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Theoretical Manual for Pile Foundations

Reed L. Mosher and William P. Dawkins

November 2000

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Theoretical Manual for Pile Foundations

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Preface

This theoretical manual for pile foundations describes the background and research and the applied methodologies used in the analysis of pile foundations. This research was developed through the U.S. Army Engineer Research and Development Center (ERDC) by the Computer-Aided Structural Engineering (CASE) Project. The main body of the report was written by Dr. Reed L. Mosher, Chief, Geosciences and Structures Division, Geotechnical and Structures Laboratory, ERDC (formerly with the Information Technology Laboratory (ITL)), and Dr. William P. Dawkins, Oklahoma State University. Additional sections were written by Mr. Robert C. Patev, formerly of the Computer-Aided Engineering Division (CAED), ITL, ERDC, and Messrs. Edward Demsky and Thomas Ruf, U.S. Army Engineer District, St. Louis.

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At the time of publication of this report, Director of ERDC was Dr. James R. Houston. Commander was COL James S. Weller, EN.

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Conversion Factors, Non-SI to SI Units of Measurement

Non-SI units of measurement used in this report can be converted to SI units as follows:

Multiply	By	To Obtain
degrees (angle)	0.01745329	radians
feet	0.3048	meters
inches	0.0254	meters
pounds (force)	4.448222	newtons
pounds (mass) per cubic inch	27,679.9	kilograms per cubic centimeter
pounds (mass) per square foot	4.882428	kilograms per square meter
pounds (force) per square inch	0.006894757	megapascals
tons (force) per cubic foot	32036.9	kilograms per cubic meter
tons (force) per square foot	95.76052	kilopascals

1 Introduction

Purpose

The purpose of this manual is to provide a detailed discussion of techniques used for the design/analysis of pile foundations. Several of the procedures have been implemented in the CASE Committee computer programs CAXPILE (Dawkins 1984, Mosher et al. 1997), CPGA (Hartman, Jaeger, Jobst, and Martin 1989) and COM624 (Reese 1980). Theoretical development of these engineering procedures and discussions of the limitations of each method are presented.

Pile Behavior

The purpose of a pile foundation is to transmit the loads of a superstructure to the underlying soil while preventing excessive structural deformations. The capacity of the pile foundation is dependent on the material and geometry of each individual pile, the pile spacing (pile group effect), the strength and type of the surrounding soil, the method of pile installation, and the direction of applied loading (axial tension or compression, lateral shear and moment, or combinations). Except in unusual conditions, the effects of axial and lateral loads may be treated independently.

Axial Behavior

A compressive load applied to the head (top) of the pile is transferred to the surrounding soil by a combination of skin friction along the embedded length and end bearing at the tip (bottom) of the pile. For relatively short piles, only the end bearing effect is significant. For relatively long piles in soil (excluding tip bearing piles on rock), the predominant load transfer is due to skin friction. Unless special mechanical provisions are present (e.g., an underreamed tip), axial tension load is resisted only by skin friction.

Lateral Behavior

Piles are often required to support loads applied perpendicular to their longitudinal axes (lateral loads). As stated previously, lateral load resistance is largely independent of axial effects. However, a high axial compression may interact with lateral displacements (the beam-column effect) to increase lateral displacements, bending moments, and shears.

Battered Piles

If the horizontal loads imparted to the pile foundation are large, a foundation consisting solely of vertical piles may not possess sufficient lateral resistance. In such circumstances, battered (inclined) piles are installed to permit the horizontal foundation load to be supported by a component of the axial pile/soil resistance in addition to the lateral resistance.

Classical Analysis and/or Design Procedures

Single piles

Prior to the development of reliable computer programs, the design of a single pile was based primarily on the ultimate load capacity of the pile as determined from a load test or from semi-empirical equations. The allowable or working load to which the pile could be subjected was taken as some fraction of the ultimate. Little, if any, emphasis was placed on the load-displacement behavior of the pile. Design methodology used in the Corps of Engineers is documented in Engineer Manual 1110-2-2906 (U.S. Army Corps of Engineers (USACE) 1995).

Pile groups

Classical methods (e.g., Culmann's method, the Common Analytical Method, the Elastic Center Method, the Moment-of-Inertia Method, etc.) of analysis for pile groups were based on numerous simplifying assumptions to allow the numerical calculations to be performed by hand. Common to these methods are the assumptions that only the axial resistance of the piles is significant and that the pile cap is rigid. Force and moment equilibrium equations are used to allot the foundation loads to the individual piles. No attempt is made in these methods to consider force-displacement compatibility (the soil-structure interaction effect). It has been shown that these classical methods frequently result in unconservative designs.

State-of-the-Corps-Art Methods for Hydraulic Structures

System modelling

Rational designs must be based on solutions in which equilibrium and force-displacement compatibility are simultaneously satisfied. Ongoing research has resulted in the development of mathematical models for the pile/soil system which permit analysis of the entire range of load-displacement response for single piles subjected to axial and/or lateral loads. Methods have been developed for the design of pile groups in which the soil-structure interaction characteristics of single piles have been incorporated. These methods and the considerations leading to their development are described in detail in Chapters 2-4. A synopsis is provided in the following paragraphs.

Axially loaded piles

For analysis of a pile subjected to axial loads, the soil surrounding the embedded length of the pile is modelled as a distribution of springs which resist longitudinal displacements of the pile. The resistance of the soil springs is representative of the skin friction of the soil on the pile. The effect of tip resistance is represented by a concentrated spring. The characteristics of these springs are provided in the form of resistance-displacement (load-transfer) curves representing the skin friction effects (Seed and Reese (1957), and other references) and a force-displacement curve representing the tip reaction.

The load-transfer curves and tip reaction curves have been obtained from field tests of instrumented piles subjected to axial compression. Research is continuing to permit evaluation of load-transfer curves for piles in tension. The underlying principles on which the load-transfer curves and tip reaction curve are based and the modelling of the pile/soil system are presented in Chapter 2.

Laterally loaded piles

The soil which resists displacements of a laterally loaded pile is also replaced by distributed springs. The force-displacement characteristics of the springs are presented as curves which have been extracted from field tests of laterally loaded piles. Techniques for lateral load analysis are discussed in Chapter 3.

Pile head stiffnesses

Computer programs (e.g. CAXPILE, CPGS, COM624G) are available which permit the analysis of load-displacement response of a pile/soil system up to an ultimate or failure condition. The relationship between load and displacement

tends to be essentially linear through the range of loads usually allowed (the working loads) in design. The relationship becomes highly nonlinear as an ultimate condition is neared. For design purposes, the linearly elastic relationship between head loads and head displacements is usually presented as a matrix of stiffness coefficients. These coefficients may be extracted from the full range analyses for axially or laterally loaded piles cited above. In addition, the stiffness coefficients may be estimated using linearized solutions. These processes are discussed in Chapters 2 and 3.

Pile groups

Pile group behavior is analyzed by the procedure suggested by Saul (1968). The method considers both equilibrium and force-displacement compatibility in distributing the loads on the foundation among the individual piles. The process requires an evaluation of the linearized pile head stiffness matrix for each pile in the group. The pile head stiffness matrix may be evaluated by the single pile analysis procedures alluded to above. However, the evaluation must account for the effects of the proximity of adjacent piles.

Although the group analysis method was originally developed for linear systems with rigid pile caps, it has been extended to allow for flexible caps and, by iterative solutions, can account for nonlinear behavior (e.g. CPGA). The method is described in detail in Chapter 4.

2 Single Axially Loaded Pile Analysis

Introduction

A schematic of an axially loaded pile is shown in Figure 1. In the discussions which follow, the pile is assumed to be in contact with the surrounding soil over its entire length. Consequently, the embedded length and the total length of the pile are the same. The effect of a free-standing portion of the pile will be discussed later.

The pile is assumed to have a straight centroidal axis (the z -axis, positive downward) and is subjected to a centric load at the head (top of the pile) P_o . Displacements parallel to the axis of the pile are denoted w and are positive in the positive z -direction. The pile material is assumed to be linearly elastic for all levels of applied loads. “Ultimate” conditions referred to subsequently indicate that a limit has been reached in which any additional head load would cause excessive displacements.

The major research efforts devoted toward investigation of axially loaded piles have been performed for homogeneous soil media. Only in limited cases has the effect of nonhomogeneity been considered. In most cases the effects of layering in the soil profile and/or lateral variations in soil characteristics can only be approximated.

Load-Transfer Mechanism

The head load P_o is transferred to the surrounding soil by shear stresses (skin friction) along the lateral pile/soil interface and by end-bearing at the pile tip (bottom of the pile). The rate at which the head load is transferred to the soil along the pile and the overall deformation of the system are dependent on numerous factors. Among these are: (a) the cross section geometry, material, length, and, to a lesser extent, the surface roughness of the pile; (b) the type of soil (sand or clay) and its stress-strain characteristics; (c) the presence or absence

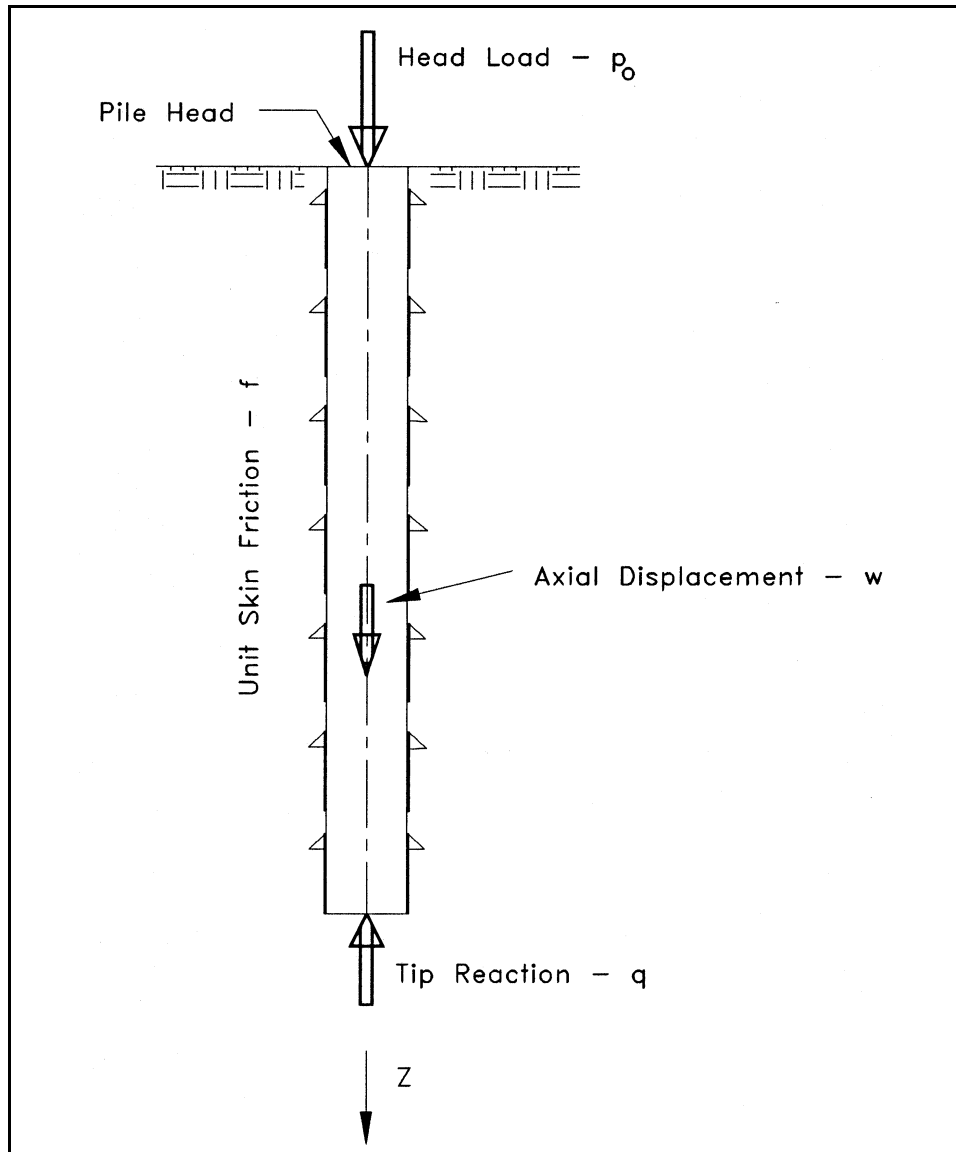


Figure 1. Axially loaded pile

of groundwater; (d) the method of installation of the pile; and, (e) the presence or absence of residual stresses as a result of installation.

A heuristic approach has been followed to reduce the complex three-dimensional problem to a quasi one-dimensional model (illustrated in Figure 2) which is practicable for use in a design environment. In the one-dimensional model, the soil surrounding the pile is replaced by a distribution of springs along the length of the pile and by a concentrated spring at the pile tip which resist axial displacements of the pile. The characteristics of these springs are presented in the form of curves which provide the magnitude of unit skin friction (f - w curves) or unit tip reaction (q - w curve) as a function of pile displacement. The nomenclature used to define axial curves is based on unit skin friction f , unit tip reaction q , and w = displacement in the z -direction for axial loads.

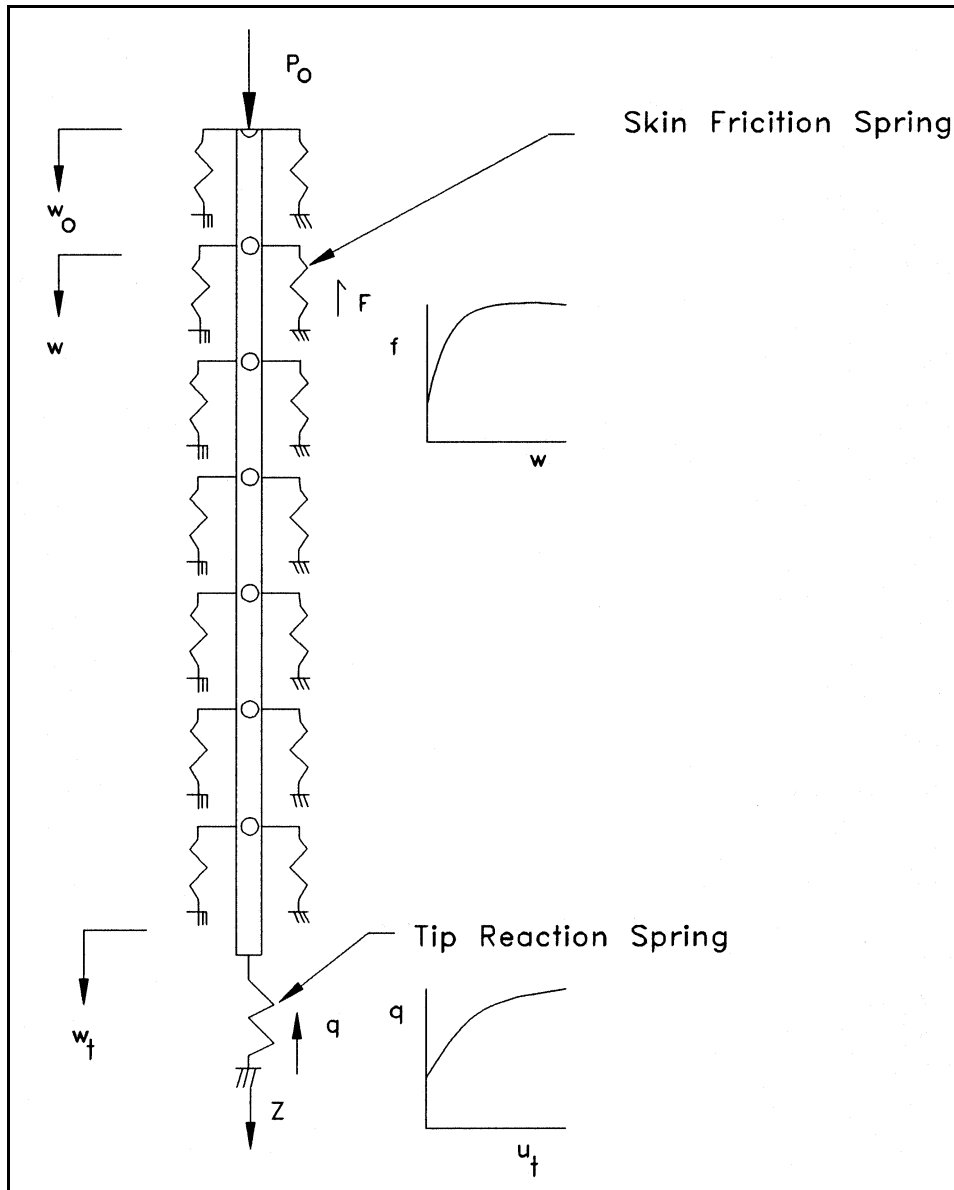


Figure 2. One-dimensional model of axially loaded pile

The $f-w$ and $q-w$ curves have been developed using the principles of continuum and soil mechanics and/or from correlations with the results of field tests on instrumented axially loaded piles. Several different criteria are presented below for development of $f-w$ and $q-w$ curves. The reliability of any method in predicting the behavior of a particular pile depends on the similarity of the system under investigation with the database used to establish the method. Most of the methods account explicitly or implicitly for the three factors cited on page 5 (a, b, and c). In all cases the pile is assumed to be driven into the soil or to be a cast-in-place pier. Only one of the procedures attempts to account for the effects of residual stresses; the remaining methods exclude these effects.

Synthesis of f - w Curves for Piles in Sand Under Compressive Loading

Mosher (1984)

Mosher (1984) utilized the results of load tests of prismatic pipe piles driven in sand and the work of Coyle and Castello (1981) to arrive at the hyperbolic representation of the f - w curve (see Figure 3).

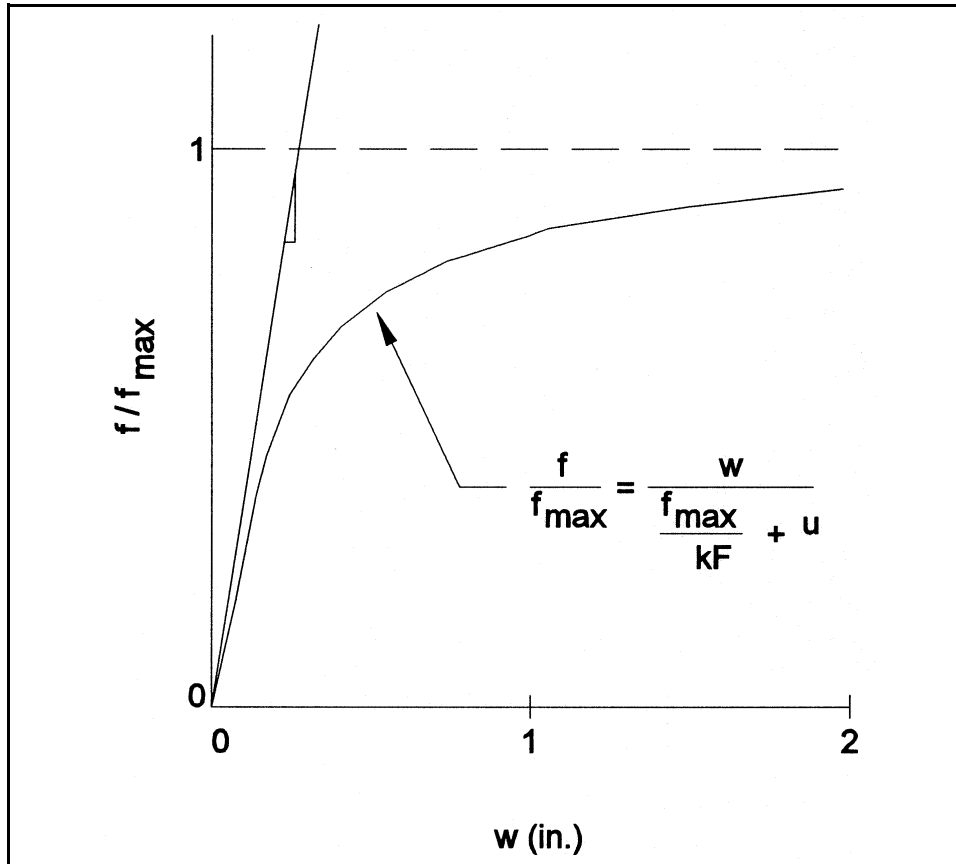


Figure 3. f - w curve by Method SSF1

$$f = \frac{w}{\frac{1}{k_f} + \frac{w}{f_{max}}} \quad (1)$$

The initial slope k_f of the curve is given in Table 1 as a function of the angle of internal friction and the ultimate side friction f_{max} is given in Figure 4 as a function of relative depth (depth z below ground surface divided by the diameter of the pile $2R$).

Table 1 k_r (psf/in.) as Function of Angle of Internal Friction of Sand for Method SSF1	
Angle of Internal Friction (degrees) ¹	k_r (psf/in.)
28 - 31	6,000 - 10,000
32 - 34	10,000 - 14,000
35 - 38	14,000 - 18,000

¹ A table of factors for converting non-SI units of measurement to SI (metric) units is presented on page x.

