY LOADED PILES

36. The computer code PX4C3 utilizes finite difference approximations for describing the load-deformation response of axially loaded piles. In addition, the code BENT1 (that predicts the load-deformation response of a foundation supported by a group of piles) requires the top load deformation curves of the individual piles in the foundation which is the particular response that is computed by PX4C3.

Mechanics of Axial Load Transfer

37. An axial load applied to the top of a pile is resisted by the shearing resistance developed along the shaft of the pile and the pressure on the base of the pile. The transfer of load from the pile to the soil is illustrated in Figure 8^8 and may be stated mathematically by the equation

$$Q_{t} = \int_{x=0}^{x=L} F \, dx + Q_{b}$$
 (42)

where

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Q_t = axial load applied to the top of a pile L = length of pile

- F = shear force per unit length transferred to the soil as a function of the location along a pile
- x = distance along axis of pile
- $Q_{\rm b}$ = load due to the normal pressure on the base of a pile

This equation involves only statics, and its solution will only assure that the forces on the pile are in equilibrium. It provides no insight into the deformation pattern that is necessary to produce the base pressure and shear transfer along the shaft for equilibrium. For the ultimate strength approach, this equation is sufficient since the deformations are not considered, and the assumption is made that the maximum base pressure and maximum shear transfer occur simultaneously. If,



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however, the load-deformation behavior of the pile is to be considered, the compatibility between loads and deformations must be considered. To represent this compatibility condition, another mathematical expression must be formulated relating load and deformation.

Development of Difference Equations

38. The derivation of an analytical expression for this purpose is suggested by Seed and Reese⁹ and expanded by Reese.¹⁰ Considering a segment of an axially loaded pile as shown in Figure 9, the expression



Figure 9. Element from an axially loaded pile

for the strain in the pile at depth x is given by

$$\frac{\mathrm{d}z}{\mathrm{d}x} = \frac{\mathrm{Q}}{\mathrm{E}\mathrm{A}} \tag{43}$$

where

z = axial movement of pile

Q = axial load in pile

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A = cross-sectional area of pile

This equation may be rearranged to yield

$$Q = EA \frac{dz}{dx}$$
(44)

Differentiation of Equation 44 with respect to x, assuming EA constant, yields

$$\frac{dQ}{dx} = EA \frac{d^2z}{dx^2}$$
(45)

Summing forces on the pile segment, shown in Figure 9, yields the equilibrium expression

$$\frac{\mathrm{dQ}}{\mathrm{dx}} = \mathrm{F} \tag{46}$$

The shear force per unit area is defined as

$$f = \frac{F}{C}$$
 (47)

where

f = shear force per unit area transferred to the soil as a function of the location along a pile

C = pile circumference

Equation 46 may now be written as

$$\frac{\mathrm{d}Q}{\mathrm{d}x} = \mathrm{fC} \tag{48}$$

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If ψ is a function which relates the shear stress to the relative deflection between the pile, and soil so that

$$\mathbf{f} = \psi \mathbf{z} \tag{49}$$

then Equation 48 may be written as

$$\frac{\mathrm{d}Q}{\mathrm{d}x} = \psi z C \tag{50}$$

Equations 45 and 50 may be equated for $\frac{dQ}{dx}$ yielding

$$EA \frac{d^2 z}{dx^2} = \psi_Z C$$
(51)

which is the desired compatibility expression. To obtain a solution for

Equation 51, the function ψ and two boundary conditions must be known. For realistic problems, considering nonlinear soil behavior, the function ψ usually cannot be defined analytically, and a numerical solution is necessary.

39. A numerical solution to the nonlinear differential Equation 51 is suggested by Seed and Reese,⁹ Reese,¹⁰ and Coyle and Reese.¹¹ The first step in obtaining a solution is to write Equation 51 in finite difference form. Referring to Figure 10, the difference form of the equation for sta i may be written as



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Figure 10. Load distribution along an axially loaded pile

$$\frac{\left(\frac{dz}{dx}\right)_{i-1} - \left(\frac{dz}{dx}\right)_{i+1}}{2h} = \frac{\psi_i z_i^{C_i}}{EA}$$
(52)

Substituting Equation 43 into Equation 52 and simplifying yields

$$Q_{i-1} - Q_{i+1} = 2h\psi_i z_i C_i$$
(53)

which is the desired form of the equation. Equation 44 can also be written in difference form as

$$\frac{Q_{i}}{EA} = \frac{z_{i-1} - z_{i+1}}{2h}$$
(54)

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$$\frac{2hQ_{i}}{EA} = z_{i-1} - z_{i+1}$$
(55)

40. Equation 53 is simply a statement that the difference between the forces in the pile at sta i+l and i-l is equal to the load transferred to the soil between these two points. Equation 55 is simply a statement that the deformation that occurs in the pile over a segment 2h in length can be computed from the strain at the midpoint of the seg-

ment which is equal to the load in the pile at the midpoint of the segment divided by the product of the pile area and modulus of elasticity. Furthermore, the load distribution within the pile is assumed to be linear between these two points. The slope of the straightline load distribution is approximated by the rate of load distribution at the midpoint between sta i+l and i-l. This procedure results in a concentration of the shear force, $h\psi_i z_i C_i$, at sta i. The physical significance of this assumption leads to the mechanical model of an axially loaded pile, illustrated in Figure 11. The mechanical model can be used to develop equations which are analogous to Equations 54 and 55 and to formulate a procedure for solving the equations, which will yield the desired




load-deformation response of an axially loaded pile.

Development of Mechanical Model and Equations for Model

41. The mechanical model represents the pile by n springs, of length h, connected by rigid joints (Figure 11). The springs, representing the pile, are linear and have a spring constant as shown. The nonlinear springs, representing the load transfer to the soil, are attached to the rigid joints. The spring attached to joint 1 will represent the load transferred from the ground surface to a depth of h/2. The spring attached to joint n+1 will represent the load transferred to the soil through the pressure on the pile base rather than through shear along the pile shaft as it is for all other springs. The spring attached to joint n will represent the load transferred from the



Figure 12. Joint j of the mechanical model of

an axially loaded pile

base. The interior springs represent the load transferred over a distance of h/2 above and below the joint. The concentration of the shear transfer for an arbitrary interior joint represented by force SF is illustrated in Figure 12. Summing forces on a joint yields:

pile base to a distance of 3h/2 above the

$$Q_{j-1} - Q_j = SF_j = h\psi_j C_j z_j$$
(56)

This equation is the same as Equation 53 except it considers only the load change or transfer over one increment rather than two.

Solution Procedure for Equations

42. If curves are available describing the load transfer, Equation 56 can be used to obtain the load-deformation behavior of the pile. The solution procedure may be formulated by considering the mechanical

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model in Figure 11. If a load Q_t is applied to joint 1, the model will deform in such a way that conditions of equilibrium and compatibility are satisfied. The first step in the procedure is to assume a deflection of the pile base. From the nonlinear spring at joint n+1, the force SF_{n+1} may be found for the assumed deflection. The force Q_n may now be found by considering the equilibrium of joint n+1, and solving Equation 56 at sta n+1. Solution of this equation yields $Q_{n+1} = SF_{n+1}$. With the force Q_n known, the deflection z_n may be obtained by considering the deformation in the linear spring between sta n and n+1. The deflection is expressed mathematically as

$$z_n = z_{n+1} + \frac{Q_n h}{(EA)_n}$$
(57)

With z_n and Q_n known, Equations 56 and 57 may be solved for each joint and spring until the top of the pile is reached. This procedure will yield a top load Q_t and a top deflection z_1 . Additional values may be assumed for the base deflection, and the procedure repeated until a complete load-deflection curve is obtained for the top of the pile.

43. It should be noted that in the derivation of Equations 54 and 55 it was assumed that EA was constant. With the mechanical model and for Equations 56 and 57, this assumption was not necessary. It is only necessary that EA be constant over each increment length.

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PART IV: PILE GROUP THEORY

44. The computer program BENT1 provides a method for analyzing foundations which are supported on pile groups consisting of vertical and batter piles. The procedures are similar to those described by Reese and Matlock.¹²⁻¹⁴ In this part, equations for describing the load-deformation response of a pile-supported foundation will be developed.

Coordinate Systems and Sign Conventions

45. Two types of coordinate systems are established as shown in Figure 13. A horizontal axis u and a vertical axis v are



Figure 13. Geometry of foundation

established relative to the foundation. Foundation movements, forces, and dimensions are related to these axes. The location of this system is completely arbitrary, but proper location will simplify calculations for most foundations.

46. For each pile an x-y coordinate system is established. The x axis is parallel to the pile and the y axis is perpendicular to the pile. Subscripts are used to indicate the particular pile. Pile deflection and forces are related to these systems.

⁴7. The coordinates of the pile heads as related to the u-v axes are all positive for the example (Figure 13). The batter of the piles is positive counterclockwise from the vertical and negative clockwise from the vertical as shown. The variable θ will be used to denote the angular measure of pile batter.

48. The external loads on the foundation are resolved into a vertical and horizontal component through the origin of the structural coordinate system and a moment about the origin. The sign convention established is illustrated in Figure 14.

49. The external loads M_e , P_v , and P_u will cause the foundation to move. If the u-v coordinate system is considered to be rigidly attached to the foundation, the movement of the foundation may be related to the movement of the coordinate system. These



Figure 14. Sign convention for foundation forces and movements

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movements (Δ_{v} , Δ_{u} , and Γ) are shown with positive signs (Figure 1^h).

50. Due to the movement of the foundation, forces will be exerted on the foundation by the piles. The sign convention for these forces is illustrated in Figure 15 in two ways: (a) conventions consistent with





a. FORCES AND MOMENT STRUCTURAL SIGN CONVENTION b. FORCES AND MOMENT-PILE SIGN CONVENTION

Figure 15. Forces and moment on pile head



51. The sign conventions for movements of the pile head (Figure 16) are consistent with the x-y coordinate system. A movement in the positive x direction, which constitutes an axial compression, is considered as a positive movement. A movement in the positive y direction



Figure 16. Pile-head movements on the x-y coordinate system

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is considered as a positive movement. A rotation of the pile head will cause a change in the slope at the top of the pile. The sign convention for slope is consistent with the usual manner in which slope is defined.

Relations Between Foundation Movements and Pile-Head Movements

52. When the structure moves, the pile heads move. Two assumptions are made in order to relate structure movement to pile-head movements. The first assumption is that the foundation is rigid so that the pile heads maintain the same relative positions before and after movement. Because of this assumption the approximation

$$\Gamma \approx \tan \Gamma$$
 (58)

is valid.

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53. In Figure 17a, diagrams are given of the lineal movements at the pile head of a given pile in terms of the structural movements. The movement of the structure is defined by the shift of the u-v axes to the position indicated by the u'-v' axes. The total movement of the pile head is resolved into a component parallel to the u axis $(\Delta_{\mu} + v\Gamma)$ and a component parallel to the v axis $(\Delta_{\mu} + u\Gamma)$.

54. Figure 17b illustrates the resolution of the horizontal and vertical components of movement into components parallel and perpendicular to the direction of the pile. These movements are designated as x_t and y_t . From the same figure, the axial component of pile-head movement may be written as

$$x_{t} = (\Delta_{y} + v\Gamma) \sin \theta + (\Delta_{y} + u\Gamma) \cos \theta$$
(59)

and the corresponding lateral movement as

$$y_{t} = (\Delta_{y} + v\Gamma) \cos \theta - (\Delta_{y} + u\Gamma) \sin \theta$$
 (60)



55. In addition to the lineal displacements of the pile head, the change in slope of a tangent to the elastic curve will be considered. The change in the slope will depend on the manner in which the pile is attached to the foundation. If the pile is fixed to the structure, then the change in slope will be equal to the rotation of the foundation. For the restrained case the change in slope will depend on the moment applied to the pile top. For a pinned connection the slope will depend on the deflected shape of the pile.

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Relations Between Foundation Forces and Pile Reactions

56. The forces acting on the foundation and pile are illustrated, along with sign convention, in Figure 15. It has been noted that inconsistencies in the sign conventions are present. However, these will be corrected while deriving the relations between the forces.

57. From Figure 15, the relationship between moments on the structure and moment on the pile may be expressed as

$$M_{s} = -M_{t}$$
(61)

The relations between forces are obtained by resolving the forces on the pile into components in the horizontal and vertical directions. With the sign conventions considered, the components are summed as follows:

 $F_{v} = P_{t} \sin \theta - Q_{t} \cos \theta$ (62)

$$F_{\rm u} = -Q_{\rm t} \sin \theta - P_{\rm t} \cos \theta \tag{63}$$

Relations Between Pile-Head Movement and Pile Reaction

58. In the preceding paragraphs the movement of the pile head and the forces acting on the pile head have been defined. Relations between

pile reaction and movement will be developed below.

59. For computational purposes the pile shown in Figure 18a may be simulated by the set of springs as shown in Figure 18b. The springs





a. PILE AND FOUNDATION b. SPRINGS AND FOUNDATIONS

Figure 18. Spring representation of pile = = = -

will produce a force parallel to the pile axis, Q_t , and a force acting perpendicular to the pile axis, P_t . The rotational spring will yield a moment about the pile top, M_t .

60. The forces produced by the springs will depend on the deflection of the springs. Since the springs are nonlinear, the movement and reaction are not related by a single constant. It is assumed that curves can be obtained which show spring reaction as a function of deflection. In Figure 19, a hypothetical set of load-deflection curves are drawn for a set of springs. If the curves are single valued, then the spring reactions may be calculated for a particular deflection by

 $Q_{t} = J_{x} x_{t}$ (64)

$$P_{t} = J_{y}y_{t}$$
(65)

$$M_{t} = J_{m} y_{t}$$
(66)

where J_x , J_y , and J_m are the secant modulus values as illustrated in the figure.

61. It should be noted that the moment produced by the rotational

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spring is proportional to the lateral deflection rather than the rotation. For a rotational spring this procedure is inconsistent with usual concepts. This concept is used because it provides a convenient means for deriving and solving the equilibrium equation for the structure.

62. The curves in Figure 19 do not adequately explain the behavior of a pile. It is not necessary that the exact nature of the curves be known. The representation shown is only for the formulation of the equilibrium equations. The procedure for calculating values for J_x , J_y , and J_m will be discussed in the following paragraphs. However, for the formulation of the equilibrium equations, Equations 64-66 are sufficient, since they will be applicable no matter what kind of relationship exists between the loads on the pile tops and the resulting displacements.

Equilibrium Equations

63. The relations between forces and movements for the structure and the pile, previously developed, will now be combined to form three equations of equilibrium for the structure. The form of the equations is such that an iterative type solution may be used. This is necessary since the system is nonlinear.

64. Consider a foundation supported by n piles. The coordinate system and the ith pile are shown in Figure 20. The external loads



Figure 20. Forces on the piles and foundation

applied to the foundation are resolved into the forces and moment through and about the origin of the coordinates. The forces and moment exerted by each pile are designated as F_{vi} , F_{ui} , and M_{si} in the figure. The three equations are obtained by summing forces in the horizontal and vertical directions and by summing moments about the origin of the u-v coordinate system. Performing these operations the equilibrium equations may be written as

$$\sum_{i=1}^{n} F_{vi} + P_{v} = 0$$
 (67)

$$\sum_{i=1}^{n} F_{ui} + P_{u} = 0$$
 (68)

 $\sum_{i=1}^{n} (M_{si} + u_{i}F_{vi} + v_{i}F_{ui}) + M_{e} = 0$ (69)

where M_{e} , P_{u} , and P_{v} symbolize external moment horizontal force, and vertical force applied to the foundation at the origin of u-v coordinate system. Substituting Equations 61-63 into Equations 67-69 and rearranging

$$P_{v} = \sum_{i=1}^{n} (Q_{ti} \cos \theta_{i} - P_{ti} \sin \theta_{i})$$
(70)

$$P_{u} = \sum_{i=1}^{n} (P_{ti} \cos \theta_{i} + Q_{ti} \sin \theta_{i})$$
(71)

$$M_{e} = \sum_{i=1}^{n} \left[M_{ti} + u_{i} (Q_{ti} \cos \theta_{i} - P_{ti} \sin \theta_{i}) + v_{i} (P_{ti} \cos \theta_{i} + Q_{ti} \sin \theta_{i}) \right]$$
(72)

Substituting Equations 64-66 into Equations 70-72 the equilibrium equations may be expressed as

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$$P_{v} = \sum_{i=1}^{n} (J_{xi}x_{ti} \cos \theta_{i} - J_{yi}y_{ti} \sin \theta_{i})$$
(73)

$$P_{u} = \sum_{i=1}^{n} (J_{yi}y_{ti} \cos \theta_{i} + J_{xi}x_{ti} \sin \theta_{i})$$
(74)

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$$M_{e} = \sum_{i=1}^{n} \left[-J_{mi} y_{ti} + u_{i} (J_{xi} x_{ti} \cos \theta_{i} - J_{yi} y_{ti} \sin \theta_{i}) + v_{i} (J_{yi} y_{ti} \cos \theta_{i} + J_{xi} x_{ti} \sin \theta_{i}) \right]$$
(75)

The equations are modified further by substituting equations \cdot 59 and 60 into Equations 73-75 and rearranging to obtain

$$P_{v} = \sum_{i=1}^{n} \left\{ \left(J_{xi} \cos^{2} \theta_{i} + J_{yi} \sin^{2} \theta_{i} \right) \Delta_{v} + \left[\left(J_{xi} - J_{yi} \right) \sin \theta_{i} \cos \theta_{i} \right] \Delta_{u} + \left[u_{i} \left(J_{xi} \cos^{2} \theta_{i} + J_{yi} \sin^{2} \theta_{i} \right) + v_{i} \left(J_{xi} - J_{yi} \right) \sin \theta_{i} \cos \theta_{i} \right] r \right\}$$
(76)
$$P_{u} = \sum_{i=1}^{n} \left\{ \left[\left(J_{xi} - J_{yi} \right) \left(\sin \theta_{i} \cos \theta_{i} \right) \right] \Delta_{v} + \left(J_{yi} \cos^{2} \theta_{i} + J_{xi} \sin^{2} \theta_{i} \right) \Delta_{u} + \left[u_{i} \left(J_{xi} - J_{yi} \right) \sin \theta_{i} \cos \theta_{i} + \left(v_{i} J_{yi} \cos^{2} \theta_{i} + J_{xi} \sin^{2} \theta_{i} \right) \right] r \right\}$$
(77)

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$$M_{e} = \sum_{i=1}^{n} \left\{ \begin{bmatrix} J_{mi} \sin \theta_{i} + u_{i} (J_{xi} \cos^{2} \theta_{i} + J_{yi} \sin^{2} \theta_{i}) \\ + v_{i} (J_{xi} - J_{yi}) \sin \theta_{i} \cos \theta_{i} \end{bmatrix} \Delta_{v} + \begin{bmatrix} -J_{mi} \cos \theta_{i} \\ -J_{mi} \cos \theta_{i} \end{bmatrix} \\ + u_{i} (J_{xi} - J_{yi}) \sin \theta_{i} \cos \theta_{i} + v_{i} (J_{yi} \cos^{2} \theta_{i} + J_{xi} \sin^{2} \theta_{i}) \end{bmatrix} \Delta_{u} \\ + \begin{bmatrix} J_{mi} (u_{i} \sin \theta_{i} - b_{i} \cos \theta_{i}) + u_{i}^{2} (J_{xi} \cos^{2} \theta_{i} + J_{yi} \sin^{2} \theta_{i}) \\ + v_{i}^{2} (J_{yi} \cos^{2} \theta_{i} + J_{xi} \sin^{2} \theta_{i}) + 2 (J_{xi} - J_{yi}) (\sin \theta_{i} \cos \theta_{i}) u_{i} v_{i} \end{bmatrix} \Gamma \right\}$$
(78)

65. Equations 76-78 constitute a complete set of equilibrium equations for a foundation. The loads on the foundation, the distance to the pile tops, and the batter of the piles are known quantities. If the spring modulus values are known, the three equations may be solved simultaneously for Δ_v , Δ_u , and Γ . However, since the system is nonlinear, J_m , J_x , and J_y will not be constants. Thus, an iterative solution is required. The procedure utilized for solving the equilibrium equations is described in the following paragraphs.

Computational Procedure for Solution of Equilibrium Equations

66. The iterative procedure used for the solution of the equilibrium equations is illustrated in Figure 21. The iterative procedure is necessary for establishing the deflected position of the foundation so that equilibrium and compatibility are satisfied.

67. To begin the procedure, values of Δ_v , Δ_u , and Γ are set equal to zero. In addition, the deflections of each pile top (x_{ti}, y_{ti}) are set equal to one. These values are used only for starting the iterative procedure and have no bearing on the final solution.

68. Values of x_{ti} are used directly with load-deflection curves for the individual piles to obtain values of J_{xi} . A typical loaddeflection curve and the procedure for computing J_{xi} are shown in Figure 22. The use of a unique single valued curve for the axial loaddeflection response of a pile is based on the assumption that the axial behavior of a pile is unaffected by any lateral effects. That is to say, the axial load on the pile is dependent only on the axial deflection of the pile. This is not rigorously correct since it is known that lateral forces on the pile top will cause lateral movement which will decrease the axial load carrying capacity of the pile. However, for realistic situations the influence of the lateral forces on the axial response will be small and thus is ignored in this procedure.

69. Values of $y_{t,i}$ are used with a lateral loaded pile

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Figure 21. Block diagram for iterative solution



Figure 22. Axial load-settlement curve

subroutine, similar to COM62, to obtain values of J_{yi} and J_{mi} . The subroutine requires two boundary conditions for the top of the pile. For the initial iteration, one of these boundary conditions is that the lateral deflection of the top of the pile is 1 in.* The second boundary

^{*} A table of factors for converting U. S. customary units of measurement to metric (SI) units is presented on page 4.

condition will depend on the manner in which the pile is connected to the foundation and is set equal to zero. For pinned connections this means that the moment at the pile top is zero, for fixed connections the slope at the pile top is set equal to zero, and for restrained connections the stiffness of the rotational restraint spring is set equal to zero. In addition to the above boundary conditions, the axial forces applied to the top of the piles are obtained directly from the axial load-deformation curves. The axial forces are included because it is felt that these forces significantly affect the lateral response of the piles. However, this is contrary to what is assumed for the effects of lateral forces on the axial response. The reasoning for these assumptions are as follows:

- a. The majority of the axial load is transferred to the soil in the lower part of the pile. For practical problems the lateral forces only cause significant lateral movement in the upper part of the pile where the axial load transfer is small--hence, the assumption that lateral forces have little influence on the axial response.
- b. The majority of the lateral load is transferred to the soil in the upper part of the pile. This means that the maximum deflections, bending moments, and lateral soil reactions occur near the top of the pile. Because the axial forces in the pile may be quite large near the top, the effects on the lateral behavior may be significant--hence, the inclusion of the effects of axial load on lateral behavior.

70. With the initial boundary conditions, the finite difference equations for the piles are solved and values of moment and shear at the pile top computed. With the moment and shear at the pile top known, values of J_{yi} and J_{mi} are computed by dividing the moment and shear by the top deflection which is 1 in. for the initial iteration.

71. With spring moduli for each pile, the equilibrium equations for the foundation movement are solved for Δ_v , Δ_u , and Γ . The new values of Δ_v , Δ_u , and Γ are then used to start the second iteration.

72. To start the second and each preceding iteration, deflections of the pile top (x_{ti} and y_{ti}) are computed using current values of Δ_v , Δ_u , and Γ . New values of J_{xi} are computed directly from

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the load deflection curves for the individual piles as was done for the initial iteration. To calculate new values of J_{yi} and J_{mi} , it is necessary to establish boundary conditions for the top of the pile as was done for the initial iteration. One boundary condition is the lateral load at the top of the pile. The lateral load is found by multiplying J_{yi} from the previous iteration by y_{ti} . The second boundary condition will depend on the manner in which the pile is connected to the foundation. For pinned conditions the second boundary condition is that the top moment is zero. For fixed connections the slope at the top of the pile is set equal to the rotation of the structure (Γ). For restrained connections the second boundary condition is that stiffness of the rotational restraint spring. The axial forces are computed by multiplying J_{xi} by x_{ti} . With the boundary conditions established the remainder of the procedure is the same as for the initial iteration.

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73. The values of Δ_v , Δ_u , and Γ are compared with values from the previous iteration. The correct solution is obtained when the movements agree within the specified allowable tolerance. If closure is not obtained, the procedure is repeated. If closure is obtained, a control is set and the forces and moments exerted by each pile on the foundation are computed. In addition, the deflected shape, moment distribution, and soil reaction for each pile are calculated.

74. A computer program GROUP, developed by Dr. Katsuyuki Awoshika and Prof. L. C. Reese¹⁵ at the University of Texas, is currently available. GROUP can perform the same type of analysis as BENT1 but is considered more general and efficient.

PART V: CRITERIA FOR DEVELOPING SOIL-PILE INTERACTION CURVES

75. The UT method of analysis for single piles (loaded laterally or axially) and group of piles (discussed previously) requires the development of nonlinear soil resistance-pile movement curves for both lateral and axial loading conditions. This subject is quite complex, and no attempt will be made in this report to review the work that has been done in this area. A concise presentation on this topic is given by Awoshika and Reese¹⁵ and Parker and Cox;¹⁶ the material in this part is principally extracted from these two reports. The discussions here will be limited to the establishment of criteria that are used internally in the computer codes documented in this report.

76. The actual pile-soil systems are quite complex and the interaction will be affected by a number of parameters, such as time effect on soil behavior, disturbance of soil due to pile driving/placing, cyclic loading of soil, settlement of the soil surrounding the pile due to negative skin friction, and interference of adjacent piles. The criteria presented have been derived for static, short-term loading conditions and are based on semi-empirical considerations.

77. Soil criteria for lateral and axial loading conditions are developed separately. Also, the criteria are developed separately for two common but extreme soil types, clay and sand. One may expect other soils to exhibit characteristics somewhere between those for clay and sand.

Laterally Loaded Pile

78. In Part III, the effect of the soil on a laterally loaded pile was shown as a distributed reaction p. The soil reaction p was defined as

$$\mathbf{p} = \mathbf{E}_{\mathbf{g}} \mathbf{y} \tag{79}$$

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where E_s is the soil modulus and y is the lateral deflection. The soil modulus values vary generally with p and y in a nonlinear manner. The subsequent paragraphs discuss the methods to obtain these p-y curves.

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79. The p-y curves will depend on the soil properties. For most cases the properties of the soil in a profile are not constant with depth, the usual case being that the strength of the soil increases with depth. A typical variation of shear strength of soil with depth is shown in Figure 23a. Since the strength of the soil will affect the p-y curves obtained, a variation similar to that illustrated in Figure 23b might be expected. It should be pointed out that the shear strength is not the only parameter which will affect the p-y curve, although it does have considerable influence. The purpose of the variation shown in Figure 23b is only to illustrate the variability of the p-y relation.

Soil Criteria

80. Soil resistance movement for both clays and sands are constructed assuming that the p-y curves can be divided into two segments. These two segments are designated as O-A and A-B in Figure 24. The segment O-A represents the early part of the curve, and the segment A-B, the ultimate part of the curve. Because of this division, the construction of p-y curves may be carried out in two steps. First, the ultimate soil resistance is calculated and then the shape of the early part of the curve is obtained. Secondly, the horizontal line representing the ultimate soil resistance and the early part of the curve are then joined to form a continuous curve. In the following paragraphs the procedure will be explained first for clay and then for sand. Criteria for clay

81. For clay two methods are employed to obtain p-y curves. If stress-strain data are available, the method proposed by McClelland and Focht¹⁷ is used, with one modification. For this method stress-strain



Figure 24. Construction of p-y curve

curves, similar to the one shown in Figure 25, are required. The curve is obtained from a triaxial test in which the confining pressure σ_3



is as close as possible to the confining pressure on the soil in the field. McClelland and Focht recommend that the p-y curve be obtained by using the following relations:

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 $p = 5.5 d\sigma_{\Lambda}$ (80)

and

$$y = 1/2d\varepsilon \tag{81}$$

where

d = diameter of pile or equivalent diameter σ_{Δ} = soil deviator stress $(\sigma_1 - \sigma_3)$ from triaxial compression test in psi ϵ = axial soil strain from triaxial compression test 82. Skempton¹⁸ has suggested the following relationship for calculating deflections of footings: An average value to use for deflection would be one between the values

calculated using Equations 81 and 82. The equation suggested is

$$y = d\varepsilon$$
 (83)

(82)

Using Equations 80 and 83 and the stress-strain curve, a corresponding p-y curve may be obtained.

83. It is assumed that the test is run until failure is obtained. That is, the maximum value for σ_{Δ} obtained will represent the ultimate value which may be carried by the soil. Consequently, the value for p calculated using the ultimate value of σ_{Δ} is considered to be the ultimate soil resistance.

Reese's criteria

84. If no stress-strain curves are available, but the shear strength and unit weight are known, p-y curves can be obtained. Two expressions are available for calculating the ultimate soil resistance for clay. These equations suggested by Reese¹⁹ are as follows:

$$p_{u} = \gamma dX + 2cd + 2.83cX$$
 (84)

and

$$p_{ij} = llcd$$
 (85)

where

 γ = effective unit of soil

X = depth from soil surface

c = cohesion of clay

Equations 84 and 85 are usually plotted (Figure 26), and the smaller of the two values is used in constructing p-y curves. Equation 84 will control near the surface since it is based on the occurrence of a wedgetype failure, and Equation 85 will control at depth since it is based on



Figure 26. Ultimate soil resistance for clays

the soil failing by flowing around the pile. At such depths, there is sufficient restraint to prevent the upward movement of the soil. Early part of curve

85. The early part of the curve is obtained by Equations 80 and 83. Since no stress-strain curve is available, values of σ_{Δ} and ε must be found. These are found by approximating the stress-strain curve. The following assumptions are made for drawing approximate stress-strain diagrams:

$$\sigma_{\Delta 50} = c = q_u/2$$

$$\varepsilon_{50} = 0.005 \text{ (brittle or stiff clays)}$$

$$\varepsilon_{50} = 0.02 \text{ (soft plastic clay)}$$

$$\varepsilon_{50} = 0.01 \text{ (no consistency data available)}$$

where

 $\sigma_{\Delta 50}$ = deviator stress corresponding to 50 percent strain

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The values of

^σΔ50

$$\varepsilon_{50} = 50$$
 percent of the maximum axial strain from triaxial compression test

and ε_{50} are plotted as shown in Figure 27. A

 $o_{\Delta 50}$

Figure 27. Approximate log-log plot of stress-strain curve

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straight line with a slope of 0.5 is drawn through this point to represent the stress-strain curve for the soil. With this curve the early part of the curve may be obtained by applying Equations 80 and 83. <u>Criteria for sand</u>

86. For sand the following two equations for calculating the ultimate soil resistance¹⁹ are used:

$$p_{u} = \gamma dX \left[\frac{\tan \beta}{\tan(\beta - \phi)} - K_{A} \right] + \gamma X^{2} \left[\frac{\tan^{2}\beta \tan \alpha}{\tan(\beta - \phi)} + \frac{K_{o} \sin \beta \tan \phi}{\cos \alpha \tan(\beta - \phi)} + K_{o} \tan \beta \tan \phi \sin \beta - K_{o} \tan \beta \tan \alpha \right]$$
(86)

and

$$p_{u} = \gamma dX \left\{ \left(\tan^{2} 45^{\circ} - \frac{\emptyset}{2} \right) \left[\tan^{8} \left(45^{\circ} + \frac{\emptyset}{2} \right) - 1 \right] + K_{o} \tan \emptyset \tan^{4} \left(45^{\circ} + \frac{\emptyset}{2} \right) \right\}$$
(87)

where

$$\beta = 45^{\circ} + \emptyset/2$$

$$\emptyset = \text{angle of internal friction of sand}$$

$$K_A = \text{active earth pressure coefficient}$$

$$K_o = \text{coefficient of earth pressure at rest}$$

$$\alpha = \begin{cases} \emptyset/2 \text{ to } \emptyset/3 \text{ (loose sand)} \\ \emptyset \text{ (dense sand)} \end{cases}$$

Equation 86 is for wedge-type failure (near surface), and Equation 87 is for flow around failure (at depth). Equations 86 and 87 are shown plotted in Figure 28a. The lower of the two values obtained from the equations will be used in constructing the p-y curves.

Early part of curve

87. The early part of the curve is obtained by applying theory developed by Terzaghi.²⁰ This results in a linear variation between p and y, with the slope defined as

Slope =
$$\frac{H\gamma X}{1.35}$$
 (88)

where H is the constant depending on relative density of sand. Suggested values for H are 200 for loose sand, 600 for sand with medium density, and 1500 for dense sand. The unit weight used is the effective unit weight.

88. If the slope of the early part of the curve is known, the p-y curve can be constructed by connecting a straight line through the origin, with a slope (expressed by Equation 88) to the horizontal line defined by the ultimate soil resistance. This results in a p-y curve which consists of two straight lines (Figure 28b). When one considers the behavior of a sand, it will be noted its behavior is not linear.

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Figure 28. Reese's criteria for p-y curves in sands

As a result, the p-y curve obtained should be considered as an approximation.

Program MAKE

89. A computer program MAKE, documented in Appendix B, is programmed for computing Equations 80 through 88. The program can also produce p-y curves at various depths and various size piles embedded in clays or sands.

Other criteria for computing p-y curves

90. There are various other criteria for computing p-y curves for laterally loaded piles in clays and sands. Worthy of particular mention are Matlock's²¹ criteria for constructing p-y curves for static and cyclic loading in soft clay and Parker and Reese's²² criteria for developing p-y curves in sands. A summary of these two and other criteria is contained in Reference 15.

General comments on p-y curves

91. It must be emphasized that the procedures explained herein to develop p-y curves are based on semi-empirical relations. This points out that these procedures need to be carefully evaluated with regard to the problem environment before being used in analyses. Perhaps the most important consideration regarding p-y curves is whether or not there are validating experimental results. The oil industry has funded several experimental (both laboratory and field) programs to obtain confidence in the methods employed for constructing these curves. When the results become available in the public domain, the level of confidence in the techniques proposed is likely to increase.