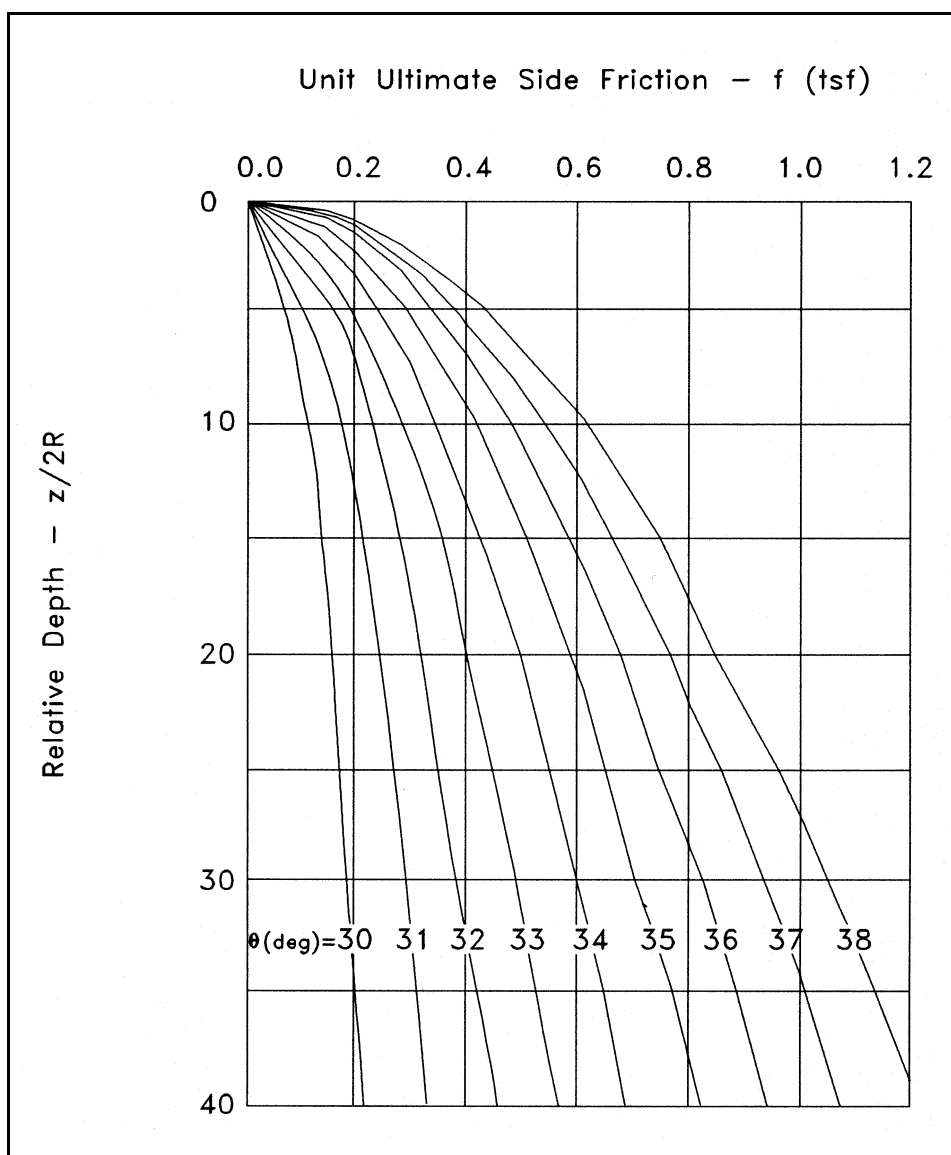


Figure 4. Ultimate side friction for Method SSF1

The effects of groundwater, layering, and variable pile diameter may be accounted for approximately by adjusting the relative depth at each point as follows. The effective depth z' below ground surface is obtained by dividing the effective vertical soil pressure at a point by the effective unit weight at that point; the relative depth is obtained by dividing the effective depth by the pile diameter at that point. This approximation will result in unrealistic discontinuities in the distribution of $f-w$ curves at soil layer boundaries, at the location of a subsurface groundwater level, and at changes in pile diameter.

The method may also be extended to approximate the behavior of noncircular cross sections using the equivalent radius of the pile as indicated in Figure 5.

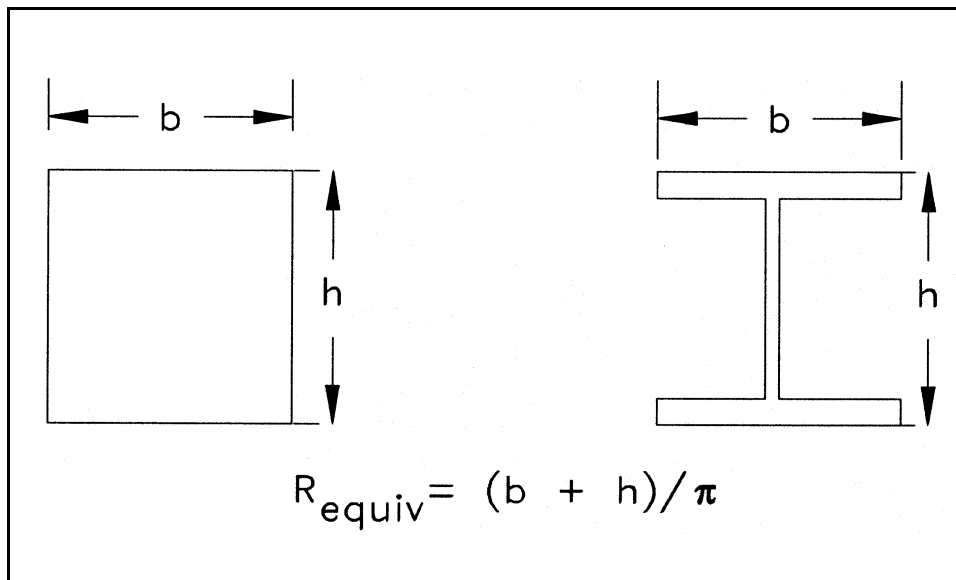


Figure 5. Equivalent radius for noncircular cross sections

Kraft, Ray, and Kagawa (1981)

Numerous analyses (Randolph and Wroth 1978; Vesic 1977; Kraft, Ray, and Kagawa 1981; Poulos and Davis 1980) have been performed in which the pile/soil system is assumed to be radially symmetric and the soil is assumed to be a vertically and radially homogeneous, elastic medium. The principles of continuum mechanics as well as finite element methods have been used to arrive at the relationship between side friction and axial pile displacement. The process due to Kraft, Ray, and Kagawa (1981) is outlined below.

Shear stresses are assumed to decay radially in the soil according to

$$\tau = fR/r \tag{2}$$

where

τ = shear stress in the soil

f = side friction at pile/soil interface

R = pile radius

r = radial distance from the pile centerline

If radial deformations of the soil are ignored, the shear strain at any point in the soil may be expressed as

$$\gamma = \frac{dw}{dr} = \frac{\tau}{G} = \frac{fR}{Gr} \quad (3)$$

where G is the soil shear modulus of elasticity.

The axial displacement at the interface is obtained by integrating Equation 3 to obtain

$$w = \frac{fR}{G} \int_R^{r_m} \frac{dr}{r} = \frac{fR}{G} \ln \left(\frac{r_m}{R} \right) \quad (4)$$

where

w = axial displacement of the pile

r_m = a limiting radial distance beyond which deformations of the soil mass are negligible

Randolph and Wroth suggested

$$r_m = 2L\rho(1 - \nu) \quad (5)$$

where

L = embedded length of the pile

ρ = a factor to account for vertical nonhomogeneity of the soil medium to be discussed later

ν = Poisson's ratio for the soil

Combination of Equations 4 and 5 yields a linear relationship between pile displacements and side friction as

$$w = \frac{fR}{G} \ln \left[\frac{2L\rho(1 - \nu)}{R} \right] \quad (6)$$

The side friction-displacement relationship expressed in Equation 6 is appropriate only for very small displacements. To account for deviations from linearity, a hyperbolic variation in side friction-displacements proposed by Kraft, Ray, and Kagawa (1981) is

$$w = \frac{fR}{G} \ln \left[\frac{\frac{2L\rho(1 - \nu)}{R} - \frac{fR_f}{f_{max}}}{1 - \frac{fR_f}{f_{max}}} \right] \quad (7)$$

where R_f is a curve fitting parameter (Kraft, Ray, and Kagawa 1981) which may be taken as 0.9 for most conditions. The value of f_{max} may be obtained from the curves due to Mosher (Figure 4) or may be estimated as suggested under method SSF3 which follows.

After f_{max} has been reached, the f - w curve becomes a horizontal line at f_{max} . The f - w curve produced by this method is illustrated in Figure 6 by the solid curve 0 - 1 - 2 .

Some soils exhibit a degradation in strength after a maximum resistance has been reached. The results of a direct shear test for a softening soil illustrated in Figure 7 are used to construct the descending branch of the f - w curve for softening soils shown by the dashed line in Figure 6 as follows. The displacement beyond the maximum f_{max} required to reduce the side friction to its residual value is obtained by adjusting the direct shear displacement to account for elastic rebound of the pile due to the reduction in side friction. This adjustment is given by

$$w = \frac{f_{max}R}{G} \left\{ \ln \left[\frac{\frac{2L\rho(1 - \nu)}{R} - R_f}{1 - R_f} \right] - \ln \left[\frac{\frac{2L\rho(1 - \nu)}{R} - \frac{f_{resid}R_f}{f_{max}}}{1 - \frac{f_{resid}R_f}{f_{max}}} \right] \right\} \quad (8)$$

The softening portion of the f - w curve is obtained by scaling the normalized direct shear curve to the f - w curve (dashed line 1-3 in Figure 6).

Because the shear strength of sands increases with depth (i.e. confining pressure), the shear modulus G is not constant along the length of the pile. Finite element analyses have indicated, for a linear increase in G with depth, the value of ρ to be

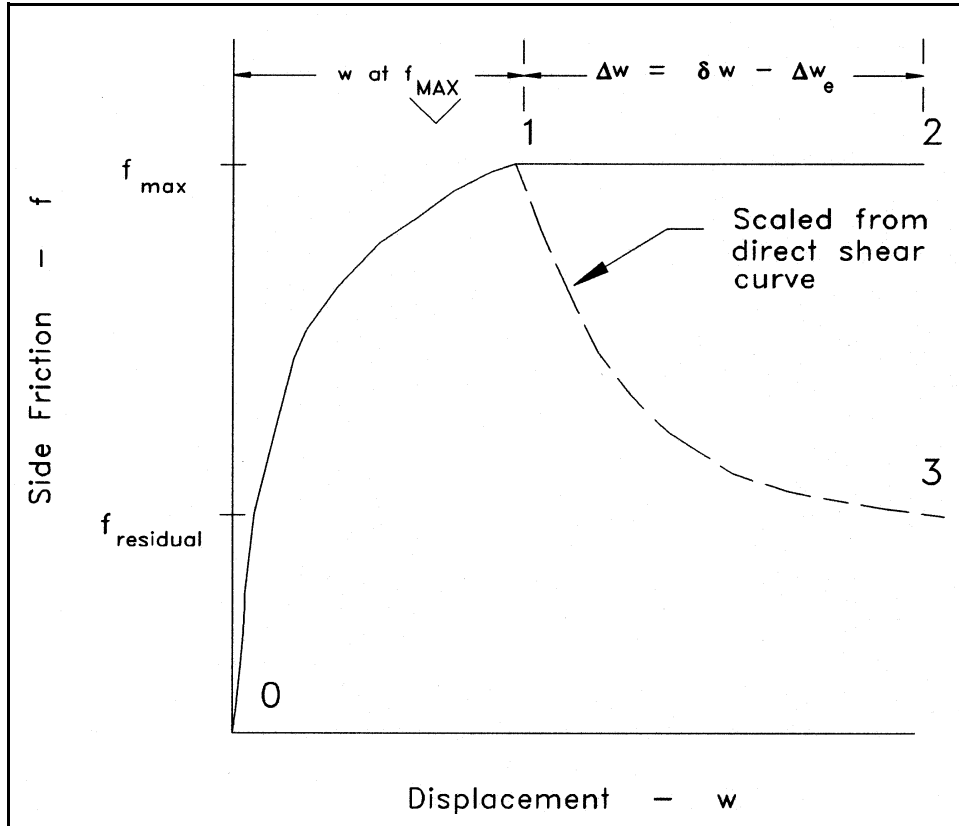


Figure 6. f - w curve by Method SSF2

$$\rho = \frac{G_m}{G_t} \tag{9}$$

where

G_m = soil shear modulus at mid-depth of the pile

G_t = shear modulus at the pile tip

The preceding equations also assume that the soil modulus G is unaffected by the pile installation. Randolph and Wroth (1978) performed finite element analyses for two hypothetical variations of shear modulus radially away from the pile. These variations and the effective shear modulus were:

a. $G = G_\infty/4$ for $1 \leq r/R \leq 1.25$; $G = G_\infty$ for $r/R > 1.25$ which produced

$$G_{eff} = \frac{G_\infty}{3 \ln 1.25 + \ln \left[\frac{2 L \rho (1 - \nu)}{R} \right]} \tag{10}$$

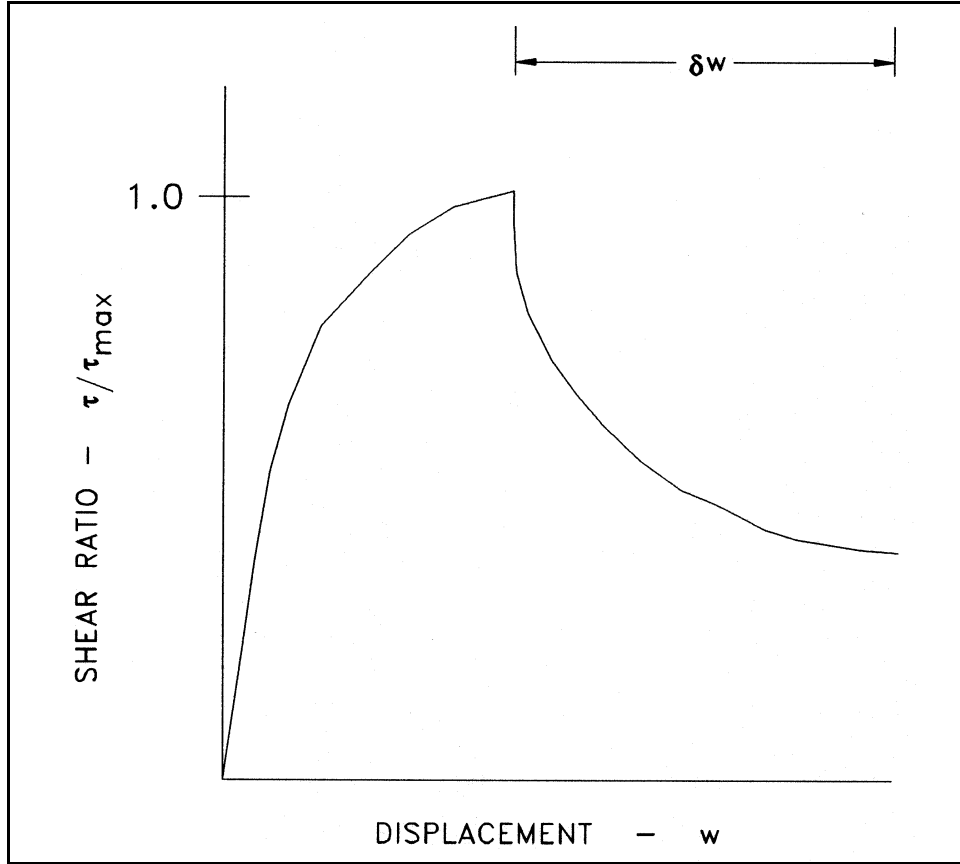


Figure 7. Direct shear test of softening soil

- b. $G = G_{\infty}/4$ for $1 \leq r/R \leq 1.25$; $G = G_{\infty}$ for $r/R > 2$; G varied linearly between $1.25 \leq r/R \leq 2$ which produced

$$G_{eff} = \frac{G_{\infty}}{5 \ln 1.25 + \ln \left[\frac{2L\rho(1 - \nu)}{R} \right]} \quad (11)$$

where

G_{eff} = reduced effective shear modulus

G_{∞} = shear modulus of the undisturbed soil

The shear modulus G in the preceding equations should be evaluated at a low strain value such as in the range of values obtained from seismic velocity tests conducted in situ or from resonant column tests. As an alternative, the following expression may be used

$$G = 83\kappa \sqrt{\sigma'_o} \quad (12)$$

where

κ = a function of relative density, varying from 50 at a relative density of 60 percent to 70 at a relative density of 90 percent

σ'_o = mean effective stress in the soil (vertical stress plus two times horizontal stress); with G and σ'_o in psi

Vijayvergiya (1977)

Vijayvergiya (1977) proposed a relationship between side friction and pile displacement of the form

$$\frac{f}{f_{max}} = 2 \sqrt{\frac{w}{w_c} - \frac{w}{w_c}} \quad (13)$$

where w_c is the displacement required to develop f_{max} . For w greater than w_c , f remains constant at f_{max} . Vijayvergiya gives limiting values of f_{max} as 1 tsf for clean medium dense sand, 0.85 tsf for silty sand, 0.7 tsf for sandy silt, and 0.5 tsf for silts. The suggested values of w_c range from 0.2 to 0.3 in. for nominal sized piles. A typical f - w curve by this method is shown as the solid curve in Figure 8.

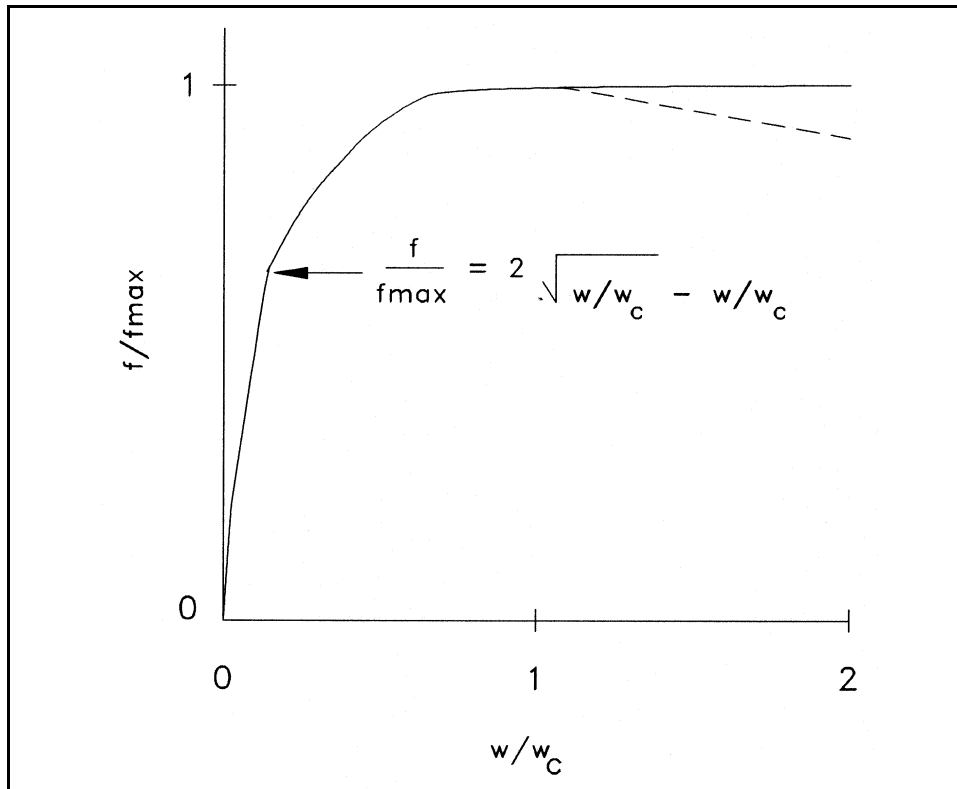


Figure 8. f - w curve by Method SSF3

Coyle and Sulaiman (1967)

Coyle and Sulaiman (1967) performed tests on miniature piles in sand and correlated the laboratory results with data from field tests of instrumented piles in sand. They concluded that skin friction increases with pile deflection up to pile displacements of 0.1 to 0.2 in. They further concluded that the ratio of skin friction to soil shear strength is high (greater than one) near the ground surface and decreases to a limiting value of 0.5 with increasing depth. Two curves, as shown in Figure 9, were proposed for the analysis of axially loaded piles in sand. Curve A was proposed for use at depths less than 20 ft below the surface and Curve B for depths greater than 20 ft.