Axially Loaded Pile

Type of interaction curves needed

92. The mechanics of the axially loaded pile problem described in Part II requires the determination of a set of load transfer curves along the pile and the point resistance curve at the tip of the pile. The load transfer curve refers to a relationship between the skin friction developed on the side of a pile and the absolute axial displacement of a pile section. The point resistance curve expresses the total axial soil resistance on the base of the pile tip in terms of the pile-tip movement.

Factors affecting interaction curves

93. The properties of soil which determine the load transfer curve and the point resistance curve may be considerably affected by

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pile driving. In the case of clays, Seed and Reese⁹ reported that soon after the pile driving a loss in shear strength was observed in clays adjacent to the pile equal to 70 percent of that for total remolding. They also observed that the recovery of shear strength with the passage of time resulted in a five-fold increase in the load-carrying capacity of a pile, even in insensitive clays. As is pointed out by Kishida,²³ the pile driving in a loose sand results in the increase in the relative density and in the confining pressure, both of which are major factors affecting the load transfer curves and the point resistance curve. The action of arching observed in sands around a pile (Robinsky and Morrison²⁴), may be another important factor to be considered.

94. In spite of all these complex factors, presently available soil criteria are based only on the soil properties before pile driving. In view of the fact that the effect of different methods of pile installation on the soil properties with the passage of time are excluded from the soil criteria, in the following paragraphs the soil criteria described must be regarded as tentative.

Criteria for Clay

Coyle and Reese's criteria for load transfer curves

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95. To develop soil criteria for the load transfer curves for a pile in clays, Coyle and Reese¹¹ proposed (after Woodward, Lundgren, and Boitano²⁵) a reduction factor K to express the relationship between the cohesion of a clay and the shear strength that can be assumed to be effective in resisting axial load on a pile. Figure 29 shows that the reduction factor K is less than unity if the shear strength of a clay is over 1000 psf.

96. Coyle and Reese expressed the rate of load transfer developed on the side of a pile as a function of absolute pile movement. Curves were given for various depths (Figure 30).

97. The procedure for developing a load transfer curve for the side of a pile is summarized as follows:



Figure 30. Nondimensional load transfer curves of a pile in clays

- Step 1. Estimate the distribution of cohesion of the clays along the length of the pile from available soil data.
- Step 2. Compute the effective shear strength as a function of depth from Figure 29 using the reduction factor K.
- Step 3. Obtain the distance from the ground surface to the midpoint of the section where the load transfer curve needs to be developed.
- Steo 4. Select the curve A, B, or C in Figure 30 depending on the depth.
- Step 5. Choose a pile movement; obtain the ordinate from the selected curve in Figure 30.
- Step 6. Compute load transfer for the selected pile movement by multiplying the ordinate obtained in step 5 by the effective shear strength obtained in step 2 and the circumferential area of the pile.
- Step 7. Repeat steps 5 and 6 for other pile movements to construct the entire load transfer curve at that depth.
- Step 8. Repeat steps 2 through 7 for varying depths to obtain a set of load transfer curves along a pile.

Skempton's criteria for tip resistance curves

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98. The point resistance curve for a pile in a clay may be generated by Skempton's¹⁸ criteria. Starting with the theory of elasticity, Skempton found a correlation between the load-settlement curve of the shallow foundation and the stress-strain curve for the undrained triaxial compression test. The validity of the same correlation for a deep foundation was attested by examining the effect of the foundation depth on the pertinent variables in the basic equation. The correlation for piles can be expressed by

$$z_b = 2A_b \varepsilon$$
 (89)

$$q_{\rm b} = m\sigma_{\Delta}A_{\rm b} \tag{90}$$

where

 z_{h} = axial movement of base of pile

- A_{h} = area of base of pile
- q_b = normal pressure on base of pile
- m = coefficient that can be taken as 5.0 to 5.5

99. If a stress-strain curve from undrained triaxial test is available, it is readily transformed to a point resistance curve as described for a laterally loaded pile earlier in this part. If no stressstrain curve is available, the procedure shown in Figure 27 can be followed to develop approximate stress-strain curves.

Criteria for Sand

100. Limited studies have been made for sands to establish generally applicable soil criteria for generating a set of load transfer curves along a pile and a point resistance curve at the tip of the pile. Two soil criteria are described below.

Coyle and Sulaiman's criteria

101. Coyle and Sulaiman²⁶ experimentally investigated the load transfer curves of a pile in sand. The ultimate shear transfer or skin friction on the side of a pile wall is expressed in the simplest form by

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$$f_{u} = K\gamma X \tan \delta$$
 (91)

where

 f_{11} = maximum shear transfer in psi

K = horizontal earth pressure coefficient at pile-soil interface whose value may lie somewhere between the active earth pressure coefficient K_A and the passive earth pressure coefficient K_B

 δ = friction angle between the pile and the surrounding sand

102. Assuming that the earth pressure coefficient K is equal to one and the friction angle is equal to the angle of internal friction of the sand before disturbance, Coyle and Sulaiman found the relationship between the load transfer of a pile in a sand and the pile displacement.

103. Their conclusion, however, does not agree with the

experimental observation by Parker and Reese.²² Coyle and Sulaiman state that at shallow depth there is a considerable increase in the actual maximum load transfer over that calculated by Equation 91 with the assumption of constant K and constant δ throughout the length of the pile. They further state that the maximum load transfer is reached at the lower portion of the pile with smaller pile displacement than at the upper portion. The observation by Parker and Reese indicated that the actual maximum load transfer at shallow depth is close to that obtained from Equation 91 with the same K and δ at all depths. Parker and Reese also found that the pile displacement necessary to reach the maximum load transfer increases linearly with depth. <u>Parker and Reese's criteria</u>

104. Empirical criteria were established by Parker and Beese²² for generating a set of load transfer curves along a pile in sand. The criteria correlates the load transfer curve with the stress-strain curve of a triaxial compression test. Their criteria includes a recommendation for the estimation of a point resistance curve.

105. The description of the procedure for generating a set of load transfer curves and a point resistance curve is given as follows:

- Step 1. Determine the relative density of sand and the stress-strain curve of a triaxial test with the ambient pressure equal to the overburden pressure.
- Step 2. Obtain the correction factor for the maximum load transfer as a function of the relative density of sand (Figure 31).
- Step 3. Obtain modified correlation coefficients, which relate the deviator stress in the triaxial test with the load transfer on the side of the pile. The modified correlation coefficient for uplift loading is calculated by dividing the value obtained by Equation 92 with the correction factor (step 2).

$$U_{t} = \frac{D_{t}}{\tan^{2}(45^{\circ} + \emptyset/2) - 1}$$
(92)

where

U_t = correlation coefficient for uplift loading

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Figure 31. Correction factor for maximum load transfer

D_t = tension'skin friction coefficient which is a function of the earth pressure coefficient and the friction angle. The value of 4.06 is assumed by Parker and Reese.

The modified correlation coefficient for a compression pile is calculated by dividing the value of Equation 93 with the correction factor (step 2).

$$U_{c} = \frac{D_{c}}{\tan^{2}(45^{\circ} + \phi/2) - 1}$$
(93)

where

- U_c = correlation coefficient for compression loading
- D_c = compression skin friction coefficient which is a function of the earth pressure coefficient and the friction angle. Parker and Reese assume the value 5.3 or the value computed from 7.0 - 0.04x.

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Step 4. Compute a load transfer curve from a stress-strain curve. Multiply the deviator stresses with the modified correlation coefficient (step 3) to obtain the values of load transfer. Then calculate the displacement of the pile by multiplying the axial strain in the triaxial test with the value obtained from Equation 94 or 95.

$$B_t = 0.15 + 0.012x$$
 (94)

$$B_{a} = 0.4 + 0.016x$$
 (95)

where

- B_{t} = factor correlating upward pile movement to axial strain
- B_c = factor correlating downward pile move-ment to axial strain
- Step 5. Repeat steps 1 through 4 for depths up to 15 times the pile diameter. The curve for a depth of 15 pile diameters is used for the remainder of the pile.
- Construct a point resistance curve by combining Step 6. any one of the bearing capacity formulas with the theory of elasticity solution for the settlement of a rigid footing on an elastic material (Skempton¹⁸).

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Meyerhof's criteria for tip resistance

106. After Skempton, Yassin, and Gibson, ²⁷ Meyerhof²⁸ proposed a simple criterion (Equation 96) for generating a point resistance of a pile in sands.

$$z = \frac{dq_b}{30q_{bu}}$$
(96)

where q_{bu} = unit ultimate bearing capacity

107. Considering the diversity of values of q_{bu} by various bearing capacity formulas (Vesić, ²⁹ McClelland, Focht, and Emrich³⁰), the unit ultimate bearing capacity of a pile point may be readily obtained from the empirical relationship with the standard penetration test (Meyerhof²⁸).
$$q_{bu} = 60N \tag{97}$$

where N denotes the number of blows per foot penetration in the standard penetration test.

Summary

108. A set of load transfer curves along a pile in clays can be computed from the criteria by Coyle and Reese.¹¹ A point resistance curve for a pile in clays can be constructed from Skempton's criteria.

109. The load transfer curves along a pile in sands may be determined by the procedure given by Parker and Reese.²² A point resistance curve for a pile in sands may be computed either according to the recommendation by Parker and Reese or according to Meyerhof's criteria.

110. Existing soil criteria can only make a rough prediction of the axial behavior of a pile. For a more accurate prediction of axial behavior of a pile, future development is needed of the theory for the mechanism of load transfer and of point resistance. The employment of the finite element method to solve the pile-soil interaction problems can perhaps eliminate the use of semi-empirical criteria to develop load transfer and point resistance curves.

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PART VI: DISCRETE ELEMENT THEORY FOR BEAM-COLUMNS

111. The computer code BMCOL51, developed by Matlock and Taylor.³ utilizes a discrete element mechanical model for describing the loaddeformation response of a beam-column. The equations obtained from the discrete element model are similar to those obtained with finitedifference approximations for the differential equations for bending, and the results are approximately the same. However, the equations obtained from the discrete element model can be grouped into a system of equations that allows a variety of boundary conditions to be applied; whereas the system of equations obtained with finite difference theory permit only the application of certain boundary conditions at definite locations along the beam-column, i.e. two at both ends. As a result, BMCOL51 is a more versatile program than COM62 since a wide variety of problems can be solved with BMCOL51 while COM62 is designed exclusively for the analysis of piles or beams on grade. However, BMCOL51 is limited to problems where the reactions can be characterized by linear springs, whereas COM62 can consider nonlinear soil response. It must be noted that BMCOL51 is one of the earlier BMCOL programs written under the guidance of Prof. Matlock. Currently available versions of BMCOL programs are more versatile and can account for nonlinear material and geometric properties.

112. The discrete element model for representing a beam-column will be described in subsequent paragraphs. The development of the model and equations for describing the model are taken directly from Matlock and Haliburton.³¹ Likewise, the figures used in the development were extracted from Matlock and Haliburton with changes made to the notation to ensure compatiblity with the remainder of the report. Equations expressing the response of the discrete element model will be derived and used in formulating a set of simultaneous equations for predicting the response of a beam-column. Finally, the procedure utilized in BMCOL51 for solving the simultaneous equations will be presented. This code also has the capability of solving problems with moving loads.

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Discrete Element Representation of the Response of a Simple Beam

113. To begin the development, a mechanical model representing a conventional beam will be considered. The model shown in Figure 32 was developed by Matlock and Haliburton.³¹ Figure 32(a-c) illustrates how the deformation of a linear elastic beam element under the action of pure bending may be represented. If we consider the overall behavior of the element, then a mechanical analog of the element in Figure 32c may be formed by the rigid plates, hinge, and linear springs in Figure 32d. The stiffness of the springs represent the flexural stiffness of the beam element. To form a beam a number of the mechanical elements can be strung together as shown in Figure 32e. The mechanical model thus formed would truly represent the behavior of the beam if the individual mechanical elements were infinitely small. However, for practical problems, as with any mechanical model or approximate numerical procedure, accuracy must be sacrificed in order that the number of calculations required be kept within practical limits. As it turns out, a cruder model (Figure 32f), where the rigid plates are replaced by rigid bars of length h, may be used to represent the beam without serious loss of accuracy.

114. The equations describing the behavior of the mechanical model may be formulated by considering the deformed segment of a finiteelement beam model in Figure 33. The deformable element of the model is represented schematically as a deformable joint with the same behavior as the spring and hinges in Figure 32. If we assume that the effect of a lateral force w distributed along the beam for a distance h/2on either side of a joint) may be represented by a concentrated force

$$W_{i} = hW_{i} \tag{98}$$

acting at the deformable joint, then the equation describing the behavior of the beam may be formulated.

115. The change in slope, ϕ_i , between bars A and B may be written as





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Figure 32. Finite mechanical representation of a conventional beam



$$\phi_{i} = \frac{y_{i-1} - 2y_{i} + y_{i+1}}{h}$$
(99)

In order to establish the similarities between the equations obtained using finite difference approximations and discrete element theory, Equation 99 is written as

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$$\phi_{i} = h \left(\frac{y_{i-1} - 2y_{i} + y_{i+1}}{h^{2}} \right)$$
(100)

The expression in the parenthesis is equivalent to Equation 2, the expression for the second derivative of deflection. The second derivative represents the curvature of the elastic curve and the finite difference expression represents an approximation of the curvature so that the moment-curvature relationship could be approximated by Equation 12. If we assume that ϕ_i represents the concentration of the beam curvature for one increment, then the moment curvature relationship for an arbitrary joint i may be expressed as

$$M_{i} = \frac{R_{i} \rho_{i}}{h}$$
 (101)

If we assume that all external forces are applied to the beam as concentrated forces at the deformable joints, then the summation of forces on the deformable joint yields

$$W_{i} + V_{A} - V_{B} = 0$$
 (102)

where V_A and V_B are the shear in bars A and B, respectively. Summation of moments about bars A and B yield, respectively,

$$M_{j-1} - M_{j} + V_{\Delta}h = 0$$
 (103)

and

$$M_{i} - M_{i+1} + V_{Bh} = 0$$
 (104)

Equations 103 and 104 may be substituted into Equation 102 and the shear $\rm V_A$ and $\rm V_B$ eliminated to yield

$$M_{i-1} - 2M_i + M_{i+1} = hW_i$$
 (105)

The expression for moment in Equation 101 when substituted into Equation 105 yields

$$R_{i-1}\phi_{i-1} - 2R_i\phi_i + R_{i+1}\phi_{i+1} = h^2W_i$$
 (106)

Substituting the expression for the beam curvature, Equation 99 into Equation 106 yields

$$R_{i-1}\left(\frac{y_{i-2} - 2y_{i-1} + y_{i}}{h}\right) - 2R_{i}\left(\frac{y_{i-1} - 2y_{i} + y_{i+1}}{h}\right) + R_{i+1}\left(\frac{y_{i} - 2y_{i+1} + y_{i+2}}{h}\right) = h^{2}W_{i} \quad (107)$$

Simplifying Equation 107 yields

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$$y_{i+2}(R_{i+1}) + y_{i+1}(-2R_{i+1} - 2R_i) + y_i(R_{i+1} + 4R_i + R_{i-1}) + y_{i-1}(-2R_i - 2R_{i-1}) + y_{i-2}(R_{i-1}) = h^3 W_i$$
(108)

The above equation is identical to Equation 10 if the effects of axial load are omitted in Equation 10 and the expressions for the applied lateral load are equated. The effects of lateral load in Equation 10 are represented by the expression $y_i E_{si} h^4$, where the distributed lateral force that resulted from the soil reaction was given by the expression

$$\mathbf{w}_{i} = \mathbf{E}_{si}\mathbf{y}_{i} \tag{109}$$

Since the expression for the concentrated force at the joint is given by the expression

$$W_{i} = hW_{i}$$
(110)

it can be seen that expressions 108 and 10 are identical except for the sign of the term for the lateral force. This difference results simply from the sign convention used in developing the equations and has no physical significance.

Discrete Element Representation of the Response of a Generalized Beam-Column

116. For simple beams, with only lateral forces applied, closed form solutions are available for most cases. However, realistic engineering problems usually involve the application of axial loads and a variety of external loading and restraint conditions. The mechanical model representation of a beam-column and the equations describing the response of the beam-column will be developed below.

117. The external forces and restraints that will be considered are presented in Figure 34. The forces and restraints are shown acting in the positive sense. Lowercase letters represent distributed loads and restraints while corresponding capital letters denote concentrated forces and restraints.

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Figure 34. Loads and restraints considered in the generalized beam-column solution. All effects are shown acting in a positive sense in relation to the x-direction

118. Equations describing the behavior of a generalized beamcolumn may be derived by considering the beam-column element in Figure 35 deflected a distance y and rotated through an angle dy/dx. Summing moments about the right end of the element yields

$$dM - V dx - t dx - w \frac{(dx)^2}{2} + sy \frac{(dx)^2}{2} - g dy - Q dy - dQ \frac{dy}{2} = 0$$
 (111)

where

t = distributed externally applied moment or torque

w = distributed lateral force

s = distributed lateral restraint

g = distributed rotational restraint

Q = axial force

Neglecting higher order terms and dividing both sides of the equation by dx yields



(112)

(113)

Summation of vertical forces on the element in Figure 35 yields

sulting equation to eliminate the shear yields

 $\frac{\mathrm{d}V}{\mathrm{d}x} = \mathbf{w} - \mathbf{s}\mathbf{y}$

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Differentiating Equation 112 and substituting Equation 113 into the re-

 $\frac{d^2M}{dx^2} = w - sy + \frac{d}{dx} \left[t + (g + Q) \frac{dy}{dx} \right]$ (114)

The above equation corresponds to Equation 7 but with the addition of the effects of externally applied moments, rotational resistance, an axial load that is variable with x , and externally applied lateral The term E_y in Equation 7 is analogous to the term sy in loads. the above equation in that they both represent the effects of lateral restraints. However, the variable E_s is a secant modulus value obtained from a nonlinear curve while s symbolizes a linear

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relationship between load and deflection. The above equation is next converted into finite difference forms and the effects of distributed applied loads and restraints concentrated in order to develop a mechanical model that will represent the response of the beam as predicted by the finite difference equations.

119. The left side of Equation 114 is converted into finite difference form by first writing the expression

$$\left(\frac{\mathrm{d}^{2}M}{\mathrm{d}x^{2}}\right)_{i} \approx \frac{M_{i-1} - 2M_{i} + M_{i+1}}{\mathrm{h}^{2}}$$
(115)

The equations for the moment at the nodal points given by Equation 101 are substituted into Equation 115 yielding

$$\begin{pmatrix} \frac{d^{2}M}{dx^{2}} \\ i \end{pmatrix}_{i} \approx \frac{1}{h^{4}} \left[y_{i+2}(R_{i+1}) + y_{i+1}(-2R_{i+1} - 2R_{i}) + y_{i}(R_{i+1} + 4R_{i} + R_{i-1}) + Y_{i-1}(-2R_{i} - 2R_{i-1}) + y_{i-2}(R_{i-1}) + y_{i-2}(R_{i-1}) \right]$$

$$(116)$$

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The right-hand side of Equation 11^4 is converted to finite difference form by writing w as w_i and sy as $s_i y_i$. The remainder of the expression is converted by writing

$$\left(\frac{dt}{dx}\right)_{i} \approx \frac{t_{i+1} - t_{i-1}}{2h}$$
(117)

and

$$\frac{d}{dx} \left[(g + Q) \frac{dy}{dx} \right] = \frac{1}{2h} \left[(g_{i+1} + Q_{i+1}) \frac{y_{i+2} - y_i}{2h} - (g_{i-1} + Q_{i-1}) \frac{y_i - y_{i-2}}{2h} \right]$$
(118)

Writing the right-hand side in its entirety yields

$$\left(\frac{d^{2}M}{dx^{2}}\right)_{i} = w_{i} - s_{i}y_{i} + \frac{1}{2h} \left[t_{i+1} + (g_{i+1} + Q_{i+1}) \frac{y_{i+2} - y_{i}}{2h} - t_{i-1} - (g_{i-1} + Q_{i-1}) \left(\frac{y_{i} - y_{i-2}}{2h}\right) \right]$$
(119)

Equating Equations 116 and 119 yields for nodal point i the expression

$$\frac{1}{h^{4}} \left[y_{i+2}(R_{i+1}) + y_{i+1}(-2R_{i+1} - 2R_{i}) + y_{i}(R_{i+1} + 4R_{i} + R_{i-1}) + y_{i-1}(-2R_{i-1}) + y_{i-2}(R_{i-1}) \right]$$

$$= y_{i} - s_{i}y_{i} + \frac{1}{2h} \left[t_{i+1} + (g_{i+1} + Q_{i+1}) \left(\frac{y_{i+2} - y_{i}}{2h} \right) - t_{i-1} - (g_{i-1} + Q_{i-1}) \left(\frac{y_{i} - y_{i+2}}{2h} \right) \right]$$
(120)

Combining terms, Equation 120 is written as

$$y_{i+2} \left[R_{i+1} - \frac{h^2}{4} (g_{i+1} + Q_{i+1}) \right] + y_{i+1} (-2R_{i+1} - 2R_i) + y_i \left[R_{i+1} + 4R_i + R_{i-1} + h^4 s_i + \frac{h^2}{4} (g_{i+1} + Q_{i-1} + g_{i-1} + Q_{i-1}) \right] + y_{i-1} (-2R_i - 2R_{i-1}) + y_{i-2} \left[R_{i-1} - \frac{h^2}{4} (g_{i-1} + Q_{i-1}) \right] = h^4 w_i + \frac{h^3}{2} (t_{i+1} - t_{i-1})$$
(121)

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The distributed externally applied loads and restraints may be lumped at the nodal points as concentrated forces, W_i , concentrated springs S_i , concentrated moments T_i and concentrated rotational restraints G_i , by the following equations:

$$W_{i} = hW_{i}$$
(122)

$$S_{i} = hs_{i}$$
(123)

$$T_{i} = ht_{i} \tag{124}$$

$$G_{i} = hg_{i} \tag{125}$$

Substituting Equations 122-125 into Equation 121 results in an equation describing the behavior of the mechanical model shown in Figure 36. The flexural stiffness R_i is concentrated at the increment point in the

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Figure 36. Mechanical model corresponding exactly to beam-column equations

form of a spring-restrained hinge between two rigid segments. All load and support values are ultimately felt by the beam as transverse forces applied at nodal points. This is obvious for the lateral load W_i and for the couple created by forces $T_i/2h$. It is also true for the reaction from the spring S_i as well as for two equal but opposite reactions from the angular restraint mechanism which acts as an exact analog for the combined effect of a rotational spring G_i and the axial tension (or compression) Q_i .

120. The deflections that result from the solution of Equation 121 represent a set of deflections for the nodal points of the mechanical model for the beam-column that will satisfy compatibility and equilibrium at each nodal point and of each nondeformable bar in the model. In the subsequent paragraphs the procedure for solving the equations will be described.

Recursive Solution Technique

121. Equation 121 may be written in the following form:

$$a_{i}y_{i+2} + b_{i}y_{i+1} + c_{i}y_{i} + d_{i}y_{i-1} + e_{i}y_{i-2} = f_{i}$$
 (126)

where

$$a_{i} = R_{i+1} - \frac{h}{4} (G_{i+1} + Q_{i+1}h)$$
 (127)

$$b_i = -2(R_{i+1} + R_i)$$
 (128)

$$c_i = R_{i+1} + 4R_i + R_{i-1} + h^3 S_i + \frac{h}{4} (G_{i+1} + hQ_{i+1} + G_{i-1} + hQ_{i-1})$$
 (129)

$$d_{i} = -2(R_{i} + R_{i-1})$$
(130)

$$e_i = R_{i-1} - \frac{h}{4} (G_{i-1} + hQ_{i-1})$$
 (131)

$$f_{i} = h^{3}W_{i} + \frac{h^{2}}{2}(T_{i+1} - T_{i-1})$$
 (132)

For a beam-column represented by a mechanical model as illustrated in Figure 37a, a set of simultaneous equations composed of Equation 126 written for each nodal point may be formulated. The simultaneous equations when written in matrix form result in the matrix equation

$$[K]{y} = {f}$$
(133)



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The stiffness matrix [K] is a diagonally banded matrix containing terms a through e. The deflection matrix {y} is a single column matrix as is the load matrix {f}. The unknown matrix in the matrix equation is the deflection matrix. A recursive technique is utilized to solve for the deflections. Once the deflections are found, the moments, shear, or any force exerted by a restraint spring may be computed by substituting the appropriate deflections into the appropriate equation.

122. In order to begin and end the recursive process, it is necessary to establish three fictitious stations at each end of the beam-column. The fictitious stations have no flexural stiffness and thus act as multiple hinges. If such a system were added to the mechanical model, the response of the remainder of the model would not be affected; therefore, the solution obtained for the equations is not affected by this addition. These fictitious stations are added for computational purposes only and are generated automatically by the computer code BMCOL51.

The recursive solution technique is illustrated in Fig-123. ure 37d. Each equation contains five unknown deflections. In the first pass, two unknown deflections are eliminated from each equation. Starting from the top, the deflections y_{i-2} and y_{i-1} are eliminated. The resulting equations form a diagonally banded matrix in which each equation contains only three unknown deflections. During the reverse pass the solution for the deflection at sta i is computed. The deflection y_i can be determined only when y_{i+1} and y_{i+2} are known. During the forward pass the application of boundary and specified conditions will establish values or relationships between deflections such that y_{i+1} and y_{i+2} are known after completion of the forward pass. This permits the computation of y, during the reverse pass. After the reverse pass is completed, the deflections at each nodal point are known. With these values, moments, shear slope, or reaction may be obtained by applying the appropriate finite difference equation.

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a_i, b_i, c_i

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Recursive coefficients computed (in solution of finite difference equations

- A Cross-sectional area of pile
- ${\rm A}_{\rm h}$. Area of base of pile
- . B Factor correlating downward pile movement to axial strain
- B_{+} Factor correlating upward pile movement to axial strain
 - c Cohesion of clay
 - C Pile circumference
 - d Diameter of pile for circular piles or equivalent diameter of other shapes
- D_ Compression skin friction coefficient
- \mathbb{D}_t .Tension skin friction coefficient.
- E Modulus of elasticity of pile material
- E Soil modulus (lateral soil reaction divided by lateral deflection)
- f Shear force per unit area (as a function of the location . . along a pile)
- f. Maximum shear transfer in psi

Shear force per unit length

 F_{μ}, F_{ν}, M_{s} Forces and moment exerted by each pile

g Distributed rotational restraint

- G Concentrated rotational restraint
- h Increment length
- 11 Constant depending on relative density of sand
- . I Moment of inertia of pile section

Secant modulus values

J_x,J_y,J_m K

F

- Horizontal earth pressure coefficient at pile-soil interface
- $\mathbf{K}_{\mathbf{A}}$. Coefficient of active earth pressure
- K_{O} Coefficient of earth pressure at rest
- L Length of pile
- m Coefficient

.. M Bending moment

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M_{e}, P_{u}, P_{v}	External moment, horizontal force, and vertical force (applied at origin of u-v coordinate system)
M _i ,M _{i+1} ,M _{i-1}	Moment at the respective joints
M ₊	Bending moment applied to top of pile
. N	Number of blows per foot penetration
р	Lateral soil reaction per unit length
p_{11}	Ultimate lateral soil reaction
P	Resultant force per unit length of pile
P _t	Lateral load applied to top of pile
^q b	Normal pressure on base of pile
ġ, _{bu}	Unit ultimate bearing capacity in psi
, g	Unconfined compressive strength
· Q	Axial load; axial force
Q _b	Load due to the normal pressure on the base of a pile
Q	Constant axial load in pile
Qt	Axial load applied to top of pile
R	EI (flexural rigidity)
`• S	Distributed lateral restraint
S	Concentrated lateral restraint
SF	Force representing concentration of shear transfer at joint
t	Distributed externally applied moment or torque
· T	Concentrated externally applied moment or torque
u-v	Coordinate system (for describing geometry of the foundation)
U	Correlation coefficient for compression loading
U _t .	Correlation coefficient for uplift loading
; V	Shear
v _A ,v _B	Shears in bars A and B
W	Distributed lateral force
. W	Concentrated lateral force
, х	Distance along axis of pile
Х	Depth from soil surface
у	Lateral deflection
Z	Axial movement of pile

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- z_b Axial movement of base of pile
- α Constant (values for loose and dense sand)
- β Constant = $45^{\circ} + \emptyset/2$
- γ Effective unit weight of soil

Components of foundation movement

 δ Friction angle (between the pile and the surrounding sand)

 $\Delta_{v}, \Delta_{u}, \Gamma$

- ε Axial soil strain (from triaxial compression test)
- ε_{50} Fifty percent of the maximum elastic axial soil strain (from triaxial compression test)
 - θ Angular measure of pile batter

 λ_1, ν_1 Boundary condition coefficients (computed in solution of finite difference equations)

- σ_{Λ} Soil deviator stress $(\sigma_1 \sigma_3)$
- $\sigma_{\Delta 50}$ Deviator stress corresponding to 50 percent maximum = elastic axial strain
- σ_1, σ_3 Axial and confining stress (in triaxial compression test) ϕ Angle of internal friction of sand
 - ψ A function relating axial load to the relative axial movement between the pile and soil
 - Ω_{t} Slope at top of pile

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APPENDIX B: USER'S GL DE FOR PROGRAM COM62

General Introducton

1. Documentation for the computer program COM62 - to analyze laterally loaded piles in nonlinear soil media - is presented in this appendix and includes a general introduction, program listing, flow charts, guide for data input, and input-output data for two example problems.

2. COM62 is a finite difference computer code (developed by Dr. L. C. Reese, University of Texas (UT), Austin, Texas) that can solve for deflection, shear, moment, and reactions in a single pile under a variety of boundary conditions specified at the top of the pile. The quantities input at the top of the pile can be one of the following combinations: lateral load and a moment; lateral load and a specified slope; lateral load and a specified moment/slope value. The forcedeformation characteristics of the soil are represented by a series of nonlinear springs.

3. Typical curves that relate the soil resistance to the lateral movement of the pile are shown in Figure Bl. Procedures for obtaining





Figure Bl. Examples of p-y curves at various depths in soil

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such curves from laboratory soil test data are described in the text (Part V). The computer program MAKE that can automatically generate such curves from laboratory soil data is documented in Appendix D. COM62 can handle variable flexural rigidity (EI) of the pile and layered soil media. If an axial load is specified at the top of the pile, it is assumed to be constant throughout the length of the pile.

4. In the analysis used in COM62, compatibility is achieved between the inelastic soil and the elastic pile (which is elastically restrained by the superstructure) by repeated application of the elastic theory. The soil stiffness constants are adjusted for each trial in accordance with the specified force-deformation relations for the soil. Thus, the iterative analysis consists of a conventional beam on elastic foundation analysis coupled with the proper prediction of forcedeformation characteristics of the soil.

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5. Input may be input interactively at execute time, or input may be in a prepared data file. Output will be directed to an output file.

Flow Charts

6. A flow chart for the program is shown in Figure B2. The sequence of operations for subroutine soil is diagramed in Figure B3.



Figure B2. Flow chart for COM62



soil for COM62

Guide for Data Input

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7. Data should be input to program COM62 according to the following guide. All input is in free-field format. Group 1 - Title RUN RUN = 60 character problem heading Group 2 - Problem Parameters PT, BC2, D, H, TOL, N, KODE, NEWPY PT = Lateral load at top of pile, lb ುವ್ 🦉 🍈 BC2 = Secondary boundary condition value (i.e., value of MT (in.-lb), ST, or MT/ST - see KODE below) $\mathbf{D} = \mathbf{Pile} \, \mathbf{diameter}, \, \mathbf{in}, \, \mathbf{f} \in [\mathbf{a}, \mathbf{f}]$ H = Increment length, in. TOL = Increment tolerance for deflections, in. N = Number of increments (Product of N and H equals length of pile.) 1381666662333 KODE = Boundary condition control parameter 1 ---- use lateral load (PT) and moment (MT). 2 --- use lateral load (PT) and slope (ST). 3 ---- use lateral load (PT) and MT/ST. NEWPY = Control parameter to specify if a new p-y curve will be read in. 0 --- Program will not read p-y curves (will use old p-y data)(Do not specify Group 3). 1 --- A new set of p-y curves will be read. Group 3 - Soil Resistance-Pile Movement Data Α. NX, NUM NX = Number of p-y curvesNUM = Number of points on each p-y curve

- Β. (i) X(K) (ii)YM(J,K), PP(J,K)X(K) = Distance from top of pile to the Kth p-y curve, ft YM(J,K) = Deflection at Jth point on Kth p-y curve. J goesfrom 1 to NUM and K goes from 1 to NX, in. PP(J,K) = Soil resistance at Jth point on Kth p-y curve.J goes from 1 to NUM and K goes from 1 to NX, 1b/in. Note: Set B is repeated until NX number of p-y curves have been supplied. Line (ii) of Set B is repeated within each set until NUM deflections and soil resistances have been supplied for that set. A p-y curve must always be specified at the top of the pile. Group 4 - Flexural Rigidity Data Á. RR(J),XX(J)Β. I = Number of different flexural rigidity values for a pile. manipalania
 - RR(J) = The Jth flexural rigidity value, lb x in². J goes from 1 to I.
 - XX(J) = The distance from top of pile to point where Jth
 flexural rigidity value occurs. J goes from
 l to I.
 - Note: Set B should be repeated until I number of flexural rigidity and their location values have been supplied.

Group 5 - Axial Load Data

PX

PX = Axial load at the top of pile, 1b

Example Problems

8. To illustrate the preparation of input data for program COM62, two example problems (in one run) will be solved. Figures B4 and B5 show the physical problems; Figure B6, the input p-y curve for both examples; and Table B1, the input data to the program. The computer outputs for the first and second examples are given in Tables B2 and B3, respectively. The results are also plotted in Figures B7-B9 for Example Problem 1 and in Figures B10-B12 for Example Problem 2.





Table Bl

Input for Example Problems 1 and 2

```
*LIST DAT62
           10 RUN 1 COM62 - LATERAL LOAD=100000 AXIAL LOAD=1
           21 100000.0.30.10.0.001.100.1.1
           30 2.2
           40 0.0
           50 0,0,0,0
           60 20.,1000.
           70 1000.
           80 0.0.0.0
           90 20.,1000.
           100 1
           110 2.1E11,1000.
           120 1.
                                                      - -
           130 RUN 2 COM62 - LATERAL LOAD=100000 AXIAL LOAD=10000
3
           140 100000.,0.0,30.,10.,0.001,100.1,0
           150 1
        160 2.1E11,1000.
170 10000.
```

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(BertSheet);

```
DO YOU WANT TO RUN AN EXISTING DATA FILE?
=YES
ENTER NAME OF INPUT DATA FILE
=DAT62
ENTER NAME OF OUTPUT DATA FILE
FILE DESCRIPTION (47 CHARACTERS MAX), TYPE ? FOR INFO ON FORM
=OUT62
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Table B2 Output for Example Problem 1 LIST OUT62 AUN 1 COM62 - LATERAL LOAD=100000 AXIAL LOAD=1 ITERATION INFORMATION YT, IN, ITER, NO. 0.72159E 01 0.11287E 02 1 2 0.11287E 02 3 LATERALLY LOADED PILE PROGRAM ార్ జ్ - 1 INPUT INFORMATION PTILB BC2 BC CASE DIAMETER, IN 0.30000E.02 ñ.10000E 06 . g. 1 . : ·· ·· · INCREMENT LENGTH, IN NUMBER OF INCREMENTS 0,10000E 02 100 AXIAL COMPRESSION AT PILE TOP = 0,10000E 01 LENGTH OF PILE,FT ITERATION TOLERANCE IN 0.83333E 02 0,10000E402 中国和新疆新疆 DEPTH TO P-Y CURVE, IN. Y, IN. P+LB/IN. 0. Ο. đ. 0.20000E 02 0.10000E 04 **OUTPUT INFORMATION** 0.10000E 04 0. 0. 0.20000E 02 0.10000E 04 OUTPUT INFORMATION X,ET. Y.IN. ES,LB/IN2 P,LB/IN. M,IN-LB ELLB/1N2
 n.
 0.1129E
 02
 0.5000E
 02-0.5644E
 03
 0.2100E
 12

 n.8333E
 00
 0.1098E
 02
 0.9721E
 06
 0.5000E
 02-0.5489E
 03
 0.2100E
 12

 n.1667E
 01
 0.1067E
 02
 0.1889E
 07
 0.5000E
 02-0.5334E
 03
 0.2100E
 12

 n.2500E
 01
 0.1036E
 02
 0.2752E
 07
 0.5000E
 02-0.5180E
 03
 0.2100E
 12
 A.3333E 01 0.1005E 02 0.3564E 07 0.5000E 02-0.5026E 03 0.2100E 12 n.4167E 01 0.9747E 01 0.4324E 07 0.5000E 02-0.4874E 03 0.2100E 12

(Continued)

(Sheet 1 of 3)

Table B2 (Continued)

	-		0.04445					40				
	n.2000E	01	0.94446	01	0,2039E	07	0,5000E	02-0,4/226	03	0.2100E	12	
	n,5833E	01	0.9143E	01	0,56998	07	0.5000E	02-0,49/1F	03	0,2100E	12	
	1,000/E	01	0.08446	01	0.031/E	07	0.20006	02-0.44226	03	0.21000	12	
	7./200E	01	0.8549E	01	0.08925	07	0,5000E	02+0.42/5E	03	0,2100E	12	
	n.8353E	01	0.8257E	01	0.7423E	07	0,5000E	02-0.4129F	03	0.2100E	12	
	0.910/E	01	0.7909E	01	0.7914E	07	0.5000E	02-0.3984E	03	0,21002	12	
	1.1000E	02	0.7684E	01	0.8366E	07	0.50008	02-0.3842E	03	0.2100E	12	
	n,1083E	02	0.7403E	01	0,8781E	07	0,5000E	02-0.37026	03	0,21006	12	
	0,110/E	02	0./127E	01	0.9199E	07	0.5000E	02-0.3504E	03	0.2100E	12	
	0,1250E	02	0.0855E	01	0,9501E	07	0,5000E	02-0.3427E	03	0,2100E	12	
	n.1333E	02	0.6587E	01	0.9809E	07	0,5000E	02-0.3294E	03	0.2100E	12	
	n,1417E	02	0.6324E	01	0.1008E	08	0,5000E	02-0.3162E	03	0.2100E	12	
	1,1500E	02	0,6066E	01	0,1033E	08	0,5000E	02+0.3033E	03	0.2100E	12	
	A.1583E	02	0,5813E	01	0.1054E	08	0,5000E	02-0.2907E	03	0.2100E	12	
	1.1667E	02	0.5565E	01	0,1072E	08	0.5000E	02-0.2782E	03	0.2100E	12	
	1.1750E	02	0,5322E	01	0,1088E	08	0,5000E	02-0.2661F	03	2100E مر0	12	
	ñ,1833E	02	0.5084E	01	0,1101E	08	0,5000E	02-0.2542E	03	05,2100E	12	
2.4826.50	1.1917E	02	0,4851E	01	0,1111E	08	0,5000E	02-0.2426E	03	0,2100E	12	
	A.2000E	02	0.4624E	01	0,1120E	08	0,5000E	02-0.2312E	03	0,2100E	12	
	A.2083E	02	0.4402E	01	0.1125E	08	0,5000E	02-0,2201E	03	0.2100E	12	
	1.2167E	02	0,4185E	01	0,1129E	08	0,5000E	02-0.2093E	03	0,2100E	12	
والأركر بيرا الأرجري أبير ومعرور المراكز الأراك المراكز	1.2250E	02	0.3974E:	01.	0.1130E	08	0.50008	02-0.1987E	.03	0,2100E	12	
	A.2333E	02	0,3768E	01	0,1130E	08	0.5000E	02-0.1884E	03	0.2100E	12	
	A.2417E	02	0,3567E	01	0.1127E	08	0.5000E	02-0.1784E	03	0,2100E	12	
	A.2500E	02	0.3372E	01	0.1123E	08	0.5000E	02-0.1686E	03	0.2100E	12	
	ñ,2583E	02	0,3182E	01	0.1117E	08	0,5000E	02-0.1591E	03	0.2100E	12	
	n.2667E	02	0.2998E	01	0,1109E	08	0.5000E	02-0.1499E	03	0.2100E	12	
	A.2750E	02	0.2819E	01	0.1100E	08	0,5000E	02-0.1409E	03	0,2100E	12	
1	n.2833E	02	0.2645E	01	0.1090E	80	0,5000E	02-0,1322E	03	0.2100E	12	
an e caralte a valet	1.2917E	02	0.2476E	01	0,1078E	08	0,5000E	02-0.1238E	03	0,2100E	12	
HOLE OF BUILDING	A.3000E	02	0,2312E	01	0.1065E	08	0.5000E	02-0.1156F	03	0.2100E	12	
	h.3083E	02	0.2153E	01	0.1051E	08	0.5000E	02-0.1077E	03	0.2100E	12	
	n.3167E	02	0.2000E	01	0.1036E	08	0.5000E	02-0.9999E	02	0.2100E	12	
	1.3250E	02	0.1851E	01	0.1020E	08	0.5000E	02-0.92566	02	0.2100E	12	
	n.3333E	02	0.1707E	01	0.1003E	08	0,5000E	02-0.8537F	02	0.2100E	12	
	n,3417E	02	0.1568E	01	0.9849E	07	0.5000E	02-0.7842F	02	0.2100E	12	
	A.3500E	02	0.1434E	01	0.9662E	07	0.5000E	02-0.7170F	02	0.2100E	12	
	n.3583E	02	0.1304E	01	0.9468E	07	0.5000E	02-0.6522F	02	0.2100E	12	
	4.3667E	02	0.1179E	01	0.9268E	07	0.5000E	02-0.58965	ñ2	0.2100E	12	
	0.3750E	02	0.10586	01	0.9061E	07	0.5000E	02-0.5292F	02	0.2100F	12	
	A.3833E	02	0.9419E	00	0.8849E	07	0.5000E	02-0.4709E	02	0.2100F	12	
	1.3917E	02	0.8296E	0.0	0.8633E	07	0.5000E	02-0.4148E	02	0.2100E	12	
	A.4000E	02	0.7214E	00	0.8412E	07	0.5000E	02-0.3607F	ñ2	0.2100E	12	
	ñ.4083F	02	0.6172E	00	0.8187F	07	0.5000F	02-0.3086=	ñ2	0.2100F	12	
	n.4167E	02	0.5170E	00	0.7960F	07	0.5000E	02-0.2585	ñ2	0.2100F	12	
	A.4250F	02	0.4205E	00	0.7730F	07	0.5000F	02-0.21035	02	0.2100F	12	
	1.4333F	n2	0.3277F	õň	0.7497F	07	0.5000F	02-0.1639=	n2	0.2100F	12	
	1.4417F	02	0.2385E	õõ	0.7264F	07	0.5000F	02-0.1192=	ñ2	0.2100F	12	
	A.4500F	02	0.1527E	00	0.7028F	07	0.5000F	02-0.7637	01	0.2100E	12	
		_				~ •			~ •	- ,		

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(Sheet 2 of 3)

Table B2 (Concluded)

	ñ.4583F 02 0.7032E⇔01 0.6793E 07 0.5000E 02+0.3516F 01 0.2100E 12	
	4.4667E 02=0.8859E=02 0.6557E 07 0.5000E 02 0.4429E 00 0.2100E 12	
	\dot{a} , 475 ng a_{2} a_{1} , 8492 g_{1} a_{2} , 632 ng a_{2} , 0, 56 ng a_{2} , 0, 424 g_{2} , 0, 21 ng 12	
. <i>,</i>		
•		
	7,5083E 02-0,3602E 00 0,5384E 07 0,5000E 02 0,1801E 02 0,2100E 12	
	A.516/E 02+0.4223E 00 0,5153E 07 0.5000E 02 0.2112E 02 0.2100E 12	
	0.5250E 02-0.4820E D0 0.4925E 07 0.5000E 02 0.2410E 02 0.2100E 12	
	0.5333E 02-0.5393E 00 0.4699E 07 0.5000E 02 0.2697E 02 0.2100E 12	
	6.5417E 02-0.5944E 00 0.4476E 07 0.5000E 02 0.2972E 02 0.2100E 12	
	A.5500E 02-0.6474E 00 0.4256E 07 0.5000E 02 0.3237E 02 0.2100E 12	
	A,5583E 02-0.6983E 00 0.4039E 07 0.5000E 02 0.3491E 02 0,2100E 12	
	0.5667E 02-0.7473E 00 0.3825E 07 0.5000E 02 0.3736E 02 0.2100E 12	
	0.5750E 02+0.7945E 00 0.3615E 07 0.5000E 02 0.3972E 02 0.2100E 12	
	1.5833E 02~0.8400E 00 0.3409E 07 0.5000E 02 0.4200E 02 0.2100E 12	
	7.5917E 02=0.8838E 00 0.3208E 07 0.5000E 02 0.4419E 02-0.2300E 12	
	A 6000E 02-0.9261E 00 0.3011E 07 0.5000E 02 0.4631E 02 0.2100E 12	
1		
:		
		•
	1,041/E 0240.1110E 01 0.2090E 0/ 0.5000E 02 0.5590E 02 0.2100E 12	
	7.0000E 02=0.1153E 01 0.1931E 07 0.5000E 02 0.5765E 02 0.2100E 12	
	1,6583E 02-0.1187E 01 0.1770E 07 0.5000E 02 0.5936E 02 0.2100E 12	
r T	1.6667E 02-0.1220E 01 0.1616E 07 0.5000E 02 0.6102F 02 0.2100E 12	
1	4,6750E 02-0.1253E 01 0,1467E 07 0,5000E 02 0.6265E 02 0.2100E 12	
:	n.6833E 02-0,1285E 01 0,1324E 07 0,5000E 02 0,6424E 02 0,2100E 12	
1	ñ.6917E 02-0.1316E 01 0.1188E 07 0.5000E 02 0.6580E 02 0.2100E 12	
	ñ.7000E 02-0.1347E 01 0.1059E 07 0.5000E 02 0.6733E 02 0.2100E 12	
and sea and se	n.7083E 02-0.1377E 01 0.9362E 06 0.5000E 02 0.6883E 02 0.2100E 12	
	0.7167E 02-0.1406E 01 0.8203E 06 0.5000E 02 0.7032E 02 0.2100E 12	
	1.7250E 02-0.1436E 01 0.7113E 06 0.5000E 02 0.7178E 02 0.2100E 12	
	0.7333F 02+0.1465F 01 0.6095F 06 0.5000F 02 0.7323F 02 0.2100F 12	
	0.7417E 02+0.1493E 01 0.5150E 06 0.5000E 02 0.7466E 02 0.2100E 12	
	= 7447 + 3260 + 15700 + 0.0107070 + 0.00000 + 0.00000 + 0.00000 + 0.00000 + 0.00000 + 0.00000 + 0.00000 + 0.00000 + 0.0000000 + 0.000000 + 0.000000 + 0.000000 + 0.000000 + 0.000000 + 0.000000 + 0.000000 + 0.000000 + 0.000000 + 0.000000 + 0.000000 + 0.000000 + 0.000000 + 0.000000 + 0.000000 + 0.000000 + 0.000000 + 0.00000000	
	π , 70676 02-0, 15766 01 0, 27676 06 0, 50006 02 0, 76096 02 0, 21006 12	
	4.7750E 02-0.1600E 01 0.2129E 06 0.5000E 02 0.6029E 02 0.2100E 12	
	m,/035E 02-0.1635E 01 0.19/2E 06 0.5000E 02 0.8167E 02 0.2100E 12	
	n./y1/E U2=U.1601E U1 0.109/E U6 0.5000E 02 0.8306E 02 0.2100E 12	
	7.8000E 02-0.1689E 01 0.7003E 05 0.5000E 02 0.8444E 02 0.2100E 12	
	n.8083E 02-0.1717E 01 0.4005E 05 0.5000E 02 0.8583E 02 0.2100E 12	
	0.8167E 02-0.1744E 01 0.1793E 05 0.5000E 02 0.8721E 02 0.2100E 12	
	1.8250E 02-0.1772E 01 0.4506E 04 0.5000E 02 0.8859E 02 0.2100E 12	
	A.8333E 02-0.1799E 01 0. 0.5000E 02 0.8997£ 02 0.2100E 12	

(Sheet 3 of 3)

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(Sheet 1 of 3)

Table B3 (Continued)

	n.8333E n.9167E n.1000E n.1083E n.1167E ñ.1250E n.1333E	01 0.8281E 01 01 0.7991E 03 02 0.7705E 03 02 0.7423E 03 02 0.7145E 03 02 0.6872E 03 02 0.6603E 01	0.7465E 0 0.7960E 0 0.8416E 0 0.8833E 0 0.9213E 0 0.9556E 0 0.9866E 0	7 0.5000E 7 0.5000E 7 0.5000E 7 0.5000E 7 0.5000E 7 0.5000E 7 0.5000E	02-0.4140E 03 02-0.3996E 03 02-0.3853E 03 02-0.3712E 03 02-0.3573E 03 02-0.3436E 03 02-0.3302E 03	0.2100E 12 0.2100E 12
	n.1417E n.1500E n.1583E n.1667E n.1750E n.1750E n.1917E n.1917E n.2000E	02 0.6339E 01 02 0.6080E 01 02 0.5826E 01 02 0.5576E 01 02 0.5332E 01 02 0.5093E 01 02 0.4860E 01 02 0.4631E 01	0,1014E 0 0,1039E 0 0,1060E 0 0,1078E 0 0,1094E 0 0,1107E 0 0,1118E 0 0,1126E 0	6 0.5000E 8 0.5000E 8 0.5000E 8 0.5000E 8 0.5000E 8 0.5000E 8 0.5000E 8 0.5000E	02-0.3040F 03 02-0.2913F 03 02-0.2788E 03 02-0.2666E 03 02-0.2547E 03 02-0.2430E 03 02-0.2316F 03	0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12
	n.2167E (n.2167E (n.2250E (n.2333E (n.2417E (n.2500E (02 0.4408E 01 02 0.4191E 01 02 0.3979E 01 02 0.3772E 01 02 0.3570E 01 02 0.3374E 01	0,1131E 00 0,1135E 00 0,1136E 00 0,1136E 00 0,1133E 00 0,1133E 00	B 0,5000E B 0,5000E B 0,5000E B 0,5000E B 0,5000E B 0,5000E B 0,5000E	02-0.2204F 03 02-0.2095F 03 02-0.1989E 03 02-0.1886E 03 02-0.1785E 03 02-0.1687E 03	0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12
	n.2583E (n.2667E (n.2750E (n.2833E (n.2917E (n.3000E (02 0.3184E 01 02 0.2999E 01 02 0.2819E 01 02 0.2644E 01 02 0.2475E 01 02 0.2310E 01	0.1123E 08 0.1116E 08 0.1107E 08 0.1096E 08 0.1084E 08 0.1071E 08	3 0.5000E 3 0.5000E 3 0.5000E 3 0.5000E 3 0.5000E 3 0.5000E	02-0.1592E 03 02-0.1499E 03 02-0.1409F 03 02-0.1322E 03 02-0.1237E 03 02-0.1155E 03	0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12
opitentingen	n.3167E 0 n.3250E 0 n.3333E 0 n.3417E 0 n.3500E 0 n.3583E 0	2 0.1997E 01 2 0.1897E 01 2 0.1848E 01 2 0.1704E 01 2 0.1564E 01 2 0.1429E 01 2 0.1299F 01	0.1042E 08 0.1026E 08 0.1026E 08 0.9903E 07 0.9715E 07	0.5000E 0.5000E 0.5000E 0.5000E 0.5000E 0.5000E	02-0.1076E 03 02-0.9985F 02 02-0.9239E 02 02-0.8518E 02 02-0.7147E 02 02-0.7147E 02	0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12
	4.3667E 0 4.3750E 0 4.3833E 0 4.3917E 0 4.4000E 0 6.4083E 0	2 0.1174E 01 2 0.1052E 01 2 0.9355E 00 2 0.8229E 00 2 0.7145E 00 2 0.6100E 00	0.9317E 07 0.9109E 07 0.8896E 07 0.8677E 07 0.8455E 07 0.8229E 07	0.5000E 0.5000E 0.5000E 0.5000E 0.5000E 0.5000E	02-0.5868F 02 02-0.5262E 02 02-0.4678F 02 02-0.4115E 02 02-0.3572F 02 02-0.3050E 02	0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12
	n.4167E 0 n.4250E 0 n.4333E 0 n.4417E 0 n.4500E 0 n.4583E n	2 0.5095E 00 2 0.4128E 00 2 0.3197E 00 2 0.2303E 00 2 0.1443E 00 2 0.6176E=01	0.8000E 07 0.7768E 07 0.7534E 07 0.7299E 07 0.7062E 07 0.6825E 07	0.5000E 0.5000E 0.5000E 0.5000E 0.5000E 0.5000E	02-0.2547E 02 02-0.2064E 02 02-0.1599E 02 02-0.1152E 02 02-0.7217E 01 02-0.3088E 01	0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12 0.2100E 12
	n.4667E 0 n.4750E 0 n,4833E 0	2-0.1759E-01 2-0.9379E-01 2-0.1670E 00	0.6587E 07 0.6350E 07 0.6112E 07	0.5000E 0.5000E 0.5000E	02 0.8793E 00 02 0.4690E 01 02 0.8349E 01	0.2100E 12 0.2100E 12 0.2100E 12

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(Sheet 2 of 3)

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Table B3 (Continued)

	0.8333E 01 0.8281E	01 0.7465E 07	0.5000F 02-0.414	AC A3 0.2100E 12	>
	A 9147E A1 A 7001E	01 0074006 07	0 50000 02-0 300	AF AT A 2100E 17	- >
	A 1000E 02 0 7705E	11 0 8416E 07	0,20000 02-0,395	30 03 0 24000 12	2
•	0 10935 02 0 74235)1 N 89335 07	0 50005 02-0 371	2 03 0 2400E 42	2
	A 1147E 02 0 7146C	1 0 0243E 07	0 50005 02-0 357	20 03 0 2400E 12	
	ñ 12505 02 0 68725	01 0.92102 07	0,00000 02-0,000	An 03 0 2100E 12	- >
	A 13330 02 0 66030	11 0 08665 07	0 50005 02+0 330	25 AT 0 21005 12	- 2
	A 14170 A2 A 63300	1 0 10000 07	0 50000 02-0+0300	2E 00 0+2100E 12	<u>.</u>
	A 1500C 02 0 6080C	10 101110 10 10110 10 10110 10 1010 10 10 10 100	0 5000E 02-0:31/	00 07 0 21000 12	-
	- 1583C 02 0.5000C	11 0 1007E 00	0 50000 02-0:004	30 03 0 21000 12	<u>-</u>)
	<u>8,16676 02 0,56206</u>	1 0,10785 08	0,00000 02-0,278	85 A3 A 240A5 12	- >
	A 1750C 02 0 5332C	1 0 1004C 08	0.50000 02 012/0	AE 03 0 2100E 12)
	à 18330 A2 A 5A036 I	1 0 11076 00	0.50005 02-0 264	78 03 0 74005 12	-
	A 1917E A2 A 486AE A	1 0,110/2 00	0 50000 02-0 243	7E 03 0 2100E 12	
	A 2000E 02 0 4631E 0	1 0.1126E 00	0.50000 02-0.240	65 03 0 21005 12	
	A 20835 02 0 44085 1	1 0 1131E 00	0 50005 02-0 220	45 03 0 2100E 12)
	A 21675 02 0 41915 (1 0 11355 08	0 50000 02-01220	7 00 0 2100E 12 5c 03 0 2408E 12	<u>-</u>
	n.2250F 02 0 3970F 0	1 0.11365 08	0 50000 02+0.198	06 03 0 2100E 12	<u>-</u>
	A 2333E A2 0 3772E (1 0 1136E 00	0 50000 02-01190	7E US 0+2100E 42	-
· •	A 2417E 02 0 3570E (1 0 1100C 00	0 50000 02-01100	SE NJ 0 2400E 12	-)
:	A 2500C 02 0.0374C (1 0 11000 08	0 50005 02-0.1/0	75 03 0+21005 12 75 03 0+21005 12	2
-	A 2583E 62 0 3184E 0	1 0 11236 08	0 5000E 02-01100	7 <u>5</u> 00 0+21005 12	
the transfer of the state of the state	A 2667E A2 A 2000E (1 0 11165 08	0 5000E 02-0.109	CE NA NICIONE 12	
• • •	A 27505 02 0,29992 0	4 0 11076 00	0 50005 02-0 440	25 00 0181005 12)
Ì	A.28336 02 0.26446 0	1 0 40965 08	0.50000 02-0,140	9F 03 0 2100E 12)
l i	A 29176 A2 A 24766 A	1 0 10845 00	0 50000 02-0+102	26 US V:2100E 12 76 A3 A 24AAE 12	
	A 3000E 02 0.2479E 0	1 0 10715 08	0 50006 02-0 115	25 03 0 24005 42 26 03 0 24005 42	
	6.3083E 02 0.2010E 0	1 6 10576 08	0 50000 02-0,107	KE 03 042100E 42	I
	A.3167E 02 0.1997E 0	1 0.10420 08	0.5000E 02*0.207	5E 02 0 2100E 12)
	A.3250E 02 0.1848E 0	1 0.10266 08	0.5000E 02+0.923	06 h2 h 21000 12	1
144114114114	A.3333E 02 0.1704E 0	1 0.10085 08	0,5000E 02-0,920 0.5000E 02-0.851	7E UZ U,2100E 12 Re n2 n 21nnE 12	
27.2.2.4.4.4.4.4.4.4.4.4.4.4.4.4.4.4.4.4	A 34175 02 0 18645 0	1 0.00030 07	0 50005 02-0,0710	JE UZ U,2100E 12	
,	0.3500E 02 0.1429E 0	1 0.97158 07	0.5000E 02-0.714	76 82 0.24006 12	
	ñ.3583E n2 0.1299E n	1 0.95196 07	0.50008 02-0.649	SE 02 0:2100E 12	
	1.3667F 02 0.1174F 0	1 0.9317E 07	0.5000E 02=0.586	3E 02 0.2100E 12	
	1.3750F 02 0.1052F 0	1 0.9109E 07	0.50000 02-0.526	2E 02 0.2100E 12	
	A.3833F 02 0.9355F 0	0 0.8896F 07	0.5000E 02-0.467	SE 02 0.2100E 12	
	1.3917F 02 0.8229F 0	0 0.8677F 07	0.5000F 02-0.411	SE 02 0.2100E 12	
	A.4000F 02 0.7145F 0	0 0.8455F 07	0.5000E 02-0.357	C 02 0.2100E 12	
	0.4083F 02 0.6100F 0	0 0.8229F 07	0.5000F 02-0.305	16 02 0.2100E 12	
	4.4167F 02 0.5095F 0	0 0.8000F 07 1	0.50008 02-0.254	7E 02 0.2100E 12	
	0.4250F 02 0.4128F 0	0 0.77688 07	0.5000E 02-0.2064	E 02 0.2100E 12	
	A.4333F 02 0.3197E 0	0 0.7534F 07 1	0.5000E 02-0.1599	E 02 0.2100E 12	
	0.4417E 02 0.2303E 0	0.72998 07	0.5000E 02-0.1152	E 02 0.2100E 12	
	1.4500E 02 0.1443F 0	0 0.70628 07	0.5000E 02-6.7217	'E 01 0.2100E 12	
	1.4583E 02 0.6176F=0	1 0.68256 07 1	0.5000E 02-0.308P	E 01 0.2100E 12	
	A.4667E 02-0.1759E+0	1 0.6587E 07 0	0.5000E 02 0.8793	SE 00 0:2100E 12	
	n.4750E 02-0.9379E-0	L 0.6350E 07 (.5000E 02 0.4690	E 01 0.2100E 12	
	n.4833E 02-0.1670E 0	0.6112E 07 (0.5000E 02 0.8349	F 01 0.2100E 12	

(Continued)

(Sheet 2 of 3)
Table B3 (Concluded)

	ñ.4917E n.5000E n.5083E	02-0.2372E 02-0.3047E 02-0.3695E	00 00 00	0,5876E 0,5641E 0,5407E	07 07 07	0.5000E 0.5000E 0.5000E	02 02 02	0.1186F 0.1524F 0.1848F	02 02 02	0.2100E 0.2100E 0.2100E	12 12 12
	6.5167E	02-0.4317E	00	0,5175E	07	0.5000E	02	0.2159E	02	0.2100E	12
	A.5250E	02-0,49158	00	D,4945E	07	0.5000E	02	0.2457E	02	0.2100E	12
	4,5333E	02-0.5489E	00	0.4718E	07	0.5000E	0 2	0.27446	02	0,2100E	12
	n.5417E	02-0.6040E	00	0,44938	07	0.5000E	02	0.3020F	02	0.2100E	12
	ñ.5500E	02~0.6570E	00	0.4272E	07	0.5000E	02	0.3285F	02	0.2100E	12
	n.5583E	02-0.7080E	00	0.4053E	07	0.5000E	02	0.3540E	02	0,2100E	12
	n.5067E	02+0.7570E	00	0.3838E	07	0.5000E	02	0.3785E	02	0.2100E	12
	1.5/50E	02-0.8043E	00	0.3627E	07	0.5000E	02	0.40218	02.	0.2100E	12
	7,2833E	02+0.84976	00	0.34206	07	0.50002	02	0.42498	02	0,2100E	12
	n+271/E	02-0.07500	00	0.32105	07	0.20005	02	0.4408	02	0,2100E	12
	7.0000E	02-0 07685	00	0 29240	0.7	0,50000	02	0.40002	02	0,21000	42
	A 61675	02-0,9700E	00	0.26202	07	0,20002	02	0.5092	02	0 24005	+ 2
• • • • • • •	A. 6250E	02-0.10556	01	0.20076	07	0.50000	02	a.5971#	62	100C	12
	6.63335	62-0.1092E	01	0.22758	07	0.50002	02	0.54506	62	0.21000	12
	ñ.6417F	02-0.1128E	01	0.2102E	07	0.50008	ñ2	0.56396	02	0.2100F	12
	A.6500E	02-0.1163E	01	0.1935E	07	0.5000E	02	0.58146	02	0.2100E	12
	A.6583E	02-0.1197E	01	0.1773E	07	0.5000E	02	0.5985F	02	0.2100E	12
	n:5667E	02-0.1230E	101	0.16188	07	0.5000E	02	0.61515	02	0.2100E	12
•	n.6750E	02-0.1263E	01	D.1468E	07	0,5000E	02	0.6314E	02	0,2100E	12
	ñ.6833E	02-0,1295E	01	0.1325E	ΰ7	0.5000E	02	0,6473E	02	0,2100E	12
	A.6917E	02-0.1326E	01	0,1188E	07	0.5000E	02	0.6629E	02	0,2100E	12
:	7000E	02-0.1356E	01	0,1059E	07	0,5000E	02	0.6782E	02	0.2100E	12
	9.7083E	02-0.1386E	01	0.9356E	06	0.5000E	02	0.6932F	02	0,21008	12
1	0.7167E	02-0.1410E	01	0.81956	06	0.5000E	02	0.70808	02	0.2100E	12
i	n./250E	02-0.14426	01	0,/1008	00	0.5000E	02	0+72276	02	0.2100E	12
and a state of the	n,/000E	02-0.14/48	01	0.00005	00	0.5000E	02	0./3/1F	02	0.21005	12
909-02070707070892;	4 7500C	02-0 15315	04	0.2177C	06	0.50000	02	0+72148 0 7454F	02	0.21005	42
	A.7583F	02-0.15596	01	0.34808	00	0.50000	n2	A.77976	02	0.21005	12
	n.7667F	n2-0.1587E	<u>n</u> 1	0.2762E	06	0,5000E	ñ2	0.79375	02	0.21005	12
	6.7750F	02-0.1615E	01	0.2124E	06	0.5000E	ñ2	0.80775	n2	0.21006	12
	n.7833F	02-0.1643E	01	0.1567E	06	0.5000E	02	0.8216F	ñ2	0.2100E	12
	n.7917E	02-0.1671E	01	0.1091E	06	0.5000E	02	0.83546	62	0.2100E	12
	ñ 8000E	02-0.1699E	01	0.6991E	05	0.5000E	ŏ2	0.8493E	02	0.2100E	12
	A.8083E	02-0.1726E	01	0.3933E	05	0.5000E	02	0.8631E	02	0,2100E	12
	ñ,8167E	02-0.1754E	01	0,1740E	05	0,500DE	02	0.8769E	02	0,2100E	12
	A.8250E	02-0.1781E	01	0.42248	04	0,5000E	02	0.8907F	02	0.2100E	12
	ń.8333E	02-0.1809E	01	0.		0.5000E	02	0,9045E	02	0,2100E	12

(Sheet 3 of 3)

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Figure Bll. Variation of moment along pile for Example Problem 2

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APPENDIX C: USER'S GUIDE FOR PROGRAM PX4C3

General Introduction

1. Documentation for the computer program PX4C3 - to analyze axially loaded piles in nonlinear soil media - is presented in this appendix and includes a general introduction, program listing, guide for data input, and input-output data for two example problems.

2. PX4C3 is a finite difference computer program (developed by Drs. L. C. Reese, UT at Austin, and H. M. Coyle, Texas A&M University)* that may be used to compute load-displacement relationships for axially loaded piles, where the pile has a constant outside diameter. The program employs a set of load transfer curves along the pile and a point resistance curve at the tip of the pile. Piles of different outside diameters can be solved using PX4C3 by adjusting the load transfer curves for a constant diameter.

3. A load transfer curve relates the skin friction developed on the side of a pile to the absolute axial displacement of a pile section. The point resistance curve refers to a relationship between the total axial soil resistance on the base of the pile tip and the pile tip movement. PX4C3 can handle nonlinear curves for both the above relationships. Some procedures for obtaining these nonlinear soil relations are described in the text (Part V).

4. PX4C3 employs finite difference equations to achieve compatibility between pile displacement and load transfer along the pile and between soil resistance and displacement at the tip of the pile. The method has been found to give good prediction for piles in clays. The program needs to be used with caution as load transfer curves used in the program are presently derived from semi-empirical criteria.

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^{*} H. M. Coyle and L. C. Reese, "Load Transfer for Axially Loaded Piles in Clay," <u>Journal, Soil Mechanics and Foundation Division, American</u> Society of Civil Engineers, Mar 1966.

5. Input may be input interactively at execute time, or input may be in a prepared data file. Output will come directly back to the terminal, or output will be directed to an output file.

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Guide for Data Input

Data should be input to program PX4C3 according to the follow-6. ing guide. All input is in free-field format.

Group I - Title

RUN

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RUN = 60 character problem heading

Group 2 - Problem Parameters

IQ, IJ, NA, IT, LSO
IQ = Number of increments on pile
IJ = Number of assumed tip movements (see \overline{Group} 7)
NA = Number of depths at which AE values are specified (see Group 4) (AE = cross-sectional area of pile X modulus of elasticity of pile)
IT = Number of points on the point bearing vs tip move- ment curve (see Group 5)
LSO = Option control to print out load-settlement data only 1 if only load settlement results are desired F1 all results are printed
Group 3 - Load Transfer Curve Data

Α.	NX,	NUM	 	 	 	

NX = Number of T-Z curves along the depth of the pile

NUM = Number of points on a T-Z curve. A zero point on a T-Z curve is required to be input.

Β.

(i) X(K)

(ii) PP, ZM

> X = Distance from top of pile to K^{th} T-Z curve. K goes from 1 to NX

PP = Load transfer lb/sq ft in T-Z curve ZM = Pile movement (in.) in T-Z curve Note: Set B should be repeated until NX T-Z curves have been specified. Line (ii) of Set B should be repeated with each set until NUM number of PP and ZM values have been specified for that set.

Group 4 - AE Data

AE(M),	ZAE(M)		 	····	
					•	
	A 77	<i>a</i>	 	 	- 0 - 7 -	

AE = Cross-sectional area times modulus of elasticity, lb ZAE = Depth to AE value, ft

Note: Repeat until NA sets of AE and ZAE values have been specified by putting one set per line.

Group 5 - Tip Load-Movement Data

TIPLD(M), TIPMV(M)

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- TIPLD(M) = Point bearing in the point bearing (lb) vs tip movement (in.) curve
- TIPMV(M) = Tip movement in the point bearing vs tip movement (in.) curve
- Note: Repeat until IT sets of TIPLD and TIPMV values have been specified by putting one set per line.

Group 6 - Pile Data

U, ALGTH, OD

U = Tolerance for convergence on displacements (in.)

ALGTH = Length of pile, ft

OD = Outside diameter of pile, ft

Group 7 - Desired Tip Movements

P

P = Assumed tip displacements, in.

Note: This line is repeated IJ number of times.

Example Problems

Example Problem 1

7. The first example problem illustrating the use of program PX4C3 shows a pile being subjected to a pullout test (Figure Cl). The input T-Z curves and the input data for this example are shown in Figure C2 and Table Cl, respectively. The computer output is presented in Table C2, and the load-displacement curve is plotted in Figure C3.



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Figure C2. Input load transfer (T) versus pile movement (Z) curves for Example Problem 1

Table Cl

Input Data for Example Problem 1

10 20 30	PREĎ 33,1 7,9	1CT 3+2	101 12.	v (DF	PULLOUT	CURVE	FÖR	A	PILE
50	0.0									
60	0.0,	1								
70	0.0.	2								
80 60	0.0.	3 ∡								
100	5.01	.5								
110	0,0	.6								
120	0+1	0								
130	DiĪ	D								
140	0.7	5								
150	0+ Ņ	¤ 7								
100	81.	221 36.	0+1)UU 102	ןע. ₽7					
	400	.8.	8.(304	15					
190	112	.0.	00	62	-					
200	120	.3,	Ö • (508	5					
210	126	• 0 •	<u>0</u> 0	28						
220	120	.0.	2.4)1						
200 248	120		10							
250	- 0 - 0									
260	132	.2,	0.1	001	L6					
270	268	.8,	Ŭ+1	004	18					
280	337	.2,	0.1	00)					
290	381		0+1	013						
300	410	• 4 •	0.1	31° 77	12					
320	402	. 6 .	6.1	, / n i i i	22					
330	441	. 6 .	30							
340	3.5									
350	0.0									
360	237	.6.	0+	002	25					
370	486	• 0 •	<u>Ö</u> Ö	74						
300	- 810 - 407	·U•	010	24 841	1 A					
400	- 87/ - 75n		19 1 19 2 1	シン・	••					
410	789	. 6,	02	02	72					
420	805	.2,	0.	02	96					
430	811	.2,	ĩ0							
440	5									
450	0.0		•	·						
100 470	338	141	Ū+	U () . n 4	35					
=70	- 7 0 9	.01	0.	μL.						

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(Continued)

Table Cl (Concluded)

480 890.4.0.0167 490 1008,0.0233 500 1086.0.03 510 1146.0.0367 520 1188,0.0433 530 1188,10 540 6.5 550 0,0 560 436.8,0.004 570 906,0.0126 580 1158,0.021 590 1317,0.0294 600 1440,0,0378 610 1488,0,046 620 1554:0-0545 630 1560:10 640 8.25 650 0,0 660 549.6,0.00535 670 1152.0.0165 680 1476+0-02676 690 1674:0-0374 700 1806:0.0482 710 1908.0.0588 720 1986:0-0695 730 1992.10 740 11500000,0 750 11500000,8.25 760 0.0 770 0,10 780 0.000178.25,0.167 790 0.0001 800 0.0007 810 0.0015 820 0.003 830 0.005 840 0.01 850 0,016 560 0.02 870 0.03 880 0.05 890 0.1 900 0.11 910 0.12

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Table C2 Output Data for Example Problem 1

PREDICTION OF PULLOUT CURVE FOR A PILE

AXYALLÝ LOADED PILE, CONSTANT OD

	P-Z	CURVE NO.	1	NO, OF BOINTS	9	DEPTH TO	CURVETT	Ø.
		LCAD TRANSFER LD/SQ FT 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.	·	PILE MOVEMENY INCHES 0. 0.2000E 00 0.2000E 00 0.3000E 00 0.3000E 00 0.5000E 00 0.5000E 00 0.4000E 02 0.4000E 02				-
	P+Z	CURVE NO.	2	NO. OF REINTS	9	DEPTH TO	CURVE,FT	0.750E 0f
×		LOAD TRANSFER LB/SQ FT 0. 4152E 02 0.8136E 02 0.1008E 03 0.1208E 03 0.1208E 03 0.1266E 03 0.1266E 03 0.1266E 03		PILE MOVEMENT INCHES 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.				
	₽÷Z	CURVE NO.	3	NO. OF ROINTS	9	DEPTH TO	CURVEFT	0.200E 01
		LOAD TRANSFER LB/SQ FT 0.1322E 03 0.2688E 03 0.3372E 03 0.3816E 03 0.4104E 03 0.4320E 03 0.4416E 03		PILE MOVEMENT INCHES 0. 20. 2000E-02 0.4800E-02 0.4800E-02 0.4800E-02 0.4100E-01 0.1450E-01 0.1450E-01 0.1450E-01				

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(Sheet 1 of 4)

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Table C2 (Continued)

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		0.4418E 0	5	041000E 02					
	P-Z	CURVE NO.	4	NO. OF ROINTS	9	DEPTH TO	CURVEFT	0.350E 01	
		LOAD		WILE					
		TRANSFE	7	HOVEMENT					
		LB/SQ F	ſ	INCHES					
		0.2378E D	5	0.25088-02					
		0.4860E 01	5	0.7408E-02					
		0.6180E 0	5	0+1248E+01					
		0.6972E 0	5	0117488-01					
		0.7900E 00) (0.42295704					
		0.80528 03	Ś	0.29685-01					
		0,8112E 0	5	0.1008E 02					
	'-Z	CURVE NO.	5	NO. OF POINTS	9	DEPTH TO	CURVE FT	0,500E 01	
		LOAM		P 11 5					
		RANSFE	2	MOVEMENÝ					
•••••••		LB/SQ F	Ι	INCHES					
an an an Christer ann an Anna			 •	0,000		an an an Artainn. An Artainn			•••
		0,33048 00	, t	0.4000C-02		,			
		0.8904E 0	ĵ,	0.16785-01					
		0,1008E 0/	ł	0+2338E-01					
		0.1086E 00		D-5008E-01					
		0.1146E 04		0,43389+0%					
		0,1188E 04	ļ	0.1008E 02					
		CUDVE NO	6	NO OF POINTS	0		CHONE . FT	A 65A5 88	
	-7	CURVE NOT	0	NUT OF BUINTS	У	DEFIG TO	GUNYEIFI	0.0205 01	
		LOAD		PILE ·					
		TRANSFER	1	HD VEHEN T					
			Ī	ANCHES					
		0.4368E 05	5	0,4008E-02					
•		0.9060E 03	5	0-1268E-01					
		0.1158E 04	ł	0.2108E-04					
		0,1317E 04	•	D-2948E-01					
		0.1488F 04	1	0.460BE-01					
		0.1554E 04	ļ	0,54586-01					
		0,1560E 04	ļ	0.1000E 02					
	- Z	CURVE NO.	7	NO. OF ROINTS	9	DEPTH TO	CURVE . FT	0,825E 81	
		1048		92 T I 15					
		-RANSFEI	1	MOVEMEN					
		LB/SQ F1		INCHES					
				10	•	a)			

(Continued)

(Sheet 2 of 4)

Table C2 (Continued)

• • •	0. 0. 0.5496E 03 0.5 0.1152E 04 0.1 0.1476E 04 0.2 0.1674E 04 0.4 0.1674E 04 0.4 0.1806E 04 0.4 0.1908E 04 0.5 0.1986E 04 0.5 0.1992E 04 0.1	350E-02 650E-01 676E-01 740E-01 820E-01 880E-01 950E-01 00BE 02	
	AE PILE LBSV 0.11500E 08 0.11500E 08	DEPTA Ft. 0.82500E 01	
. i	POINT BEARING LOAD D. O.	TIR MOVEMENT 0. 0.10000e dz	
an servan oo soo Maajiy	TOLERANCE 0,1000E-03	PILE LENGTH FT U.8250E 01	O,1670E 00
-3915355809555	ASSUMED TYP MOVEMENT IN 0.1000E+03 0.7000E+03 0.1500E+02 0.3000E+02 0.1000E+01 0.1600E+01 0.3000E+01 0.3000E+01 0.3000E+01 0.3000E+01 0.1000E 00 0.1100E 00 0.1200E 00	POINT BEARING LB C. O. O. O. O. O. O. O. O. O. O. O. O. O.	