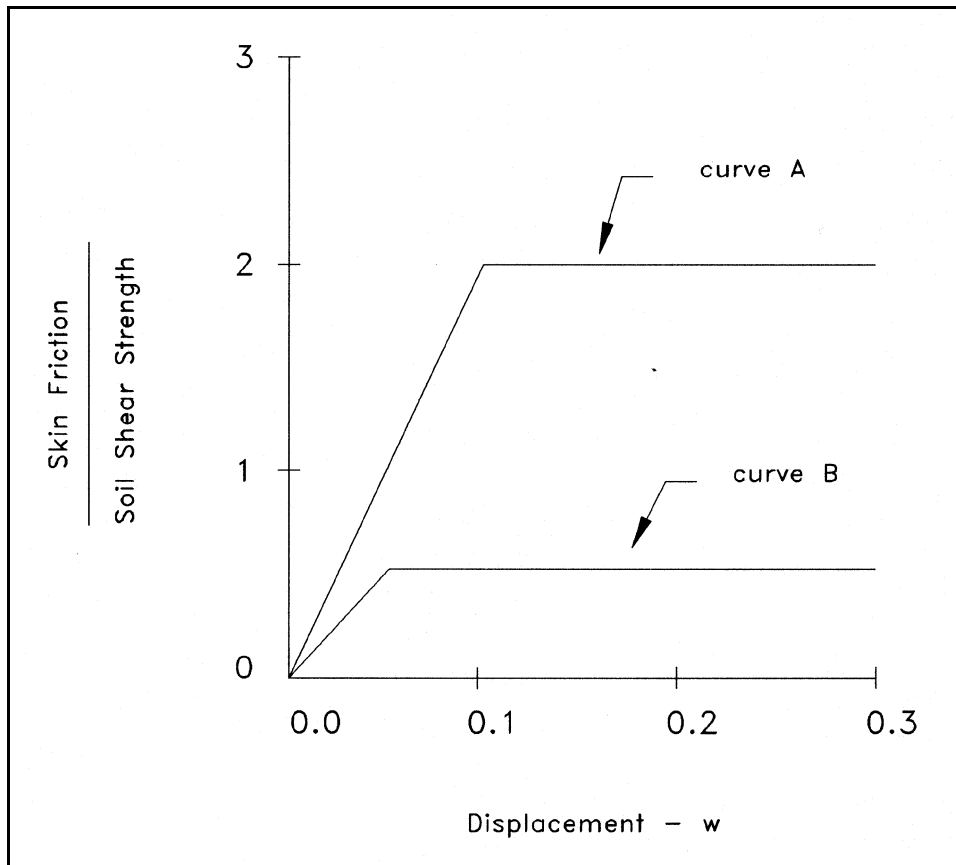


Figure 9. $f-w$ curves by Method SSF4

Briaud and Tucker (1984)

Analyses using the $f-w$ curves discussed above do not consider the presence of residual stresses in the pile/soil system which result from the installation process. Field tests of instrumented piles indicate that significant residual stresses may be encountered in long, flexible piles driven in sand or gravel (see, for instance, Mosher (1984)). If the $f-w$ curves and tip reaction representation (see later) are both based on ignoring residual stresses, the predicted pile head

displacement at any load will be essentially unaffected. However, the distribution of axial load and the predicted tip reaction may be in error. Briaud and Tucker (1984) extracted the residual stresses from field tests of piles in sand. A hyperbolic representation of the f - w curve (Figure 10) was proposed for inclusion of the effects of residual stresses as

$$f = \frac{W}{\frac{1}{k_f} + \frac{w}{f_{max} - f_r}} - f_v \quad (14)$$

with

$$k_f = 5.01(N_s)^{0.27} \quad (15)$$

$$f_{max} = 0.224(N_s)^{0.29} \quad (16)$$

$$\Omega = k_f \frac{C}{AE} \quad (17)$$

$$f_r = 5.57L\Omega \frac{A_t}{A_s} < f_{max} \quad (18)$$

where

N_s = number of blows per foot in a standard penetration test

$C = 2\pi R$ = pile circumference

A = pile cross section area

E = pile modulus of elasticity

L = length of pile

A_t = tip reaction area

$A_s = CL$ = area of pile-soil interface; with k_f in tsf/in.; and f_{max} and f_r in tsf

Synthesis of f - w Curves for Piles in Clay Under Compressive Loading

Coyle and Reese (1966)

The results of load tests of instrumented piles in clay as well as the results of laboratory tests of model pile/soil systems were used by Coyle and Reese (1966)

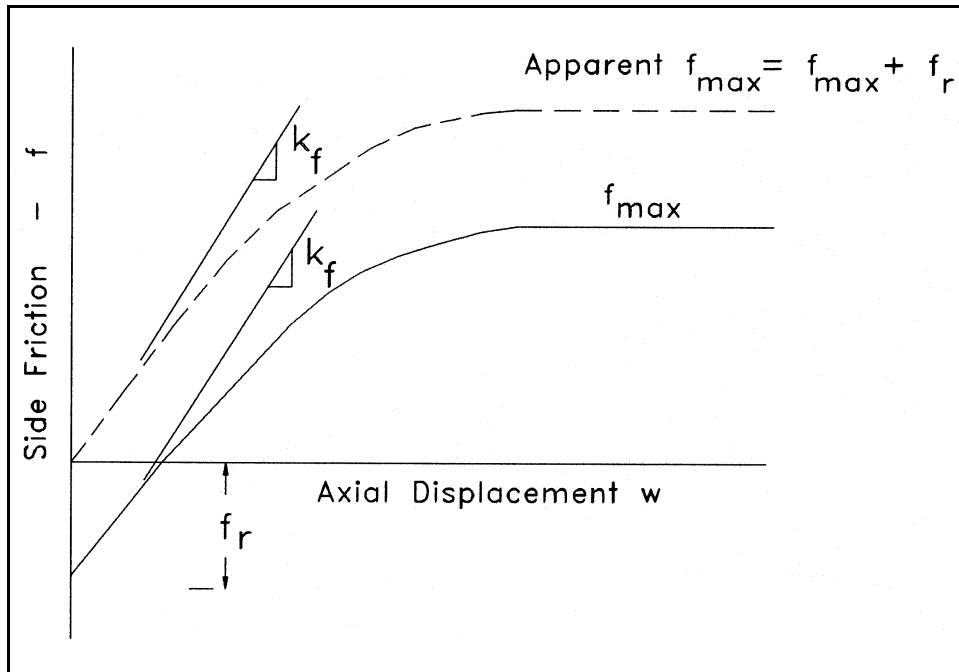


Figure 10. f - w curve by Method SSF5

to establish the three load transfer curves shown in Figure 11. Curve A is applicable for points along the pile from the ground surface to a depth of 10 ft, curve B applies for depths from 10 ft to 20 ft, and curve C is applicable for all depths below 20 ft.

The relationship between maximum side friction and soil shear strength provided by Coyle and Reese is shown in Figure 12.

Aschenbrener and Olson (1984)

Data obtained from a large number of field load tests of piles in clay were examined by Aschenbrener and Olson (1984) with the intent to devise load transfer relationships which provided the best fit to the diverse pile and soil properties represented by the database. The simple bilinear relationship shown in Figure 13 was selected as a result of their study.

Aschenbrener and Olson expressed the relationship between f_{max} and soil shear strength as

$$f_{max} = \alpha s_u \quad (19)$$

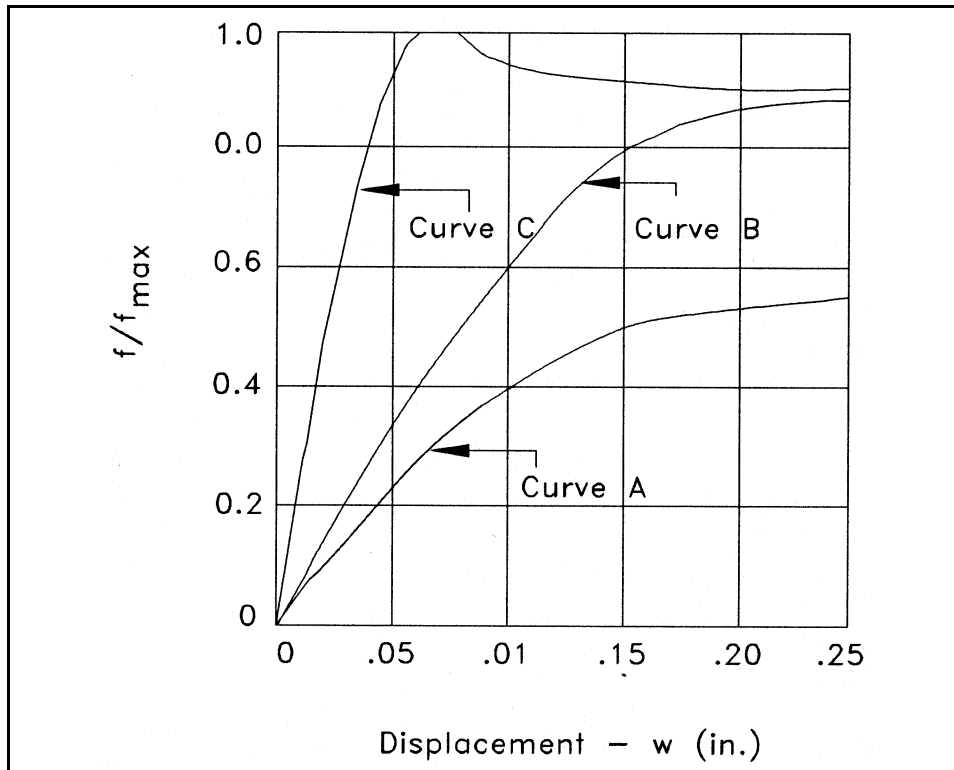


Figure 11. f - w curves by Method CSF1

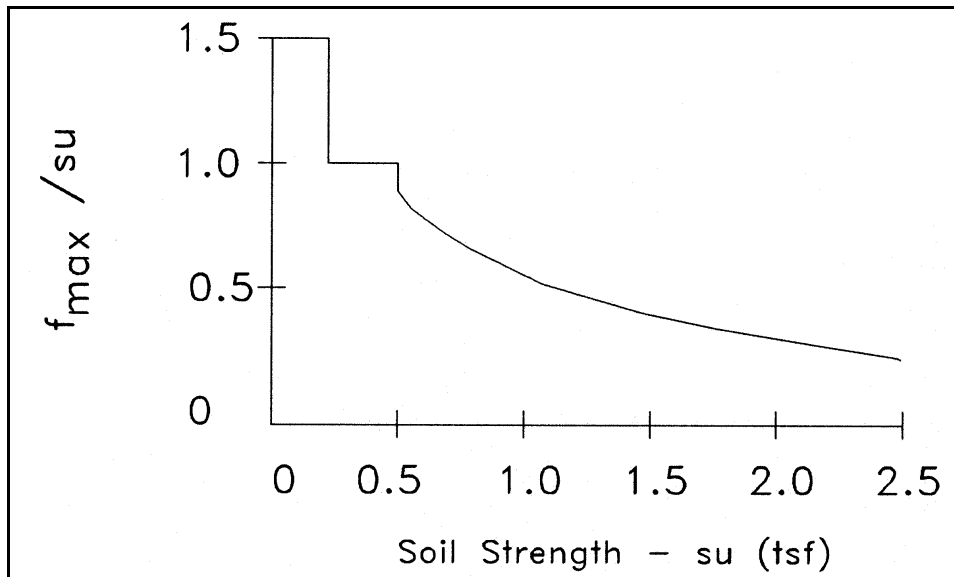


Figure 12. Side friction - soil strength relation for Method CSF1

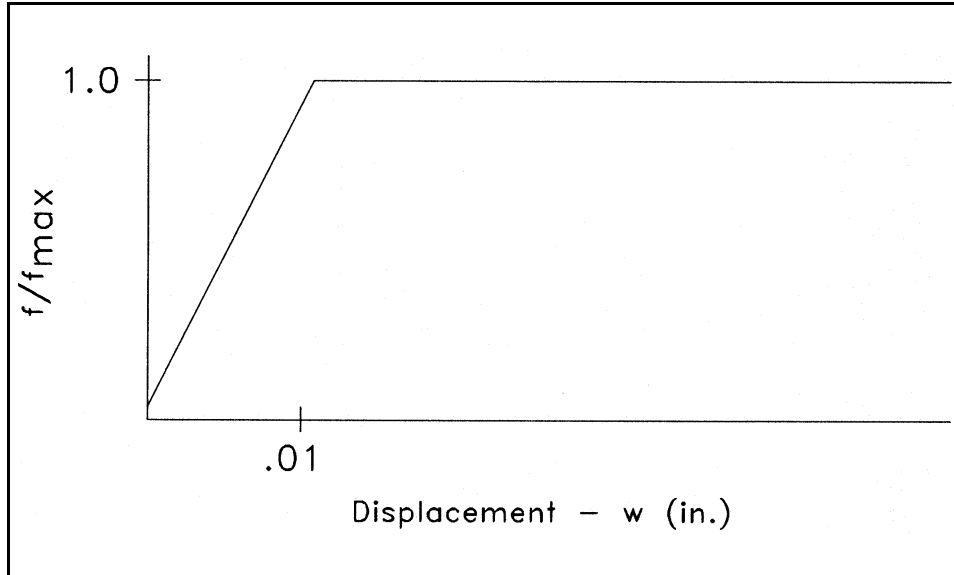


Figure 13. f - w curve by Method CSF2

where

α = a proportionality factor

s_u = undrained shear strength

Aschenbrenner and Olson were able to evaluate α from the field test data as

$$\alpha = \frac{(P_{ou} - P_{tu})}{s_u A_s} \quad (20)$$

where

P_{ou} = pile head load at failure

P_{tu} = tip load at failure

s_u = undrained shear strength

A_s = area of pile-soil interface

In a design situation, the ultimate head and tip loads will not be known. For design, the value of α may be obtained from the curves provided by Semple and Rigden (1984) shown in Figure 14 as

$$\alpha = a_p a_l \quad (21)$$

where

a_p = peak strength reduction factor from Figure 14a

a_l = length factor from Figure 14b

In Figure 14, s_u is the undrained shear strength; σ_v is the effective overburden pressure; L is the length of pile; and, R is the pile radius.

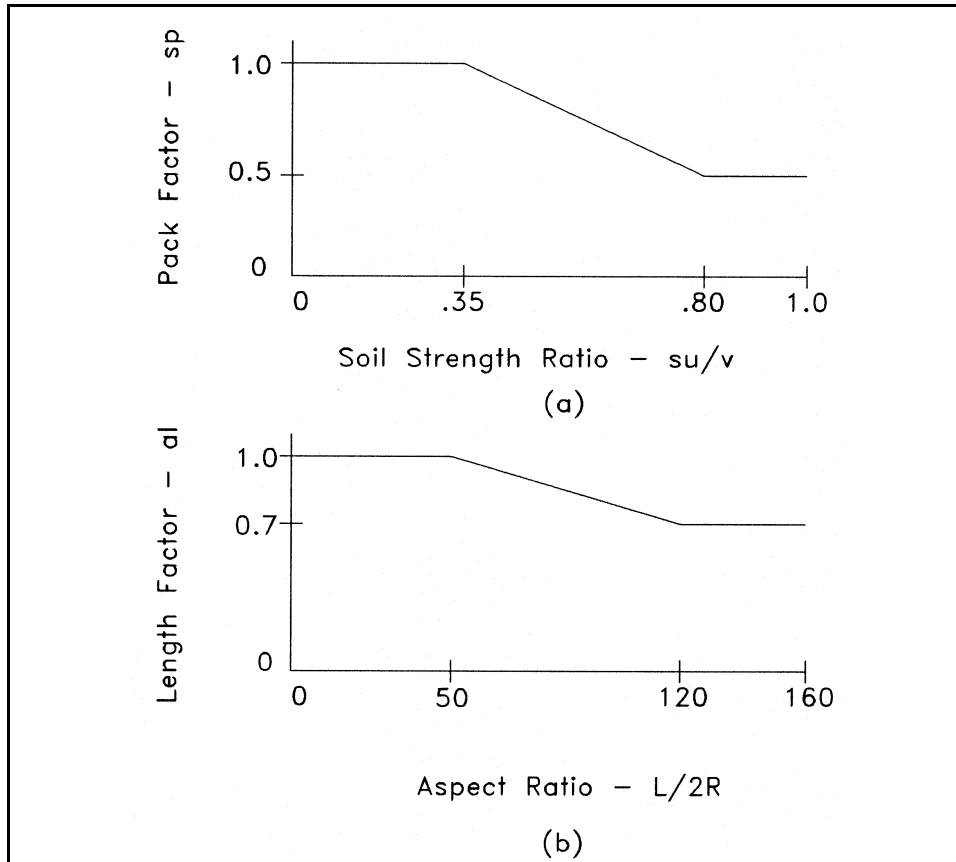


Figure 14. Strength reduction coefficients

Kraft, Ray, and Kagawa (1981)

The procedure of Method SSF2 due to Kraft, Ray, and Kagawa (1981) described previously for sand side friction, may be applied to piles in clay. For clays, the shear modulus may again be evaluated from seismic tests, from resonant column tests, approximated as 400 to 500 times s_u , or evaluated from the modulus of elasticity as $E/3$ for undrained conditions and $E/2.75$ for drained conditions.

Heydinger and O'Neill (1986)

Finite element and finite difference analyses were performed by Heydinger and O'Neill (1986) to develop $f-w$ curves for piles in clay. An axisymmetric model including interface elements to account for slippage of the pile-soil system was used in the finite element analyses. An unconsolidated-undrained condition was assumed to exist in the soil and the initial mean effective stresses were computed from radial consolidation theory in which the pile installation process was represented by an expanding cylindrical cavity. A general equation for the $f-w$ curves (illustrated in Figure 15) was selected as

$$\frac{f}{f_{max}} = \frac{\frac{E_f}{f_{max}} \frac{w}{2R}}{\left[1 + \left(\frac{E_f}{f_{max}} \frac{w}{2R} \right)^m \right]^{1/m}} \quad (22)$$

where the parameters E_f and m were determined by statistical correlations with the analytical results as

$$E_f = E/\exp \left(0.36 + 0.38 \ln \frac{L}{2R} \right) \quad (23)$$

and

$$m = \exp \left(0.12 + 0.54 \ln \frac{E_{avg}}{p_a} - 0.42 \ln \frac{L}{2R} \right) \quad (24)$$

where

E = initial undrained modulus of elasticity of the soil at the depth of interest

E_{avg} = the average initial undrained modulus of elasticity over the entire length of the pile

p_a = atmospheric pressure in the same units as E_{avg}

The value of E should be measured at very low strains. An approximation for E is cited as 1,200 to 1,500 times s_u .

Vijayvergiya (1977)

Vijayvergiya (1977) indicated that Equation 13 for $f-w$ curves in sand, Method SSF3, is applicable for piles in clay. As for piles in sand, Vijayvergiya suggests values of the critical pile displacement w_c of 0.2 to 0.3 in. Although a

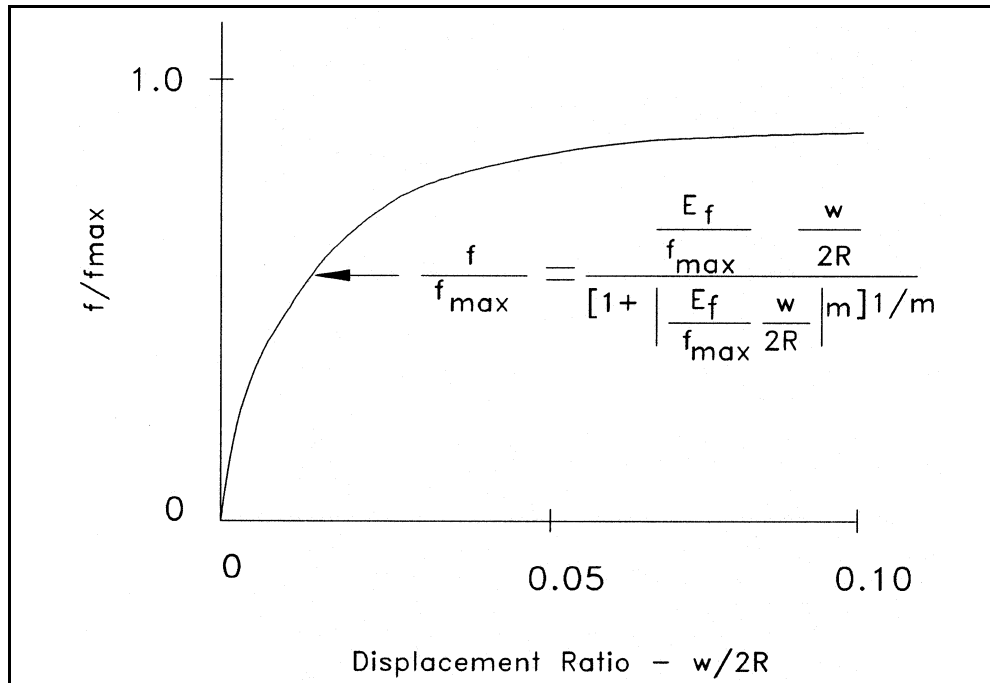


Figure 15. f - w curve by Method CSF4

method for evaluating f_{max} is presented by Vijayvergiya, he suggests that other less complex methods are equally suitable, e.g., the process of Method CSF2 discussed previously.

Tip Reactions

The influence of the tip reaction on the axial load-displacement behavior depends on the relative stiffness of the pile as well as side friction stiffness of the soil. In the following paragraphs several curves are presented for assessing the tip reaction as a function of the tip displacement. In general these curves have been developed primarily from a consideration of the properties of the soil at the tip elevation. However, numerous theoretical studies (see, for instance, Randolph and Wroth (1978)) have indicated that the tip reaction depends on the characteristics of the soil both above and below the tip elevation. Some of the methods for developing q - w curves for the tip reaction account for the profile in the vicinity of the tip by using average soil properties. Other methods, derived from test results where the soil at the test site was relatively homogeneous, are dependent on the properties of the soil at the tip.

The curves presented below are for unit tip reaction (i.e. force per unit of tip area). To evaluate the total tip reaction, this unit force must be multiplied by the area of the pile tip actually bearing on the soil. For solid or closed-end piles the tip bearing area is reasonably taken as being equal to the gross cross section area. For open-end piles (e.g. pipes) or H-piles the effective tip area may be as little as the material area of the pile or may be as much as the gross section area.

Synthesis of q - w Curves for Piles in Sand Under Compressive Loading

Mosher (1984)

Mosher (1984) expanded the work of Coyle and Castello (1981) to determine the q - w relationship for piles in sand. Mosher proposed the exponential q - w curve shown in Figure 16. Values of ultimate unit tip reaction q_{max} are given as a function of relative depth ($L/2R$) in Figure 17.

Kraft, Ray, and Kagawa (1981)

Kraft, Ray, and Kagawa (1981) did not attempt to produce a q - w curve corresponding to their analytical f - w curve, but approximated the q - w relationship by the elastic solution for a rigid punch according to

$$w = \frac{2Rq(1 - \nu^2)}{E} I_t \quad (25)$$

where

w = tip displacement

R = radius of pile tip reaction area

q = tip pressure

ν = Poisson's ratio for the soil at the tip

E = secant modulus of elasticity of the soil appropriate to the level of soil stress associated with q

I_t = influence coefficient ranging from 0.5 for long piles to 0.78 for very short piles

Vijayvergiya (1977)

Vijayvergiya (1977) proposed an exponential representation for the q - w curve for a pile in sand similar to those in Method ST1. For $w < w_c$

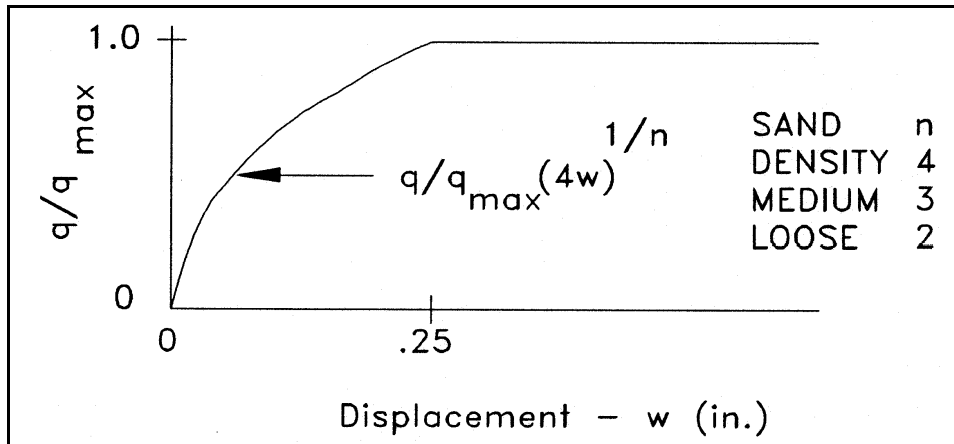


Figure 16. q - w curve by Method ST1

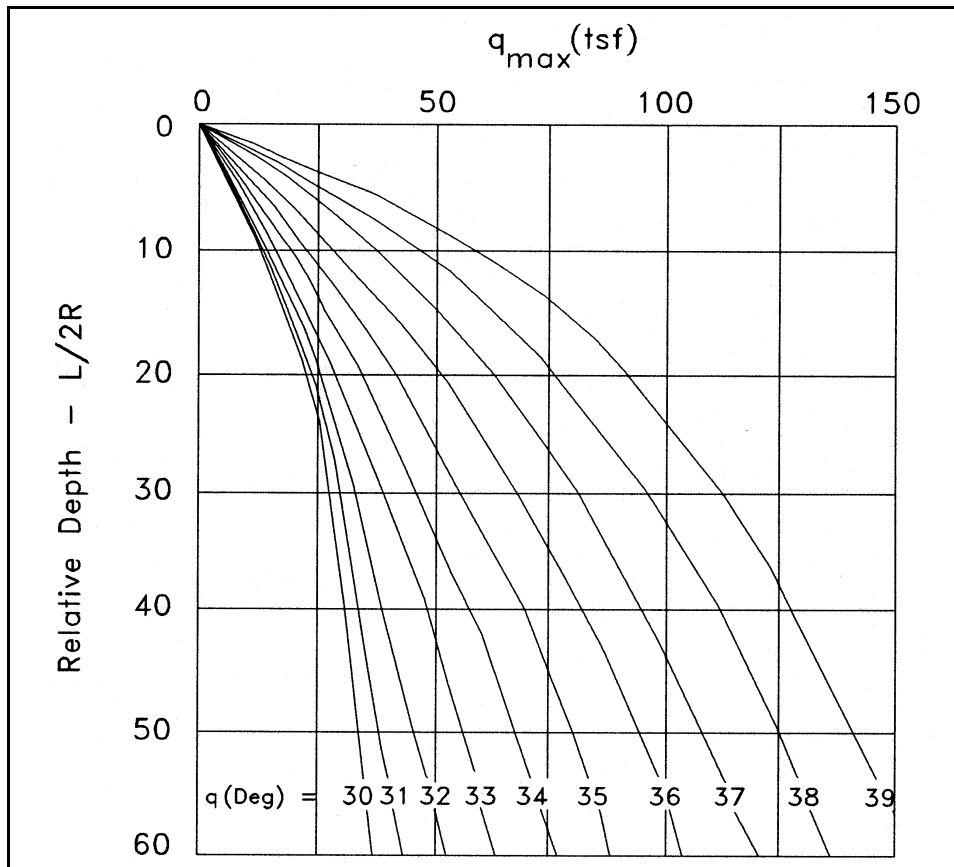


Figure 17. Ultimate tip resistance for Method SF1

$$\frac{q}{q_{max}} = \left(\frac{w}{w_c} \right)^{1/3} \tag{26}$$

where w_c is the critical tip displacement given by Vijayvergiya as ranging from 3 to 9 percent of the diameter of the tip reaction area. For $w > w_c$, $q = q_{max}$. Vijayvergiya did not suggest adjusting the exponent to account for density.

Briaud and Tucker (1984)

Briaud and Tucker (1984) offer a means of accounting for the presence of residual stresses due to pile installation on the tip reaction. The hyperbolic relationship between unit tip reaction and tip displacement shown in Figure 18 is given by

$$q = \frac{w}{\frac{1}{k_q} + \frac{w}{q_{max} - q_r}} + q_r \quad (27)$$

$$q_{max} = 19.75(N)^{0.36} \quad (28)$$

$$q_r = 5.57L\Omega \quad (29)$$

$$K_q = 467.1(N)^{0.0065} \quad (30)$$

where

N = uncorrected average blow count of a standard penetration test over a distance of four diameters on either side of the tip

k_q = initial slope of the q - w curve in tsf/in.

q_{max} , q_r = ultimate and residual unit tip resistances, respectively, in tsf. Other terms are defined on page 6

Coyle and Castello (1981)

Coyle and Castello (1981) provided ultimate tip reactions based on correlations for instrumented piles in sand as shown in Figure 19. Coyle¹ recommended the tip reaction curve shown in Figure 20.

¹ Unpublished Class Notes, 1977, H. M. Coyle, "Marine Foundation Engineering," Texas A&M University, College Station, TX.

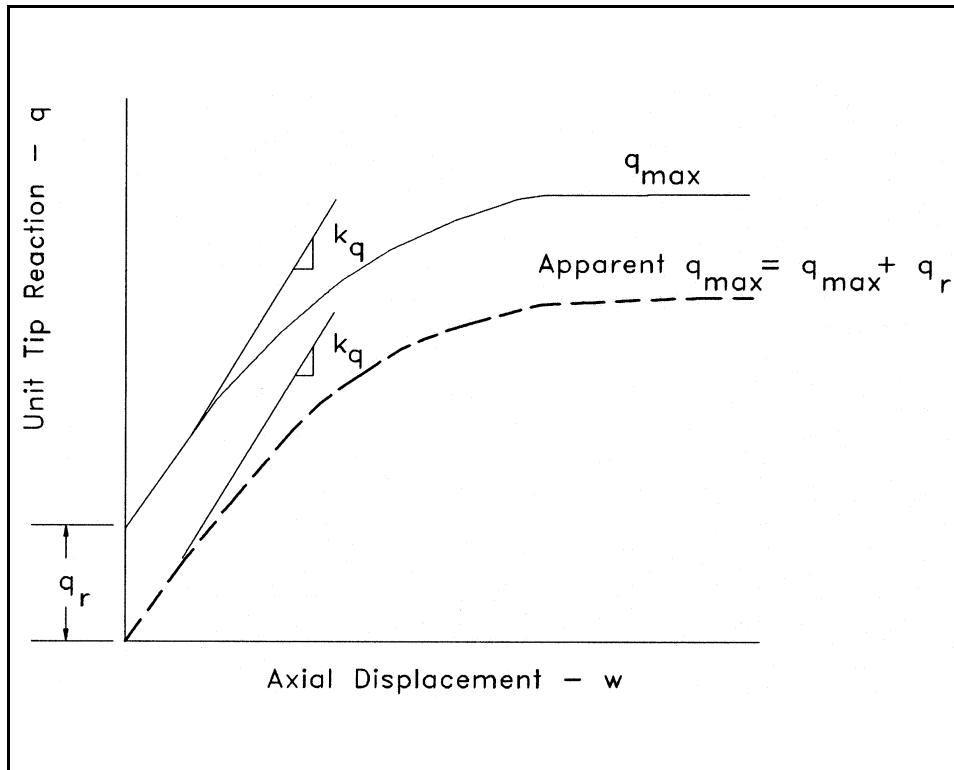


Figure 18. q - w curve by Method SF4

Synthesis of q - w Curves for Piles in Clay Under Compressive Loading

Aschenbrener and Olson (1984)

Data for tip load and tip settlement were not recorded in sufficient detail in the database considered by Aschenbrener and Olson (1984) to allow establishing a nonlinear q - w relationship. It was concluded that the sparsity and scatter of field data warranted nothing more complex than a simple elasto-plastic relationship. In their representation, q varies linearly with w reaching q_{max} at a displacement equal to 1 percent of the tip diameter and remains constant at q_{max} for larger displacements. Ultimate tip reaction was evaluated according to

$$q_{max} = s_u N_c \quad (31)$$

where

s_u = undrained shear strength

N_c = bearing capacity factor

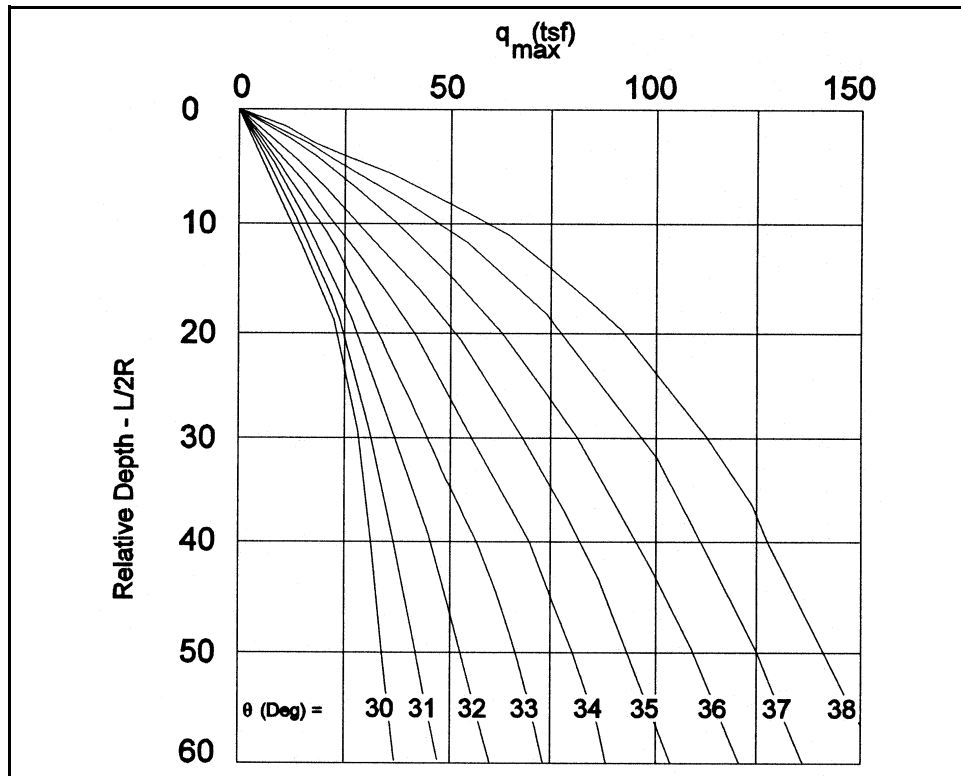


Figure 19. Ultimate tip resistance for Method ST5

Test data indicated that N_c varied from 0 to 20 and had little correlation with shear strength. When ultimate tip reaction was not available from recorded data, Aschenbrenner and Olson used a conventional value for N_c equal to 9.

Vijayvergiya (1977)

Vijayvergiya (1977) recommends that the exponential $q-w$ curve for sand as discussed on pages 24-26 is applicable for piles in clay. He indicates that q_{max} can be calculated from Equation 31 above but provides no guidance for the selection of N_c .

Other Considerations

Uplift loading

For some design cases it may be necessary to evaluate the behavior of an axially loaded pile for uplift (tension) loading. Considerably less is known about uplift loading than about compression loading. However, it is believed to be sufficiently accurate to analyze prismatic piles in clay under uplift using the same

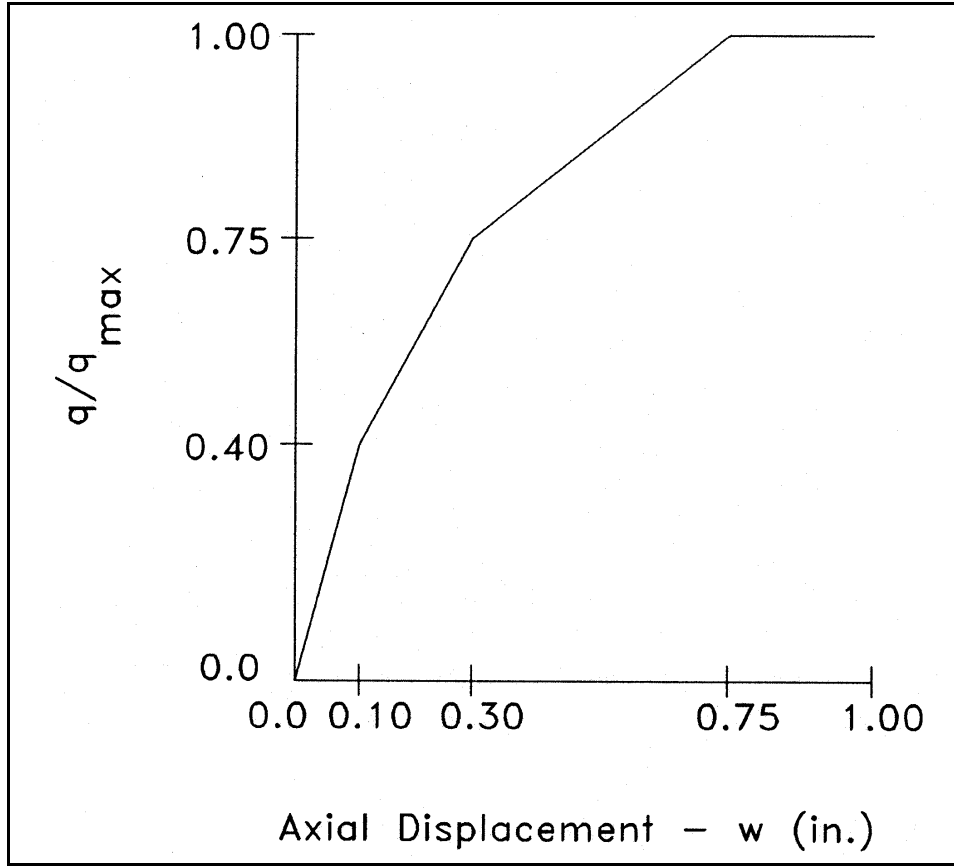


Figure 20. q - w curve by Method SF5

procedures used for compression loading, except that the tip reaction should be omitted unless it is explicitly accounted for as discussed below. In sands, use of the same procedures employed in compression loading is recommended, with the exception that f_{max} should be reduced to 70 percent of the maximum compression value.

For the methods that explicitly include residual driving stress effects in nonlinear f - w and q - w curves (pages 16-17 and 26), it is recommended that the appropriate curves for uplift loading be generated by extending the solid curves in Figures 10 and 18 in the negative w direction with the same initial slopes as exist in the positive w direction and assuring that the q - w curve terminates at $q = 0$. That is

$$f = \frac{w}{\frac{1}{k_f} - \frac{w}{0.7f_{max} + f_r}} - f_r \quad (32)$$

where w is negative and f_{max} , f_r , and k_f are positive. And

$$q = \frac{w}{\frac{1}{k_q} - \frac{w}{q_r}} + q_r \quad (33)$$

where w is negative and q_r and k_q are positive. All parameters appearing in Equations 32 and 33 are evaluated as for compressive loading.

Bearing on Rock

The tip reaction-tip displacement relationship for a pile driven to bearing on rock may be assumed to be linear. The tip reaction stiffness given by Equation 25 may be used where the modulus of elasticity and Poisson's ratio should reflect the characteristics of the surficial zone of the rock. The influence coefficient I_t in Equation 25 may be taken as 0.78 for very sound rock but should be reduced to account for such effects as fracturing of the rock surface due to driving.

Cyclic Loading

Studies have shown (Poulos 1983) that the principal concern associated with cyclic axial loading is the tendency for f_{max} to reduce as the ratio of the cyclic component of axial load P_{oc} to the ultimate static capacity P_{ous} increases beyond some critical value. As long as the ratio remains below the failure envelope shown in Figure 21, no significant degradation of the pile capacity or force-displacement behavior is likely to occur.

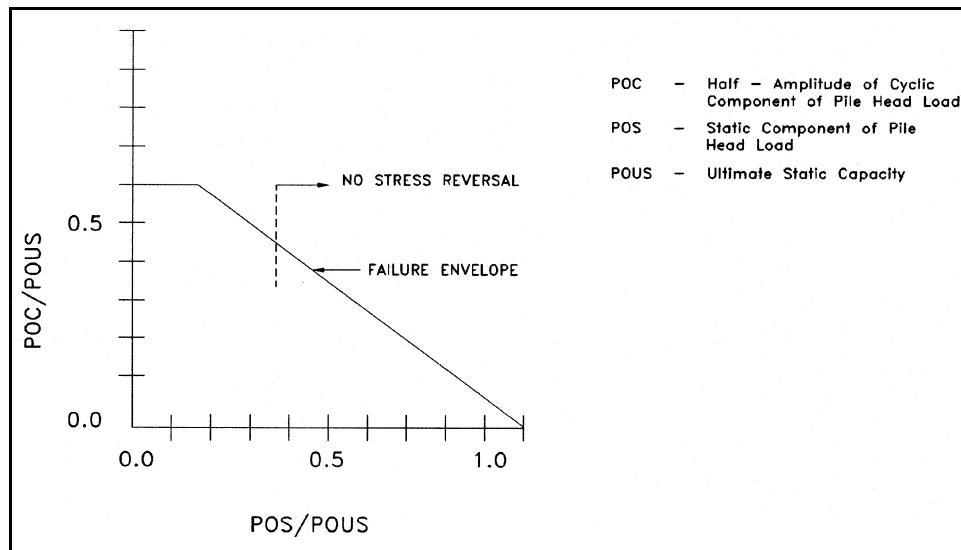


Figure 21. Assessment of degradation due to static loading

Algorithm for Analysis of Axially Loaded Piles

The derivation of the $f-w$ and $q-w$ curves from theoretical considerations or from experimental data described in the preceding sections was in all cases based on the assumption that the side friction f or tip reaction q at any point is a function only of the pile displacement at that point (i.e. the well known Winkler assumption). For this assumption and the one-dimensional model of the pile-soil system shown in Figure 2, the governing differential equation for a prismatic, linearly elastic pile is

$$EA \frac{d^2w}{dz^2} - 2\pi Rf(z,w) = 0 \quad (34)$$

where

E = modulus of elasticity of the pile material

A = pile material cross section area

w = axial displacement

R = effective radius of pile soil interface; and $f(z,w)$ is the unit side friction, which is a function of both position on the pile as well as pile displacement

Because the displacements must be known before the side friction $f(z,w)$ can be determined, numerical iterative solutions of Equation 34 are required. The most common approach to the solution is to replace the continuous pile-soil system with a discretized model (Coyle and Reese 1966, Dawkins 1982, Dawkins 1984) defined by a finite number of nodes along the pile at which displacements and forces are evaluated. The solution proceeds by a succession of trial and correction solutions until compatibility of forces and displacements is attained at every node.