AXTALLY LOADED PILE, DONSTANT OD

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(Continued)

(Sheet 3 of 4)

TOP LOAD IOP FOVEMENT LBS INCHES 0.5811E 02 0.3409E-03 0.2372E-02 0.3918E 03 0.7652E 03 0.4950E-02 0.1315E 04 0.93116-02 0.1809E 84 0.1406E-01 8.2552E 84 0.2338E-01 0.3113E 84 0.3294E-01 8.3366E 04 0.3855E-01 1.3756E 84 0.5119E-01 0.4096E 04 0.7361E-01 6.4190E 04 0.1243E 00 0.1343E 00 0.4190E 04 0,4190E 84 0.1443E 00 ್ರಶ 🐔 🔭

Table C2 (Concluded)

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(Sheet 4 of 4)





Example Problem 2

8. To demonstrate further the use of program PX4C3, a second example problem is given. Figure C4 shows the physical problem for this example. The input T-Z curves and the input data for this problem are shown in Figure C5 and Table C3, respectively. The computer output is presented in Table C4, and the load-deflection curve for the pile is plotted in Figure C6.







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Input Data for Example Problem 2

	0010	TEST 201 12.7	5 DIA PILE	L _O ADED	IN COMPRESSION	FROM ARKA	NSAS RIVER
	0030	7.8					
•	0040	0					
	0050	0,0					
	0000	0,5					
	0080	0.5					
	0090	0,5					
	0100	0,5					
	0120	0,5					
	0130	1,6667					
ť	0140						
i i i i i i i i i i i i i i i i i i i	0150 0160	37,510,0105 81,510,0346					-
	0170	91,0,055					
	05180	100,0.0735					
	0190	100,1					
	0200	100+2					
	0220	5	* • . • * *				
	0230	0.0					
·	0240	169:0.0346					
-	0250	272+0-1035					
!	0270	295,0,138					
	0280	310,00173					
สายสายสายสายสายสายสายสายสายสายสายสายสายส	0270	310+2					
n or regeneration of the second second	0310	8.3333					
	0320	0.0					
	0330	273,0,051					
	0350	448.0.153					
	0380	486,0,204					
	0370	510,0,255					
	0380	510.2					
• • •	8390 1411	210,2 11,6667					
	0410	0.0					
	0420	379,0,0674					
	0430	235,0,1450 615,0 202					L
	0450	675:0027					
		· · · · · · ·					

(Continued)

Table C3 (Concluded)



Table C4

Output Data for Example Problem 2

	TES	Ť 201 ≰2,75	DIÁ	PILE LOADED IN C	DMPRE	SSION FROM	ARKANSAS	RIVER	
		AXTALLY	LOAD	ED PILE, GONSTAN	T 0D				
	P4Z	CURVE NO.	1	NO. OF POINTS	8	DEPTH TO	CURVE, FT	0.	
		LOAD Transfer Lb/sg ft		RILE Movemeny Inches					
		0, 0, 0,		019008E 01 019008E 01 019008E 01 019008E 01 019008E 01			<i></i>		
		0. 0. 0.		0.9008E 01 0.9008E 01 0.9008E 01			.::C #		
e de la companya de l	PrZ	CURVE NO.	2	NO. OF BOINTS	8	DEPTH TO	CURVE.FT	0.167E	01
		LOAD TRANSFER Lo/sq ft	, ., ., ., ., ., ., ., ., ., ., ., ., .,	RILE MOVEMENT INCHES					
กระบบสีรายการเป็น		0. 0.5950E 02 0.8150E 02 0.9100E 02 0.1000E 03 0.1000E 03 0.1000E 03 0.1000E 03		0. 0.1830E-01 0.5666E-01 0.5508E-01 0.7358E-01 0.1008E 01 0.2008E 01 0.2008E 01					
	P - Z	CURVE NO.	3	NO. OF ROINTS	8	DEPTH TO	CURVE, FT	8,500E	01
1		LOAD TRANSFER LB/SQ FT		RILE MOVEMEN _T Inches 0.					
<i>!</i>		0,169#E 03 0,2380E 03 0,272nE 03		0,6918E-01 0,6918E-01 0,1037E 08					
:		0.295pE 03 0.3100E 03 0.3100E 03 0.3100E 03 0.3100E 03		0+1388E 00 0+1738E 00 0+2008E 01 0+2008E 01				•	
	P-Z	CURVE NO.	4	NO. OF ACINTS	8	DEPTH TO	CURVE,FT	Ø,833E	01

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(Sheet 1 of 3)

Table C4 (Continued)

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		LOAD TRANSFER LB/SQ FT		RILE MOVEMENT Inches	
Υ.		0.2735E 03 0.3876E 03		0.9100E-04 0.1020E-04	
		0,4480E 08 0.4860E 08 0.51065 03		0.1538E 00 0.2048E 00 0.2558E 00	
		0.5100E 03 0.5100E 08		0+2008E 01 0+2008E 01	
	P-Z	CURVE NO.	5	NO. OF HOINTS 8	DEPTH TO CURVE, FT 0.117E 02
	/	LOAD Transfer Lo/SQ Ft		RILE Movemen i Inches	
takan 1		0. 0.379dE 08 0.535dE 03		0. 0.4748E+01 0.11456E 00	
ta ay ina kanalan tan	7	0.0100E 03 0.6750E 03 0.7136E 03 0.7136E 03	• •	0.2708E 00 0.5368E 00 0.2008E 00 0.2008E 01	te l'élégie de la substance en la sub-
:	P-Z	0.7138E 08	6	NO. OF POINTS 8	SEPTH TO CHRVE.FT & 1566 B#
1919		LOAD TRANSFER LB/SQ FT	-	RILE Movemen ş Anches	
		0. 0.4805E 05 0.6825E 05 0.7935E 03		0+ 0+8358E+04 0+3678E 08 0-3568E 08	
		0.8640E 08 0.9100E 08 0.9500E 03		0.5345E 00 0.4155E 00 0.2005E 00	
•	P∸Z	0.9500E 03 CURVE NO.	7	0.7008E 01	
		LOAD TRANSFER LB/SQ FT	·	RILE MOVEMENT (NCHES	
		0.4800E 08 0.6820E 08 0.7930E 03		0.8350E-01 0.1670E 00 0.2500E 00	
		0.9108E 03		0.4180E 00	

(Continued)

(Sheet 2 of 3)

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Table C4 (Concluded)

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	0.9500E 03 0. 0.9500E 03 0.	9008E 00 9008E 01	
	AE PILE	DEPTH	
	0.49608E 09 0.49608E 09	0.53333E 02	
	POINT BEARING LOAD	TÎR MOVEMENT 0,	
• • •	0.2000bE 05 0.40000E 05 0.50000E 05	0.10000E+01 0.20000E+01 0.40000E+01	
de la companya da companya Tanàna dia kang da cana da companya da c	0+70008E 05 0+80008E 05 0+90008E 05 0+90008E 05	0.10000E 00 0.32000E 00 0.10000E 01 0.10000E 02	
	TOLERANCE	PTIE LENGTA	OUTER DIA
	0+1000E+03	8.5333E 02	0,1060E 01
ESS ING STATE	ASSUMED TYP MOVEMENT IN 0.2000E+01 0.4000E+01 0.8000E+01 0.1000E 00 0.1900E 00 0.2000E 00	POINT BEARING LB 0.4000E 05 0.5000E 05 0.6333E 05 0.7000E 05 0.7227E 05 0.7455E 05	
	0.3000E 00 0.6000E 00 0.1200E 01 0.2000E 01	0.7909F 05 0.8412E 05 0.9000E 05 0.9000E 05	
	AXYALLÝ LOXDED Top Load Løs	PILE, CONSTANT OD Top Movement Inches	
	8487E 85 8.1164E 86	0.9748E+01 0.1461E 00	>
	ロ・1220日 日の き・1771日 きん ビ・1861日 ぎん ※ メタガマロ あん	0,2586E 00 0,2586E 00 0,3229E 00 0,3832E 00	
	0.17732 00 0.2184E 06 0.2285E 06 0.2344E 06 0.2344E 06	0,4989E 00 0,4989E 00 0,4144E 00 0,4422E 01 0,2222E 01	

(Sheet 3 of 3)





APPENDIX D: USER'S GUIDE FOR PROGRAM MAKE

General Introduction

1. Documentation for the computer program MAKE - to generate soil resistance versus lateral pile movement curves based on laboratory triaxial test results - is presented in this appendix and includes a general introduction, program listing, guide for data input, and inputoutput data for two example problems.

2. MAKE is a computer program (developed by Dr. Frazier Parker, WES) that can generate soil resistance (p) versus pile movement (y) curves for soils surrounding a laterally loaded pile based on certain laboratory soil test results. The program uses different criteria for clays and sands (as explained in Part V of this report) and can be used (with some minor modifications) as a subroutine to the laterally loaded pile program (COM62) or to the BENTL program. MAKE can handle any number of stratums of clay or sand and can also account for various pile diameters.

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Input may be input interactively at execute time, or input may be in a prepared data file. Output will be directed to an output file.

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Guide for Data Input

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	4. Data should be input to program MAKE according to the follow- ing guide. All input is in free-field format and should be in units of
	pounds, inches and radians. A flow chart for data input is shown in
	Group 1 - Profile Data
	INSOILP
	NSOILP = Number of soil profiles (one value per run)
	Group 2 - Soil Data
ų	A. INSTYPE
	NSTYPE = Number of soil stratums (one value per profile)
	B. TSOIL
	TSOIL = Alphanumeric designation of type of soil in stratum (sand or clay)(one value per stratum)
	= Sand input line set C and omit line set D for this stratum
n musika	= Clay input line set D and omit line set C for this stratum
	Note: A space (blank) must be left between the file line number and the parameter TSOIL.
	C. Sand Properties
÷	GAMMA, PHI, DIS1, DIS2, KDENSE
:	
:	GAMMA = Unit weight of soil
	PHI = Angle of internal friction
	DIS1 = Distance from ground line to top of stratum
	DIS2 = Distance from ground line to bottom of stratum
	KDENSE = Alphanumeric designation for relative density of sand
	= DENSE, MEDIUM, OR LOOSE
•	۲ d

D.	Clay Properties
	(i) GAMMA, SHEARS, DIS1, DIS2, INFO, ICON
	GAMMA = Unit weight of clay
	SHEARS = Cohesion of clay
	DIS1 = Distance from ground line to top of stratum
	DIS2 = Distance from ground line to bottom of stratum
	<pre>INFO = Control for input of stress-strain curve 0 Omit data for curves by omitting cards that follow in this group 1 Input data for curves by specifying cards that follow in this group</pre>
	ICON = Alphanumeric designation for consistency of clay (SOFT or STIF)
	(ii) NCURVS
	NCURVS = Number of curves per stratum
	(iii) DIST, NPOINT
	DIST = Distance from ground line to curve
	NPOINT = Number of points on curve
	(iv) SIGD, EP
	SIGD = Principal stress difference $(\sigma_1 - \sigma_3)$
	EP = Axial strain

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- Note: Repeat (iv) until NPOINT number of points have been specified for that curve.
- Note: Repeat (iii) until NCURVS number of curves have been specified for that stratum.
- Note: Repeat Group 2B and 2C or Group 2B and 2D NSTYPE times.

Group 3 - Pile Data

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NPISP Α. NPISP = Number of different piles in this soil profile (one value per soil profile) Note: Repeat set B until NPISP sets have been specified. (i) KS, NOC, NDD Β. KS = Numeric identifier for set of p-y curves NOC = Number of curves in set NDD = Number of different diameters used for p-y curves (ii) D, DISD1, DISD2 ్ లో క D = Pile diameterDISD1 = Distance from top of pile to top of section DISD2 = Distance from top of pile to bottom of section Note: Repeat (ii) until NDD sets of values have been specified. (iii) DTC DTC = Distance from top of pile to p-y curve Note: Repeat (iii) until NOC values have been specified.

Note: Repeat Groups 2 and 3 NSOILP number of times.

D5



INPUT FLOW CHART

Figure D1. Input flow chart for MAKE

Example Problems

5. To illustrate the use of program MAKE two example problems will be demonstrated. The soil profiles and the pile dimensions used in the two examples are shown in Figure D2. The soil profile for the first example consists of two layers of clay and for the second example,



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two layers of sand. Each example requires the generation of two sets of p-y curves corresponding to two different pile configurations. The input and output data for both examples are given in Tables D1 and D2. The generated p-y curves are shown plotted in Figures D3 and D4 for Example Problem 1 and Figures D5 and D6 for Example Problem 2.

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Table D1

MAKE Input Data for Example Problems 1 and 2

0010 2 0020 2 0030 CLAY 0040 0.09+40+0220020+8 0050 CLAY 0060 0.07,60,2140010,0 0070 2 0080 1,4,1 0090 10,0,400 0100 0 the state of the s at in the second . 0130 400 0140 2,3,2 0150 10,0,100 0169 5,1007400 0170 0 0180 100 0190 300 0200 2 0210 SAND 0220 0.05/0.524,0/2001 MEDUM 0230 SAND 0240 0.06,0.7855,200,400, DENSE 0250 2 0260 4.5.1 0270 10:0:400 0280 0 0290 100 0300 200 0310 300 0320 400 0340 20,0,100 0350 10,108,400 0360 0 0370 50 0380 200 0390 300 0400 400

D8

Table D2 Output Data for Example Problems 1 and 2

INPUT OF SOIL PARAMETERS

STRATUN NO. . 1 TYPE SOIL CLAY SOIL PROFILE NO. 1 UNIT CORESION TOP BOTTOM CONSISTENCY DEPTH DEPTH WEIGTH 0,2000E 07 0v4000E 82 0. 0 0+9000E-01 STRATUM NO ... SOIL PROFILE NO. 2 TYPE SOIL CLAY 1 CONSISTENCY BOTTOM UNIT COHESION TOP WEIGTH **BEPTH** DEPTH 0.2000E 01 0.4000E 07 0 0,7000E-0¥ 076000E 62

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PROPERTIES OF PILE USED FOR GENERATION OF PY-CURVES

SET IDENTYFIER NOV 1 NUMBER OF CURVES IN SET 4

DIAMETER DISTRIBUTION FOR PILE

DIAMETER	TOR DIS	BOT DIS
0,1000E 02	02	0,4000E 03

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1	DEPTH	TO CURVE 0.
		DEFLECTION
		0.
		0.12006-01
		0.1000E 03
	1	1 DEPTH

CURVE NO.	2	DEPTH	TO CURVE 0,1000E	03
SOIL REACTION			DEFLECTION	
Ü.			0.	
0,1391E 04			0.4000E-01	
0,1968E 04			0.0006-01	
0.24102 04			0.\$2005 00	
Ø.2783E 04			0.1600E 00	
0.3111E 04			0,2000E 00	
0.34088 04			0.240NE 00	
0.3681E 04			0.2800E 00	
0,3935E 04			0.4200E 00	
0.4174E 04			0.3600E 00	
0.4400E 04			0.4000E 00	
0.44002 04			0.1000E 03	

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(Sheet 1 of 5)



(Continued)

(Sheet 2 of 5)



DIAMETER DISTRIBUTION FOR PILE DIAMETER TOP DIS BOT DIS 0.1000E d2 0. 0,4000E 03 CURVE NO. 1 DEPTH TO CURVE 0. SOIL REACTION DEFLECTION Ò, ٥. 0.1000E 01 Ö. . ٥. 0.1000E 03 CURVE NO. 2 DEPTH TO CURVE 0,1000E 03 SOIL REACTION DEFLECTION 0. ٥. 0.11242 04 0.5057E 00 0.11246 04 0.1000E 03 SOIL REACTION DEFLECTION 0. ۵. 0.2908E 04 0.6543E 00 0.2908E 04 0.1000E 03 CURVE NO. 4 DEPTH TO CURVE 0,3000E 03 SOIL REACTION DEFLECTION ٥. 0. 0.3491E 05 0.1904E 01 0.3491E 05 0.10008 03 CURVE NO. 5 DEPTH TO CURVE 0,4000E 03 SOIL REACTION DEFLECTION 0. 0. 0.46548 05 0.1904E 01 0.46548 05 0,£000E 03 SET IDENTIFIER NOV 5 NUMBER OF CURVES IN SET 5 DIAMETER DISTRIBUTION FOR PILE DIAMETER TOP DIS BOT DIS 0.2000E 02 Û¥. 0.1000E 03 0.1000E d2 0.1000E 83 0.4000E 03

(Continued)

(Sheet 4 of 5)

Table D2 (Concluded)

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CURVE NO. 1 DEPTH TO CURVE 0, SOIL REACTION DEFLECTION ٥. Ο. ٥. 0.1000E 01 0.2000E 03 ٥. CURVE NO. 2 DEPTH TO CURVE 0,5000E 02 SOIL REACTION DEFLECTION 0,3811E 03 0,3811E 03 0. 0.3430£ 00 . 0.2000E 03 CURVE NO. 3 DEPTH TO CURVE 0,2000E 03 SOIL REACTION DEFLECTION ್ರುಲ 🗐 🕈 0. 0. 0.6543E 00 0.29088 04 0.2908E 04 0.1000E 03 • • • CURVE NO. 4 DEPTH TO CURVE 0,3000E 03 . . . SOIL REACTION DEFLECTION Ò. 0. 0.3491E 05 0.1904E 01 0.3491E 05 0.1000E 03 ł . CURVE NO. 5 DEPTH TO CURVE 0,4000E 03 SOIL REACTION DEFLECTION 新聞開始 ō. ō. 0.46548 05 0.1904E 01 0.4654E 05 0.10008 03

(Sheet 5 of 5)





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Figure D4. p-y curves for Example Problem 1 - Set 2 $\,$



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Figure D6. p-y curves for Example Problem 2 - Set 2

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APPENDIX E: USER'S GUIDE FOR PROGRAM BENTL

General Introduction

1. Documentation for computer program BENT1 - to analyze twodimensional group pile problems - is presented in this appendix and includes a general introduction, a computational flow chart, a glossary of notation, program listing, guide for data input, and two example problems with input-output data.

2. BENTL is a computer program (developed by Drs. L. C. Reese, UT at Austin, and F. Parker,* WES) written to solve two-dimensional problems involving pile-supported foundations subjected to inclined and eccentric loadings. It is a modification of programs developed previously at UT, Austin. It consists of an iterative solution for the three equilibrium equations developed in Part IV using methods described in . Part V to handle the nonlinear behavior of individual piles. The purpose of the iterative procedure is to find the deflected position of the structure so that equilibrium and compatibility are satisfied. The pile cap is assumed to be rigid in the analysis. BENTL uses COM62 and MAKE as subroutines in the program.

3. Input for BENT1 consists essentially of the geometry of the foundation and the axial load-settlement curve. The lateral behavior of individual piles may be either described by inputting a table of p-y curve values or by inputting soil properties and activating subroutine MAKE to generate the p-y curves. Subroutine COM62 is used to compute response of individual piles in the group to lateral loads.

4. The program outputs the lateral load, bending moment, and axial load sustained by each pile in a group pile foundation besides providing other supplementary information. Successive applications of the program can be made to determine the optimum design of pile

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^{*} F. Parker, Jr., and W. R. Cox, "A Method for Analysis of Pile Supported Foundations Considering Nonlinear Soil Behavior," Research Report 1171, 1969, Center for Highway Research, University of Texas, Austin, Tex.

foundations including pile sizes and arrangement of pile in the foundation.

5. Input may be input interactively at execute time, or input may be in a prepared data file. Output will be directed to an output file.

6. A group pile program called GROUP developed by Dr. Katsuyuki Awoshika* under the guidance of Prof. L. C. Reese is presently available. GROUP can perform the same type of analysis as BENT1 but is considered more efficient.

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^{*} K. Awoshika and L. C. Reese, "Analysis of Foundation with Widely Spaced Batter Piles," Research Report 117-3F, 1971, Center for Highway Research, University of Texas, Austin, Tex.

- Flow Chart

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7. A flow chart for the iterative solution used in the program is shown in Figure El.



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Guide for Data Input

8. Data should be input to program BENT1 according to the following guide. All input is in free-field format and should be in units of pounds, inches, and radians. The data input for subroutine MAKE with its input flow chart (Figure E2) is also included.

· Group 1 - Title

ANUM	

ANUM = 60 character variable to identify problem

Group 2 - Foundation Load and Control Data

	PV, PH, TM, TOL, KNPL, KOSC	
	PV = Vertical load on foundation	
	PH = Horizontal load on foundation	
	TM = Moment on foundation	• • • • •
	TOL = Iteration tolerance (tolerable deflection dif	ference)
	KNPL = Number of pile locations	
i niddilechings	KOSC = Switch to control oscillating solution 0 for normal use 1 if solution oscillates	
Grou	p 3 - Control Data for Pile Locations	

DISTA,	DISTB,	THETA,	POTT,	ĸs,	KA
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	DISTA =	Horizontal coordinate of pile top
	DISTB =	Vertical coordinate of pile top
	THETA =	Pile batter
	POTT =	Number of piles at a location
	KS =	Identifier to relate to p-y curve
	KA =	Identifier to relate to axial settlement curve
Not	e: Repeat	Group 3 until KNPL sets have been specified

	A. NN, HH, DPS, NDEI, TC, FDBET, E
	NN = Number of increments
	HH = Increment length
	DPS = Distance from pile top to soil surface
	NDEI = Number of different flexural stiffness values specified
	TC = Alphanumeric designation for top connection of pile (FIX; PIN; or RES)
	FDBET = Rotational restraint value (not needed unless TC=RES)
	E = Pile diameter or width
	B. RRI, XX1, XX2
	RRI = Flexural stiffness (EI) of a section
	XX1 = Distance from pile top to top of section
4	XX2 = Distance from pile top to bottom of section
storingholder -	Note: Repeat Set B until NDEI sets have been specified.
	Note: Repeat Group 4 until KNPL sets have been specified.

Group 5 - Control Data for Soil Properties

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NKA, NKS, KOK NKA = Number of load settlement curves NKS = Number of sets of p-y curves KOK = Switch for input of p-y curves (KOK = 0 p-y curves input KOK = 1 p-y curves generated) Group 6 - Control and Data for Axial Load Settlement Curves

Α. IDEN, IO IDEN = Identifier for axial load settlement curve (corresponds to KA) IO = Number of points on curve ZZZ, SSS в. ZZZ = Axial settlement SSS = Axial load Note: Repeat Set B until IO sets have been supplied. Note: Repeat Group 6 until NKA sets have been supplied. Group 7 - Control Data for p-y Curves (Necessary only if KOK = 0, NKS sets per problem) Α. IDPY, KNC IDPY = Identifier for set of p-y curves (correspond to KS) KNC = Number of curves in set в. NP, XS NP = Number of points on curve XS = Distance from ground line to curve Note: Repeat Set B until KNC values have been supplied. YC. PC C. YC = Deflection on curve PC = Soil reaction on curve Note: Repeat Set C within each Set B until NP sets are specified.

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Note: Repeat Group 7 until NKS sets have been supplied.

If p-y curves are to be generated (i.e., KOK = 1), the data for subroutine MAKE will follow.

Subroutine MAKE

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Group 8 - Profile Data

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NSOILP = Number of soil profiles (one value per run)

Group 9 - Soil Data

A. NSTYPE

NSTYPE = Number of soil stratums (one value per profile)

- B. TSOIL
 - TSOIL = Alphanumeric designation of type of soil in stratum (sand or clay) - one value per stratum
 - = Sand --- input line Set C and omit line Set D for this stratum
 - = Clay --- input line Set D and omit line
 Set C for this stratum
- Note: A space (blank) must be left between the file line number and the parameter TSOIL.
- C. Sand Properties

GAMMA, PHI, DIS1, DIS2, KDENSE

GAMMA = Unit weight of soil PHI = Angle of internal friction DIS1 = Distance from ground line to top of stratum DIS2 = Distance from ground line to bottom of stratum

- - = DENSE, MEDIUM, or LOOSE
- D. Clay Properties
 - (i) GAMMA, SHEARS, DIS1, DIS2, INFO, ICON

GAMMA = Unit weight of clay

- SHEARS = Cohesion of clay
 - DIS1 = Distance from ground line to top of stratum
 - DIS2 = Distance from ground line to bottom of stratum
 - INFO = Control for input of stress-strain curve
 0 --- omit data for curves by omitting cards that
 follow in this group
 1 --- input data for curves by specifying cards
 that follow in this group

(ii) NCURVS

NCURVS = Number of curves per stratum

(iii) DIST, NPOINT

DIST = Distance from ground line to curve

NPOINT = Number of points on curve

(iv) SIGD, EP

SIGD = Principal stress difference $(\sigma_1 - \sigma_2)$

EP = Axial strain

Note: Repeat (iv) until NPOINT number of points have been specified for that curve.

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- Note: Repeat (iii) until NCURVS number of curves have been specified for that stratum.
- Note: Repeat Group 9B and 9C or Group 9B and 9D NSTYPE times.

Group 10 - Pile Data

A. -NPISP

NPISP = Number of different piles in this soil profile one value per soil profile

Note: Repeat Set B until NPISP sets have been specified.

B. (i) KS, NOC, NDD KS = Numeric identifier for set of p-y curves NOC = Number of curves in set NDD = Number of different diameters used for p-y curves (ii) D, DISD1, DISD2 D = Pile diameter DISD1 = Distance from top of pile to top of section DISD2 = Distance from top of pile to bottom of section Note: Repeat (ii) until NDD sets of values have been specified. (iii) DTC

DTC = Distance from top of pile to p-y curve

- Note: Repeat (iii) until NOC values have been specified.
- Note: Repeat Groups 9 and 10 NSOILP number of times.

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Figure E2. Input flow chart for subroutine MAKE

Example Problems

9. The two example problems (extracted from Parker and Cox*) are associated with actual bents, used by the Texas Highway Department for supporting bridges on the Gulf Coast of Texas. The geometry of the bents, properties of the piles and soil, and loads on the bents were obtained from highway department files.

10. The bents considered in the example problems are used in bridges located on the Gulf Coast of Texas. There are two basic reasons why bents of this type were selected for analysis by the proposed method. The first reason is that soil conditions in this area are consistently bad which makes piles necessary for bridge foundations. The second reason is that high lateral loads are common. These are due primarily to wind and wave action. During hurricanes the lateral loads may be quite high. The use of long piles and high lateral loads makes the proposed method of analysis seem very attractive for these bents. Copano Bay Causeway

The first example problem considered will be one of the bents 11. used in the Copano Bay Causeway. The bridge is located in Aransas County on State Highway 35 between Port Lavaca and Rockport. The bridge is 920 ft in length and provides 50 ft vertical clearance at the center of the span. The roadway is supported by precast-prestressed concrete girders. The bent caps, columns, and footings are reinforced concrete. The bent heights vary from 20 to 50 ft. The bent analyzed is shown in Figure E3. The piles used are battered in four directions to resist horizontal forces perpendicular and parallel to the roadway. Only the case where the horizontal load is perpendicular to the roadway will be considered. For this case, the two interior piles in each footing, which are battered parallel to the roadway, will be treated as vertical piles. The bottom tie beam is considered to provide sufficient rigidity so that the assumption that the pile heads remain in the same plane after movement is valid.

12. The geometry necessary for describing the foundation for the

* Ibid p. El

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computer solution is presented in Figure $E^{l_{4}}$ and the following tabulation.



Figure E4. Foundation representation for Example Problem 1

	Pile Location	a Coordinate in	b Coordinate in.	No. Piles at <u>Location</u>	Batter <u>radians</u>
lander	l	-126	0	l	-0.244
	2	-90	0	2	0.0
	3	+90	0	2	0.0
	4	+126	0	l	+0.244

The coordinate system and the resulting forces on the bent are also shown in this figure. The piles are 18-in.-square prestressed concrete piles. They have an effective flexural rigidity of 4.374×10^{10} lb-in.² (assuming a modulus of elasticity for concrete of 5×10^{6} psi) and a length of 93 ft.

13. A pile similar to the ones used in the bent was driven near the site of the bent. A load test was performed on this pile. The load settlement curves obtained and used in the computer solution are shown in Figure E5.



Figure E5. Load deflection curve for Example Problem 1 14. The piles are driven through what is classified as muck or very soft clay to bearing on a dense sand or firm sandy clay. The location of the stiffer strata is variable, and so the length of pile and length of embedment in the stiffer strata will be variable. For this analysis, the piles are assumed to be 93 ft in length with an embedment length of 83 ft.

15. For generation of p-y curves, the soil is treated as a clay. That is, the soil is treated as a frictionless material with the shear strength composed entirely of cohesion. Some thin sand layers are encountered, but their effect is considered insignificant. The tip of the pile may also be buried to several feet in a sand or sandy clay, but the effect on the lateral behavior will be insignificant and will be ignored.

16. After considering boring logs from the vicinity of the bent and after a review of triaxial data, a variation of cohesion with depth was assumed and used for predicting lateral pile-soil interaction. This assumed distribution of cohesion along the pile length is shown in Figure E6. The depth given is the distance from the soil surface. The top of the piles is located at the water surface which is 10 ft above

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the soil surface. The scourline is assumed to be 5 ft below the soil surface. The saturated unit weight of the soil is taken as 92 pcf, and the consistency is soft.

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17. A solution was obtained for this problem by using the program BENT1. The movement of the bent is described by the following movements of the origin of the a-b coordinate system:

∆ _v	=	7.664	×	10 ⁻²	in.
∆ _u	11	1.004	×	10 ⁻¹	in.
Г	=	8.536	×	10 ⁻⁵	radians

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The loads transferred to each pile and the movements of sach pile top are given in the following tabulation:

	Pile Location	Axial Load per.Pile kips	Lateral Load	Moment per Pile <u>inkips</u>	Axial Movement : in	Lateral Movement	• • •
	1	78.7	1.7	-253.3	0.0397	0.1134	
	2	133.4	1.5	-218.9	0.0689	0.1004	
	3	156.5	1.5	-218.8	0.0843	0.1004	
- International	4	193.6	1.1	-155.2	0.1091	0.0763	

The forces and movements at the pile tops are related to the x-y coordinate system set up for each pile.

18. The deflection of the a-b coordinate system defines the equilibrium position for the structure. When the foundation is in this position, the piles exert on the foundation the given forces and moments which satisfy the three equilibrium equations. A complete listing of the coded input and output is presented in Tables El and E2 beginning on page E38.

19: If the movement of the structure and the loads carried by each pile are considered, it would appear that the design is conservative. This is probably true, but it should be pointed out that factors such as settlement caused by consolidation and cyclic loading have not been considered.

Table El

Input Data for Example Problem 1