Observations of System Behavior

An expedient device in obtaining the numerical solutions described above is to replace the nonlinear $f-w$ and $q-w$ curves by equivalent linearly elastic springs during each iteration. The stiffnesses of these linear springs are evaluated as the secant to the $f-w$ or $q-w$ curve for the displacement calculated during the preceding iteration. It is to be noticed that ultimate side friction increases with depth while pile displacements decrease with depth. Hence it can be concluded that the stiffness of the load transfer mechanism for side friction increases with depth. If the distribution of the side friction for any given head load can be determined then a solution may be obtained from a linearly elastic solution without the need for iterations.

3 Single Laterally Loaded Pile Analysis

Introduction

Although the usual application of a pile foundation results primarily in axial loading, there exist numerous situations in which components of load at the pile head produce significant lateral displacements as well as bending moments and shears. Unlike axial loads, which only produce displacements parallel to the axis of the pile (a one-dimensional system), lateral loads may produce displacements in any direction. Unless the pile cross section is circular, the laterally loaded pile/soil system represents a three-dimensional problem. Most of the research on the behavior of laterally loaded piles has been performed on piles of circular cross section in order to reduce the three-dimensional problem to two dimensions. Little work has been done to investigate the behavior of noncircular cross section piles under generalized loading. In many applications, battering of the piles in the foundation produces combined axial and lateral loads. However, the majority of the research on lateral load behavior has been restricted to vertical piles subjected to loads which produce displacements perpendicular to the axis of the pile. In the discussions which follow, it is assumed that the pile has a straight centroidal vertical axis. If the pile is nonprismatic and has a noncircular cross section, it is assumed that the principal axes of all cross sections along the pile fall in two mutually perpendicular planes and that the loads applied to the pile produce displacements in only one of the principal planes.

A schematic of a laterally loaded pile is shown in Figure 22. The x - z plane is assumed to be a principal plane of the pile cross section. Due to the applied head shear V_o and head moment M_o , each point on the pile undergoes a translation u in the x -direction and a rotation θ about the y -axis. Displacements and forces are positive if their senses are in a positive coordinate direction. The surrounding soil develops pressures, denoted p in Figure 22, which resist the lateral displacements of the pile.

The principles of continuum mechanics and correlations with the results of tests of instrumented laterally loaded piles have been used to relate the soil

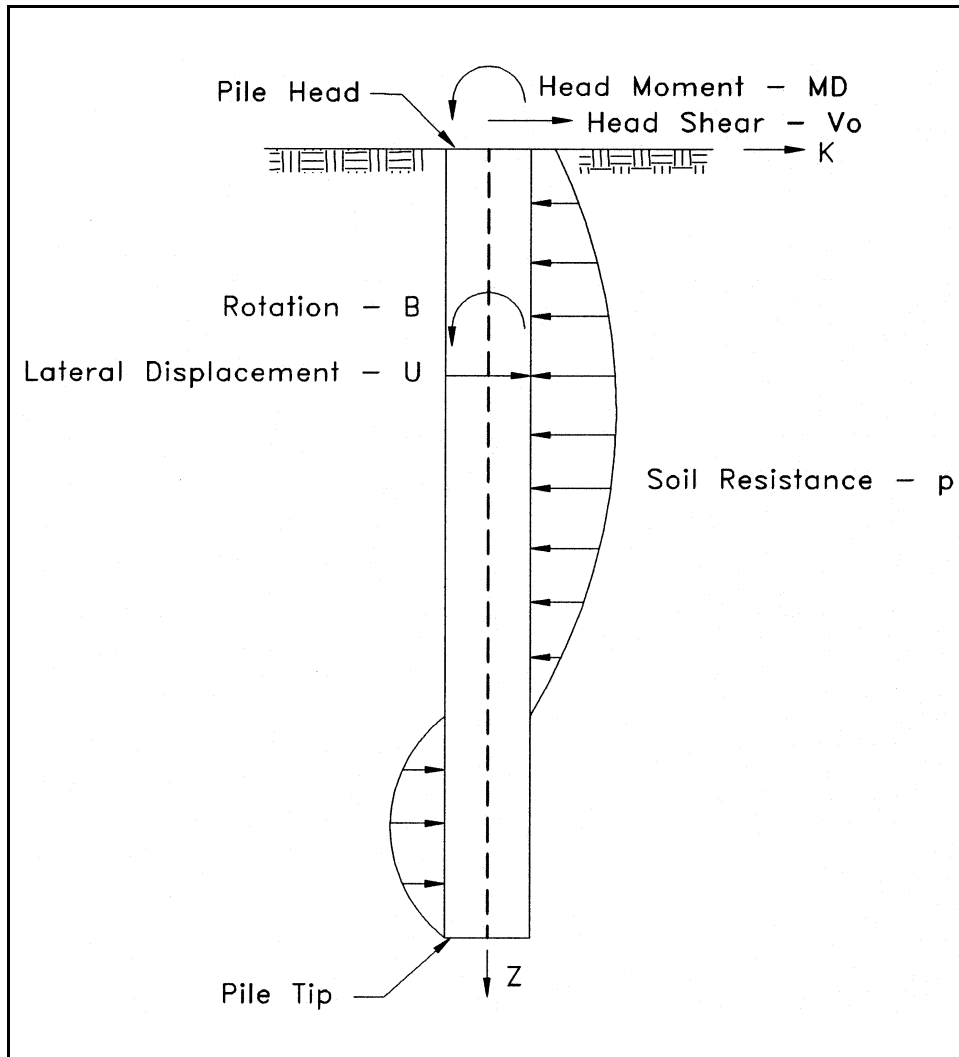


Figure 22. Laterally loaded pile

lateral resistance p at each point on the pile to the lateral displacement u at that point (i.e. the Winkler assumption). The relationship between soil resistance and

lateral displacement is presented as a nonlinear curve - the $p-u$ curve. Several methods are summarized in the following paragraphs for development of $p-u$ curves for laterally loaded piles in both sands and clays. In all of the methods, the primary $p-u$ curve is developed for monotonically increasing static loads. The static curve is then altered to account for the degradation effects produced by cyclic loads such as might be produced by ocean waves on offshore structures. Methods designated SLAT1 and CLAT1 through CLAT4 have been incorporated into the CASE Project Computer program CPGS.

Load Transfer Mechanism for Laterally Loaded Piles

The load transfer mechanism for laterally loaded piles is much more complex than that for axially loaded piles. In an axially loaded pile the axial displacements and side friction resistances are unidirectional (i.e., a compressive axial head load produces downward displacements and upward side friction resistance at all points along the pile). Similarly, the ultimate side friction at the pile-soil interface depends primarily on the soil shear strength at each point along the pile. Because the laterally loaded pile is at least two-dimensional, the ultimate lateral resistance of the soil is dependent not only on the soil shear strength but on a geometric failure mechanism. At points near the ground surface an ultimate condition is produced by a wedge type failure, while at lower positions failure is associated with plastic flow of the soil around the pile as displacements increase. In each of the methods described below, two alternative evaluations are made for the ultimate lateral resistances at each point on the pile, for wedge type failure and for plastic flow failure, and the smaller of the two is taken as the ultimate resistance.

Synthesis of p - u Curves for Piles in Sand

Reese, Cox, and Koop (1974)

A series of static and cyclic lateral load tests were performed on pipe piles driven in submerged sands (Cox, Reese, and Grubbs 1974; Reese, Cox, and Koop 1974; Reese and Sullivan 1980). Although the tests were conducted in submerged sands, Reese et al. (1980) have provided adjustments by which the p - u curve can be developed for either submerged sand or sand above the water table. The p - u curve for a point a distance z below the pile head extracted from the experimental results is shown schematically in Figure 23. The curve consists of a linear segment from 0 to a , an exponential variation of p with u from a to b , a second linear range from b to c , and a constant resistance for displacements beyond c .

Steps for constructing the p - u curve at a depth z below the ground surface are as follows:

- a. Determine the slope of the initial linear portion of the curve from

$$k_p = kz \tag{35}$$

where k is obtained from Table 2 for either submerged sand or sand above the water table.

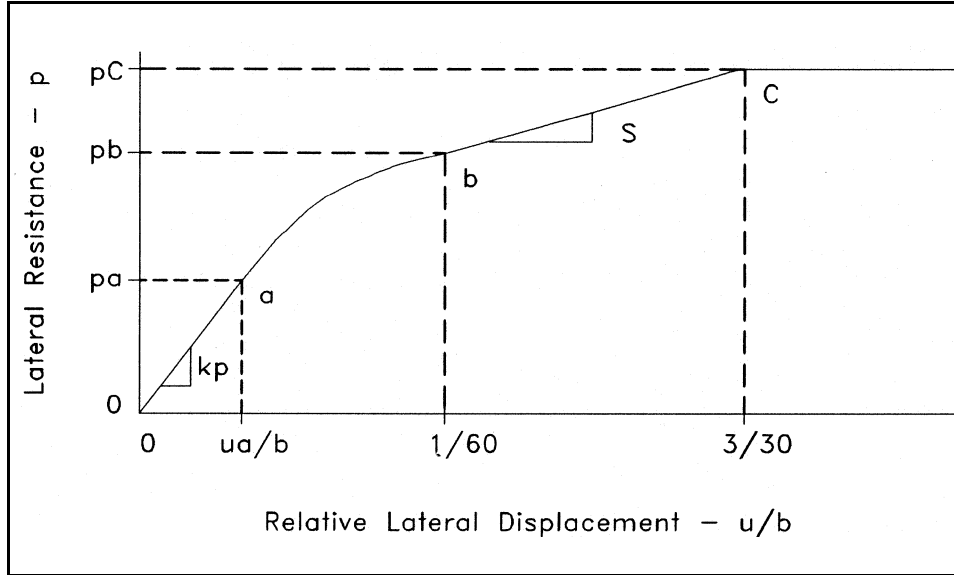


Figure 23. p - u curve by Method SLAT1

Table 2			
Representative Values of k for Method SLAT1			
Sand	Relative Density		
	Loose	Medium	Dense
Submerged (pci)	20	60	125
Above water table (pci)	25	90	225

b . Compute the ultimate lateral resistance as the smaller of

$$p_s = (C1 z + C2 b) \gamma' z \quad (36)$$

for a wedge failure near the ground surface; or

$$p_s = C3 b \gamma' z \quad (37)$$

for a flow failure at depth; with

$$C1 = \frac{K \tan \phi \sin \beta}{\tan (\beta - \phi) \cos \phi/2} + \frac{\tan^2 \beta \tan \phi/2}{\tan (\beta - \phi)} + K \tan \beta (\tan \phi \sin \beta - \tan \phi/2) \quad (38)$$

$$C2 = \frac{\tan \beta}{\tan (\beta - \phi)} - \tan^2 (45 - \phi/2) \quad (39)$$

$$C3 = K \tan \phi \tan^4 \beta + \tan^2 (45 - \phi/2) (\tan^8 \beta - 1) \quad (40)$$

where

γ = effective unit weight of the sand

z = depth below ground surface

K = horizontal earth pressure coefficient chosen as 0.4 to reflect the fact that the surfaces of the assumed failure model are not planar

ϕ = angle of internal friction

$\beta = 45 + \phi/2$

b = width of the pile perpendicular to the direction of loading

Values of $C1$, $C2$, $C3$, and the depth z_{cr} at which the transition from wedge failure (Equation 36) to flow failure (Equation 37) occurs are shown in Figure 24.

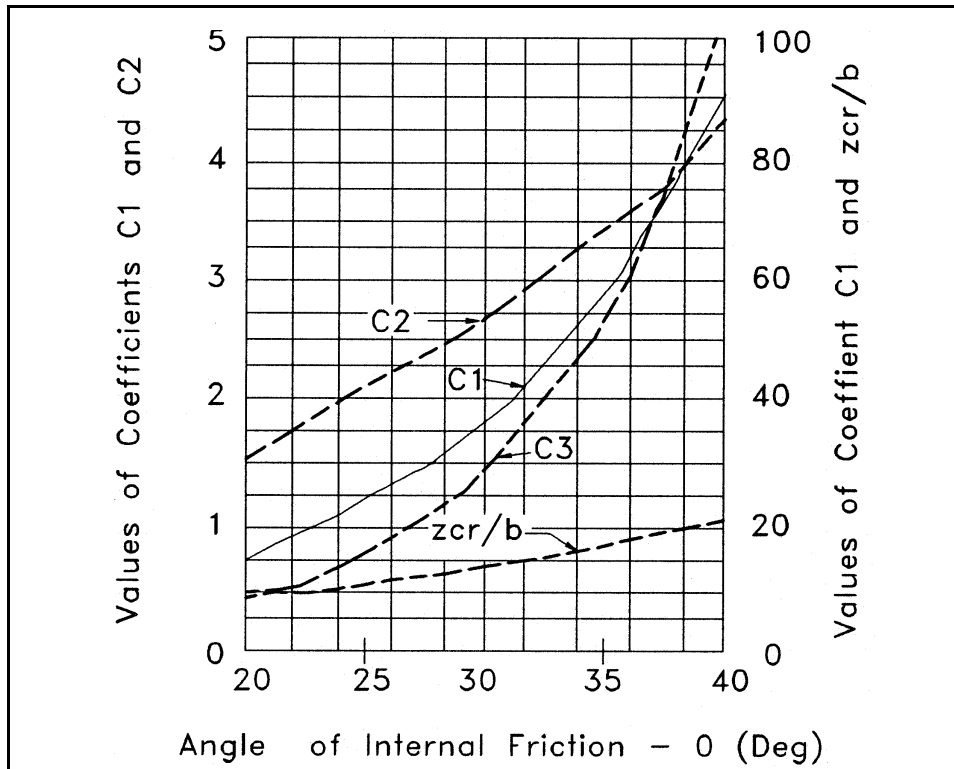


Figure 24. Factors for calculation of ultimate soil resistance for laterally loaded pile in sand

- c. Compute the lateral resistance for the transition points c and b on the curve (Figure 23) from

$$p_c = A p_s \quad (41)$$

$$p_b = B p_s \quad (42)$$

where A and B are reduction coefficients from Figures 25 and 26, respectively, for the appropriate static or cyclic loading condition. The second straight line segment of the curve, from b to c , is established by the resistances p_b and p_c and the prescribed displacements of $u = b/60$ and $u = 3b/80$ as shown in Figure 27. The slope of this segment is given by

$$s = \frac{40(p_c - p_b)}{b} \quad (43)$$

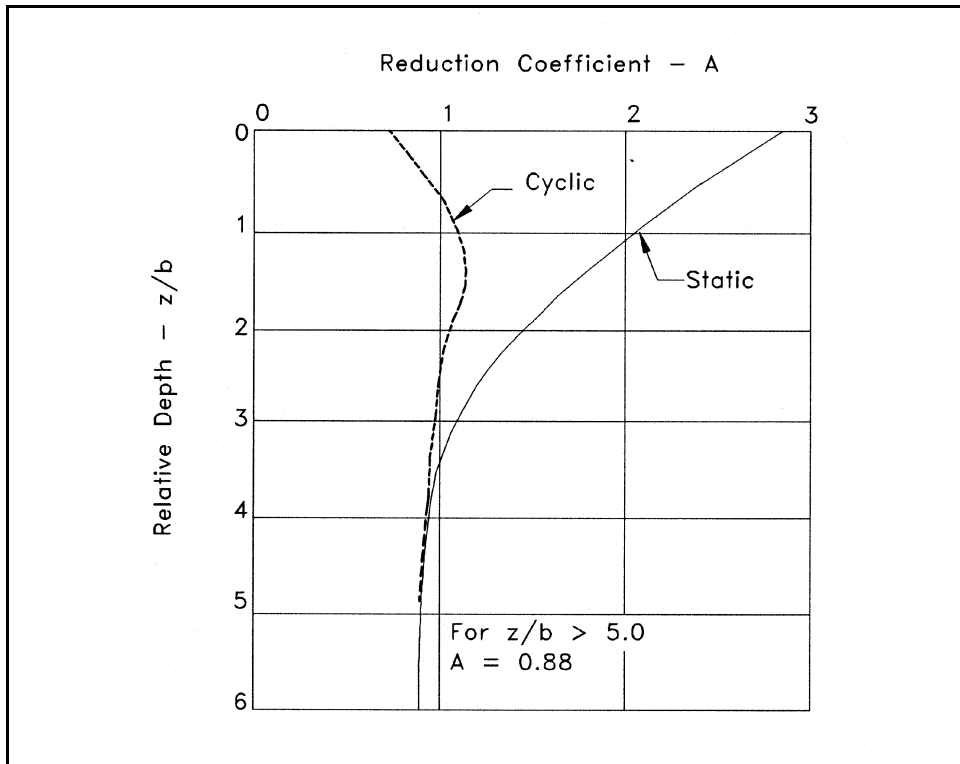


Figure 25. Resistance reduction coefficient - A for Method SLAT1

- d. The exponential section of the curve, from a to b , is of the form

$$p = Cu^{1/n} \quad (44)$$

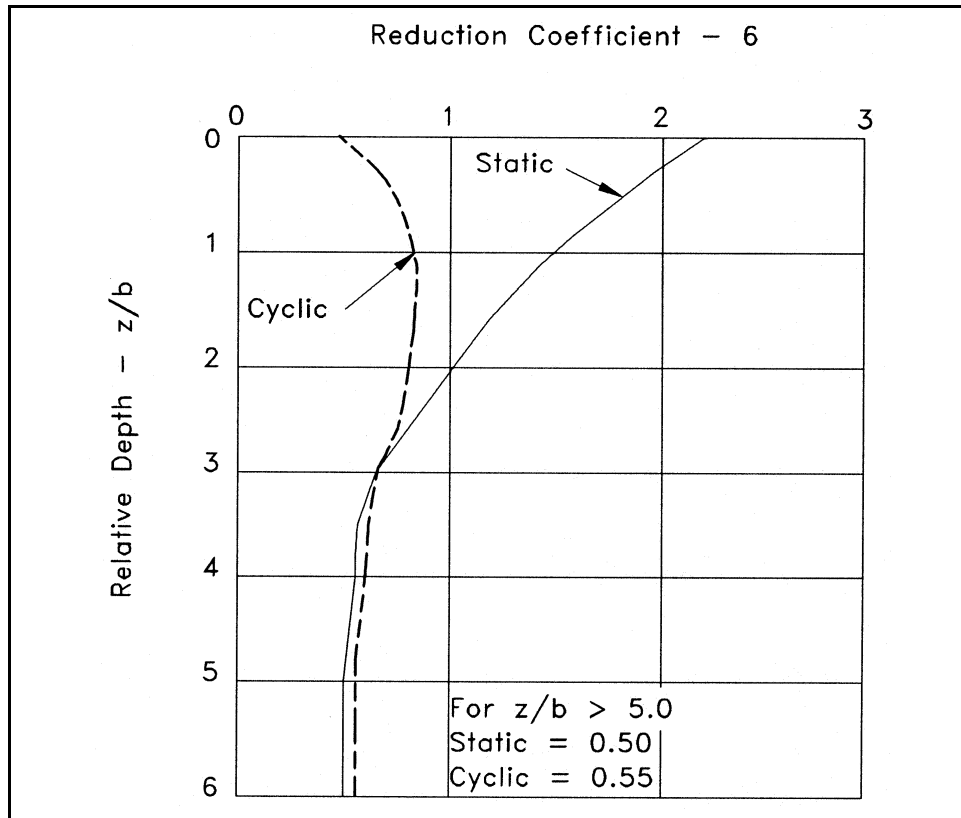


Figure 26. Resistance reduction coefficient - B for Method SLAT1

where the parameters C , n , and the terminus of the initial linear portion p_a and u_a are obtained by forcing the exponential function in Equation 44 to pass through p_b and u_b with the same slope s as segment bc and to have the slope k_p at the terminus of the initial straight line segment at a . This results in

$$n = \frac{p_b}{s u_b} \quad (45)$$

$$C = \frac{p_b}{u_b^{1/n}} \quad (46)$$

$$u_a = \left(\frac{C}{k_p} \right)^{n/(n-1)} \quad (47)$$

$$p_a = k_p u_a \quad (48)$$

(Note: In some situations Equations 45 through 48 may result in unrealistic values for u_a and/or p_a . If this occurs, the exponential portion is omitted and the initial linear segment is extended to its intersection with the straight line

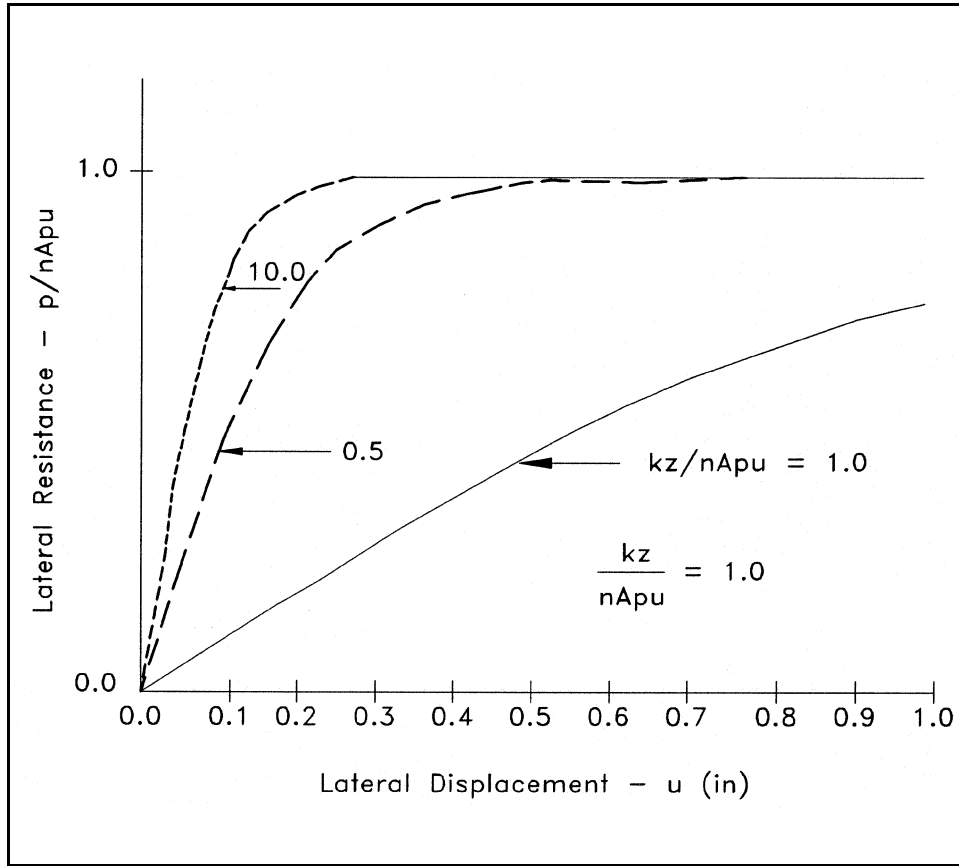


Figure 27. p - u curves by Method SLAT2

section bc or until the maximum resistance p_c is reached whichever comes first. If segments $0a$ and bc do not intersect at realistic values of p_a and u_a , segment bc is omitted.)