```
100 EX 1 COPANO BAY CAUSEWAY, ARANSAS COUNTY TEXAS, US HIGHWAY 35
                      110 844000.0,36400.0,16817000.0,0.001,4,0
                      120 -126.0.0.0.-0.244.1.0.1.1
                     130 -90.0,0.0,0.,2.0,1,1
                      140 90.0.0.0.2.0.1.1
                      150 126.0.0.0.0.244.1.0.1.1
                      160 31,36.0,120.0,1, FIX ,0,18.0
                      170 43740000000.0.0.0.1116.0
                      180 31,36.0,120.0,1, FIX ,0,18.0
                      190 43740000000.0.0.0.1116.0
 •
                      200 31,36.0,120.0,1, FIX ,0,18.0
                      210 43740000000.0.0.0.1116.0
                      220 31,36.0,120.0,1, FIX ,0,18.0
                      230 43740000000.0.0.0.1116.0
                      240 1,1,1
                                                                          ್ರದ 🐔
                      250 1,15
                      060 -10.0,-360000.0
                      270 -65.0,-360000.0
                     280 -0.19,-280000.0
                      290 -0.16,-260000.0
                300 -0.14,-240000.0
        · · · · · ·
                      310 0.0.0.0
                      320 0.03,40000.0
                     330 0.04,80000.0
                      340 0.05,100000.0
                     350 0.06,120000.0
                      360 0.14,240000.0
                      370 0.16,260000.0
                     380 0.19,280000.0
19928939999
                      390 0.65,360000.0
                      400 10.0.360000.0
                     410 1
                     420 3
                     430 CLAY
                      440 0.0,0.001,0.0,60.0,0, SOFT
                      450 CLAY
                      460 0.0174,3.8,60.0,894.0,0, SOFT
                      470 CLAY
                      480 0.0174,15.0,894.0,1000.0,0, SOFT
                      49Ø 1
                      500 1,9,1
                      510 18.0.0.0.1000.0
                      520 0.0
                      530 60.0
                      540 61.0
                      550 96.0
                      560 132.0
                      570 168.0
                      580 204.0
                      590 240.0
                      600 996.0
```

Table E2

Output Data for Example Problem 1

	1=X	1 COPAN	IST OF IN	SEWAY, AR	INSAS COUL	NTY TEXASIU	S HIGHWAY 35		
		· L	151 UF 1NF	UE DATA					
		р 0.8440	₩ E+06 (РН),3640Е+()5 0+1	TH 1682E+08	TOL 0,1000E-02	KNPL KO 4 O	SC
		CON	ITROL DATA	FOR PILE	S AT EACI	+ LOCATION		•	
		PILE N 2 3 4	0 DIST -,1260 -,9000 0,9000 0,1260	0E+03 0. 0E+02 0. 0E+02 0. 0E+03 0.	DISTB 0000E+00 0000E+00 0000E+00 0000E+00	BATTER 2440E+0 0.0000E+0 0.0000E+0 0.2440E+0	0 0.1000E+0 0 0.2000E+0 0 0.2000E+0 0 0.2000E+0 0 0.1000E+0		KS KA 1 1 1 1
	e en la companya esta esta esta esta esta esta esta est	LE NO. 2 3 4	NN 31 0.36 31 0.36 31 0.36 31 0.36	HH 9000E+02 9000E+02 9000E+02	0.1200 0.1200 0.1200 0.1200	DPS ND DOE+03 1 DOE+03 1 DOE+03 1 DOE+03 1	EI CONNECT FIX FIX FIX FIX FIX	DN FDBET 0+00000000000000000000000000000000000	00 00 00 00
				F	RI	X×1	xx	2	
		PILE N	10 1	0.437	40E+11	0.00000E+	00 0.1116	0E+04	
湖桃寺		PILE N	0 2	0.437	40E+11	0.00000E+	00 0,1116	0E+04	
		PILE N	0 3	0,437	40E+11	0.00000E+	00 0,1116	DE+04	
	Y	PILE N	10 4	0.437	40E+11	0.0000E+	00 0,1116	0E+04	
N. S.		A	XIAL LOAD	SETTLEME	NT DATA				
		I	DENTIFIER	1	$\begin{array}{c} 222 \\100008 \\650008 \\190008 \\160008 \\ 0.000008 \\ 0.300008 \\ 0.400008 \\ 0.500008 \\ 0.500008 \\ 0.600008 \\ 0.140008 \\ 0.140008 \end{array}$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	SSS 6000E+06 6000E+06 6000E+06 4000E+06 0000E+06 0000E+05 0000E+05 0000E+05 0000E+06 2000E+06 4000E+06		
					(Conti	inued)		(Sheet 1	of Q)
								YOUGGO T	VI 31
					E18				

;

0.16000E+00 0.26000E+06 0.28000E+06 0,19000E+00 0.65000E+00 0.36000E+06 0.36000E+06 0.10000E+02

INPUT OF SOIL PARAMETERS

ł

SP 101 14 14

SOIL PROFILE NO. STRATUM NO. 1 TYPE SOILCLAY 1 COHESION TOP DEPTH BOTTEM DEPTH CONSISTENCY GAMMA 0,6000E+02 SOFT 0.0000E+00 0.1000E-02 0.0000E+00 TYPE SOILCEAY 2 SOIL PROFILE NO. 1 STRATUM NO. TOP DEPTH BOTTEM DEPTH CONSISTENCY GAMMA COHESION 0.1740E-01 0,8940E+03 SOFT 0,60002+02 0.3800E+01 SOIL PROFILE NO. 1 STRATUM NO. 3 TYPE SOILCLAY • • • the second second BOTTEM DEPTH CONSISTENCY TOP DEPTH

COHESION GAMMA 0.1000E+04 SOFT 0,1740E-01 0.1500E+02 0+8940E+03

DIAMETER DISTRIBUTION FOR PILE

DIAMETER TOP DIS BOT DIS 0.1800E+02 0.0000E+00 0.1000E+04

1 P-Y CURVES SET IDENTIFIER NO. 1 NUMBER OF CURVES IN SET 9

CURVE NO. 1 DEPTH TO CURVE 0,0000E+00

SOIL REACTION	DEFLECTION
0.0000E+00	0.0000E+00
0,3600E-01	0.4320E-01
0.3600E-01	0.1800E+03

CURVE NO. 2 DEPTH TO CURVE 0.6000E+02

(Continued)

(Sheet 2 of 9)

:

	SOTI DEAC TON	DEELEC-ION	
		- 0-0000E+00	
•	0.62615-01	0.14406+00	
	U.8855E-01	0.2880E+00	
	U.1084E+00	0.43205+00	
	0,1252E+00	0.5760E+00	
	U.1400E+00	0.7200E+00	
	0,1534E+00	0.8640E+00	
	U,1657E+00	0.1008E+01	
	0,10705.00	U•1172E▼U1 2 4084E+01	
	0,10/02+00	0 4406+01	•
	U.1980E+00	0.18006+03	
	CURVE NO. 3	DEPTH TO CURVE 0.6100E+02	
÷			
	SOLL REACTION	DEFLECTION	
	U.UUUUE+00 U.23705.03	0.0000E+00	,
	0,23792+03	0.28805+00	
	0.41215+03	0.43206+00	
	10.47596+03	0140202400 0.5760F♦00	
	U.5320E+03	0.7200E+00	
	0.5828E+03	0.8640E+00	
	U,6295E+03	0.1008E+01	•
	0,6730E+03	0.1152E+01	
	0.7138E+03	0.1296E+01	
	0,7524E+03	0.1440E+01	
;	0,7524E+03	0.1800E+03	
animaliana	CURVE NO. 4	DEPTH TO CURVE 0.96006+02	
	SOIL REACTION	DEFLECTION	
	U,U0U0E+00	0.0000E+00	
	0,23792+03	0.144UE+UU 0.7880E+AA	
	0.03092+03	C. 2000E-00	
	1 4759EAR3	0.57605+00	
	8,5320F+03	0.72005+00	
	U.5828E+03	0.8640E+00	
	0,6295E+03	0.1008E+01	
	0,6730E+03	0.1152E+01	
	0,7138E+03	0.1296E+01	
	0.7524E+03	0.1440E+01	
	0,7524E+03	0 .1800E+03	
	CURVE NO. 5 1	DEPTH TO CURVE 0.1320E+03	
	SALL REACTION	DECLEATION	
	U.DAGARADA D.DAGARADA	0.0000E+00	
	0,23796+03	0.1440 = +00	
	· · · · · · · · · · · · · · · · · · ·		
		(Continue	a)
		(0011011140)	(Sheet 3 of 9)



E21



	PILE LENGTH,	IN DEPTH TO S	OIL ITERATION	TOL,BO	UNDRY CONI	0.2
	0.1116E+	04 9.1200	E+03 0,100	0E-02 0.	.0000E+00	
·			OUTPUT INFORMA	TION		
	X.IN	Y, IN	MOMENT, IN-LB	ES,L8/	IN	P LB/IN
	0,00000000000000000000000000000000000	0.11335E+00 0.10653E+00 0.94066E-01 0.77842E-01 0.59745E-01 0.41667E-01 0.25499E-01 0.13127E-01 0.48086E-02 38435E-04 23113E-02 29101E-02 25924E-02 19972E-02 1993E-03 23392E-03 23392E-03 23392E-03 27354E-04 0.76110E-04 0.51938E-04 0.27703E-04 0.10867E-04 0.10867E-04 0.10867E-05 2309E-05 27309E-05 17040E-05 76045E-06	25329E+06 19032E+06 12691E+06 63202E+05 0.65153E+03 0.64462E+05 0.12810E+06 0.13684E+06 0.11714E+06 0.86880E+05 0.56498E+05 0.30932E+05 0.30932E+05 0.12400E+05 0.94991E+03 63459E+04 63459E+04 63459E+04 57184E+04 57184E+04 35317E+03 0.89837E+02 0.24971E+03 0.24971E+03 0.18351E+03 0.10773E+03 0.13085E+02 28149E+01 58414E+01	0.00000000000000000000000000000000000	0 0 0000000000000000000000000000000000	00 00 00 00 01 01 01 01 01 01
1EX 1	0,10800E+04 0,11160E+04 COPANO BAY C	0.99826E-08 0.69498E-06 AUSEWAY.ARANS	-,28833E+01 -,46574E+02 AS COUNTY TEXA	0,62909E+04 0,65222E+04 S.US HIGHWAN	4 -,62799E 4 -,45328E 7 35	-04 -02
	PILE NUM	DISTA,IN -,90000E+02	DISTB, IN 0.00000E+00	THE 0,00000E4	TA, RAD	
	PX,LB 0,13344E+06 INPUT INFORM	XT; IN 0,68963E-01 ATION	PT,LB 0.14908E+04	M 1 -,21892E4	, IN-L8 06 0,100418	YT,IN 5+00
	TC TO	P DIA, IN	NC, LENGTH, IN	NO, OF	INC KS P	< <u>A</u>
	FIX 0	+1800E+92	0,3600E+02	31	1 1	

(Continued)

(Sheet 6 of 9)

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	PILE LENGTH,	IN DEPTH TO	SOIL ITERATION	TOL.80	UNDRY COND.2	2
	0.1116E+	04 0.1200	DE+03 0,100	0E-02 0,	0000E+00	
	-		OUTPUT INFORMA	TION		
- · ·	X, IN	YIIN	MOMENT, IN-LB	ES,LB/	IN P	LB/IN
Same and a star of the star of a star of the star of the	$\begin{array}{c} 0, 00000 \pm 00\\ 0, 36000 \pm 02\\ 0, 72000 \pm 02\\ 0, 10800 \pm 03\\ 0, 14400 \pm 03\\ 0, 14400 \pm 03\\ 0, 216000 \pm 03\\ 0, 25000 \pm 03\\ 0, 26800 \pm 03\\ 0, 32400 \pm 03\\ 0, 32400 \pm 03\\ 0, 39600 \pm 03\\ 0, 39600 \pm 03\\ 0, 43200 \pm 03\\ 0, 43200 \pm 03\\ 0, 50400 \pm 03\\ 0, 50400 \pm 03\\ 0, 57600 \pm 03\\ 0, 58400 \pm 03\\ 0, 68400 \pm 03\\ 0, 58400 \pm 0, 58400 \pm 03\\ 0, 58400 \pm 0, 58$	$\begin{array}{c} 0.10040\pm00\\ 0.94089\pm-03\\ 0.82902\pm-03\\ 0.82902\pm-03\\ 0.68478\pm-03\\ 0.52465\pm-03\\ 0.36516\pm-03\\ 0.22283\pm-03\\ 0.114109\pm-03\\12051\pm-03\\22990\pm-03\\22990\pm-03\\22990\pm-03\\25964\pm-03\\22990\pm-03\\25964\pm-03\\22990\pm-03\\25964\pm-03\\22990\pm-03\\25964\pm-03\\22990\pm-03\\25964\pm-03\\22990\pm-03\\2290\pm-0$	$\begin{array}{c} -& 21891E + 06 \\ +& .16440E + 06 \\ +& .10923E + 06 \\ +& .53645E + 05 \\ 0 & 21595E + 04 \\ 0 & .57916E + 05 \\ 0 & .11342E + 06 \\ 0 & .10319E + 06 \\ 0 & .10319E + 06 \\ 0 & .76410E + 05 \\ 0 & .76410E + 05 \\ 0 & .76410E + 05 \\ 0 & .49577E + 05 \\ 0 & .49577E + 05 \\ 0 & .66426E + 03 \\ +& .36723E + 04 \\ -& .36723E + 04 \\ -& .10474E + 0$	0,00000000000000000000000000000000000	0.00000000000000000000000000000000000	
1Ex 1	U.72000E+03 D.75600E+03 U.82800E+03 U.82800E+03 U.90000E+03 U.90000E+03 U.93600E+03 U.93600E+03 U.10080E+04 D.10600E+04 D.11160E+04 COPANO BAY C	0,70138E-0 0,45903E-0 0,24289E-0 0,10823E-0 -,23859E-0 -,23859E-0 -,24372E-0 -,24372E-0 -,15077E-0 -,66346E-0 0,22341E-0 0,63148E-0 AUSEWAY,ARANS	429958E+03 4 0.88494E+02 4 0.22617E+03 5 0.22333E+03 5 0.94947E+02 5 0.42486E+02 5 0.42486E+02 5 0.10991E+02 528761E+01 725876E+01 541871E+02 SAS COUNTY TEXAS	0,39713E+04 0,42032E+04 0,44351E+04 0,46670E+04 0,513627E+04 0,553627E+04 0,55946E+04 0,55946E+04 0,55946E+04 0,60584E+04 0,62905E+04 0,65222E+04 S,US HIGHWAY	27854E+00 19294E+00 10772E+00 43764E+01 53025E-02 0.12241E-02 0.13635E-02 0.13635E-02 0.87846E+02 0.40195E+02 14054E+02 14054E+02 35	
	PILE NUM 3	DISTA:IN 0.90000E+02	DIST8,1N 0.0000000+00	THE 0.00000E+	TĂ, RAD 00	
	PX;LB 0+15649E+06 INPUT INFORM	XT; IN 0,84327E-01 ATION	PT,L8 1 0,14825E+04	H T +,21883E+	,IN+LB 06 0,10041E+(YT.IN Do
	TC TO	P DIA-IN I	INC, LENGTH, IN I	N0, 0F	INC KS KA	
	FIX 0	,1800E+02	0.3600E+02	31	1 1	
	PILE LENGTH,	IN DEPTH TO S	SOIL ITERATION	TOL.BO	UNDRY COND.2	2
			(Continued)		(Sheet '	7 of 9)

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	0.1116E+04	0.1200	E+03 0,100	0E+02 0.0	1000E+00	
		C	OUTPUT INFORMA	TION		
· · · ·	X, IN	Y, IN	MOMENT, IN-LB	ES,LB/	IN P	LB/IN
	0,00000E+00 0,36000E+02 0,72000E+02 0.10800E+03 0,14400E+03	0.10039E+00 0.94085E-01 0.82897E-01 0.68469E-01 0.52450E-01	21882E+06 16447E+06 10934E+06 53722E+05 0+21539E+04	0.00000E+00 0.00000E+00 0.00000E+00 0.00000E+00 0.58566E+00	0,00000E+00 0,00000E+00 0,00000E+00 0,00000E+00 -,00718E=01	1
	0.18000E+03 0.21600E+03 0.25200E+03 0.28800E+03 0.32400E+03 0.32400E+03 0.32600E+03	0.22257E+01 0.22257E+01 0.11382E-01 0.40895E-02 14334E-03 21107E-02 26087E-02	0.11351E+06 0.12086E+06 0.10328E+06 0.76460E+05 0.49592E+05 0.27013E+05	0,16523E+04 0,16523E+04 0,16523E+04 0,16523E+04 0,16523E+04 0,16523E+04	100080-01 367795+02 18807E+02 0.236835+00 0.348755+01 0.49153E+01	}
	0.43200E+03 0.46800E+03 0.50400E+03 0.54000E+03 0.57600E+03 0.61200E+03	-,23063E-02 -,16875E-02 -,10503E-02 -,54064E-03 -,99577E-05 -,99577E-05	0.10679E+05 0.62135E+03 43044E+04 56985E+04 50960E+04 36817E+04	0,21161E+04 0,23480E+04 0,25799E+04 0,28118E+04 0,30437E+04 0,32756E+04	0.48804E+01 0.39623E+01 0.27097E+01 0.15202E+01 0.60814E+00 0.32617E-01	en Maria de Calendaria en Sal
	0.68400E+03 (0.72000E+03 (0.75600E+03 (0.79200E+03 (0.82800E+03 (0.86400E+03 (0.86133E-04 0.70474E-04 0.46027E-04 0.24292E-04 0.93285E-05 0.10245E-05	+.10460E+04 29657E+03 0.91541E+02 0.22850E+03 0.22478E+03 0.16359E+03	0.37394E+04 0.37394E+04 0.39713E+04 0.42032E+04 0.44351E+04 0.46670E+04 0.48989E+04	+.32209E+00 +.27987E+00 19346E+00 10773E+00 43536E+01 50189E+02	
	U.90000E+03 U.93600E+03 U.97200E+03 U.10080E+04 U.10440E+04 U.10800E+04	.24324E-05 .30706E-05 .24522E-05 .15127E-05 .66244E-06 .27127E-07	0.95133E+02 0.42412E+02 0.10835E+02 30120E+01 54226E+01 26068E+01	0.51308E+04 0.53627E+04 0.55946E+04 0.58265E+04 0.60584E+04 0.62906E+04	0.12480E=01 0.16467E=01 0.13719E=01 0.88137E=02 0.40134E=02 =.17064E=03	
1EX 1	COPANO BAY CAUS	EWAY,ARANSA	+.42248E+02 S COUNTY TEXAS	U,65222E+04 S:US HIGHWAY	++41/07E+02 35	
	PILE NUM DI 4 0.1	STA, IN 2600E+03	D1STB,1N 0.00000E+00	THE 0.24400E+0	TA, RAD	
	PX,LB 0+19360E+06 (INPUT INFORMATI	XT:IN 0.10906E+00 0N	PT,LB 0,10624E+04	M T; -,15520E+(IN-LB 06 0,76322E=0	YT.IN 1
	TC TOP I	DIA, IN IN	IC, LENGTH, IN I	NO, OF	INC KS KA	
	FIX 0.1	00E+02	0,3600E+02	31	1 1	
	PILE LENGTH, IN	DEPTH TO SC	DIL ITERATION	TOL.BO	UNDRY COND.2	

(Continued)

(Sheet 8 of 9)
Table E2 (Concluded)

	0+1116E+04	0.1200	E+03	0,100	0E-02	0.0000E+00					
- -	OUTPUT INFORMATION										
	-X+IN	Y.IN	MOMENT,	IN-LB	ES.LB/	IN	P LB/IN				
	0,0000E+00	0,76289E-01	-,1552	1E+0%	0.00000E+0	00 0.00000E+0	0				
	0,36000E+02	0.70917E-01	1159	1E+06	0.00000E+1	00 0+00000E+0	0				
	0.72000E+02	0.621108-01	-,7596	5E+05	0.00000E+0	00 0+00000E+0	0				
	U.10800E+03	0.51053E-01	3557	56+05	0.00000E+	00 0.00000E+0	0				
	0,14400E+03	0,38941E-01	0.5017	76+04	0,67393E+	0026243E-0	1				
	0.18000E+03	0.26978E-01	0.4554	86+05	0,43481E+	00 -+11730E+0	1				
	0,21600E+03	0.16365E-01	0.8580	26+05	0,16523E+0	04 -,27039E+0	2				
	0.25200E+03	0.82936E-02	0.9052	1E+05	0.16523E+(04 +:13704E+0	2				
	0.28800E+03	0.29046E-02	0.7696	0E+05	0,16523E+1	0447993E+0	1				
	0,32400E+03	20405E-03	0.5673	9E+05	0,16523E+	04 0.33716E+0	ō				
	0,36000E+03	-,16316E-02	0.3662	9E+05	0,16523E+	04 0.26959E+0	1				
	0,39600E+03	-,19739E-02	0.1980	26+05	0,18842E+8	04 -:0∓3∓191E+0	1				
and the second	0.43200E+03	17294E-02	0.7682	1E+04	0.21161E+	04 0.36596E+0	1				
	0.46800E+03	-,12573E-02	0.2608	0E+03	0,23480E+(04 0+29522E+0	1				
	0.50400E+03	77750E-03	-,3336	0E+04	0,25799E+	04 0+20059E+0	1				
	0.54000E+03	-,39653E-03	- 4314	0E+04	0,28116E+(04 0,11149E+0	1				
and a state of the second state	0.57600E+03	- 14338E-03	-, 38,22	4E+04	_0,30437E+(04 0-43641E+0	0				
	0.61200E+03	-,34921E-05	- 2743	2E+04	0.32756E+(04 0.11438E-0	1				
	0.64800E+03	0.55119E-04	+.1633	4E+04	0.35075E+(04 -•19333E+0	0				
	0,08400E+03	0.65332E-04	-,7648	7E+03	0,37394E+(]4 -+24430E+D	0				
į	0./2000E+03	0.52882E-04	-,2085	3E+03	0,39713E+(04 -+21001E+0	0				
	0,/5600E+03	0,34253E-04	0.7682	9E+02	0,42032E+()4 -,14397E+0	0				
: /	0,79200E+03	0,17901E-04	0.1751	6E+03	0,44351E+(J4 -,79392E-0	1 .				
	0,82800E+03	0,67385E-05	0.1696	0E+03	0.46670E+(04 -+31449E+0	1				
	0,06400E+03	0.60140E-06	0.1223	0E+03	0,48989E+(J4 -,29462E+0	2				
	0,9000E+03	19118E-05	0,7049	3E+02	0,51308E+(34 0.96092E-0	2				
	0.93000E+03	23364E-05	0.3098	8E+02	0,53627E+(04 0.12529E-0	1				
	0.97200E+03	~,18427E-05	0,7543	1E+01	0,55946E+(34 0.10309E-0	1				
	V.10080E+04	-,11256E-05	- 2284	16+01	U.58265E+(]4 0+65584E+0	2				
	0+10440E+04	-,48505E-06	4196	9E+01	0.60584E+()4 0.29386E+0	2				
	U.10800E+04	0.31152E-07	- 1977	26+01	0.62906E+()4 -19596E-0	3				
	U+11160E+04	0.48877E+06	-,3194	1E+02	0,65222E+()4 - .31879E-0	2				

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(Sheet 9 of 9)

Houston Ship Channel

20. The second example problem considered will be one of the bents used in a bridge across the Houston Ship Channel. The bridge is located in Harris County on Interstate Highway 610. Details of the bent analyzed are shown in Figure E7. The bent is reinforced concrete and is supported by 142 eighteen-inch-square, precast-prestressed concrete piles. The piles in this example are battered parallel to the roadway to resist horizontal loads from the superstructure. It is assumed that the 7-ft-thick pile cap provides sufficient rigidity so that the assumption of plane movement is valid.

21. The geometry necessary for describing the foundation for the computer solution is shown in Figure E8 and the following tabulation:

Pile Location	a Coordinate <u>in.</u>	b Coordinate in.	No. Piles; at <u>Location</u>	Batter radians	
1	-150	0	. 24	-0.166	
2	-90	0	23	-0.083	
3	-30	0	24	-0.042	
<u>)</u>	30	0	24	0.042	
5	90	0	23	0.083	
6	150	0	24	0.166	

Same in the

> The coordinate system and the loads on the structure are also designated in the figure. The piles have an effective flexural rigidity of 4.374×10^{10} lb-in.² (assuming a modulus of elasticity of concrete of 5×10^6 psi) and a length of 44 ft.

22. No axial load-deflection curves obtained from load tests are available for the piles used in the bent. As a result, it was necessary to estimate the axial behavior of the piles. The ultimate bearing capacity of the piles was estimated as 650 kips in compression and 600 kips in tension. The ultimate deflection is estimated as 0.5 in. The loaddeflection relationship is assumed to be linear resulting in a curve as shown in Figure E9.

23. The properties of the soil used for predicting the lateral pile-soil interaction were obtained from the highway department borings.



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E28



Figure E8. Foundation representation for Example Problem 2

The properties used for generation of p-y curves are illustrated in Figure ElO. It should be pointed out that the profile shown is a simplification of the actual profile. The top 13 ft of soil, defined as very dense sandy silt, will be treated as a sand when p-y curves are generated. That is, it will be treated as a cohesionless material. The bottom 31 ft, defined as very stiff silty clay, will be treated as a clay. That is, it will be treated as a frictionless material. Depths given are measured from the top of the pile. From the given soil properties, p-y curves are generated.

24. A solution was obtained for the Ship Channel problem by using the program BENTL. The movement of the bent, when loaded, is described

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for Example Problem 2

... E30 by the following movements of the origin of the a-b coordinate system:

$$\Delta_{v} = 1.512 \times 10^{-1} \text{ in.}$$

 $\Delta_{u} = 3.321 \times 10^{-2} \text{ in.}$
 $\Gamma = 4.183 \times 10^{-4} \text{ radians}$

The loads transferred to each pile and the movements of each pile top are given in this tabulation:

Lo	Pile cation	Axial Load per Pile <u>kips</u>	Lateral Load per Pile <u>kips</u>	Moment per Pile <u>inkips</u>	Axial Movement <u>in.</u>	Lateral Movement in.
	1	106.3	3.3	-46.0	0.0818	0.0474
	2	143.6	2.5	0.4	0.1104	0.0425
	3	178.3	2.0	32.8	0.1372	0.0390
	4	214.5	0.3	122.1	0.1650	0.0263
	5.	248.3	0.2	83.8	0.1910	0.0174
• •	6	281.5	0.0	-15.2	0:2165	-0.0026

The forces and movements at the pile tops are related to the x-y coordinate systems set up for each pile. A complete listing of the coded input and output for the program is given in Tables E3 and E4 beginning on page E53. 25. The small deflections and loads obtained for the piles would tend to indicate that the design is conservative. This is probably true and is to be expected. However, it should be pointed out that a number of factors, such as consolidation and cyclic loading, have not been considered and that the load deflection curve used is only a rough approximation. The value used for ultimate load is probably fairly reliable, but the deflection at which the load stops increasing is only an educated guess. Because of this, a linear variation of load with movement was considered to provide sufficient refinement. The effect will be disclosed in the loads and deflections obtained for the piles. The loads obtained will probably be fairly accurate, but the accuracy of the movements obtained will depend on the accuracy of the value which was assumed for the deflection at which the load stops increasing.

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Table E3

Input Data for Example Problem 2



Table E4

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Output Data for Example Problem 2

LI	ST OF INP	UT DATA			
PV 0,2760E	+08 0	РН .1126E+07	TM 0+8657E+09	TOL KN 0,1000E-02 6	PL KOSC O
CONT	ROL DATA	FOR PILES AT	EACH LOCATION		
PILE NO 1 2 3 4 5 6	DISTA -,1500 -,9000 -,3000 0,3000 0,9000 0,9000 0,1500	DISTE E+03 0.0000E E+02 0.0000E E+02 0.0000E E+02 0.0000E E+03 0.0000E	BATTER +001660E+00 +008300E-01 +004200E-01 +00 0.4200E-01 +00 0.6300E-01 +00 0.1660E+00	POTT 0.2400E+02 0.2300E+02 0.2400E+02 0.2400E+02 0.2300E+02 0.2400E+02	KS K 1 1 1 1 1 1 1 1 1 1 1 1 1 1
 PILE NO. 1 3 2 3 3 3 4 3 5 3 6 3	NN 3 0.16 3 0.16 3 0.16 3 0.16 3 0.16 3 0.16 3 0.16	HH 000E+02 000E+00E+02 000E+02 000E+02 000E+02 000E+02 000E+02 000E+02 000E	DPS NDE 00000E+00 1 00000E+00 1 00000E+00 1 00000E+00 1 00000E+00 1 00000E+00 1	I CONNECTION (FIX 0.0) FIX 0.0 FIX 0.0 FIX 0.0 FIX 0.0 FIX 0.0 FIX 0.0	FDBET 000E+00 000E+00 000E+00 000E+00 000E+00 000E+00
		RRI	XX1	XX2	
PILE NO PILE NO	1 2	0.43740E+1	1 0.00000E+0	0 0.52800E+0	3
PILE NO	3	0.437402+1	1 0.00000E+0	0 0.52800E+0. 0 0.52800E+0.	3
PILE NO	4	0.43740E+1	1 0+00000E+0	0 0,52800E+0	3.
PILE NO PILE NO	5 6	0.43740E+1	1 0.00000E+0	0 0,52800E+0	3

AXIAL LOAD SETTLEMENT DATA

IDENTIFIER	1	ZZZ	SSS
		-,10000E+02	~.60000E+06
		-,50000E+00	60000E+06
		0,00000E+00	0.00000E+00

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		0.50000E+00 0.10000E+02	0.65000E+06 0.65000E+06	
	INPUT OF SOIL PA	RAMETERS		
	SOIL PROFILE NO.	1 STRATUM NO.	1 TYPE SOILSAN	D
	GAMMA ANGLE U.JOUDE-01 0.4	OF FRIC. TOP DEPTH 5000E+00 0.0000E+00	BOTTEM DEPTH DI 0 0,1560E+03 Di	ENSITY Ense
	SOIL PROFILE NO.	1 STRATUM NO.	2 TYPE SOILCLA	Y
	GAMMA CU 0,1700E-01 0+14	DHESION TOP DEPTH 400e+02 0,1560 e+03	BOTTEN DEPTH 1 0.5280E+03 STI	CONSISTENCY F
	DIAMETI	R DISTRIBUTION FOR PIL	.e	·, · · · · · · ·
	DIAMETER 0.1800E+02	TOP DIS 801 0.0000E+00, 0.52	DIS 280E+03	
	1			
i	SET IDENTIFIER NO.	P-Y CURVES 1 NUMBER OF CURVE	S IN SET 10	
adalahan aras aras aras aras aras aras aras ar				
	CURVE NO. 1 DEPTH	TO CURVE 0.0000E+00		
	SOIL REACTION U.UGUDE+00 U.UUUDE+00 U.UUUDE+00 U.00UDE+00	DEFLECTION 0.0000E+00 0.1000E+01 C.1800E+03		
	CURVE NO. 2 DEPTH	TO CURVE 0,1200E+02		
	SOIL REACTION 0.0000E+00 0.3363E+02 0.3363E+02	DEFLECTION 0.0000E+00 0.8409E=01 0.1800E+03		
	CURVE NO. 3 DEPTH	TO CURVE 0.2400E+02		
	SOIL REACTION	DEFLECTION		
		(Continued)	(Shee	et 2 of 10)

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0.0000E+00 0.9157E+02 0.0000E+00 0.1144E+00 0,9157E+02 C.1800E+03 CURVE NO. 4 DEPTH TO CURVE 0,4800E+02 SOIL REACTION DEFLECTION 0.0000E+00 0.2803E+03 0,0000E+00 0.1752E+00 0,2803E+03 0.1800E+03 . CURVE NO. 5 DEPTH TO CURVE 0,9600E+02 SOIL REACTION DEFLECTION 0,0000E+00 0.0000E+00 ್ ಪ್ ಕ್ 0,9494E+03 0.2967E+00 0.9494E+03 0.1800E+03 CURVE NO. 6 DEPTH TO CURVE 0,1440E+03 . e de la deste de and the second second 1 . . • • SOIL REACTION DEFLECTION 0.0000E+00 0.0000E+00 0.2007E+04 0.4182E+00 0.2007E+04 0.1800E+03 CURVE NO. 7 DEPTH TO CURVE 0,2280E+03 SOIL REACTION DEFLECTION 0,0000E+00 0,8766E+03 0.0000E+00 0.3600E-01 0 1239E+04 0.7200E-01 0.1518E+04 0.1080E+00 0,1753E+04 0.1440E+00 0.1800E+00 0,1960E+04 0,2147E+04 0.2160E+00 U,2319E+04 0.2520E+00 0.2479E+04 6.2880E+00 0.2630E+04 0.3240E+00 U.2772E+04 0.3600E+00 0.2772E+04 0.1800E+03 **CURVE NO.** 8 DEPTH TO CURVE 0,2290E+03 DEFLECTION SOIL REACTION 0 0000E+00 0.0000E+00 0.3600E-01 U.8766E+03 0,1239E+04 0.7200E-01 0 1518E+04 0,1080E+00 0,1753E+04 0.1440E+00