Murchison and O'Neill (1984)

Murchison and O'Neill (1984) simplified the process of Method SLAT1 by replacing the three-part p - u curve with a single analytical expression as follows.

$$\frac{p}{p_u} = nA \tan h \left(\frac{kz u}{nA p_u} \right) \quad (49)$$

where

p_u = ultimate lateral soil resistance from either Equation 36 for $z < z_{cr}$ or Equation 37 for $z > z_{cr}$

n = geometry factor = 1.5 for tapered piles or 1.0 for prismatic piles

$A = 3 - 0.8(z/b) \geq 0.9$ for static loads or $= 0.9$ for cyclic loading

k = soil stiffness from Table 2

z = depth at which the p - u curve applies

Several illustrative curves for this method are shown in Figure 27.

Synthesis of p - u Curves for Piles in Clay

Matlock (1970)

A series of lateral load tests on instrumented piles in clay (Matlock 1970) were used to produce the p - u relationship for piles in soft to medium clays subjected to static lateral loads in the form

$$\frac{p}{p_u} = 0.5 \left(\frac{u}{u_c} \right)^{1/3} \quad (50)$$

with p_u , the ultimate lateral resistance, given by the smaller of

$$p_u = \left(3 + \frac{\gamma'}{s_u} z + \frac{J}{b} z \right) s_u b \quad (51)$$

for a wedge failure near the ground surface, or

$$p_u = 9s_u b \quad (52)$$

for flow failure at depth; and u_c , the lateral displacement at one-half of the ultimate resistance, given by

$$u_c = 2.5\epsilon_{50}b \quad (53)$$

where

γ' = effective unit weight of the soil

s_u = shear strength of the soil

$J = 0.5$ for a soft clay or 0.25 for a medium clay

ϵ_{50} = strain at 50 percent of the ultimate strength from a laboratory stress-strain curve

Typical values of ϵ_{50} are given in Table 3. The depth at which failure transitions from wedge (Equation 51) to flow (Equation 52) is

$$z_{cr} = \frac{6s_u b}{(\gamma' b + J s_u)} \quad (54)$$

The static $p-u$ curve is illustrated in Figure 28a.

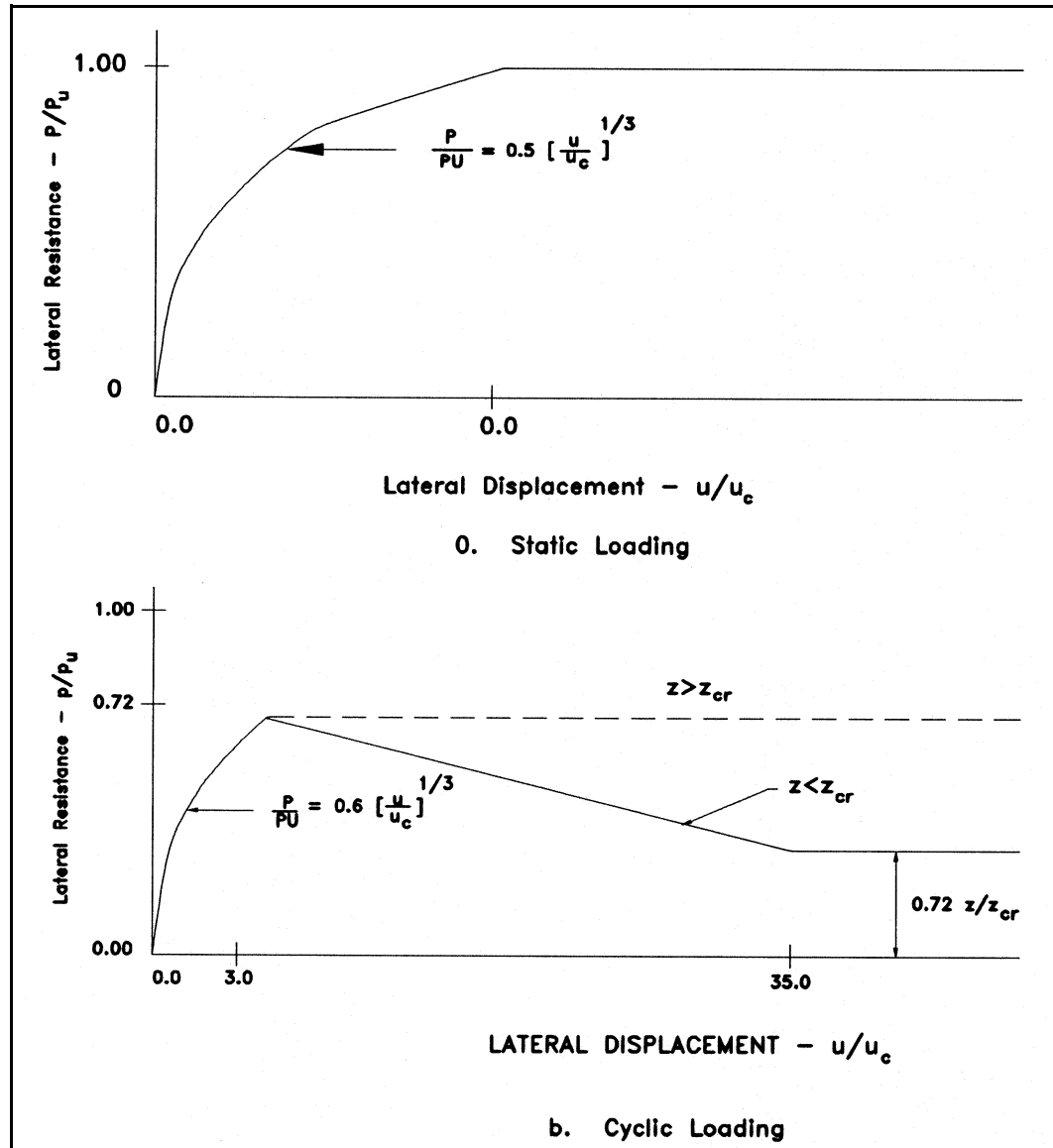


Figure 28. $p-u$ curves by Method CLAT1

For cyclic loads, the basic $p-u$ curve for static loads is altered as shown in Figure 28b. The exponential curve of Equation 50 is terminated at a relative displacement $u/u_c = 3.0$ at which the resistance diminishes with increasing displacement for $z < z_{cr}$ or remains constant for $z > z_{cr}$.

Table 3 Representative Values of ϵ_{50}	
Shear Strength (psf)	Percent
250-500	0.02
500-1,000	0.01
1,000-2,000	0.007
2,000-4,000	0.005
4,000-8,000	0.004

Reese, Cox, and Koop (1975)

Reese, Cox, and Koop (1975) performed lateral load tests of instrumented piles to develop $p-u$ curves for piles in stiff clay below the water table. The $p-u$ curve for static loading, Figure 29, consists of five segments determined as follows.

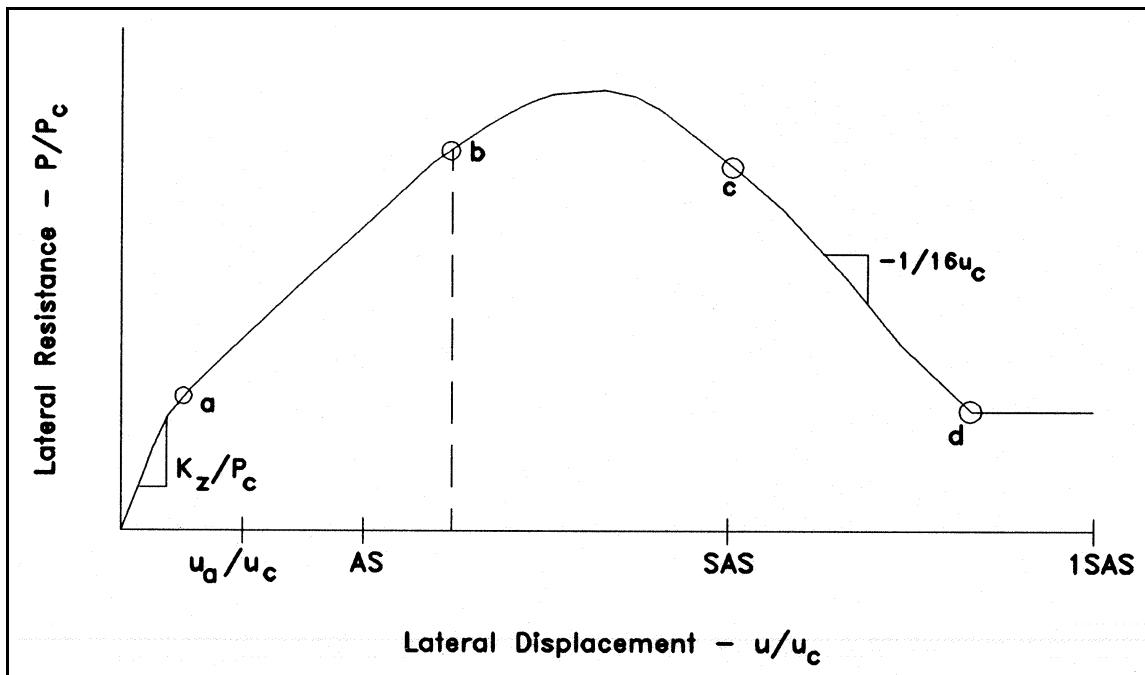


Figure 29. $p-u$ curves by Method CLAT2 for static loads

- a. The initial linear $p-u$ relationship 0a has a slope equal to the product of soil stiffness k (see Table 4) and the depth z to the location at which the curve applies.

Table 4
Representative Values of Lateral Soil Stiffness k for Piles in Clay
for Method CLAT2

Loading Type	Average Undrained Shear Strength (tsf) ¹		
	0.5 - 1	1 - 2	2 - 4
Static loading - k_s (pci)	500	1,000	2,000
Cyclic loading - k_c (pci)	200	400	800

¹ Average shear strength should be computed from the unconsolidated undrained shear strength of the soil to a depth of five pile diameters.

b. The second segment of the curve is parabolic of the form

$$\frac{p}{p_c} = \frac{1}{2} \left(\frac{u}{u_c} \right)^{1/2} \quad (55)$$

with p_c taken as the smaller of

$$p_c = \left(2 + \frac{\gamma'}{s_u} z + 2.83 \frac{z}{b} \right) s_u b \quad (56)$$

for wedge failure near the ground surface, or

$$p_c = 11 s_u b \quad (57)$$

and

$$u_c = \epsilon_{50} b \quad (58)$$

where ϵ_{50} = strain at 50 percent of ultimate strength from a laboratory stress-strain curve; and the parameter A for defining pertinent displacements in Figure 29 is obtained from the curve shown in Figure 30.

c. Points a and b , Figure 29, are joined by a parabolic curve of the form

$$\frac{p}{p_c} = \frac{1}{2} \left(\frac{u}{u_c} \right)^{1/2} \quad (59)$$

where p_c is the smaller of

$$p_c = \left(2 + \frac{\gamma'}{s_u} z + 2.83 \frac{z}{s_u} \right) s_u b \quad (60)$$

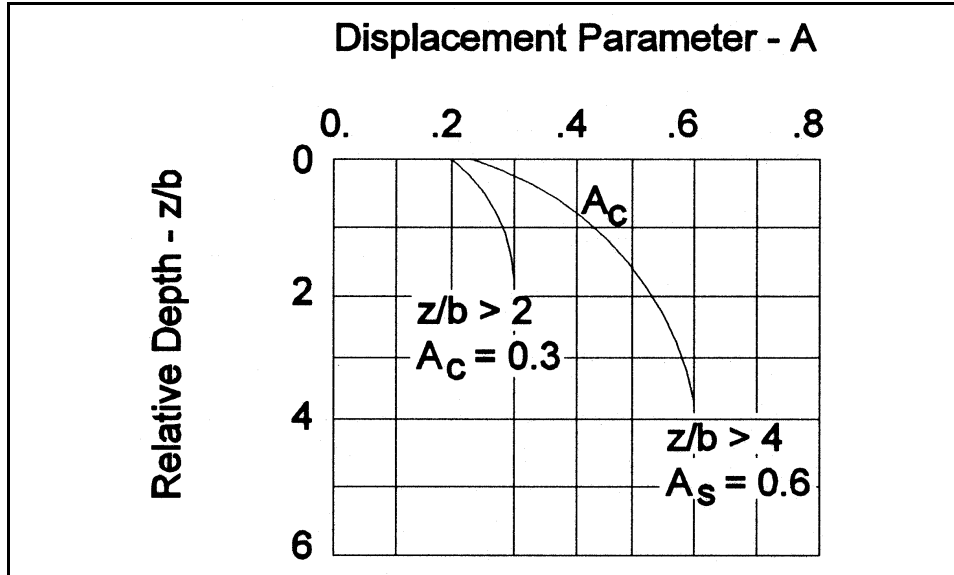


Figure 30. Displacement parameter - A for Method CLAT2

for a wedge failure near the ground surface, or

$$p_c = 11s_u b \quad (61)$$

for a flow failure at depth; and

$$u_c = \epsilon_{50} b \quad (62)$$

where

γ' = effective unit weight of the soil

s_u = undrained shear of the soil

ϵ_{50} = strain at 50 percent of ultimate strength from a laboratory stress-strain curve (see Table 3)

The parameter A_s in Figure 29 is obtained from Figure 30.

d. Segment cd of the p - u curve in Figure 29 is of the form

$$\frac{p}{p_c} = \frac{1}{2} \left(\frac{u}{u_c} \right)^{1/2} - 0.055 \left(\frac{u}{A_s u_c} - 1 \right)^{1.25} \quad (63)$$

e. A second linear segment joins points c and d at the slope indicated in Figure 29 and the lateral resistance remains constant for lateral displacements greater than $u = 18 A_s u_c$.

The p - u curve for cyclic loading provided by Reese, Cox, and Koop (1975) is illustrated in Figure 31. The curve is constructed as follows

- The initial linear p - u relationship $0a$ has a slope equal to the product of soil stiffness k (see Table 4) and the depth z to the location at which the curve applies.
- The second segment, joining points a and b (Figure 31) is an exponential relationship of the form

$$\frac{p}{A_c p_c} = 1 - \left[\text{abs} \left(\frac{u}{0.45u_p} - 1 \right) \right]^{2.5} \quad (64)$$

where

A_c = pressure reduction coefficient from Figure 30

p_c = ultimate soil resistance from Equation 56 or 57 (whichever is less)

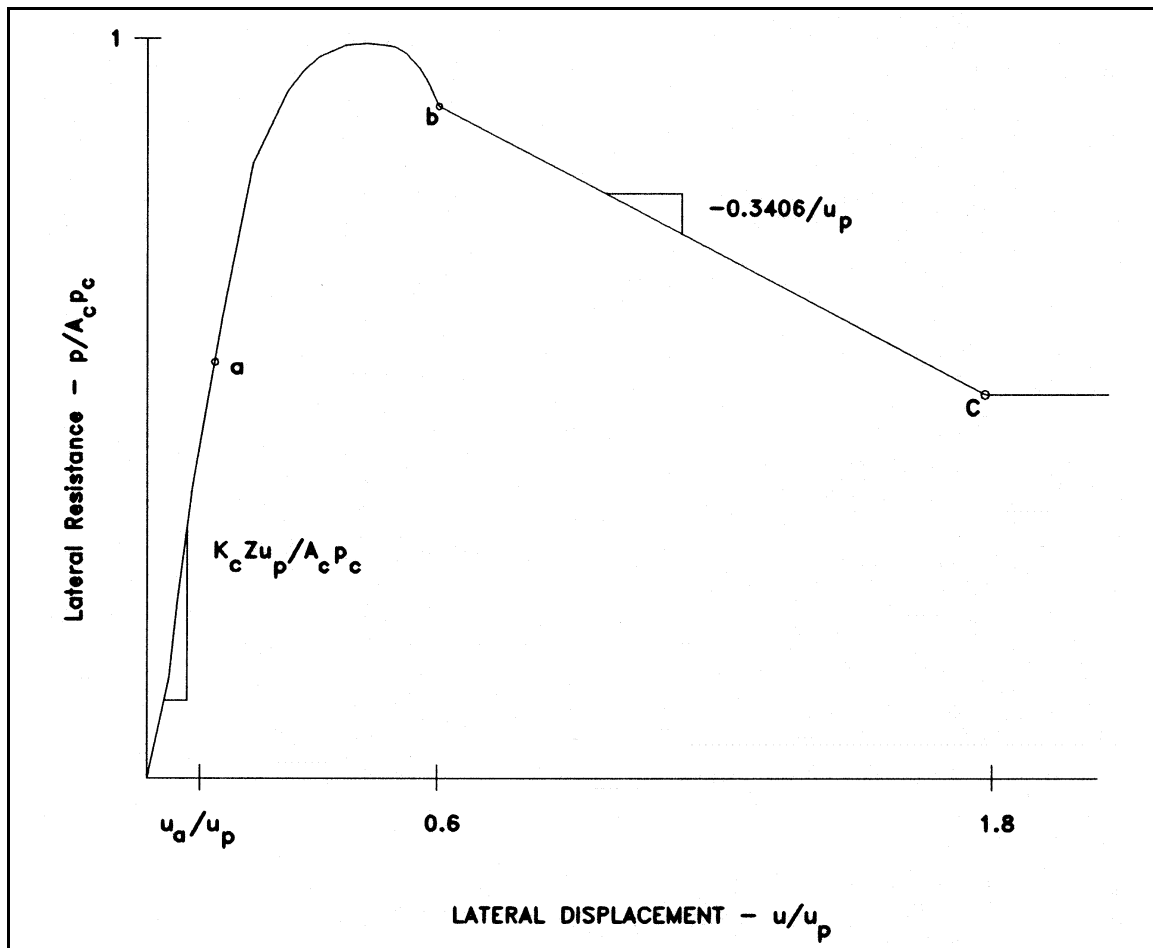


Figure 31. p - u curve by Method CLAT2 for cyclic loads

and

$$u_p = 4.1 A_c u_c \quad (65)$$

where u_c is given by Equation 62.

- c. A second linear p - u relationship joins points b and c with the slope shown in Figure 31. For displacements greater than $u = 1.8u_p$, the lateral resistance remains constant.