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	U,2319E+04	0.252	20E+00			
	0.2479E+04	0.288	0E+00			
	U,2630E+04	0.324	0E+00			
		0,300	10E+00			
	0,47726404	0.200	02-03			
	CURVE NO. 9	DEPTH TO CURV	E 0.2400E+03			
	SOIL REACTION	DEFLECT	ION			
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	0,8766E+03	0.360	06-01			
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· · · · · · · · · · · · ·	0,1960E+04	0.180	0E+00		- 5	
· · · · · · · ·	0,2147E+04	0.216	0E+00	40 ⁻		
	0,2319E+04	0.252	0E+00			
	0 26305+04	U.288	06+00			
	U.2772E+04	0.360	02+00			
	0.2772E+04	0.180	0E+03	·		• • •
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	SOIL REACTION	DEFLECT	10N			
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	0,8766E+03	0.360	0E-01			
Sussemments	0,12396+04	0.720	0E-01			
	U,1753F+04	U.108 0.144	06+00 06+00			
	0,1960E+04	0.180	0E+00			
	U,2147E+04	9.216	0E+00			
	0,2319E+04	0.252	0E+00			
	0,24/98+04	0.288	0E+00			
	0.27725+04	0.324	UE+00 0E+00			
	0.2772E+04	0.180	0E+03			
•	1	ITERATION	DATA			
		DV 0.3026E+00	DH 0.7467E-01	ALPHA 0,8315E+03		
		0.1513E+00	0.6979E-01	0.3648E+03		
		0.1512E+00	0.2654E-01	0.4280E-03		
		0.1512E+00	0.3435E-01	0,4165E-03		
		0+1 512E+00	0.3261E-01	0.4191E-03		
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		0.1512E+00	0.3310E-01	0,4185E-03	5		
1EX 2	HOUSTON SHIP	CHANNEL BRIDG	E,HARRIS CO.,H	HIGHWAY I-610) .		
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0.11132g+03 0.62309E+02 0.20906g-05 -.10047E-05 0,24350 +05 0,24350 E+05 -.50904e-01 0.24465E-01 U.48000E+03 0.49600E+03 -.37353E-05 0.19518E+02 0,24350E+05 0.90954E-01 0.51200E+03 0.15466E+00 +.63517E-05 0.153238+04 0.24350E+05 0.52800F+03 1EX 2 HOUSTON SHIP CHANNEL BRIDGE, HARRIS CO., HIGHWAY 1-610 DIST8, IN THE TA, RAD PILE NUM DISTA, IN -.83000E-01 0.00000E+00 2 -,90000E+02 T, IN~LB PT.LO YT.IN PXILB XT, IN M 0.14357E+06 0.248605+04 0.33676E+04 0.42397E+01 0.11043E+00 INPUT INFORMATION INC TOP DIA.IN INC. LENGTH, IN NO. OF KS KA TC 0.1600E+02 33 1 1 FIX 0.1800E+02 UNDRY COND 2 PILE LENGTH, IN DEPTH TO SOIL ITERATION TOL.BO 0,1000E-02 0.0000E+00 0.5280E+03 0.0000E+00 OUTPUT INFORMATION Y.IN. MOMENT, IN+LB ES, LB/ 1 N P LB/IN X.IN 0.00000E+00 0.41881E-01 0,29538E+03 0.00000E+00 0.0000E+00 0,16000E+02 0.35187E-01 0.41033E+05 0.53333E+03 -.18766E+02 0,28733E-01 0.76932E+05 0,10666E+04 -,30648E+02 0,32000E+02 0,48000E+02 0.22729E-01 0,10492E+06 0,16000E+04 -.36366E+02 0.64000E+02 0.12351E+06 -.36989E+02 0.17339E-01 0,21333E+04 0.80000E+02 0.12672E-01 0.13253E+06 0,26667E+04 -133791E+02 0.96000E+02 0.87804E-02 0,13278E+06 0,32000E+04 -.28097E+02 0.12574E+06 0.11200E+03 0.56663E-02 0.37333E+04 -,21154E+02 0.32880E-02 0,42667E+04 -.14029E+02 0,12800E+03 0.11316E+06 0.96910E+05 0,14400E+03 0.15721E-02 0.48000E+04 -.75460E+01 0.78640E+05 0.85237E+04 +,36085E+01 0.16000E+03 0.42335E-03 0.59381E+05 0.32471E+01 U,17600E+03 -,26512E-03 0,12247E+05 0,15971E+05 0,96793E+01 0.19200E+03 -,60605E-03 0.40903E+05 0,20800E+03 -.70758E-03 0.248696+05 0,19695E+05 0.13936E+02 0.12380E+05 -.66356E-03 0,23419E+05 0+15540E+02 0.22400E+03 0.24000E+03 -.54708E-03 0,38604E+04 0,24350E+05 0.13321E+02 0,99346E+01 0,24350E+05 0.25600E+03 -,40800E-03 -.12528E+04 0,24350E+05 -.27626E-03 -.38217E+04 0.67268E+01 0.27200E+03 0.28800E+03 -,16688E-03 +.46653E+04 0,24350E+05 0.40635E+01 0.30400E+03 -.84813E-04 -.44648E+04 0.243506+05 0.20651E+01 -.37319E+04 0,24350E+05 0.70307E+00 0.32000E+03 -.28874E-04 U.33600E+03 0,52227E-05 -,28158E+04 0.24350E+05 -.12717E+00 0.22839E-04 -,55613E+00 0.35200E+03 -.19299E+04 0,24350E+05 -.11847E+04 0,24350E+05 -,71005E+00 0.36800E+03 0.29161E-04 -,69513E+00 -.62040E+03 0.38400E+03 0,28548E-04 0.24350E+05 0.24304E-04 0.40000E+03 -.23347E+03 0.24350E+05 -,59179E+00 0.41600E+03 0.18694E-04 0.21639E+01 0.24350E+05 -.45519E+00 0,43200E+03 0,24350E+05 -.31889E+00 0,13096E-04 0.12126E+03 0.15863E+03 0,24350E+05 0.44800E+03 0.82083E-05 -,19987E+00

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0.24350E+05 0.24350E+05 0.42489E-05 0.14469E+03 -,10345E+00 0,46400E+03 0.10414E+03 0,48000E+03 -,27668E-01 0,11362E-05 0.49600E+03 -.13668E-05 0,56434E+02 0,24350E+05 0.33280E-01 0,24350E+05 0,51200E+03 -.35395E-05 0.17193E+02 0.86186E-01 0.52800E+03 -.56116E-05 0.13128E+04 0,24350E+05 0.13664E+00 1EX 2 HOUSTON SHIP CHANNEL BRIDGE, HARRIS CO., HIGHWAY I~610 PILE NUM DISTB, IN DISTA-IN THE TA, RAD 3 -.42000E-01 -.30000E+02 0.00000E+00 PX-LB PT,LB T, IN-L8 XT.IN YT.IN 0.32899E+05 0.38889E-01 0+17832E+06 0.13717E+00 0.19724F+04 INPUT INFORMATION TC TOP DIA, IN INC. TENGTH, IN NO. OF INC KS KA FIX 0.1800E+02 0,1600E+02 33 1,______ UNDRY COND.2 PILE LENGTH, IN DEPTH TO SOIL ITERATION TOL, BO 0.5280E+03 0.0000E+00 0.1000E+02 0.0000E+00 OUTPUT INFORMATION MOMENT, IN-L8 IN X, IN Y, IN ES,LB/ P LB/IN 0.38671E-01 0.00000E+00 0.31607E+05 0.18626E-08 -,72030E-10 0.64343E+05 0.53333E+03 -.17103E+02 0,16000E+02 0.32068E-01 -.27565E+02 0.25842E-01 0.32000E+02 0.92634E+05 0.10666E+04 0,48000E+02 0,201588-01 0.11377E+06 0,16000E+04 -.32253E+02 0.64000E+02 0,15140E-01 0,12653E+06 0,21333E+04 -,32298E+02 0,13089E+06 0,80000E+02 0.10862E-01 0,26667E+04 -.28966E+02 inininina and 0,96000E+02 0,73509E-02 0,12770E+06 0,32000E+04 +.23523E+02 0.11835E+06 0,37333E+04 -.17124E+02 0.11200E+03 0,45868E-02 0.12800E+03 0,25155E-02 0.10450E+06 0,42667E+04 -.10732E+02 0.10558E-02 0.87796E+05 0.14400E+03 0,48000E+04 -,50682E+01 -.93816E+00 0.16000E+03 0.11006E-03 0.69698E+05 0.85237E+04 -.42781E-03 U,17600E+03 0.51286E+05 0,12247E+05 0.52396E+01 0,19200E+03 -.66552E-03 0.34163E+05 0,15971E+05 0.10629E+02 0.13851E+02 0,20800E+03 -.70328E-03 0.19724E+05 0,19695E+05 0.224U0E+03 -,62560E-03 0.88114E+04 0.23419E+05 0.14651E+02 U,24000E+03 -.49635E-03 0.16399E+04 0.24350E+05 0.12086E+02 0,25600E+03 -,35750E-03 -.24394E+04 0.24350E+05 0.87051E+01 0,24350E+05 0,27200E+03 -,23293E-03 -.42877E+04 0,56718E+01 0,28800E+03 -,13346E-03 -,46795E+04 0,24350E+05 0.32496E+01 0.30400E+03 -.61368E-04 -.42345E+04 0.24350E+05 0.14943E+01 0.32000E+03 -.14063E-04 -.34026E+04 0.34244E+00 0.24350E+05 0.33600E+03 0,13327E-04 -,24794E+04 0,24350E+05 -,32451E+00 0.35200E+03 0,26206E-04 -.16367E+04 0.24350E+05 -.63811E+00 0.36800E+03 0.29506E-04 -.95569E+03 0,24350E+05 -.71846E+00 0.38400E+03 0.27213E-04 -.45759E+03 0,24350E+05 -.66261E+00 0,24350E+05 0,40000E+03 0,22241E-04 -.12864E+03 -,54155E+00 0.41600E+03 0,16516E-04 0.61805E+02 0,24350E+05 -.40216E+00 0,24350E+05 0.43200E+03 0.11153E-04 0.14923E+03 -.27158E+D0

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0.24350E+05 0.24350E+05 -.16226E+00 -.76744E-01 0.66639g-05 0.31518E-05 0.16698E+03 0.44800r+03 0.14301E+03 0.46400E+03 0.48000E+03 0,47659E-06 0.99245E+02 0.24350E+05 -.11604E-01 0,24350E+05 -.16177E-05 0,52407E+02 0-39391E-01 0,49600E+03 0,51200E+03 -,34053E-05 0,15598E+02 0,24350E+05 0.82918E-01 -.51016E-05 0.11614E+04 0.24350E+05 0-12422E+00 0.52800E+03 1EX 2 HOUSTON SHIP CHANNEL BRIDGE, HARRIS CO., HIGHWAY 1-610 PILE NUM DISTA, IN DISTB.IN THE TA, RAD 0,42000E-01 0.00000E+00 0.30000E+02 PX,LB XT.IN PTILB T, IN-L8 YT,IN 0.52109E+03 0.102176+06 0.26189E+01 0.16503E+00 0+21454E+06 INPUT INFORMATION TC TOP DIA, IN INC. LENGTH, IN NO. OF INC KS KA FIX 0,1800E+02 0,1600E+02 33 1 1 UNDRY COND.2 PILE LENGTH, IN DEPTH TO SOIL ITERATION TOL.BO 0.5280E+03 0.0000E+00 0.1000E-02 0.0000E+00 OUTPUT INFORMATION X.IN Y.IN MOMENT, IN-LB ES,LB/ ΙN P LB/IN 0.12162E+06 0.00000F+00 0,29491E-01 0,00000E+00 0.00000E+00 0.16000E+02 0.13132E+06 0,23152E-01 0,53333E+03 -+12347E+02 0.32000E+02 0,17581E-01 0.13769E+06 0,10666E+04 -.18753E+02 0.13909E+06 0,48000E+02 0,12816E-01 0,16000E+04 -,20506E+02 0.64000E+02 0.88653E-02 0.13507E+06 -.18913E+02 0,21333E+04 0.80000E+02 0,57050E-02 0.12603E+06 0,26667E+04 -+15213E+02 0.96000E+02 0.32824E-02 0.11293E+06 -+10503E+02 0,32000E+04 0,15208E-02 0.97017E+05 0.11200E+03 0.37333E+04 -+56776E+01 0,32697E-03 0,12800E+03 0.79521E+05 0.42667E+04 -,13951E+01 0.14400E+03 -,40142E-03 0.61567E+05 0+19268E+01 0,48000E+04 -.76948E-03 0.65586E+01 0,16000E+03 0-44030E+05 0,85237E+04 -.87984E-03 0.17600E+03 0.28116E+05 0.12247E+05 0.10775E+02 0,19200E+03 -.82564E-03 0.14926E+05 0.15971E+05 0+13186E+02 -.68408E-03 0.20800E+03 0.50928E+04 0.19695E+05 0+13473E+02 0.22400E+03 -.51272E-03 -.12979E+04 0.23419E+05 0+12007E+02 -,34895E-03 0,24350E+05 0.84967E+01 0.24000E+03 -,46131E+04 0,24350E+05 0.25600E+03 -,21218E-03 -.57473E+04 0:51664E+01 -,10904E-03 0.27200E+03 -.55518E+04 0,24350E+05 0.26551E+01 0,28800E+03 -.38404E-04 -.46696E+04 0.24350E+05 0.93512E+00 0.30400E+03 0.49050E-05 -.35421E+04 0.24350E+05 -.11943E+00 0.27482E-04 -.24408E+04 0.32000E+03 0,243506+05 -,66919E+00 0.35775E-04 -.15077E+04 0.33600E+03 0,24350E+05 -+87110E+00 0,35243E+04 -.79571E+03 -.85814E+00 0.35200E+03 0,24350E+05 0.30053E-04 0.36800E+03 -,30241E+03 0,24350E+05 -.73178E+00 0.23094E-04 0.39369E+01 0.38400E+03 0,24350E+05 -.56233E+00 0,16158E-04 n.16632E+03 0.40000E+03 0,24350E+05 ~.39344E+00 0.41600E+03 0.10195E-04 0.22777E+03 -+24825E+00 0.243506+05 - 13553E+00 - 54921E-01 0 55650E-05 0 22555E-05 0 24350E+05 0,24350E+05 U 43200E+03 U 44800E+03 0 2253 0E+03 0.18803E+03 0.13637E+03 0.46400E+03 0.45585E-07 0.24350E+05 - 11099E-02

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0.48000E+03 13662E-05 0.84251E+02 0.24350E+05 0.33267E-01 0.5200E+03 22649E-05 0.40547E+02 0.24350E+05 0.72226E-01 0.5200E+03 35831E-05 0.71760E+03 0.24350E+05 0.87247E-01 1EX 2 HOUSTON SHIP CHANNEL BRIDGE,HARRIS CO.,HIGHMAY 1-610 PILE NUM DISTA,IN DISTB,IN THE TA, RAD 0.24620E+06 0.19099E+00 0.80773E+02 0.93473E+05 0.17321E+01 1NPUT INFORMATION TC TO P DIA,IN INC, LENGTH,IN NO, OF INC KS KA FIX 0.1800E+02 0.1600E+02 33 1 1 PILE LENGTH,IN DEPTH TO SOLL ITERATION TOL,BO UNDRY COND.2 0.5280E+03 0.0000E+00 0.1000E+02 0.0000E+00 0.5280E+02 0.26627E=01 0.14639E+06 0.00000E+00 -10033E+00 -10012E+02 0.48000E+02 0.26722E=01 0.14639E+06 0.0000E+00 -10032E+02 -1002E+02 0.5280E+03 0.0000E+00 0.11020E+02 0.0000E+02 0.6000E+02 -16093E+02 0.4000E+02 0.26722E=01 0.14639E+06 0.000								
PILE NUM DISTA,IN DISTB,IN THE TA, RAD PX,LB XT,IN 0.00000E+00 0.83000E+01 0.83000E+01 PX,LB XT,IN PT,LB H T,IN-L6 YT,I 0.24826106 0.19099E+00 0.80773E+02 0.93473E+05 0.17321E+01 INPUT INFORMATION TC TOP DIA,IN INC, LENGTH,IN NO, OF INC KS KA FIX 0.1800E+02 0.1600E+02 33 1 1 PILE LENGTH,IN DEPTH TO SOIL ITERATION TOL.BO UNDRY COND.2 0.5280E+03 0.0000E+00 0.1000E+02 0.0000E+00 - 0.16000E+02 0.2642E=01 0.14459E+06 0.00000E+00 0.00000E+00 - 0.0000E+02 0.26667E+02 0.14459E+06 0.30000E+00 0.00000E+00 0.40000E+02 0.26667E+01 0.15127E+06 0.16666E+04 - 1092E+02 0.46000E+02 0.4600E+02 0.14455E+06 0.226667E+04 - 14092E+02 0.4600E+02 0.15087E-01 0.15127E+06 0.16066E+04 - 1092E+02 0.4600E+02 0.4600E+02 0.14455E+06 0.226667E+04 - 14092E+02 0.4400E+02		1EX 2	0.48000E+03 0.49600E+03 0.51200E+03 0.52800E+03 HOUSTON SHIP	13662E-05 22849E-05 29663E-05 35831E-05 CHANNEL BRID	5 0.84251E+02 5 0.40547E+02 5 0.11035E+02 5 0.71760E+03 0GE,HARRIS CO.,	0.24350E+05 0.24350E+05 0.24350E+05 0.24350E+05 0.24350E+05 HIGHWAY I-61	0.33267E-01 0.55637E-01 0.72228E-01 0.87247E-01 0	
PX,LB XT,IN PT,LB M T,IN-LB YT,I 0.248286+06 0.190996+00 0.80773E+02 0.93473E+05 0.17321E+01 INPUT INFORMATION TC TOP DIA,IN INC, LENGTH,IN NO, OF INC KS KA FIX 0.1800E+02 0.1600E+02 33 1 1 PILE LENGTH,IN DEPTH TO SOIL ITERATION TOL.BO UNDRY COND.2 0.5280E+03 0.0000E+00 0.1000E-02 0.0000E+00 0.5280E+03 0.0000E+00 0.1000E-02 0.0000E+00 0.5280E+03 0.0000E+00 0.1000E-02 0.0000E+00 0.5280E+03 0.0000E+00 0.1000E+00 0.00000E+00 0.5280E+03 0.0000E+00 0.1000E+02 0.20462E-01 0.14659E+06 0.00000E+00 0.40000E+02 0.20462E-01 0.14659E+06 0.53333E+03 -10012E+02 0.40000E+02 0.20462E-01 0.14659E+06 0.1000E+04 -16958E+02 0.46000E+02 0.206687E-02 0.13670E+06 0.21333E+04 -14667E+02 0.46000E+02 0.69687E-02 0.13770E+06 0.21333E+04 -14667E+02 <t< td=""><td></td><td>-</td><td>PILE NUM 5</td><td>DISTA, IN 0,90000E+02</td><td>DISTB,1N 0.00000E+00</td><td>THE 0,83000E+</td><td>TA, RAD 01</td><td></td></t<>		-	PILE NUM 5	DISTA, IN 0,90000E+02	DISTB,1N 0.00000E+00	THE 0,83000E+	TA, RAD 01	
TC TOP DIA.IN INC. LENGTH.IN NO. OF INC KS KA FIX 0.1800E+02 0.1600E+02 33 1 1 PILE LENGTH.IN DEPTH TO SOIL ITERATION TOL.BO UNDRY COND.2 0.5280E+03 0.0000E+00 0.1000E-02 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.00000E+00 0.00000			PX,LB 0+24828E+06 INPUT INFORM	XT, IN 0,19099E+00 NTION	PT,LB 0.80773E+02	M T 0.93473E+	,IN-LB YT 05 0,17321E-01	.IN
Fix 0.1800E+02 0.1600E+02 33 1 1 PILE LENGTH, IN DEPTH TO SOIL ITERATION TOL.80 UNDRY COND.2 0.5280E+03 0.0000E+00 0.1000E+02 0.0000E+00 0.5280E+03 0.0000E+00 0.1000E+02 0.0000E+00 OUTPUT INFORMATION X,IN Y,IN MOMENT,IN-LB ES,LB/ IN P LB/ 0.0000E+00 0.26722E-01 0.14859E+06 0.00000E+00 0.00000E+00 0.00000E+00 0.00000E+00 0.32000E+02 0.20462E-01 0.15127E+06 0.10666E+04 -16093E+02 0.48000E+02 0.15087E-01 0.15127E+06 0.10666E+04 -16093E+02 0.48000E+02 0.41448E=02 0.12463E+06 0.26667E+04 -11052E+02 0.48000E+02 0.41448E=02 0.12463E+06 0.32000E+04 -165609E+01 0.11200E+03 -33759E=03 0.72026E+05 0.42667E+04 -11052E+02 0.4400E+03 -33759E=03 0.72026E+05 0.42667E+04 -140674E+01 0.4404E+01 0.14404E+01 0.14404E+01 0.14404E+01 0.14404E+01 0.14404E+01 0.14404E+01 0.14404E+01 0.4577E+02 0.32678E+05 0.12471E+05 <td></td> <td></td> <td>TC TOP</td> <td>DIA.IN I</td> <td>NC, LENGTH, IN</td> <td>NO, OF</td> <td>INC KS KA</td> <td></td>			TC TOP	DIA.IN I	NC, LENGTH, IN	NO, OF	INC KS KA	
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0.5280E+03 0.0000E+00 0.1000E-02 0.0000E+0€ OUTPUT INFORMATION X.IN Y.IN MOMENT.IN-LB ES.LB/ IN P LB/ 0.00000E+00 0.26722E-01 0.14859E+06 0.00000E+00 0.00000E+00 0.16000E+02 0.20462E-01 0.15143E+06 0.53333E+0310912E+02 0.32000E+02 0.15087E-01 0.15143E+06 0.16600E+0416093E+02 0.48000E+02 0.1598E-01 0.14676E+06 0.16600E+0416093E+02 0.64000E+02 0.69687E-02 0.13770E+06 0.21333E+0414867E+02 0.64000E+02 0.41448E-02 0.12433E+06 0.32000E+0465609E+01 0.11220E+03 0.59111E-03 0.990638E+05 0.37333E+0422068E+01 0.12800E+0333759E-03 0.72026E+05 0.42667E+0426968E+01 0.12800E+0333759E-02 0.3200E+05 0.48000E+04 0.48562E+01 0.12800E+0333759E-03 0.53629E+05 0.42667E+04 0.44404E+01 0.14400E+0310183E-02 0.21115E+05 0.12247E+05 0.12471E+02 0.19200E+0310183E-02 0.21115E+05 0.4800DE+04 0.480452E+01 0.17600E+0310183E-02 0.21115E+05 0.12247E+05 0.12471E+02 0.22400E+0347895E-03 0.91007E+04 0.24350E+05 0.13374E+02 0.22400E+0330447E-03 0.65234E+04 0.24350E+05 0.13247E+01 0.22400E+0330447E-0365214E+04 0.24350E+05 0.474137E+01 0.22600E+0310815E-0365214E+04 0.24350E+05 0.474137E+01 0.22600E+0310815E-0365214E+04 0.24350E+05 0.40944E+01 0.227200E+0377410E-0459446E+04 0.24350E+05 0.40948E+01			PILE LENGTH.	N DEPTH TO S	OIN ITERATION	TOL.80	UNDRY COND.2	
X,IN Y,IN MOMENT,IN-LB ES,LB/ IN P LB/ 0.00000E+00 0.26722E-01 0.14859E+06 0.00000E+00 0.00000E+00 0.16000E+02 0.20462E-01 0.15143E+06 0.53333E+03 10912E+02 0.32000E+02 0.15087E-01 0.15127E+06 0.10666E+04 16093E+02 0.48000E+02 0.10598E+01 0.14676E+06 0.16000E+04 16093E+02 0.64000E+02 0.69687E-02 0.13770E+06 0.21333E+04 14867E+02 0.6000E+02 0.69687E-02 0.10855E+06 0.32000E+04 65609E+01 0.1200E+03 0.59111E+03 0.990638E+05 0.37333E+04 22068E+01 0.12800E+03 33759E-03 0.72026E+05 0.42667E+04 0.14404E+01 0.12800E+03 33759E-03 0.72026E+05 0.42667E+04 0.14404E+01 0.12800E+03 10377E-02 0.36291E+05 0.42667E+04 0.14404E+01 0.12400E+03 10377E-02 0.36291E+05 0.42667E+04 0.14404E+01 0.12800E+03 10377E-02 0.			0.5280E+0	0.0000	E+00 0,100	DE+02 0,	0000E+00	
X, IN Y, IN MOMENT, IN-LB ES, LB/ IN P LB/ 0.000000E+00 0.26722E+01 0.14859E+06 0.00000E+00 0.00000E+00 0.00000E+00 0.16000E+02 0.20462E+01 0.15143E+06 0.53333E+03 10912E+02 0.32000E+02 0.15087E+01 0.15127E+06 0.10666E+04 16093E+02 0.48000E+02 0.10598E+01 0.14676E+06 0.16000E+04 14958E+02 0.44000E+02 0.69687E+02 0.13770E+06 0.21333E+04 14867E+02 0.6000E+02 0.41448E+02 0.12635E+06 0.32000E+04 165609E+01 0.11200E+03 0.59111E+03 0.90638E+05 0.37333E+04 22068E+01 0.14400E+03 84474E+03 0.53678E+05 0.48000E+04 0.40547E+01 0.14400E+03 10377E+02 0.36291E+05 0.42667E+04 0.14404E+01 0.17600E+03 10377E+02 0.36291E+05 0.12247E+05 0.12477E+02 0.17600E+03 10377E+02 0.2115E+05 0.12247E+05 0.13374E+02 0.17600E+03 <		·			OUTPUT INFORMA	FION		
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$			X, IN	Y, IN	MOMENT, IN-LB	ES,LB/	IN PL	B/IN
U,28800E+03 ~,94612E-05 ~.46734E+04 0,24350E+05 0,23038E+00 U.30400E+03 0.25135E-0433365E+04 0,24350E+05 ~.61203E+00 U.32000E+03 0.40204E-0421514E+04 0.24350E+05 ~.97895E+00 U.33600E+03 0.42682E-0412137E+04 0.24350E+05 ~.10392E+01 U.35200E+03 0.38055E-0454043E+03 0.24350E+0592663E+00	ંગોરો		0.0000E+00 0.16J00E+02 0.32000E+02 0.48000E+02 0.640000E+02 0.50000E+02 0.12800E+03 0.12800E+03 0.14400E+03 0.14400E+03 0.16000E+03 0.20800E+03 0.22400E+03 0.22400E+03 0.22400E+03 0.22600E+03 0.22600E+03 0.2600E+03 0.30400E+03 0.30400E+03 0.30400E+03 0.35200E+03 0.35200E+03	0.26722E-01 0.20462E-01 0.15087E-01 0.10598E-01 0.69687E-02 0.41448E-02 0.20503E-02 0.59111E-03 33759E-03 10377E-02 10183E-02 87530E-03 47895E-03 47895E-03 47895E-03 47895E-03 16815E-03 16815E-03 16815E-03 71410E-04 94612E-05 0.25135E-04 0.40204E-04 0.42682E-04 0.38055E-04	0.14859E+06 0.15143E+06 0.15127E+06 0.13770E+06 0.13770E+06 0.12463E+06 0.10855E+06 0.90638E+05 0.72026E+05 0.53678E+05 0.53678E+05 0.36291E+05 0.36291E+05 0.36291E+05 0.43734E+04 65234E+03 43734E+04 59446E+04 33365E+04 21514E+04 21514E+04 12137E+04 54043E+03	0,00000E+00 0,53333E+03 0,10666E+04 0,21333E+04 0,21333E+04 0,2200E+04 0,32000E+04 0,37333E+04 0,42667E+04 0,42667E+04 0,42667E+04 0,12247E+05 0,12971E+05 0,23419E+05 0,24350E+05 0,243	0.00000000000000000000000000000000000	

बेच-क्रिकक्रक्री के

E41

0.14485E+03

0.25669E+03

0.27888E+03

0.24907E+03

0.19481E+03

0.13459E+03 0.79830E+02

0.37003E+02

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0,24350E+05

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0,24350E+05

0,38400E+03 0,21870E-04

U.46400E+03 -.90596E-06 U.48000E+03 -.19334E-05 U.49600E+03 -.24935E-05

U,40000E+03

0.41600E+03

0,43200E+03

0,44800E+03

0.14323E-04 0.82775E-05

0,38645E-05

0.90918E-06

(Sheet 9 of 10)

-.53253E+00 -.34875E+00

-+20155E+00

-.94098E-01

-,22138E-01

0.22060E-01

0+47076E-01

0.60716E-01

Table E4 (Concluded)

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1EX 2	0.51200E+03 0.52800E+03 HOUSTON SHIP	28371E-05 31242E-05 CHANNEL BRID	0.96659E+01 0.58283E+03 GE,HARRIS CO.,	0,24350E+0 0,24350E+0 HIGHWAY 1-6	5 0.69083E- 5 0.76072E- 10	01 01
· • •	PILE_NUM 6	DISTA.IN 0.15000E+03	DIST8,IN 0.00000E+00	THE 0.16600E	TA, RAD +00	
	PX;LB 0+28149E+06 INPUT INFORM	XT,IN 0.21653E+00 ATION	PT,LB 0.11586E-01	H +,15874E	T,IN-L0 +05 -,27207E	YT.IN -02
	TC TO	P DIAJIN I	NC, LENGTH, IN	NO, OF	INC, KS K	A
	FIX 0	.1800E+02	0,1600E+02	33	1 1	
	PILE LENGTH,	IN DEPTH TO S	OIL ITERATION	TOL.BO	UNDRY COND	,2
	0.5280E+0	03 0+0000	E+00 0,100	0E-02 0	.0000EF00	
		(OUTPUT INFORMA	TION		
	X, IN	Y.IN	MOMENT, IN-LB	ES,LB/	tN	P LB/IN
	$\begin{array}{c} 0, 0000000000000000000000000000000000$	$\begin{array}{c} 0.26238\pm-01\\ 0.19991\pm-01\\ 0.14649\pm-01\\ 0.10207\pm-01\\ 0.66322\pm-02\\ 0.38661\pm-02\\ 0.38661\pm-02\\ 0.42222\pm-03\\4528\pm-02\\ 0.42222\pm-03\\4528\pm-02\\ 0.42222\pm-03\\4528\pm-02\\ 0.42222\pm-03\\47365\pm-02\\88605\pm-03\\92734\pm-03\\92734\pm-03\\10855\pm-02\\88605\pm-03\\92734\pm-03\\10855\pm-03\\29684\pm-03\\29684\pm-03\\29684\pm-03\\29684\pm-03\\29684\pm-03\\29684\pm-03\\29684\pm-03\\29684\pm-03\\29684\pm-03\\29684\pm-03\\29684\pm-03\\29684\pm-03\\29684\pm-04\\ 0.3038\pm-04\\ 0.42676\pm-04\\ 0.3038\pm-04\\ 0.3028\pm-05\\ 0.3522\pm-05\\ 0.3522\pm-05\\ 0.3522\pm-05\\ 0.3522\pm-05\\ 0.3522\pm-05\\ 0.3522\pm-05\\ 0.3522\pm-05\\ 0.352\pm-05\\ 0.35\pm-05\\ 0.35\pm-05\\ 0.35\pm-05\\ 0.35\pm-05\\ 0.35\pm-05\\ 0.35\pm-05\\ 0$	0.15307E+06 0.15483E+06 0.15361E+06 0.13822E+06 0.13822E+06 0.12447E+06 0.10787E+06 0.52333E+05 0.7078E+05 0.52333E+05 0.52333E+05 0.34947E+05 0.34947E+05 0.34947E+05 0.362E+03 49444E+04 68842E+04 68842E+04 69623E+04 46844E+04 46844E+04 46844E+04 46844E+04 46844E+04 46844E+04 69623E+04 4684E+04 4684E+04 69623E+04 1621E+04 21028E+04 1621E+04 21028E+03 0.27424E+03 0.25419E+03 0.25419E+03 0.13464E+03 0.13464E+03 0.13464E+03 0.13464E+03 0.13464E+03 0.13464E+03 0.255419E+03 0.13464E+03 0.55916E+03 0.55916E+03	0,18626E-0 0,53333E+0 0,10666E+0 0,21333E+0 0,26667E+0 0,26667E+0 0,37333E+0 0,37332E+0 0,42600E+0 0,48000E+0 0,48000E+0 0,12247E+0 0,12971E+0 0,12971E+0 0,24350E+0	$\begin{array}{c} & & & & & & & & & & & & & & & & & & &$	10 1 02 02 02 02 02 02 01 01 01 01 01 01 02 02 01 01 02 02 02 02 02 02 02 02 02 02 02 02 02 02 02 02 02 02 01 01 01 01 01 01 01 01 01 01 01 01

(Sheet 10 of 10)

APPENDIX F: USER'S GUIDE FOR PROGRAM BMCOL51

General Introduction

1. Documentation for computer program BMCOL51 - to solve a wide variety of beam-column structural problems for moving loads - is presented in this appendix and includes a general introduction, listing of the program, summary flow chart, guide for data input, and input-output for two example problems.

2. BMCOL51 is a finite difference program (developed by Prof. H. Matlock and Dr. T. P. Taylor,* UT at Austin) that can solve a variety of simple and complex beam-column structural problems accounting for movable loads. It is one of the earlier BMCOL programs written under the guidance of Prof. Matlock. Later versions of the BMCOL programs are available and are much more efficient and versatile than BMCOL51. However, BMCOL51 is documented herein principally to show the power and versatility of this family of programs. The documentation is extracted from the report written by Matlock and Taylor.

> 3. Beam-column equations developed in Part VI are programmed in BMCOL51. Changes in load (including moving loads), flexural stiffness, support conditions, and axial loads can vary in a freely discontinuous manner from joint to joint in the model. The finite difference representation of the fourth order differential equations are consecutively solved starting at one end of the beam in terms of known boundary conditions and adjacent joints. At the other end, the process reverses and the deflections are computed in a back substitution from joint to joint. By numerical differentiation of the deflections, the slope, bending moment, shear, and reaction are determined at each point. Plot routines in the program can be activated to produce plots of deflections, moments, shear, or reactions along the length of the beam-column.

4. BMCOL51 can consider only linear soil supports; however, other

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^{*} H. Matlock and T. P. Taylor, "A Computer Program to Analyze Beam-Columns Under Movable Loads," Research Report 56-4, 1968, Center for Highway Research, University of Texas, Austin, Tex.

BMCOL programs are currently available that can account for nonlinear behavior. Programs to perform dynamic analyses are also available. A list of available reports describig some of the more versatile programs is included in paragraph 7.

5. Some of the uses of BMCOL51 can be in obtaining general solutions for linear beam-columns, moving load problems, beam on elastic foundation problems, variable beam-size problems, and buckling problems.

6. BMCOL51 runs in the WES G-635 computer in batch/remote batch/ Card-In mode. The program is saved in the system (under a user number) as BMCOL51. To run a batch/remote batch job the user can access the program through proper control cards and read in his data in the form of cards. To run a Card-In job, the user first reads in his data in a file and then runs the program (with the data file created from-afterminal or from cards). He can direct his output to any printer at the end of the run by giving proper commands.

7. The beam-column related reports (as of April 1974) of the Center for Highway Research, University of Texas at Austin, are as follows: <u>Report No. 56-1</u>, "A Finite-Element Method of Solution for Linearly Elastic Beam-Columns" by H. Matlock and T. A. Haliburton, presents a solution for beam-columns that is a basic tool in subsequent reports. September 1966.

> <u>Report No. 56-2</u>, "A Computer Program to Analyze Bending of Bent Caps" by H. Matlock and W. B. Ingram, describes the application of the beamcolumn solution to the particular problem of bridge bent caps. October 1966.

Report No. 56-3. "A Finite-Element Method of Solution for Structural Frames" by H. Matlock and B. R. Grubbs, describes a solution for frames with no sway. May 1967.

Report No. 56-4, "A Computer Program to Analyze Beam-Columns Under Movable Loads" by H. Matlock and T. P. Taylor, describes the application of the beam-column solution to problems with any configuration of movable nondynamic loads. June 1968.

<u>Report No. 56-5.</u> "A Finite-Element Method for Bending Analysis of Layered Structural Systems" by W. B. Ingram and H. Matlock, describes an alternating-direction iteration method for solving two-dimensional systems of layered grids-over-beams and plates-over-beams. June 1967.

Report No. 56-6, "Discontinuous Orthotrophic Plates and Pavement Slabs"

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by W. R. Hudson and Hudson Matlock, describes an alternating-direction iteration method for solving complex two-dimensional plate and slab problems with emphasis on pavement slabs. May 1966.

Report No. 56-7, "A Finite-Element Analysis of Structural Frames" by T. A. Haliburton and H. Matlock, describes a method of analysis for rectangular plane frames with three degrees of freedom at each joint. July 1967.

<u>Report No. 56-8</u>, "A Finite-Element Method for Transverse Vibrations of Beams and Plates" by H. Salani and H. Matlock, describes an implicit procedure for determining the transient and steady-state vibrations of beams and plates, including pavement slabs. June 1968.

<u>Report No. 56-9</u>, "A Direct Computer Solution for Plates and Pavement Slabs: by C. F. Stelzer, Jr., and W. R. Hudson, describes a direct method for solving complex two-dimensional plate and slab problems. October 1967.

Report No. 56-10, "A Finite-Element Method of Analysis for Composite Beams" by T. P. Taylor and H. Matlock, describes a method of analysis for composite beams with any degree of horizontal shear interaction. January 1968.

January 1968. <u>Report No. 56-11</u>, "A Discrete-Element Solution of Plates and Pavement Slabs Using a Variable-Increment-Length Model" by C. M. Pearre III and W. R. Hudson, presents a method for solving freely discontinuous plates and pavement slabs subjected to a variety of loads. April 1969.

Report No. 56-12, "A Discrete-Element Method of Analysis for Combined Bending and Shear Deformations of a Beam" by D. F. Tankersley and W. P. Dawkins, presents a method of analysis for the combined effects of bending and shear deformations. December 1969.

<u>Report No. 56-13</u>, "A Discrete-Element Method of Multiple-Loading Analysis for Two-Way Bridge Floor Slabs" by J. J. Panak and H. Matlock, includes a procedure for analysis of two-way bridge floor slabs continuous over many supports. January 1970.

<u>Report No. 56-14</u>, "A Direct Computer Solution for Plane Frames" by W. P. Dawkins and J. R. Ruser, Jr., presents a direct method of solution for the computer analysis of plane frame structures. May 1969.

<u>Report No. 56-15</u>, "Experimental Verification of Discrete-Element Solutions for Plates and Slabs" by S. L. Agarwal and W. R. Hudson, presents a comparison of discrete-element solutions with small-dimension test results for plates and slabs, including some cyclic data. April 1970.

Report No. 56-16, "Experimental Evaluation of Subgrade Modulus and Its Application in Model Slab Studies" by Q. S. Siddiqi and W. R. Hudson,

describes a series of experiments to evaluate layered foundation coefficients of subgrade reaction for use in the discrete-element method. January 1970.

<u>Report No. 56-17</u>, "Dynamic Analysis of Discrete-Element Plates on Nonlinear Foundations" by A. E. Kelly and H. Matlock, presents a numerical method for the dynamic analysis of plates on nonlinear foundations. July 1970.

Report No. 56-18, "A Discrete-Element Analysis for Anisotropic Skew Plates and Grids" by M. R. Vora and H. Matlock, describes a tridirectional model and a computer program for the analysis of anisotropic skew plates or slabs with grid-beams. August 1970.

<u>Report No. 56-19</u>, "An Algebraic Equation Solution Process Formulated in Anticipation of Banded Linear Equations" by F. L. Endres and H. Matlock, describes a system of equation-solving routines that may be applied to a wide variety of problems by using them within appropriate programs. January 1971.

<u>Report No. 56-20</u>, "Finite-Element Method of Analysis for Plane Curved Girders" by W. P. Dawkins, presents a method of analysis that may be applied to plane curved highway bridge girders and other structural members composed of straight and curved sections. June 1971.

<u>Report No. 56-21</u>, "Linearly Elastic Analysis of Plane Frames Subjected to Complex Loading Conditions" by C. O. Hays and H. Matlock, presents a design-oriented computer solution for plane frames structures and trusses that can analyze with a large number of loading conditions. June 1971.

<u>Report No. 56-22</u>, "Analysis of Bending Stiffness Variation at Cracks in Continuous Pavements" by A. Abou-Ayyash and W. R. Hudson, describes an evaluation of the effect of transverse cracks on the longitudinal bending rigidity of continuously reinforced concrete pavements. April 1972.

Report No. 56-23, "A Nonlinear Analysis of Statically Loaded Plane Frames Using a Discrete Element Model" by C. O. Hays and H. Matlock, describes a method of analysis which considers support, material, and geometric nonlinearities for plane frames subjected to complex loads and restraints. May 1972.

Report No. 56-24, "A Discrete-Element Method for Transverse Vibrations of Beam-Columns Resting on Linearly Elastic or Inelastic Supports" by J. Hsiao-Chieh Chan and H. Matlock, presents a new approach to predict the hysteretic behavior of inelastic supports in dynamic problems. June 1972.

Report No. 56-25, "A Discrete-Element Method of Analysis for Orthogonal Slab and Grid Bridge Floor Systems" by J. J. Panak and H. Matlock,

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presents a computer program particularly suited to highway bridge structures composed of slabs with supporting beam-diaphragm systems. May 1972.

Report No. 56-26, "Application of Slab Analysis Methods to Rigid Pavement Problems" by H. J. Treybig, W. R. Hudson, and A. Abou-Ayyash, illustrates how the program of Report No. 56-25 can be specifically applied to a typical continuously reinforced pavement with shoulders. May 1972.

Report No. 56-27, "Final Summary of Discrete-Element Methods of Analysis for Pavement Slabs" by W. Ronald Hudson, H. J. Treybig, and A. Abou-Ayyash, presents a summary of the project developments which can be used for pavement slabs. August 1972.

<u>Report No. 56-28</u>, "Finite-Element Analysis of Bridge Decks" by M. R. Abdelraouf and H. Matlock, presents a finite-element analysis which is compared with a discrete-element analysis of a typical bridge superstructure. August 1972.

Report No. 56-29F, "Final Project Report" by J. J. Panak, summarizes the project history and describes the major developments and findings in concise form. August 1972.

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8. A summary flow chart for this program is shown in Figure Fl.



Figure Fl. Summary flow diagram for BMCOL51

10. The data is input to the code in the card forms presented in this guide (extracted from 1 REACT 18 CASE = 1 for deflection only, 2 for slope only, 3 for both TABLE 3. SPECIFIED DEFLECTIONS AND SLOPES (number of cards according to Table 1; none if preceding Table 3 is held) SHEAR ومتناكم ENTER "1" TO PLOT ENVELOPES FOR MOM TABLE 2. CONSTANTS AND MOVABLE-LOAD DATA (one card, or none if Table 2 of preceding problem is held) DEFL DATA STEP ဒ္ဓ 9 TABLE STOP STA LOAD ļ POR IDENTIFICATION OF PROBLEM (one card each problem; program stops if PROB NUM = 0) 8 ADDED START . STA Input MOVABLE NUM INCRS. IN PATTERN-(Continued) **\$**] CARDS Guide for Data IDENTIFICATION OF PROGRAM AND RUN (2 alphanumeric cards per run) ş MUN SLOPE TABLE 1. PROGRAM CONTROL DATA (one card each problem) Description of problem (alphanumeric) 8 ŝ Nisisisto. a report by H. Matlock and T. P. Taylor*). 2 0 30 ¢ INCR LENGTH DEFLECTION PRIOR ŝ **GLIOH** 8 20 CASE ENTER "1" TO ENVELOPFS TABLE 2 ŝ STATION NUM 2 <u>o</u> Ibid p. Fl. PROB NUM * 154 A. W.

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TABLE 4. FIXED LOADS AND RESTRAINTS, (number of cards according to Table 1). Data added to storage as lumped quantities per increment length, linearly interpolated between values input at indicated end stations, with 1/2-values at each end station. Concentrated effects are established as full values at single stations by setting final station = initial station.

STA	to Sta	ENTER 1 LF CONT'D ON NEXT CARD	F BENDING STIFFNESS	Q _f Transve - force	RSE	S SPRING SUPPORT		T TRANSVERSE COUPLE	R ROTATIONAL RESTRAINT	P AXIAL TENSION OR COMPRESSION
							Ţ		1	1
6	ю	15 20		30	40	7	50	64	7(80

TABLE 5. MOVABLE LOADS (Number of cards according to Table 1). Data added to storage just as in Table 4.

	_	ENTER IF CON	1 T'D	Q _m		
STA	TO STA	ON NE	XT	TRANSVERSE FORCE	i.	
					· .•	
 6	ю	15	20	31 40		

TABLE 6. SPECIFIED STATIONS FOR INFLUENCE DIAGRAMS (4 cards or none).

	NUM DIAGRA	OF TYP	E OF PUT*	SPECI	FIED S	TATIONS (max = :	5 per va	riable)	<pre>*1 = Plotted Output</pre>
	6	ĩO	15	20	25	30	35	40	45	
·										MOMENT
	6	ю	45	20	25	30	35	40	-45	
									<u></u>	SHEAR
	6	\$	5	20	25	30	35	40	45	
										REACTION
	6	Ð	15	20	25	30	35	40	45	ři .
	STO	P CARD	(one	blank card	at end	i of run)		<u></u> .	÷.	
1										* · · · · · · · · · · · · · · · · · · ·

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(Continued)



TABLE 2. CONSTANTS AND MOVABLE-LOAD DATA

- The maximum number of increments into which the beam-column may be divided is 200. Typical units for the value of increment length are inches.
- The number of increments in the movable-load pattern may not exceed the number of increments in the beamcolumn. The start station is the first position at which the zero station of the movable-load pattern is placed.

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(Continued)

	• _	tive start station is permissible d pattern on the beam-column.	n one step of movement past the	ny increments as desired.	ment of pattern length, zero start		pecified is 20.	ified slope.	fied slope, except that both a		R P <u>in x Ib</u> Ib	rad in the same manner as any other cally distribute the internal effects	roblem) which would express-effects	· ·	-	
	 le (Continued)	ermissible. A nega portion of the loa	tion of no more tha	a in steps of as ma	s, enter zero incre le 5 necessary.	•	ind slopes may be s	from ther spec	ments from a speci- tame station.	• •	in Tr th	d at each station i rogram to automatic	om the preceding pi al beam-column.	ation 0.	· •	nued)
1499303359 1	Data Input Gui	Any positive start station for the movable load is p if one step of the load pattern will place some	Any stop station on the beam is allowed. A stop start fight end of the beam-column is permissible.	The movable-load pattern may be moved actoss the bea	To plot envelopes of maximum for fixed-load solution and stop stations, and 1 for step size. No Tab	TABLE 3. SPECIFIED DEFLECTIONS AND SLOPES	The maximum number of stations at which deflections	A slope may not be specified closer than 3 increment	A deflection may not be specified closer than 2 fucr- deflection and a slope may be specified at the	TABLE 4. STIFFNESS AND FIXED-LOAD DATA	Typical units, variables: F Q ; values per station: 1b × in ² 1b 1b,	Axial tension or compression values P must be state distributed data; there is no mechanism in the p of an externally applied axial force.	Data should not be entered in this table (nor held fue to the stations beyond the ends of the restions beyond the ends of the resting the second the secon	The left end of the beam-column must be located at at		(Conti

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Data Input Guide (Continued)	For the interpolation and distribution process, there are four variations in the station numbering and the referencing for continuation to succeeding cards. These variations are explained and illustrated on page 6.	There are no restrictions on the order of cards in Table 4, except that within a distribution sequence the stations must be in regular order.	5. MOVABLE-LOAD DATA	The data in Table 5 is governed by the same rules as Table 4.	6. SPECIFIED STATIONS FOR INFLUENCE DIAGRAMS	The number of cards in Table 6 is either 4 or 0.	A maximum of 5 stations may be specified for each of the four variables, deflection, bending moment, shear, and support reaction.	The data cards must be stacked in the same order as the above list.	If no influence lines are desired for one variable, a blank card must be inserted for that variable.	Shear is computed one-half increment to the left of the designated station.	If 1 is specified for the type of output, the influence lines are plotted on 4 X 10 in, axes.	If 2 is specified for the type of output, the influence lines are tabulated in numerical form in Table 10.	If 3 is specified for the type of output, the influence lines are tabuitted and plotted.			(Continued)	
	Foi	The	TABLE 5.	The	LABLE 6.	The	8 4	The	IÍ	She	Τ£	ΞĒ	Τ£				

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Example Problems

Example Problem 1

9. The first example problem demonstrating the use of program BMCOL51 shows a simply supported beam with the variable cross section loaded (Figure F2). The input and output data for this example are presented in Tables F1 and F2. The results of the variation of deflection and moment along the beam are plotted in Figures F3 and F⁴.



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Table Fl Input Data for Example Problem 1

			· . ·	·		-
PROGRAM			••		DATE	
REQUESTED BY	PREPARED BY		··· CHECE	K0 8V	PAGE	
1 2 3 4 5 5 9 8 10 11 13 13 18 18 18 18 18 18 18 18 18 18 18 20	ti 22 23 24 23 26 27 26 29 29 30	0 02 02 04 11 06 02 04 05 05 05 00 0	11 42 42 44 45 46 47 48 48 3	0 81 82 88 84 83 84 87 58 58 80	61 82 88 64 85 86 87 48 88 70 7	1 22 73 24 73 76 77 78 75 86
	La SALIOL	5.1. UNIVER	S.T.T.Y. D.F. T.	X. A.S. A.T. A.U.S		
	EXAMPLE F	Lablens. Field	a haracit	-		
. D.D.L STERLA DEMT	CALS SIME	Liv. Silvereneration	C.D. F.L.X.C.D. J	D.R. D.S. HITH	P.4.0.15.	
		L		, , , , , , , , , , , , , , , , , , ,	1	
	1.20061.01			7		
7	4.20.00.100					
1	D. D.D. 0E. 1 D.C					
1	0. 3.0.0.6.4.00			-	-	
	6.08.7.6.4.1.1	-5. 0.0.06+0.2				
	3.2.0.0.6.1.1.1	10.20E.+.0.2				
		-5.0.0.0.04				
		-11. 20.06.10.5				
$\cdot \cdot $		-1. 00021.05				
		-1.1.0.0.5.1.0.5				
		20.1.20.0.1				
		-1. 6.0.05+.05				
		-1.000£+05				
4040	* * * * * * * *	-5.0006+04				
		-5.0006+04				
50 . 50		-4.000E.1.04	, , , , , , , , , , , , , , , , , , , ,		+ + + + + + + + + + + + + + + + + + + +	
		-3.50061.04				
60.60		-3.000.1.04				
		2.5006404				
		-2.0.006.+0.4				
		-1.5006+04		11		
BELF FORM NO. 1233 LEFTENDILL LAN				•		

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Table F2

Output Data for Example Problem 1



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(Sheet 1 of 11)

Table F2 (Continued)



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	PRUGRAI CEJ94.2 Report	4 84001 51 2 Humehurk 56-1 (S) -	- MASIER - I Problem Out Fur Center Fo	ATLOCK-TAYL L, DATA CODE Dr Highway R	.UH - REV D'FUR EXAMP RESEARCH. CC	ISION DATE : Le problem (Ded by F.PA	= 08 MAK 68 SIVEN IN Sker
	PRUB ((01	CONTU) Steel &	ENT CAP; SIMP	LY SUPPORTE	D,FIXED LOA	IUS, NO ENVEI	UPES OK
	TABLE 7	- FIXED-L	OAD RESULTS				
	STA I -1	DISI -0.1206 0	DEFL 2 0.3626 00	SLUPE	HOM 0.	SHEAR	SUP REAUT 0.
	0	Û •	0.3296 00	-U.271E-02 -0.271E-02	Q.	U+	0.
	1 ·	0.120E U	2 0.296± 00		-0.184E 04		0.
• • • • • • • • • • • • • • • • • • •	2	0.240E 0	2 0.264E 00	-U.271E-02	-0.734E 04	-0.458E 0J	0.
	3	0.360E 0	2 0.231E UO	-0.272E-02	-0.165E U5	-0.760E 03	0.
	··· 4.		2: . 0:.199E. 00	-U.272E-02	-0.292E 05	-U.106E 04	0.
••	5	0.6008 0	2 0.106E 00	-0.2726-02	-0.456E 05	-0,136E 04	0.
	6	0.720E 0	2 0.133E 00	-0.2/2E-02	-0.666E 06	-0.517E 05	0.
į	7	0.8408 02	2 0.101E 00	-0.27JE-02	-0.129E 07	•0+520E 05	û .
	8	0.960£ 83	2 0.676±-01	-0.276E-02	-0.192E U7	-0,523E 05	0.
	9	0.108E 03	0.341E-01	-U+279E+02	-0.255t U7	-0.526E 05	0.
	10	0.120E U.	\$ 0.	-0.284E-02	-0.318E U7	-0.529E 05	0.3722 06
	11	0.132E 03	i ~0.349E~01	-0.291E-02	*0.557E 86	0.219E 06	0.
	12	0.144H N3	-0.699Fent	-0.292E-02	0.2466 07	U.218E 06	0.
,		0 1641 13		-0.2888-02	0.4404 07	U.218E 06	•
	10	0.130E US	,	-0.278E-02	V+408E V/	0.218E 06	ध •
	14	0.1686 03	-0.138E UO	-U.264E-02	0.7296 07	0.218E 06	θ.
	15	0.1806 03	-0.109E 00	=0.245E+02	0.990£ 07	0.1175 06	0.
	16	0.192E UJ	-0.199E 00		0.113E 08		Û.
	17	0.204E 03	-0.226t 00	-U+622E+02	0.127E 08	0.11/E 00	0 *
	18	0.216E U3	-0.249E UU	-0.19/E-02	0.141E 08	U.117E 06	0.
	19	0.228E 03	-0.269E UD	-0.169E-02	0.1556 08	0.116E 06	Q.
	20	0.240F #3	-0.2866 00	-0+139E+02	0.160k NR	U.116E 06	A .
				-0.105E-02	STROPE GO	0.572E 04	↓

Table F2 (Continued)

(Continued)

(Sheet 3 of 11)

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Table F2 (Continued)

	21	0.252E	03	-0.299E 00	-0 7205-04	0.170E	y 8	11 6490	04	0.		
	22	0.264E	43	+0.3U7E 00		0.170E	8 0		• •	Q .		
	23	0.276E	03	-0.312E 00	+U.384E-U3	, 0.171E	ġ 8	0+912E	84	0.		
· · · · · .	"24"	- 0.288E	03	-0.313E UO	-0.47UE-04	0.172E	88	0.483E	04	0.		
	25	0.3046	83	-A.309F 80	0.291E-03	A.1726	0.9	0.453E	04			
					0.6308-03			-U.106E	96	••		
	20	0.3125	83	-U.JUZE UU	0.945E-03	0.199E	08	-0.106E	96	0.		
	27	0.324E	ű 3	-0.290E 00	0.123E-02	0.147E	48	-U.106E	06	. .		
	28	0.336E	83	-0.2/5E 00	0.1506+02	0.134E	0,8	-0.1076	86	0.		
	29	0.348£	U 3	-0.257E 00	0 4745-02	0.121E	80		••	0.		
Attende 1	50	0.360E	03	+0.237E UO	0.1/46402	0.108E	89	+U+10/E	90 : []"	۳.		
	31	0.3726	U 3	-0,214£ 00	0.191E-02	0.834E	67	-#.207E	06	0.		
:	52	0.364E	83	+0.190E 00	0.2018-02	A.585F	67	-#.208E	00	٥.		
			. a Ŧ		0.209E-02	A. 3361	•••	-0.208E	. 86	.	, .	·
		. U . 370E	· ,ų .,	-044036 00.	0.213E-02	. 0.433355	U 7.	-0.208E	06			
	34	0.408E	03	-0.139E.00	0.214E-02	0.848£	06	+U.209E	86	0.		
	35	0.420Ł	03	+0.113E 00	0.2126-02	-0.166E	07	+0.3A9E	0.6	0.		
	\$6	0.432E	U 3	-0.877E-01	0.0055-00	+0.537E	07		••	·0 •		
	57	0.444E	03	-0.631E-01	9+2026-02	-0.9096	07	-0.310E	80	0.		
Republicities	38	0.456t	03	-0.3996-01	0.193E-02	-0.128E	¥ B	-0.310E	06	9.		
:	39	0.4688	03	-0.187£-01	0.177E-02	+0.165F	0.8	-0.311E	06	û .		
	4.9	8.4986	43	ů -	0.1566+02			-0.311E	06	0.600.		
		0.4000		• • • • • • •	0.129Ê-02	-0.2002	00	0.158E	06	0.9206	00	
	-	0.4928	03	0.1996-01	0.106E-02	+ 0.184E	08	0.158E	06	0.		
÷	42	0.504E	03	0.2826-01	0.844E-0J	-0.165E	89	U.158E	06	0.		
	43	0.516E	03	0.3836-01	8-4545-03	-0.146E	80	0 1E7E	84	0.		
, , , , , , , , , , , , , , , , , , ,	44	0.528E	Q3 -	0.4026-01	010202-03	-0.127E	¥8	V+12/E	40	Q.		
	45	0.540E	03	0.5216-01	0.492E-03	-0.1086	U 8	₩.157E	06	0.		
	46	0.552£	83	0.5632-01	0.3258+03	+0.953E	u7	9.106E	06	0.		
	47	0.5646	03	0.5016_01	0+229E+03	-0 9741		V.106E	06			
			•••	0.5712-01	0.122E-03	-0.0200	ų /	0+106E	80	U •		
	70	U.9/0Ł	U S	0.6U5E+Q1	0.321E-04	-0,699E	07	0.105E	06	9 .		
	49	0.5886	U 3	0.6096-01	0.419E-04	-0.573Ł	07	0.105F	86	0.		
	50	0.600£	43	0.6048-01		-0.447E	¥7'		••	0.		
					(Continue	ed)						
								(She	et 4 o	f 11)	

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Table F2 (Continued)

		0 6126 0	7 0 5016-01	-0.112E-03	U.645E 05	
	51	0.012E 0	J 0.5401-01	-0.184E-03	07 U-642E 05	0.
	52	0.0248 0	3 0.2092-01	-0.242E+03	U-639E 05	U .
	53	0.636E U	3 0.5402-01	+0.216E -0.285E-03	07 U.636E 05	0.
-	54	_ 0.648± 0	3 0.5066-01	-0.140E -0.312E-03	07 0.633E 05	0.
	55	0.660£ 0	3 0.468E-01	-0.636E -0.325E-03	06 0.280E 05	0.
•	56	0.6726 0	3 0.4296-01	-0.300Ł	06 8.277E 05	0.
	57	0.684E V	3 0.389E-01	0.316E	05 0.274E 05	0.
	58	0.696E 0	3 0.350E-01	0.360E	06	0.
	59	0.708E U	3 0.311E-01	0.685E	0.2/1E 09 06	0.
r t	00	0.720E U	3 0.2746-01	+0.309E=03 0.101E	0.208E US	0.
	61	0.732E 0	3 0.239E-01	+0.290E-03 0.964E	•0.353E 04	0.
	62	0.744E 0	3 0.287E-01	-0.271E-0J 0.918E	-0.383E 04	0.
	63	0.756E U	3 0.176E-01	-U.252E-0J 0.868E	-0.413E 04	0.
· · · · · · · · · · · · · · · · · · ·	64	0.768E 0	5 0.1486-01	-0.235E-08	-0.443E 04	n
	65	0.7896 03	5 0.122F#01	-U.219E-03	-0.473E 04	0_
	44	0 7024 0		-0.204E-03	-0.300E 05	•
	00	0.0045 0	0.9/3E=U2	-0.197E-03	₩0+303E 05	U.
	0/	U+0U4E U4	0.738E+U2	+0.196E-03	-0.306E 05	0.
i ainninittii	08	0.810E 03	0.503E+02	-0.334E -0.202E-03	06 =0.309E 05	0.
	69	0 .828 E 03	0.260E-02	-0.705E -0.216E-03	06 +0.312E 05	0.
	70	0.840E 03	0.	-0.108£	07 0.178E 05	0.694E 05
	71	0.852E 03	-0.2856-02	=0+866E	06 0.175E 05	Û •
	72	0.864E U3	-0.5916-02	-0.655E	06 0 1725 05	0.
;	73	0.876E U3	-0.9126-02	-0.276E-03	U6 U 1605 05	0.