Reese and Welch (1975)

Reese and Welch (1975) performed a lateral load test on an instrumented drilled shaft in stiff clay above the water table. The p - u curve obtained from the experimental results for static loads is shown in Figure 32. The curve consists of an exponential relationship between lateral resistance and displacement to an ultimate resistance, after which the resistance remains constant for further displacement. The requisite exponential relationship is

$$\frac{p}{p_u} = \frac{1}{2} \left(\frac{u}{u_c} \right)^{1/4} \quad (66)$$

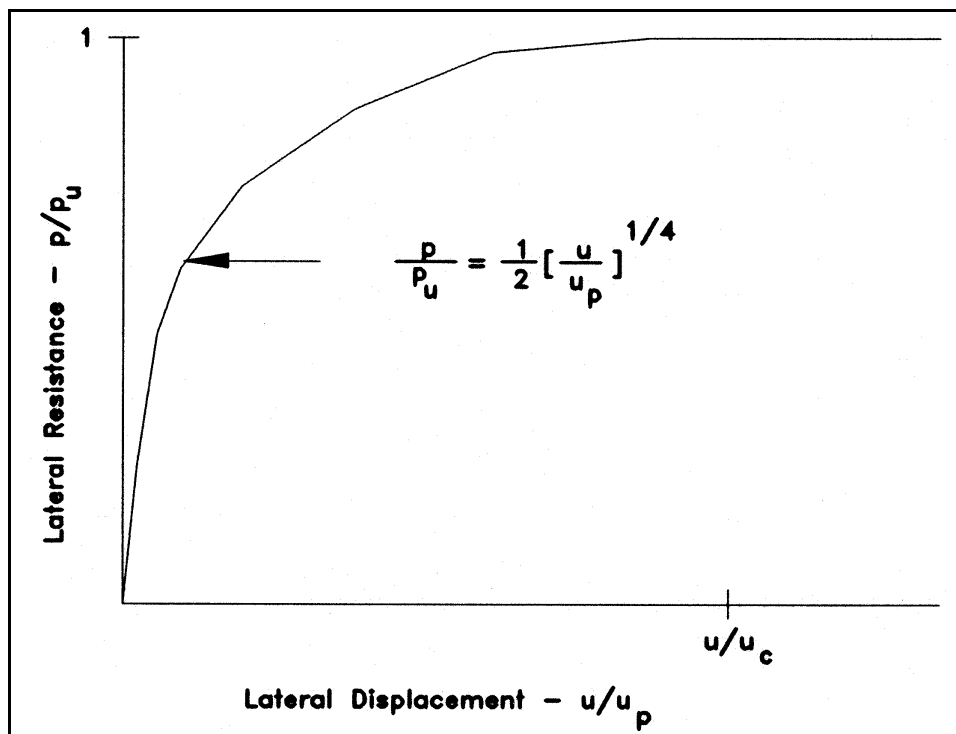


Figure 32. p - u curve by Method CLAT3 for static loads

where

p_u = ultimate resistance obtained as the smaller from Equation 51 with $J = 0.5$ or from Equation 52

u_c = critical lateral displacement obtained from Equation 88

The p - u curve for cyclic loading, shown in Figure 33, is constructed as follows:

- a. Values of p/p_u for various values of static displacement u_s/u_c are computed from Equation 66.
- b. The displacement for cyclic loading for each value of p/p_u is obtained from

$$\frac{u}{u_c} = \frac{u_s}{u_c} + 9.6 \left(\frac{p}{p_u} \right)^4 \log (N) \quad (67)$$

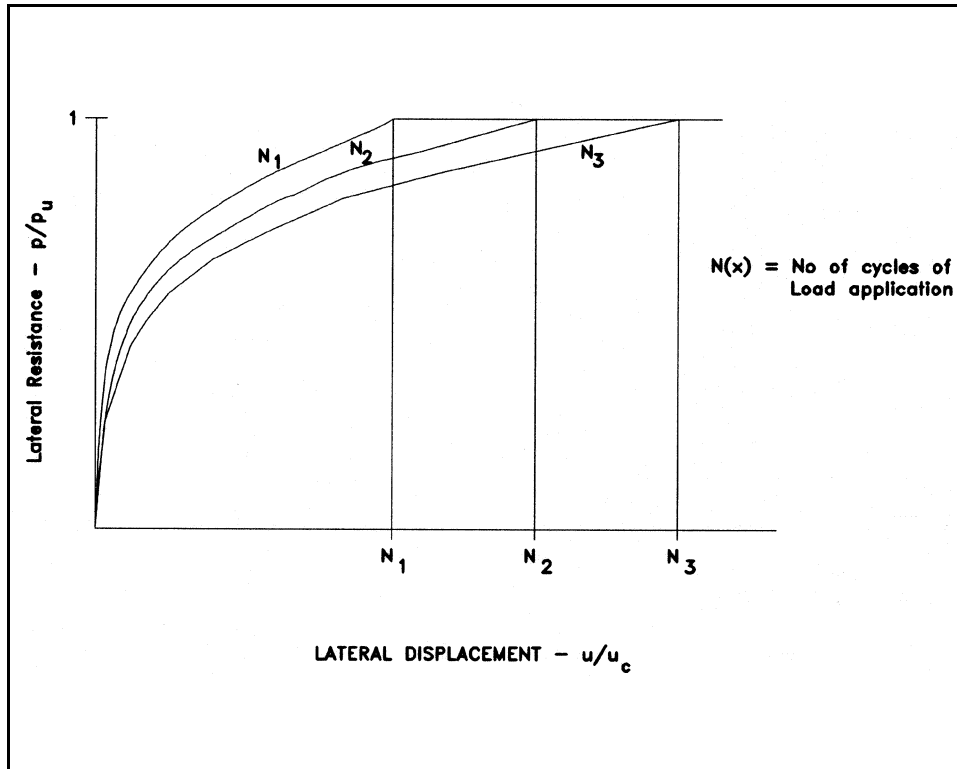


Figure 33. p - u curve by Method CLAT3 for cyclic loads

where

u_s = static displacement corresponding to p/p_u

N = number of cycles of load application

Reese and Sullivan (1980)

Each method for p - u curves for piles in clay described above was developed for a single soil profile; hence there were no recommendations provided for transitioning from “soft” clay criteria to “stiff” clay criteria. Sullivan (1977) and Sullivan, Reese, and Fenske (1979) reexamined the data for soft clays (Matlock 1970) and stiff clays (Reese, Cox, and Koop 1975) and developed a unified criterion (Reese and Sullivan 1980), which yields computed behaviors that are in reasonable agreement with both soft and stiff conditions. However, some judgement on the part of the user is required in selecting appropriate parameters for use in the prediction equations.

The p - u curve by the unified criteria for static loading, illustrated in Figure 34, consists of an initial linear segment $0a$, an exponential segment ab , a second linear segment bc and a constant lateral resistance for large displacements. The curve for static loading at a particular depth z is constructed as follows:

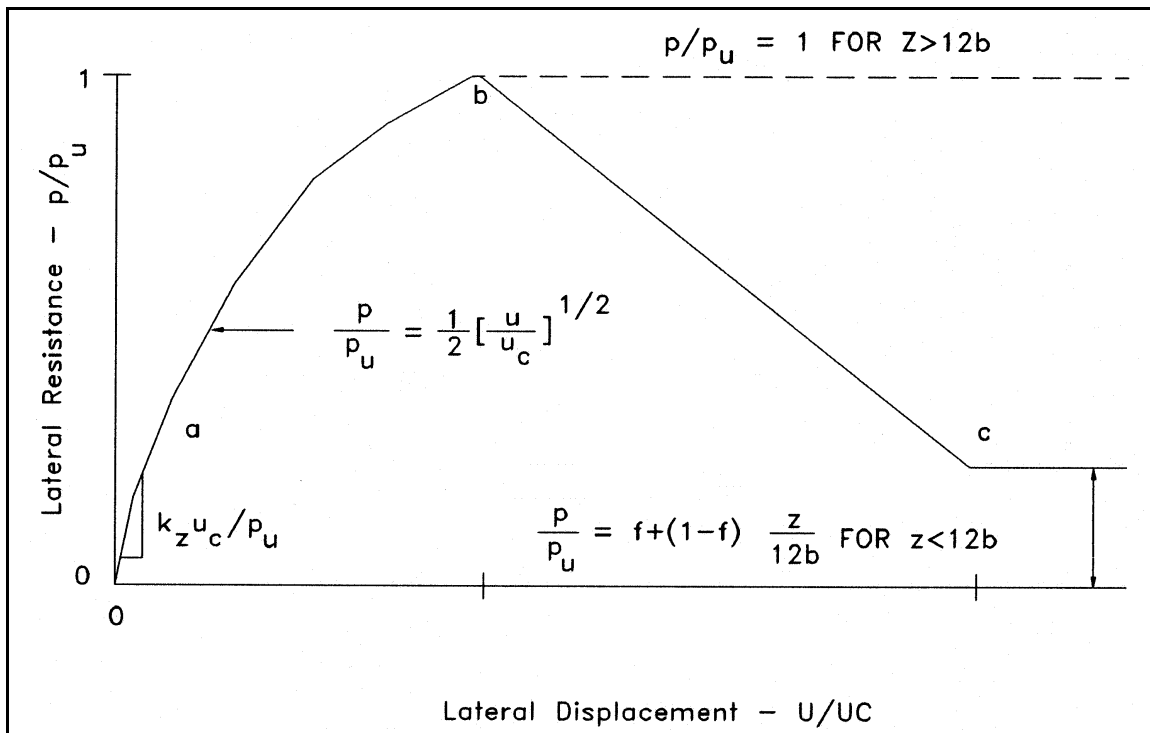


Figure 34. p - u curve by Method CLAT4 for static loading

a. The ultimate lateral resistance is

(1) For $z < 12b$, the ultimate resistance is the smaller of

$$p_u = \left(2 + \frac{\bar{\sigma}_v}{c_a} + 0.833 \frac{z}{b} \right) c_a b \quad (68)$$

$$p_u = \left(3 + 0.5 \frac{z}{b} \right) cb \quad (69)$$

where

$\bar{\sigma}_v$ = average effective vertical stress over the depth z

c_a = average cohesion over the depth z

c = cohesion at depth z

b = pile diameter

(2) For $z > 12b$, the ultimate resistance is

$$p_u = 12cb \quad (70)$$

b. Compare the properties of the soil profile under analysis with those listed in Table 5 and select the values of parameters A and F to be used in the following calculations.

c. The p - u relationship for the initial linear segment is

$$\frac{p}{p_u} = kz \quad (71)$$

where k is a stiffness parameter from Table 6 (see also Table 4).

d. The exponential segment ab is obtained from

$$\frac{p}{p_u} = 0.5 \left(\frac{u}{u_c} \right)^{1/2} \quad (72)$$

with

$$u_c = A\epsilon_{50}b \quad (73)$$

Table 5 Curve Parameters for Method CLAT4		
	Curve Parameters	
Clay Description	A	F
Soft, inorganic, intact Cohesion = 300 psf = 0.7% Overconsolidation ratio = 1 Sensitivity = 2 Liquid limit = 92 Plasticity index = 68 Liquidity index = 1	2.5	1.0
Stiff, inorganic, very fissured Cohesion = 2,400 psf = 0.5% Overconsolidation ration > 10 Sensitivity = 1 Liquid limit = 77 Plasticity index = 60 Liquidity index = 0.2	0.35	0.5

Table 6 Representative Values of k for Method CLAT4	
Cohesion (psf)	k (pci)
200-500	30
500-1,000	100
1,000-2,000	300
2,000-4,000	1,000
4,000-8,000	3,000

- e. The second linear portion extends from a displacement $u = 8u_c$ to a displacement $u = 30u_c$ where the lateral resistance is

$$\frac{p}{p_u} = F + (1 - F) \frac{z}{12b} \quad (74)$$

for $z < 12b$. For $z > 12b$, $p/p_u = 1$.

The p - u curve by the unified method for cyclic loading, Figure 35, also consists of an initial linear segment, followed by an exponential variation of p with u , a second linear segment, and a constant resistance for large displacements. Construction of the curve for cyclic loading follows the same steps as for the static curve, with the exceptions that the exponential segment terminates at a resistance equal to one half of p_u , the second linear segment terminates at a displacement $u = 20u_c$, and the constant resistance for $u > 20u_c$ is given by

$$\frac{p}{p_u} = 0.5 \left(\frac{z}{12b} \right) \quad (75)$$

for $z < 12b$. For $z > 12b$, $p/p_u = 1$.

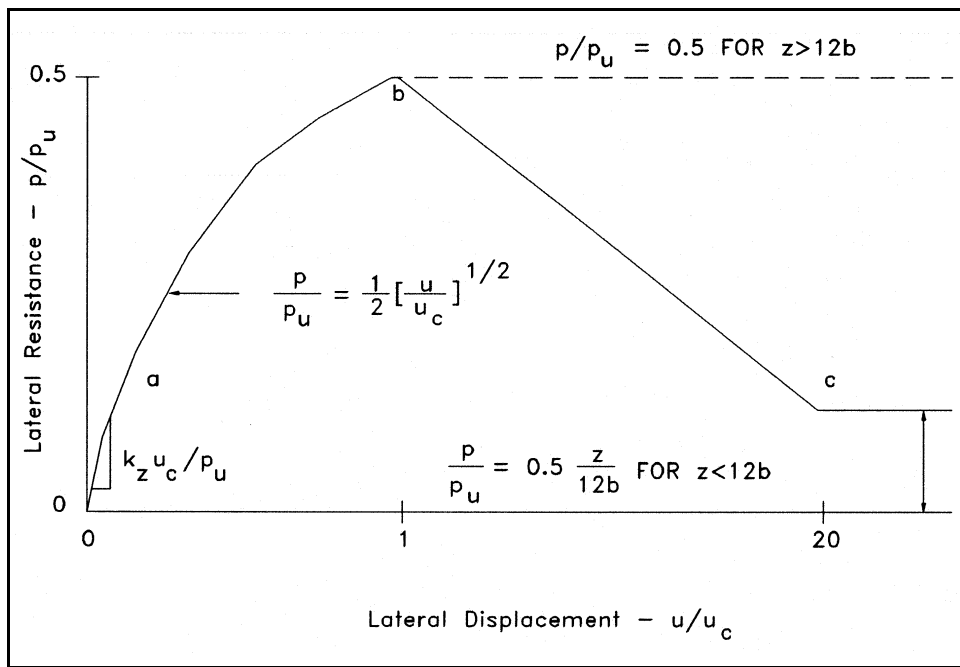


Figure 35. p - u curve by Method CLAT4 for cyclic loading

O'Neill and Gazioglu (1984)

Although the procedure presented as Method CLAT4 attempted to provide a unified criterion for all clays, the procedure requires the user to select parameters a priori which essentially convert the method to a soft-clay-like method or to a stiff-clay-like method (O'Neill and Gazioglu 1984). O'Neill and Gazioglu

reexamined the data utilized in developing the previous methods as well as the results of other tests of instrumented laterally loaded piles in clay to produce an integrated procedure for p - u curves for piles in clay. The method attempts to incorporate continuum effects and relative pile/soil stiffness characteristics which were not explicitly accounted for in the previous procedures.

O'Neill and Gazioglu, as well as other researchers, reasoned that there exists a critical length of pile such that longer piles no longer influence the pile head behavior. This critical length is presented as

$$L_c = 3 \left(\frac{EI}{E_s b^{1/2}} \right)^{0.286} \quad (76)$$

where EI = flexural stiffness of the pile; and E_s = "perhaps a secant Young's modulus at a deviator stress level of one-half of the deviator stress at failure in undrained triaxial compression," with all length units in inches. E_s is evaluated for the average UU triaxial shear strength between the ground surface and the depth L_c . Hence the determination of L_c is an iterative process. Representative values of E_s are given in Table 7.

Table 7 Soil Modulus for Method CLAT5	
Undrained Shear Strength c (psf)	Soil Modulus E_s (psi)
<500	50
500 - 1,000	50 - 150
1,000 - 2,000	150 - 450
2,000 - 4,000	450 - 1,500
4,000 - 8,000	1,500 - 5,000
>8,000	5,000

The reference lateral displacement u_c (see Equations 53, 58, 62, and 73) is obtained from

$$u_c = A' \epsilon_{50} b^{1/2} \left(\frac{EI}{E_s} \right)^{1/8} \quad (77)$$

where A' = constant taken as 0.8 by O'Neill and Gazioglu; E_s = soil modulus from Table 7 for the depth of interest; and all length units are in inches.

The ultimate soil resistance is expressed as

$$p_u = FN_p cb \quad (78)$$

where F = reduction factor from Table 8 for the appropriate loading condition;
and N_p is given by

$$N_p = 3 + 6 \frac{z}{z_{cr}} \leq 9 \quad (79)$$

Table 8 Soil Degradability Factors				
Factor	Loading Condition	UU Triaxial Compression Failure Strain		
		<0.02	0.02-0.06	>0.06
F_s	Static	0.50	0.75	1.00
F_c	Cyclic	0.33	0.67	1.00

where $z_{cr} = L_c/4$, indicating a transition from wedge type failure to flow failure at a depth equal to one fourth the critical length which, unlike the previous methods, reflects the relative pile/soil stiffness.

The p - u curves for static load (Figure 36) and cyclic loads (Figure 37) have an initial exponential relationship between lateral resistance and displacement given by

$$\frac{p}{p_u} = 0.5 \left(\frac{u}{u_c} \right)^{0.387} \quad (80)$$

with the static curve terminating at $p/p_u = 1$ and the cyclic curve at $p/p_u = 0.5$. The second linear section of the curves terminates at

$$\frac{p}{p_u} = F_s + (1 - F_s) \frac{z}{z_{cr}} \quad (81)$$

and the cyclic curve at

$$\frac{p}{p_u} = 0.5F_c \frac{z}{z_{cr}} \quad (82)$$

where F_s and F_c are given in Table 8.

Algorithm for Analysis of Laterally Loaded Piles

The p - u curves described in the preceding paragraphs were derived on the assumption that the lateral resistance p at any point on the pile is a function only of the lateral displacement u at that point (i.e., the Winkler assumption). For this assumption and the one-dimensional model of the pile-soil system shown in

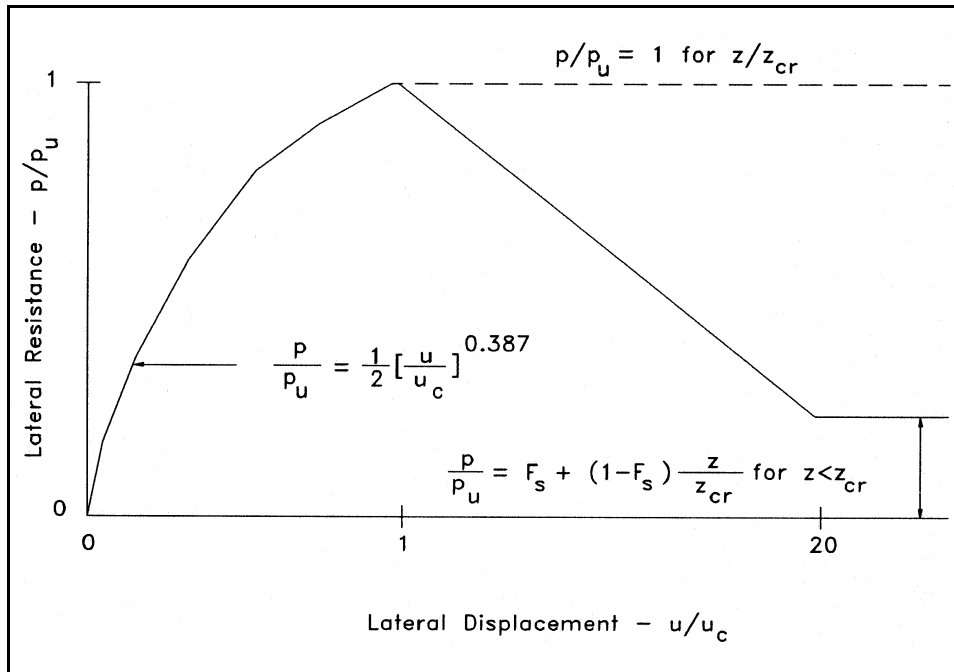


Figure 36. p - u curve by Method CLAT5 for static loading

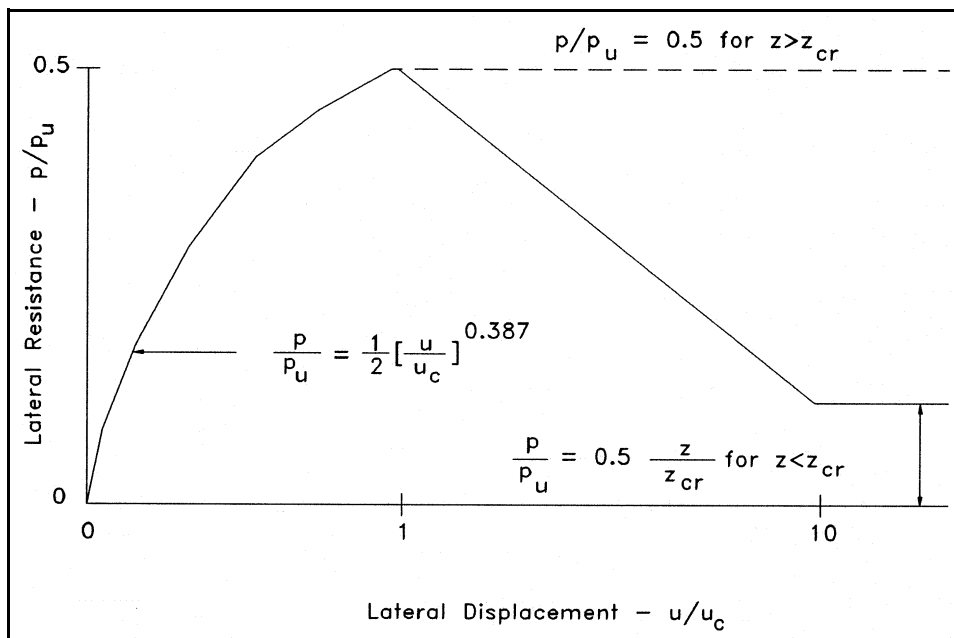


Figure 37. p - u curve by Method CLAT5 for cyclic loading

Figure 38, the governing differential equation for bending in the x - z plane of a prismatic, linearly elastic pile is