	74	0.888£ U3	-0.124E-01	-0.270E-03 -0.245E	0.10VE 09	0.
	75	0.900E U3	-0.1586-01	-0.450E	0.166E 05 05	0.
	76	0.912E 03	-0.1926-01	+0.282E-03 +0.288t	0.135E 04 05	0.
	77	0.924 <u>E</u> 03	-0,226E-01	-0.283E+03 -0.1624	0.105E 04	0.
	78	0.9361 03	-0.2006-01	-0.283E-03 -0.720F	0.749E 03	0.
	79	A.9486 83	-0.2946-01	-0.283E-03	0.450E 03	0
			<u>አትዋኑ አሮ</u> …ስዋዋ	-0+100E +0+283E=03	0.150E 03	¥ 4
	80	0.960E U3	-0.328E-01	0. -U.283E+03	⊎ .	0 .
	81	0.972E 03	-0.362 <u>+</u> 01	(Continued)		0.
				, <i>-</i> ,	(She	eet 5 of 11)
Table F2 (Continued)

	PRUB 001	(CONTD) Steel ben	T CA	P. SIMPLY SUPP	URTED.F	IXED LUADS,	N0 :	ENVELUPES OK	
·· :	•								
	TABLE	84- ENVELOPES	UF	MAXINUMS +	≠ HELD	FROM PRIOR	PRO	BLEN	
	STA	NAX +DEFL	LOC	MAX -DEFL	L00	NAX +HOM	LOC	MAX -BOM (L06
	-1	0.362E 00	-4	U.	999	U .	999	Ü.	999
	Ű	0.329E 00	-4	U.	999	ΰ.	999	Ű.	999
	1	0.296E 00	-4	0.	999	0.	999	-0.184E 04	-4
	2	U+264E DU	=4	θ.	999	Ü.	999	-0.734E 04	-4
	3	0.231E QU	+4	U .	999	Ú.	¥99	-0.169E 05	-4
	4	0.199E 00	-4	U	994	ٿ .	999	+0.292E 05	-4
	5	0.166E 00	+4	Ü .	99 9	U .	99¥	-0.450E 05	-4
	6	0.13JE 00	+4	G.	999	Ű.	999	-V.660E Do	-4
ļ	7	0+101E 00	=4	U.	999	¥.	999	-0.12YE 07	-4
	8	U+676E-01	-4	Ű.	999	0.	999	-0_192E 0/	-4
ļ	9	0.J41E-01	-4	U.	999	Ű.	999	- F. 255E 07	-4
	10	0.	<u> 999</u>	U.	999	U .	999	-U.316E 07	-4
}	11	ų.	999	-0.349E-01	-4	0.	999	-0.557E 06	
	12	0.	999	-0.699E-01	~4	0.206E 07	-4	U	199
	13	li .	999	+0.104E 00	-4	0.468E 07	-4	0. 1	199
	14	₩ •	999	-U.138E.UU	•••	U./29E U/	- 4	ten en e	199
	15		444	-U.109E UU		0.990E 07		· U.	/yy
	10	U. • ·	YYY	+U.199E UU		U+113E V8	-4	U • 1	/ / /
	10	¥ •	999	-+ 2405 00		0+12/E 00	- 4	U• 3	/ //
1	10	U .	777 00u	-U.Z.77C 00 -U.269E 00	-4	041410 00		U • 1	477 400
	21	0 .	400	-0.207E 00 -0.286F 00		0.160E 0N		6	400
ł	21	6.	000	-H-294E BH	-4	8.17HE AH	-	0.	400
;	22	ů .	999	-#.307E 0#		#.17#E 08	- 4	8	494
!	23	Ű.	499	-0.312E 00	-4	0.171E 08	- 4		99
a construction of the	24	ί.	999	-8.313E 86	+4	0.172E 08		8. 1	999
1939月4月19月18月	25	0.	999	-0.309E 00	-4	0.172E 08	-4	<u>8</u> .	99
	26	0.	999	-0.302E 00	-4	8.159E 08	-4	Ű	199
	27	0.	999	-0.290E 00	-4	0.147E 08	- 4	0. 5	199
	28	0.	999	-U.275E 0U	- 4	0.134E 00	- 4	8. 5	199
	29	0.	999	-0.257E 00	-4	0.121E 08	-4	U. 3	¥99
	30	Û .	999	-0.237E 00	-4	0.108E 08	-4	θ. Υ	¥99 ·
	. 31	Û.	999	-0.214E 00	÷4	0.834E 0/	-4	U. 1	199
	32	0.	99ÿ	+U.190E OU	-4	0.585E 07	-4	0% S	199
,	33	Ü 🖕	999	+0.165E 00	-4	0.335E 07	-4	Ű. Y	199
i	34	Ű.	999	+0.139E 00	-4	U•848E 06	-4	₩ . 5	199
	35	0.	999	-U.113E 00	-4	Ű.	999	-0.166E 07	-4
	36	0.	999	+0.877E-01	=4	Ú •	¥99	-0.537E 07	-4
	37	0.	999	-U.631E-U1	+4	θ.	999	-0.909E 07	- 4
	38	G .	999	-U.J99E-01	-4	U .	999	-0.128E 08	+4
	39	U •	999	+0.187E-01	+4	U .	999	-0.165E 08	-4
	40	U.	AAA	V.	999	U .	999	-0.203E 08	-4
	41	U+199E=01	-4	ن .	999	U .	999	-0.184E 08	• 4 - 4
		U+2028#U1 0-4948-01	- q - 4	រ រ	444	U .	777	-U+1072 U8	
	40 44	0.4400-01	-4	U •	777 ada	V •	777 606		- 4
	4 1	V+4V&E#81	- 4	4 +	777	V.	アブゾ		··· ••

(Continued)

(Sheet 6 of 11)

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Table F2 (Continued)

	46	0.5216-01	- 4	b .	000	H a	999	-8.18XF	Ûĸ	- 4
	46	0.5212-01	- 4	0 • H	uqu	6 .	400	-1.9545	50	- 4
`	47	0.5016-01	- 4	9 e	404	а. И.	úgu	- 0. 9900	07	
	4 H	0.0000000000000000000000000000000000000	- 4	0 • B .	uqu	0 .	444	-0.0202	n /	- 4
	40	-9.40026-01	- 4	ti .	000	0. A.	000	-0.57.56	07 07	- 4
	5.	0 4045-01	- 4	6	000	u .	uou	-0.J/UE	0.2	- 4
	51	0.0042-01	- 4	0 • 11	000	0	404	-044472	07	
	52	0 6600-01		67 e 1	222	U .	777 400	-0.3035	0/	
	53	0.5096-01		U •	404	••	000	-0+2725	07	- 4
	53	0+340E-01		U •	777	U •	777		07	- 4
	55	0.4645-01	- 4	U •	777	U .	777	-0+1400	0/	-4
	. 54	0.4205-01	- 4	U •	999	U • 4	777	-0.0000	00	-4
	· 90	0.3900-01	~ 4	U .	997 000	U - 314C	999 05 - 4	-0.300E	υo	
	51	8.3508001	- 4	U •	999	0.5100	0.5 -4	U., D.		77 7
	50 50	0.3115-01		U ◆	000	0.6855	06 -4	0 + fi		777 UGD
	64	8.274E=01		U •	400	0.0002	07 -4	U .		177 100
	61	042742-01		0 • A .	000	0.9648	07 -4 06 -4			,,,, ,,,,
	62	0.2076-01	- 4	0 e	000	0.0146	06 -4	0. 0. –		777 UQU
	63	0.1765-01	- 4	U e	000	0.7100	06 -4 32	ананан Тара		477 488
	6.4	0 1 4 VE-01	- 4	U • /1	777 000	0.0000	06 4			777 1.00
. '	45 65	0+1405-01	- 4	ψ	777	0.0196	00 -4			977 000
	66	0.0735-01	- 4	U • ()	777	0 100C	00 -4	U •		777 600
	47	0.7325-02	- 4	0 +	777	0.0900	00 -4	••		777
	67	0.000000	- 4	U .	997	0.0076	404		0 4	- 4
	69	0.260E+02	- - 4	U •	999	U.	· · · · · · · · · · · · · · · · · · ·	-0.331E	00	-4
	70	U.	999	U.	999	□ U.	999	+0.100E	0/	- 4
	71	0.	999	-0.285E-02	- 4	θ.	999	+0.86oE	θo	-4
	72	0.	999	+0.591E-02	-4	Ű.	999	-0.655E	θo	-4
	73	0.	999	-0.912E-02	- 4	U.	999	-U.448E	00	- 4
÷	74	μ.	999	+0.124E-01	- 4	Ο.	999	-0.245E	06	-4
	75	ti 🖡	99 9	-0.158E-01	- 4	Ű.	999	-0.45uE	05	-4
	76	U.	999	-U.192E-U1	-4	υ.	999	-0.288E	65	-4
	77	0.	999	-0.226E-01	- 4	U	999	-0.162E	05	-4
90943866669	78	U.	999	-0.260E-01	-4	0.	999	-0.720E	04	- 4
•	79	0.	999	-8.294E-01	- 4	U.	999	-0.180E	04	-4
	80	0.	999	-0.328E-01	- 4	θ.	999	ΰ.		999
	81	Ú.	999	-0.362E-01	- 4	U.	999	υ.		ý99

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(Sheet 7 of 11)

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	TABLE	88+ ENVELOPE	S UF	HAXIHUHS	HEL	D FROM PRIOK	PRUB	LEM	
	ьТА +1	MAX +SHEA	R LO	C MAX -SHEAT	₹ 1 00	MAX +REACT	LOC 999	MAX -KEAC U.	1 LOC V9V
		Û.	999) U.	999	9. 9.	900	U .	
	v	0.	999	-0.154E 0	5 -4		000		
	1	0.	999	-0.458E 8	5 -4		777	V •	***
en e	2	·· 0	999	9 +U.760E 04	5 = 4	U .	777	U.	
	3	6.	999	9 +8.106E 04	-4	V•	7 7 7	U.	AAA
	4	U.	999	9 -0.136E 04	-4	Ŭ.	999	U.	99 9
	5	0.	999	+0.517E 0	-4	Ü.	999	v.	999 999
•	6	0.	999	-0.52VE 05	-4	U •	999	U . 1	AAA
	7				_	U.	999	0.	999
	8	0.	999	-U.523E 05	• •4	ψ.	999	Ű.	999
	9	0.	995	-0.526E 05	⊨ • 4.	0.	999	· · · · · · · · · · · · · · · · · · ·	999
	10	0.	999	-U.529E 05	-4	0.372E 06	-4	U.	494
	11	0.219E 0	6 =4	ŧ ü.	999	0.	999	U.	999
	12	0.218E 0	6	k tato Vie je a teorit	.999	Ű.	994	U .	
÷	13	0.218E 0	6 -4	0 •	999	а.	904	0.	499
	14	0.218E 0	6 =4	0.	999	"	400	u •	444
:	47 42	0.218E 0	o =4	U .	999	¥.	777	V e	777 400
	17	0.117E 0	6 -4	i U.	999	Ŭ. ₽	777	U .	AAA
的制度和	10	0.117E 0	6 =4	0 .	999	¥.	999	U .	
	1/	0.117E 0	6 -4	Ú.	999	U.	YYY	U .	Y YY
	18	0.116E 0	6 -4	. 0.	999	0.	999	U .	¥99
	19	U.116E 0	6 -4	0 •	999	0.	999	V.	494
	20	Q.572E 0	4 -4	. 0.	999	Ü.	999	0.	999 999
. •	21	0.5426 0	4 -4		999	0.	999	U.	999 999
• •.	22	0 5195 A	, -, , _,		000	0.	999	V.	999
	23	U 4025 A		т Џ•	777 4440	Ű.	999	Ú.	999
	24	U.403E U	4 4	u u e	777	Ű.	999	0.	¥99
	25	U.453E 0	4 -4	U .	999	Ú.	999	U.	494
	26	Q.	999	-U.106E 06	-4	Û •	999	u.	y99
	27	0.	999	-U.106E 06	-4	0.	99 9	Ű.	V9Y
	28	0	¥99	-0.106E 06	-4	ti .	¥99	0.	999
		0.	999	-0.107E 00	-4				

Table F2 (Continued)

Contraction of the local distance of the loc

(Sheet 8 of 11)

	29	0	600	-0 1075	0.6	U.	¥99	U.	¥99
	30	U .	777 000	-0.0075	0.6 -4	ΰ.	999	Ü.	999
	31	U +	999 999	-0.20/E	UQ = 4	0.	999	U.	¥99
an tha an	32	U.e	999	-0.208E	UG4	0.	999	U.	¥99
	33	0.	999	-0.208E	00 -4	6.	999	0.	999
	34	Ű.	999	+0,208E	06 -4	U.	999	U.	y99
	35	Û.	999	+0.209E	00 -4	Ű.	999	Ű.	¥99
	74	0.	999	-0.309E	00 -4		000	0	
	30	0.	999	-0.310E	06 -4	0.	9 99		yyy
	37	U.+	999	-0.310E	00 -4	υ.	999	¥.	999
4	38	U.	999	-0.311E	06 -4	0.	999	0.	¥99
	39	Û.,	999	-0.311E	06 -4	0.	999 	0 <u>.</u>	99 9
	40	0.158E 00	5 -4	U.	999	0.520E 06	-4	0.	999
 -	41	0.158F 04	-4	Ű.	900	0.	¥99	0.	999
	42	0.1605 04		Ð	900		999	0.	999
	43	0 1676 04	· · · · · ·		400	Ü.	¥99	U.	999 [°] '
	44	041276 00		V •	***	6.	999	0.	999
	45	U.19/E UG	-4	U •	999	Ű.	999	IJ.	¥99
	46	0 .106E 06	-4	0.	999	0.	999	0.	999
918169	47	0.106E 06	-4	0.	999	0.	999	0.	99 9
	48	0.106E 06	• • 4	0.	999	8.	999	υ.	99 9
	49	0.105E 06	-4	0.	999	¥.	999	U.	999
	50	0.105E 06	-4	V .	999	0.	990	Ð.	ugo
· .	51	0.645E 05	+4	0.	999	й.	999	а.	400
	52	0.642E 05	-4	U.	99 9	••	000	••	
	57	0+639E 05	-4	0.	999	U •	,,,	0.	9 99
	20	0.636E 05	-4	0.	999	V.	999 999	U .	999
	54	0.633E 05	-4	U .	999	0.	999	Ű.	999
	55	0.28UE 05	-4	Ü.	999	Ű.	999	0.	999 999
	56	0.277E 05	-4	Ű.	999	0.	999	θ.	999
	57	0.274E 05	-4	0.	999	0.	999	0.	¥99
	58	0.271E 05	-4	ŧ.	999	Û.	999	υ.	Y99
	59	0.2685 05	• 4	0.	999	Û.	999	0.	999
	60	0	000	_0 3525 -	,,,, NA	0.	999	Û.	999
		~*		(C	ontinued	.)			

Table F2 (Continued)

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F23

(Sheet 9 of 11)

Table F2 (Continued)

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	61		400		0.4 m.4	Ú .	499	U.	999
	62	U.	999	-0.3835	44 +4	0.	999	Q.	999
	63	0.	999	-0.413E	04 +4	0.	999	0.	400
·		Ű.	999	-0.443E	84 -4	0			
•.		0	999	-U.473E	04 -4	U +	YYY	Ÿ.	999
	65	D .	999	-0.300E	85 •4	Û.	999	0.	99 9
	66		000			Ű.	999	0.	999
	67	U.	9 99	+U.3U3E	82 +4	0.	¥99	0.	999
	68	Q .	999	-U.306E	85 -4	Ű.	999	υ.	999
		0.	999	-0.309E	05 + 4		000	0	000
	07	U.	999	-0.312E	85 -4	U.	777	U .	999
	70	0.178E 0	15 +4	Ű.	999	0.694E 05	-4	U.	¥99
	71	0 4755 4		**		Ü.	999	থা,	999
:	72	A*1/25 A		U •	yyy	U .	999	0.	y99
	73	0.172E 0	15 -4	0.	999	0.	999	0.	999
		0.169E 0	5 •4	0.	999		000		600
		U.166E 0	15 -4	0.	999	•••			
	/5	0.135E 0	4 -4	0.	999	0.	999	υ.	448
:	76	0.1058 0	4 -4	A _	000	0.	999	0.	¥99
	77		· · ·	* •		8.	999	ų,	999
	78	U./492 0	3 -4	U.	999 999	Ű.	999	9 •	999
appanetten	79	0.450E 0	3 -4	0.	999	8.	999	ΰ.	499
	6 0	0.150E 0	3 -4	0.	999	•••		v •	
	av	0.	999	υ.	999	V e	¥9¥	U.	7 99
	81					ΰ.	999	θ.	499

Table F2 (Concluded)

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	TABLE 9 S(Hurizon 10 Li	CALES FOR P FAL SCALE WCHES =100.	LUTS OF THE STATIONS	ENVELUPES OF	HAXIMUMS		
• • •	VERTICAL VARIA DEFLI MOMEN	SCALES LEN Able of A CT 2 inc AT 2 inc	GTH MAX XIS VA HES ≠ 0.400E HES ≠ 0.400E	1 MUM LUE U 0 9 8			
	PRUB (CONTD) 001 Ste	EL BENT CA	P, SIMPLY SU	PPORTED, FIXED	LOADS, NO	Envelopes or	
	TABLE 10A	INFLUENCE	DIAGRAMS FOR	DEFLECTION	_ = K		
	LOCATION Of Load	STA	DESIGNATED Sta	STATIONS FOR STA	INFLUENCE STA	DIAGRAMS Sta	
		NONE		•••••••••••••••••••••••••••••••••••••••	ta ogénit Par		
	TABLE 108	INFLUENCE I	DIAGRAMS FOR	HOMENT			
	LOCATION OF LOAD	STA	DESIGNATED Sta	STATIONS FOR STA	INFLUENCE Sta	DIAGRAMS Sta	
		NONE					
	TABLE 10C	INFLUENCE D (SHEAR IS TU THE LE	DIAGRAMS FOR Computed oni FT of the di	SHEAR E HALF INCREM ESIGNATED STA	ENT ILUN)		
	LOCATION OF LOAD	STA	DESIGNATED Sta	STATIONS FOR	INFLUENCE STA	DIAGRAMS Sta	
		NONE					
	TAULE 10D	INFLUENCE D	IAGRAMS FOR	SUPPORT REACT	FION		
	LOCATION Of Load	STA	DESIGNATED Sta	STATIONS FOR STA	INFLUENCE STA	DLAGRAMS STA	
		NONE					

(Sheet 11 of 11)



Figure F4. Variation of moment along beam

Example Problem 2

10 To illustrate further the use of program BMCOL51, a second example - a braced trench problem - is given. Figure F5 shows the physical problem for this example. The input and output data are presented in Tables F3 and F4. The results of the variation of deflection and moment along the trench support are plotted in Figures F6 and F7.



Figure F5. Physical problem for Example Problem 2 (braced trench problem)

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Table F3 : Input Data for Example Problem 2

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PROGRAM		· · ·		
REQUESTED BY	PREPARED BY	- CHECKED BY	-	
		41 42 43 48 43 48 47 48 48 30 31 32 33 34 36 80 37 39 38		71 72 73 74 73 76 77 78 79 80
	MCOL51. UMINER	<u>51.1.1. 10.675 XISAIS. 97. 1</u>	10 51.2.4	
	. EXAMPLE PLUBLEMS FOR	C. LEPORT		
• • • • • • • • • • • • • • • • • • • •			-	-
10.0.2 S.H.E.ET. P.	ILE WITH AT LEST. PLESSU	CEN FILLED LOADS W	TH. PLOTS.	
		A		
		2.670,6405		
		2.670 6.405		
· · · · · · · · · · · · · · · · · · ·			-	
· · · · · · · · · · · · · · · · · · ·	1.1.550510.3			
	4. 55.06.103	1.2.5.0.5.1.04		
	· · · · · · · · · · · · · · · · · · ·			
		· • • • • • • • • • • • • • • • • • • •		
 				1 1 1 1 1 1 1 1
				-
		· • • • • • • • • • • • • • • • • • • •		-
ить Гони Ко. 1233 Агр.Тамяти чыл				
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Table F4

Output Data for Example Problem 2

PR: CE: RE:	UGRAM 8 394.2 Port 56	HCOL 51 - HA Hohemurk Pro -1 (S) Fur (STER - MATLOCK-TAYI Delem Ou1, data Cudi Center for Highway (LOR 2D FR Rese <i>i</i>	- REVISI DR EXAMPLE ARCH. CODED	0N Proi 84	UATE ≖ Blem G F.Pari	08 M IVEN Ker	AN 08 In		
PR	UB U02	SHEET PILE (NITH AT REST PRESSU	REJF	IXED LOADS,	NŪ	ENVEL	UPES	0ĸ,		
TAI	8L L 1 -	PROGRAM-CON	FROL DATA	E / 0 /	VELOPES MAXIMUNS	2	TAB J	.E Nu 4	НЬЕК Э	6	
	HULD Num	CARUS INPUT 1	ING PROBLEM (1=HOLD) This problem)	0	0 1	U U	0 6	U U	0 13	
	OPTI	ON (IF≠1) IU	PLUT ENVELOPES OF 1	1A X [P	IUNS		DEFL 1	HUM 1	<u>9</u> 9	RCT D	
IA:	SLE 2 - NUM INCK NUMB INIT FINA NUMB	CONSIANTS INCREMENTS EMENT LENGTH ER UF INCREME IAL PUSITION L PUSITION UF EN UF INCREME	NTS FOR MOVABLE LOA UF MOVABLE LOAD STA MUVABLE LOAD STA Z NTS BETHEEN EACH PU	ID Zeh Iero Isìtì	O DN OF HUVA	BĹ€	LUAU	, 	0.120	40 E 02 0 0 1.	
TAU	1LE J -	SPECIFIED DE	FLECTIONS AND SLOPE	S							
	SIA	UASE	DEFLECTION	SL	.0PE						

NONE

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TABLE 4 - STIFFNESS AND FIXED-LOAD DATA

FRUM	TU C	ONTU	F	UF	S	T	к	Р
0	40	Ű	0.500E	10 0.	θ.	0.	0.	0.
10	10	Ű	U .	0.	0.267E 06	0.	U .	0.
20	20	0	U.	0.	0.267E 06	0.	û .	0 .
Û		1	Û.	0.	U .	0.	0.	0.
	30	1	Ű.	-0.495E U4	U.	0.	U .	0.
	40	0	U .	-0.495E 04	0.125E 05	0.	Ú•	0.

TABLE 5 - MOVABLE-LOAD DATA

FRUM TU CONTU QM

NUNE

TABLE 6 - SPECIFIED STATIONS FUR INFLUENCE DIAGRAMS (SHEAR IS CUMPUTED UNE HALF INCREMENT TO THE LEFT OF THE DESIGNATED STATION)

NUNE

(Continued)

(Sheet 1 of 7)

Table F4 (Continued)

	PRUGRAM Gej94+2 Report	0HCOL 51 - Humework 56-1 (S) F(MASIER - M Problem 001 Dr Center Fo	ATLOCK-TAYL , DATA CODE R HIGHWAY R	OR – RE D FUR EXAMI Esearch• Ci	VISION DATE * PLE PROBLEM G DDED BY F.PAR	06 MAR 68 IVEN In Ker	
	PRUB (C UO2	ONTD) Sheef P1	LE HITH AT R	EST PRESSUR	E.FIXED LO	NUS, NO ENVEL	UPES OK	
	TABLE 7	- FIXED-LO	AD RESULTS					
	STA 1 +1	DISI •0+120E 02	DEFL -0.631e u0	SLUPE	HOM 0.	SHEAN	SUP REAUT 0.	
	0	0.	-0.574E 00	0.4775.00	0.129E 00	U+1U0E-U1	0.	
	1	0.120E 02	-0.517E 00	0.4775-02	0.129E UG	U+) _0 1455 01	0.	
	2	0.240E U2	-0.460E 00	0.4765-02	-0.198E 04	-U.105E U.J	0.	
:	3	0.3606 02	+0.4U2E 00	0.4746-02	-0.792E 04	-0.0005 01	б.	
;	4	0.480E U2	+0.346£ 00	0.4746=02	-0.198E US	-04770C 00	0.	
· · ·	5	0.6008 02	-0.289E 00		-0.396E 05	-4.2475 04	0.	
jah Sterr tara a	6	0.720E 02	-0.234E 00	0.443E=02	-0.693E 05	-8.3465 84	Û.	
	7	0.840£ 02	-0.181E 00	0.4175+02	-0.111E V6	-8.4625 84	0.	
Ē	8	0.960£ 02	-0.131E 00	8.37/E+02	-0.106E 06	+0.594F 04	0.	
ļ	9	0.108E 03	-0.8556-01	U.320E+02	-0.238E 06	-U.742F 04	0.	
	10	0.120E 03	-0.471E-U1	U.241E-02	-0.327E 06	8.351E 04	0.126E V5	
1-00-00000	11	0.132E U3	+0.181£-01	U.173E-02	-0.285E 06	U.169E 04	0.	
	12	0.144E 03	0.2636-02	0.110E-02	-0.264E 06	-U.288E 03	0.	
	13	0.156E 03	0.1582-01	0.455E-03	-0.268E 06	•4.243E 04	0.	
	14	0.168E 03	0.2136-01	-0.258E-03	-0.297E 06	-U.474E 04	0.	
	15	0.180E UJ	0.1826-01	-0.111E-02	+0.354E U6	=0.722E 04	0.	
	16	0.192E 03	0.408±-02	-U.216E-02	-0.440E 06	-0.9868 04	0.	
	17	0.204E U3	-0.211E-01	+0.351E-02	-0.559E 06	-W.127E 05	0.	
	18	0.216E 03	-0.632E-U1	-0.521E-02	-0.711E 06	+0.156E 05	0.	
	19	0.226E U3	-0.126£ 00	-0.737E-02	-0.898t 06	-0.188E 05	0.	
	20	0.240E 03	-0.214E 0D	-0.101E-01	+0.112E U7	0.351E 05	0.5722 05	

(Continued)

(Sheet 2 of 7)

Table F4 (Continued)

	21	0.252E UJ	-0.3356 00		-0.702E 06		0.
				-0.117E-01		0.316E 05	
	22	0.2646 03	-0.4/6E UD		-0.323E U6		0.
				-8.125E-01		0.280E 05	
	0.1	8.976L 113	-0 4246 00		0 1416 05		A .
	40	0.270C 00	-0.020E 00		U.I.JIL U/	0 040F 65	.
				+0+1556+01		U+242E U2	
	-24	0.2886 03	-0.776E 00		0.304E 06		0.
· _	•.			-0.118E-01		0.202E 05	
	25	0.3006 03	+0.917E 00		0.5476 86		0.
				-0.1056-01	••••	0.161E 05	- •
		0 74 64 07	0 4 11 41 11 4		0 7401 84		0
	20	0.012E 00	+0*104E 01		0.479VE 00		υ.
				+0.868E+02		0.118E 05	
	27	0.324E 03	-0.115E U1		0.882E 06		0.
				-0.656E-02		0.737E 04	
	28	0.3366 03	-0.123F 81	·····	0.970£ 06	•	0.
				-0.4236-02		0.2756 04	••
				-014202-02		042775 04	•
	29	0.3482 03	-U.128E 01		0.100E U/		U •
				-0.182E-02		-0.203E 04	
	30	0.360E U3	-0.130E 01		0.9798 06		0.
				0.5278-03		-0.698E 04	_
	4.1	0.3796 43	-0 1906 #1		A 9055 64		0.1616 84
	31	0.0126 00	-0.1275 01		0.0952 00	0 107C 05	0.101E 04
				0.2005-02		-0+100C 00	
	52	0.384E 03	-0.126E Ul		0.771E 06		0.315E U4
				0.453E-02		-0.121E 05	
	53	0.396E 83	-0.121E 01		0.626E 06		0.452E U4
				0.6035-02	•••••	-0.126E 06	
		6 4095 67		VICONE "UL			0 6444 04
•	34 .	0.400E 03	-0+TISE OT	6 74 TE 80	.0.479E 00		0.0000 04
				0./1/E=02		-0+110E ND	
	ა5	0.420E 03	-0.105E 01		0.333E 06		0.654E U4
				0.7976-02		-0.102E 05	
	36	0.4321 03	-8.951F 88		0.2116 06		0.713⊢ #4
	•,•			1. HARE-02		-0.8045 04	
	4.7			0+0406-02		-040000 04	
	31	0.444E VQ	₩ 0. 820£ 00		0.114E 00		0.743E U4
				0.875E-02		-Q.557E 04	
	38	0.456E 03	-0.745E 00		0.4716 05		0.7456 04
				8.886E+02		-0.308E 04	
	.10	0.4686 03	-0.638F 00		0.1826 05		0.718- 04
			- ******* **	0 0005-04	VILUEL VY	-0 8476 04	********
		0 4000 ····	0 5 101	0+0075-02		-0104/2 40	
	49	44806 43	-0.5328 00		+0.0476+01		8.332E 84
				U.889E-02		0.539E+02	
	41	0.492E U3	-0.4256 00		0.		0.

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(Sheet 3 of 7)

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PRUB (CONTU) UO2 SHE	EE PILE WITH	AT REST PRE	SSUKE,F.	IXED LUADS,	N0 E1	WELUPES ON	
TABLE BA- ENV	ELOPES OF MA	XIHUNS .	= HELD	EROM PRIOR	PRUBL	En	
STA MAX-	+DEFL LOC	MAX -UEFL	LOC	NAX +NOM	LOC	nax -n	0M LUC
-i 0.	999	+0.631E 00	Û	U.	999	θ.	999
υ ε.	999	-0.574E 00	U	0.129E 00	U	ΰ.	999
1 0.	999	-0.517E 00	U	0.129E 00	U	8.	999
2 0.	999	-0.460E OU	Û	0.	999	-U.198E	04 8
.j U.,	999	-U.402E OU	Ú	U .	999	-0.792E	04 U
4 0.	999	+0.346E 80	U	Ű.	999	-0.198E	05 U
5 Û.	999	-U.289E OU	Ű	U.	999	-0.390E	05 0
6 U.	999	-0.234E 00	Ű	0.	999	-0.693E	05 0
7υ.	999	-0.181E 00	U	U .	999	-0.111E	0 6 U
8 O.	999	-0.131E 00	ų.	0.	999	+0.160E	0o U
У С .	999	+U.855E+01	U	υ.	999	-0.236E	06 0
10 0.	999	+U.471E-01	U	U.	999	-0.327E	06 U
11 0.	999	+0.181E+01	Û	U.	999	-0.285E	06 U
12 0.20	63E-02 U	U.	999	Ú.	999	-U.264E	00 U
13 0.1	58E-01 8	U.	999	Ú.	999	-0.268E	06 Ű
14 0.23	1JE+01 0	U .	999	0.	999	-U.297E	06 0
15 0.14	82E-01 0	U .	999	0.	999	-0.354E	ນິດ ປ
16 0.41	88E+02 U	U.	999	Û.	999	-0.440E	ปีอ ย
17 0.	999	-0.211E+01			999.	+0.55YE	06 8
. 18 0.	999	-U-632E-01		0.	499	-0.711E	96 H
19 0.	999	-U.126E 0U	Ű	Ū.	999	-U.898E	00 U
20 0.	999	-0.214E 00	Ű	Ű.	999	+0.112E	07 U
21 0.	999	-U.335E 0U	Û	U .	999	-0.702E	06 8
22 0.	999	-8.476E 08	Û	U	999	-U-323E	06 0
23 0.	999	-0.626E 00	Ű	0.1318 05	U	Ű.	¥99
24 0.	999	-0.776E 00	U	0.304E 06	ů	Ú.	999
25 0.	999	-0.917E 00	Ű	0.547E 06	ā	0.	499
20 0.	999	-0.104E 01	Ű	8.740E 06	ū	0	999
27 U.	999	-0.115E 01	Ū	0.882E 06	U	0.	¥99
28 0.	999	-0.123E 01	Ű	0.970E 06	8	0.	999
29 0.	999	-0.128E 01	U	0.100E 07	ŏ	Ū.	999
30 0.	999	+0.130E 01	U	0.979E 06	Ũ	Û.	999
31 0+	999	+0.129E 01	Ű	0.895E 06	Ű	U.	¥99
32 U.	999	+0.126E 01	8	0.771E 06	Ŭ	U.	494
33 0.	999	-0.121E 01	0	0.626E 06	U	0.	999
34 U.	999	+0.113E 01	U	0.4758 06	Û	Û.	999
35 U.	999	-0.105E 01	Û	0.J3JE 06	Ū	U .	999
36 0.	999	-0.951E 00	Ű	0.211E 06	Ŭ	Ū.	999
37 0.	999	-U.85VE 00	ť	U.114E 06	ō	4 .	999
38 8.	999	-U.745E OU	Ű	0.471E 05	- 8	Ű.	999
39 8.	499	-U.638E 00	Ű	0.102E 05	Ű	Ű.	999
40 0.	999	-U.532E OU	Û	0.	499	#U.64/F-1	01 0
41 0.	999	-U.425E 0U	<u>.</u>	Ü.	999	U.	y99

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Table F4 (Continued)

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+1	MAX +SHEA	K LUC	MAX -SHE	AK	LOC	MAX +REA(T LOC	HAX = KE	ACI LO
_	0.108E-0.	1 U	Ü.		999		,,,,	••	
U	- 0.	999	11 e		999	0.	999	Ú.	<u>9</u> 9
1	<u> </u>					U.	¥99	U.	9 9
2	U .	999	-0.165E	03	U	li .	999	0	40
	ΰ.	9 99	-0.495E	03	U	•••		••	
3	U .	999	-0.990E	93	ť	0.	999	Û.	999
4	a	000				U.	999	Ú .	999
5	v •	YYY	+0.1055	U 4	U	U.	999	0.	999
6	0.	99 9	-u.247E	04	Ü				
	U .	999	-0.346E	04	U	V.	999	۔ • لی	999
7	8.	000		1 A	0	U .	99ÿ	0.	999
\$	•••		-004026	• •	v	Ü.	999	U.	999
)	υ.	999	+0.594E	04	IJ	0.	499	A .	uūu
	Ű •	999	-0.742E	04	Ų.				
	U.351E 04	Û	Ü.		999	0.120E U	5 0	ΰ.	99 9
	0.169F 04	0	4.		000	0.	¥99	U .	¥99
2			•••			υ.	999	U.	99 9
5	U.	999	-0.288E	03	Ű	Ű.	000	11 -	
	0.	999	-0.243E (04	U			••	
•	0.	999	+0.474E (04	U	Ű.	999	Ű.	y9 9
5	0	000	-H.799E (1 4	0	ð.	99 9	Ű.	999
•					U	0.	999	U .	499
,	U.	999	-U.Y86E (94	U	4 1 -	00u	a .	
	U.	999	-0.127E 0	15	Ð	••		••	,,,,
,	0.	999	-U.156E 0	15	IJ	Ð.+	999	ΰ.	¥99
•	A	000	-0 1005 0			θ.	99 9	U.	99 9
9	••	,,,	-n•Toof A	2	U	0.572E 05	D U	0.	y 99
	0.351E 05	Ű	U.	5	/99		-		

Table F4 (Continued)

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(Sheet 5 of 7)

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21	0.316F 05	O	i) .	999	ü.	999	0.	y99
22	8.280F 05	• 0	A.	999	. ♥•	999	0.	999
23	0 3495 04	0		000	Ű.	999	Ŭ.	¥99
24" '	0.2420 02	U	U •		U.	999	υ.	¥99
25	0.202E 09	U	U e	9 99	0.	999	Ű.	¥99
26	U +161E 05	U	V.	999	0.	ŶŶŶ	Ű.	99 9
27	0.118E 05	U	U.	999	0.	490	Ű.,	600
	0.737E 04	Ü	Ú •	999	4	400	0	
	0.275E 04	0	U.	999	•		•	,,,,
27	0.	999	-0.203E 04	4 0	U.	y y y	U .	***
50	Ű.	999	-0.698E 04	u u	U.	999	ु है। है '	· 999
11	0.	999	-0.103E 05	• 8	0.161E	04 0	Û.	999
2	Ű.	999	-8.1216 05	j ()	0.315E	04 0	0.	99 9
13	A.	404	-0.1258 05	5 (1	0.452E	Q4 U	0.	999
54	0.	000	-0 1145 05	. 4	0.566E	04 0	0.	999
55	•				U.654E	04 0	0.	¥99
56	U .	yyy	#U.102E US	y u	0.713E	04 0	6.	999
57	U.	999	-0.800E 04		0.743E	04 0	0.	999
38	0	999	-0.557E 04	l U	0.745E	04 0	Ű.	999
59	0.	999	-0.308E 04	i U	0.718E	04 0	٥.	999
(n	0.	999	-0.847E U3	0	ú. 3396	RA a	A .	400
1	0.539E-02	0	U.	999	4 • • • • 4 E	900 000	••	777
					¥ .	***	V e	***

Table F4 (Continued)

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Table F4 (Concluded)

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TABLE Y -- SCALES FOR PLOTS OF THE ENVELOPES OF MAXIMUMS HURIZUNTAL SCALE 10 INCHES = 50. STATIONS VERTICAL SCALES LENGIH MAXIMUM VANIABLE OF AXIS VALUE 2 INCHES = 0.200E 01 DELFCI 2 INCHES = 0.200E 07 MOHENT PRUB (CONTD) 002 SHEET PILE WITH AT REST PRESSURE, FIXED LOADS, NO ENVELOPES OK TABLE 10A -- INFLUENCE DIAGRAMS FOR DEFLECTION LOCATION DESIGNATED STATIONS FOR INFLUENCE DIAGRAMS OF LOAD STA SIA S1A - SIA STA NUNE TABLE 108 -- INFLUENCE DIAGRAMS FOR MOMENT LOCATION DESIGNATED STATIONS FOR INFLUENCE DIAGRAMS STA OF LOAD SFA STA SIA SIA NUNE TABLE 10C -- INFLUENCE DIAGRAMS FOR SHEAR C SHEAR IS COMPUTED ONE HALF INCREMENT TO THE LEFT OF THE DESIGNATED STATION) LOCATION DESIGNATED STATIONS FOR INFLUENCE DIAGRAMS OF LOAD STA STA STA SIA SIA NUNE TABLE 10D -- INFLUENCE DIAGRAMS FOR SUPPORT REACTION LOCATION DESIGNATED STATIONS FOR INFLUENCE DIAGRAMS OF LUAD STA STA STA SIA SIA NUNE PRUGRAM UMCOL 51 - MASIER - MATLOCK-TAYLOR - REVISION DATE = 08 MAR 08 CE394+2 Humehurk Problem 001, data cuded for example problem given in REPORT 56-1 (S) FUR CENTER FOR HIGHWAY RESEARCH. COUED BY F.PARKER REIURN THIS PAGE TO TIME RECORD FILE -- HM

(Sheet 7 of 7)



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Figure F7. Variation of moment along trench support

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