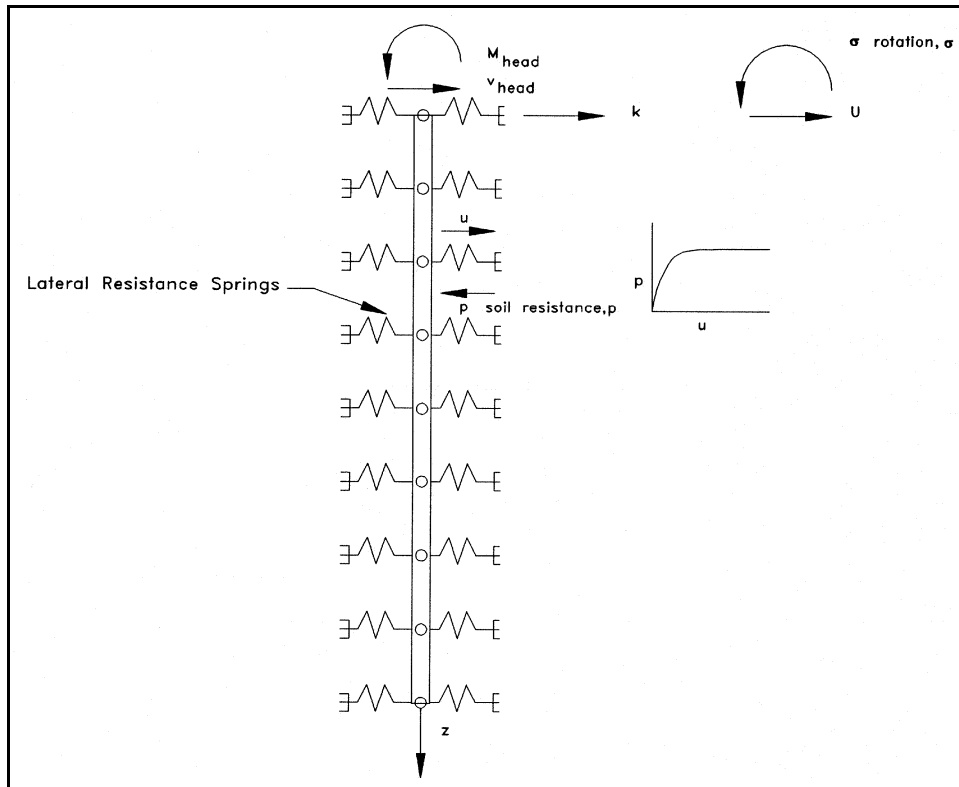


Figure 38. Model of laterally loaded pile

$$\frac{d^2}{dz^2} \left(EI \frac{d^2 u}{dz^2} \right) + \frac{d}{dz} \left[P(z) \frac{du}{dz} \right] - p(z,u) = 0 \quad (83)$$

where

E = modulus of elasticity of the pile material

I = moment of inertia of pile cross section about an axis perpendicular to the x-z plane

$P(z)$ = axial compressive force in the pile at z

$p(z,u)$ = lateral resistance which is a function of both position z on the pile and the lateral displacement u at z

Because the displacement u must be known before the lateral resistance p can be evaluated, numerical iterative solutions of Equation 83 are required. The most common approach is to represent the pile-soil system by a discretized model such as illustrated in Figure 38 where the displacements and forces are evaluated at a finite number of points (Matlock and Reese 1962, Dawkins 1982). The solution proceeds as a succession of trials and corrections until forces and displacements are compatible at every node.

Observations of System Behavior

Obtaining the numerical solutions described above is expedited by replacing the nonlinear p - u curve by equivalent linearly elastic springs during each iteration. The stiffnesses of these linear springs are evaluated as the secant to p - u curve for the displacements calculated during the preceding iteration. It is to be noted that the ultimate lateral resistance tends to increase with depth, while the pile displacements decrease as z increases. Hence it can be concluded that the secant stiffness of the lateral resistance increases with depth below the pile head. Consequently if the distribution of soil stiffnesses along the pile can be determined, the behavior may be evaluated for working loads without the need for iterative solutions.

The second term in Equation 83 represents the interaction of the axial load in the pile with the lateral displacement to increase the bending moments in the pile (the “beam-column” effect). Distribution of the axial load is not influenced significantly by lateral loading; hence, the distribution may be determined using the axial load analysis techniques described in Chapter 2 before a lateral load analysis is performed. In usual pile-soil systems, the beam-column effect is small and conservative estimates of its influence may be obtained by taking the axial force in the pile equal to the applied head load P_o .

Linearly Elastic Analyses

A linear relationship between lateral resistance and lateral displacement is expressed by

$$p(z,u) = -E_z(z)u \quad (84)$$

where $E(z)$ = secant stiffness of the lateral resistance and the minus sign indicates that the resistance is opposite in direction to the displacement. For a prismatic pile with constant axial force and a linear resistance function, Equation 83 becomes

$$EI \frac{d^4 u}{dz^4} + P_o \frac{d^2 u}{dz^2} + E_z(z)u = 0 \quad (85)$$

Even with the simplifications inherent in Equation 85, explicit closed form solutions are not possible unless the lateral resistance stiffness is constant with depth. Although the lateral resistance is not constant, insight into the lateral load behavior can be gained from the solution for constant E_z . In this case the differential equation becomes

$$EI \frac{d^4 u}{dz^4} + P_o \frac{d^2 u}{dz^2} + E_z u = 0 \quad (86)$$

The solution of Equation 86 (Hetenyi 1946) is

$$u = e^{-az/T} \left(C_1 \cos \frac{bz}{T} + C_2 \sin \frac{bz}{T} \right) + e^{az/T} \left(C_3 \cos \frac{bz}{T} + C_4 \sin \frac{bz}{T} \right) \quad (87)$$

where C_1 , C_2 , C_3 , and C_4 are constants to be determined from conditions at the pile head and tip; and

$$T^4 = \frac{4EI}{E_z} \quad (88)$$

$$a^2 = 1 - \lambda^2 \quad (89)$$

$$b^2 = 1 + \lambda^2 \quad (90)$$

$$\lambda^2 = \left(\frac{P_o T^2}{4EI} \right) < 1 \quad (91)$$

For a sufficiently long pile (see Page 51) conditions at the pile tip have no effect on the response at the pile head. In this case the relationship between loads (M_o , V_o) and displacements (u_o , ρ_o) at the pile head may be expressed as

$$\begin{Bmatrix} M_o \\ V_o \end{Bmatrix} = \frac{EI}{T} \begin{bmatrix} \frac{2}{T^2} \sqrt{(1 - \lambda^2)} & \frac{1}{T} \\ \frac{1}{T} & \sqrt{(1 - \lambda^2)} \end{bmatrix} \begin{Bmatrix} u_o \\ \rho_o \end{Bmatrix} \quad (92)$$

For a value of $\lambda^2 = 1/2$, the determinant of the coefficient matrix in Equation 92 is zero, indicating that an axial head load

$$P_o = (E_s EI)^{1/2} \quad (93)$$

is the buckling load for the long pile. Hetenyi (1946) gives the buckling load for a finite length pile with both ends fixed against displacement as less than or equal to

$$P_o = 4\pi^2 \frac{EI}{L^2} + 2(E_z EI)^{1/2} \quad (94)$$

For usual pile-soil systems the axial head load must be significantly less than the value given by Equation 93 in order to prevent overstress of the pile material at the head. Hence λ^2 is always considerably less than 1, so that the beam-column effect may be neglected and the second term of Equations 83, 85, and 86 may be omitted. Consequently, the governing differential equation for elastic analyses becomes

$$EI \frac{d^4 u}{dz^4} + E_s(z)u = 0 \quad (95)$$

Variation of Lateral Resistance Stiffness

In order to utilize Equation 95 for analysis of laterally loaded piles the variation and magnitude of the lateral resistance stiffness must be known. Terzaghi (1955) provides “coefficients of horizontal subgrade reaction” for constant E_z for clay (Table 9) and for E_s varying linearly with depth ($E_s(z) = n_h z$) for sand (Table 10). The work of Skempton (1951) has been extended to piles in homogeneous soft clays to evaluate E_s as

$$E_s = \frac{c_u}{5\epsilon_{50} b} \quad (96)$$

Table 9 Values of E_s for 1-ft-Wide Piles in Precompressed Clay			
Consistency of Clay	Stiff	Very Stiff	Hard
Values of c_u (tsf)	1-2	2-4	>4
Range of E_s (tcf)	33-67	67-133	>133
Proposed value of E_s (tcf)	50	100	200

Table 10 Values of Constant of Horizontal Subgrade Reaction n_h for a 1-ft-Wide Pile in Sand			
Relative Density	Loose	Medium	Dense
n_h (tcf) for dry or moist sand	7	21	56
n_h (tcf) for submerged sand	4	14	34

The p - u curves discussed previously provide an indication of the variation of E_s with depth. For both clays and sands, the ultimate resistance used for constructing the p - u curves increases with depth near the ground surface. At some depth, the ultimate resistance for clays reaches a limiting value. Considering that the lateral displacements of the pile decrease exponentially with depth (see Equation 87), it seems probable that the secant stiffness of the lateral reaction for both sands and clays increases as some exponential function with depth of the form (Matlock and Reese 1962).

$$E_z(z) = K_o + Kz^n \quad (97)$$

The stiffness of sand at the ground surface will be zero; hence, K_o will be zero. Although the p - u curves for clays suggest that K_o will not be zero, it is conservative to take K_o as zero for these materials. Therefore, the elastic solutions presented in the following paragraphs will take K_o to be zero in all cases.

Although explicit solutions of Equation 95 exist for E_s constant with depth ($n = 0$, $E_s = K$ in Equation 97), all solutions are presented in graphical form. Following the procedures of Matlock and Reese (1962) the following non-dimensional parameters are defined

$$T^{n+4} = \frac{EI}{K} \quad (98)$$

$$Z = \frac{z}{T} \quad (99)$$

$$Z_{\max} = \frac{L}{T} \quad (100)$$

$$u = \frac{V_o T^3}{EI} A_u(Z) + \frac{M_o T^2}{EI} B_u(Z) \quad (101)$$

where V_o and M_o are the applied head shear and moment, respectively; and $A_u(Z)$ and $B_u(Z)$ are nondimensional functions of the nondimensional depth Z .

Substitution of Equations 97 through 101 into Equation 95 yields

$$\frac{d^4 A_u(Z)}{dZ^4} + Z^n A_u(Z) = 0 \quad (102)$$

and

$$\frac{d^4 B_u(Z)}{dZ^4} + Z^n B_u(Z) = 0 \quad (103)$$

With solutions of Equations 102 and 103 available, the displacement at any point on the pile is obtained from Equation 136 and the slopes of the pile, the bending moments, and shears are evaluated from the derivatives of u as

$$\rho = \frac{du}{dz} = \frac{V_o T^2}{EI} A_s(Z) + \frac{M_o T}{EI} B_s(Z) \quad (104)$$

$$M = EI \frac{d^2u}{dz^2} = V_o T A_m(Z) + M_o B_m(Z) \quad (105)$$

$$V = EI \frac{d^3u}{dz^3} = V_o A_v(Z) + \frac{M_o}{T} B_v(Z) \quad (106)$$

The various functions of A and B are plotted in Appendix A (Figures B1 through B24) for constant, linear, and parabolic variations of E_z with depth ($n = 0, 1,$ and $2,$ respectively, in Equation 96).

Pile Head Stiffness Coefficients for Lateral Loading

Pile head stiffness coefficients for lateral loading are obtained by inverting Equations 100 and 101 with $Z = 0$ as shown in the following matrix equation

$$\begin{Bmatrix} V_o \\ M_o \end{Bmatrix} = \frac{EI}{T^3(A_{uo}B_{so} - A_{so}B_{uo})} \begin{bmatrix} B_{so} & -TB_{uo} \\ -TA_{so} & T^2A_{uo} \end{bmatrix} \begin{Bmatrix} u_o \\ \rho_o \end{Bmatrix} \quad (107)$$

where

$$A_{uo} = A_u(Z = 0)$$

$$B_{uo} = B_u(Z = 0)$$

$$A_{so} = A_s(Z = 0)$$

$$B_{so} = B_s(Z = 0)$$

The coefficients A_{uo} , B_{uo} , A_{so} , and B_{so} are shown for various relative pile lengths Z_{max} in Appendix B (Figures B25 through B28). The following items should be noted: (a) $A_{so} = B_{uo}$; (b) piles with $Z_{max} < 2$ may be treated as rigid (see page 76); and (c) The A and B coefficients remain constant for $Z_{max} \geq 4$.

As noted on page 59, piles with $Z_{max} \geq 4$ may be treated as inflexible. In this case the lateral displacement at any depth may be expressed in terms of the pile head displacements as

$$\mathbf{u} = \mathbf{u}_o + \rho_o z \quad (108)$$

and the soil resistance at that point is

$$\mathbf{p} = Kz^n \mathbf{u} = Kz^n (\mathbf{u}_o + \rho_o z) \quad (109)$$

From an equilibrium analysis of the rigid pile, the head shear and moment are given in terms of the head displacements by

$$\begin{Bmatrix} M_o \\ V_o \end{Bmatrix} = KL^{n+1} \begin{bmatrix} \frac{1}{n+1} & \frac{L}{n+2} \\ \frac{L}{n+2} & \frac{L^2}{n+3} \end{bmatrix} \begin{Bmatrix} \mathbf{u}_o \\ \rho_o \end{Bmatrix} \quad (110)$$

Evaluation of Linear Lateral Soil Resistance

In order to apply the linearized solutions described in the preceding paragraphs, the variation and magnitude of the lateral soil resistance stiffness must be evaluated. Terzaghi (1955) provides estimates of clay soil stiffness constant with depth ($n = 0$) and sand soil stiffness varying linearly with depth ($n = 1$) as shown in Tables 9 and 10. (Note: Terzaghi states that the soil stiffness values are for a “1 foot wide pile” and in order to apply these values to piles of different widths the stiffness for the 1-ft-wide pile must be divided by the actual width of the pile. In order to utilize the resulting “horizontal subgrade modulus” in the linearized analysis, Terzaghi's modulus must be multiplied by the width of the pile in contact with the soil (see Hetenyi 1941). Consequently the moduli given by Terzaghi may be used without alteration as the value of K in the linearized equations.)

Because the laterally loaded pile-soil system is highly nonlinear, particularly under large loads, immutable pile head stiffness coefficients do not exist. Although the soil stiffness moduli given in Tables 9 and 10 can be used to evaluate explicit coefficients, these values must be interpreted as only first approximations. Higher approximations may be obtained by combining the nondimensional solutions with the nonlinear p - u curves discussed earlier (Reese, Cooley, and Radhakrishnan 1984, “Executive Summary....”) as outlined in the following steps.

- a. Evaluate p - u curves for the appropriate soil profile. These curves should be closely spaced in the top 10 to 20 pile diameters.
- b. Estimate a variation and lateral stiffness (i.e., K and n in Equation 97) for the soil profile using Terzaghi's soil moduli. (Reese, Cooley, and Radhakrishnan (1983) suggest that a value of T (Equation 98) be assumed; Terzaghi's moduli provide a means for this assumption.)
- c. Evaluate the deflections at the locations of the p - u curves in step a using the appropriate nondimensional curves for head loads in the working range.
- d. Determine the slope of a secant line from the p - u curve for the deflection calculated for each location. This establishes the soil modulus E_z at each p - u curve location and allows E_z to be plotted versus depth z .
- e. Revise the variation and lateral soil stiffness (i.e., new K and n in Equation 97) to best approximate the curve of E_z versus z in step d .
- f. Repeat steps c , d , and e until convergence is achieved.
- g. Use the final values of K and n to calculate the pile head stiffness coefficients in Equations 107 and 110.

4 Algorithm for Analysis of Torsionally Loaded Single Piles

Three-dimensional analysis of a single pile requires a relationship between the resistance of the soil and the torsional displacement of the pile. There has been only limited investigation (O'Neill 1964, Poulos 1975, Scott 1981, Stoll 1972) of this torque-twist relation because its effect is small compared to the axial and lateral effects. Until more detailed data are available, the following simplistic relationship should be used.

It is assumed that the soil is a radially linearly elastic, homogenous medium, that the pile is prismatic and linearly elastic, and that the resistance of the soil at any point is a function only of the torsional displacement of the pile-soil interface at that point. Under these assumptions the soil in any plane perpendicular to the axis of the pile is in a state of plane, pure shear. The theory of elasticity solution for this case yields

$$\tau = \tau_o \left(\frac{R}{r} \right)^2 \quad (111)$$

and

$$v = \frac{\tau_o R^2}{2G_s r^3} \quad (112)$$

where

τ = shear stress at a radial distance r from the centerline of the pile

τ_o = shear stress at the pile-soil interface

R = radius of the pile

V = displacement perpendicular to the radial direction at r

G_s = shear modulus of the soil

If there is no slippage between the pile and soil at the interface, the tangential displacement of a point on the interface is

$$v = R\theta \quad (113)$$

where θ is the rotation of the pile. And, finally, the required relation is

$$\frac{\tau_o}{\theta} = 2G_s \quad (114)$$

The linear relationship between surface shear and pile rotation represented by Equation 113 is assumed to terminate when the surface shear τ_o reaches a limit of

$$\tau_{ou} = k_o \sigma_v \tan \delta \quad (115)$$

for sands, or

$$\tau_{ou} = \alpha s_u \quad (116)$$

for clays, where

τ_{ou} = ultimate surface shear resisting rotation of the pile about its longitudinal axis

k_o = at-rest pressure coefficient

δ = angle of pile-soil interface friction for sand

σ_o = vertical effective stress

α = an adhesion factor which may be obtained from Figure 12

s_u = shear strength of clay. The resistance to rotation remains constant at τ_{ou} for additional rotational displacement as shown in Figure 39

Elastic Analysis

So long as the surface shear is less than τ_{ou} , the entire pile-soil system is linearly elastic. The governing differential equation for torsional response of the linear pile-soil system is

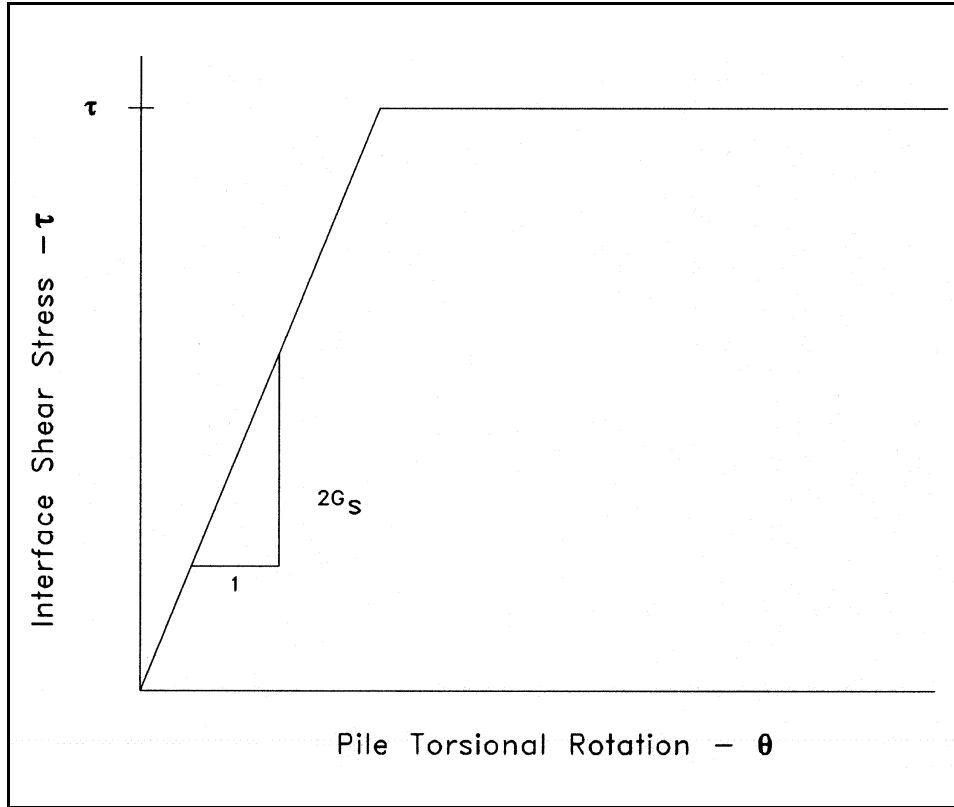


Figure 39. Proposed torsional shear - rotation curve

$$GJ \frac{d^2\theta}{dz^2} - 4\pi R^2 G_s(z)\theta = 0 \quad (117)$$

where

G = shear modulus of the pile material

J = torsional area property of the pile cross section (polar moment of inertia for a circular section)

Because Equation 116 is identical in form to the differential equation for an axially loaded pile, pile head torque-twist stiffness may be obtained from the equations and procedures appearing on pages A3-A6 of Appendix A by performing the following substitutions:

- a. In Equations A4 and A5 (in Appendix A), define $T_z = (GJ/4\pi R^2 G_s)^{1/2}$ for G_s constant with depth.
- b. In Equations A7 and A11, replace EA with GJ ; replace w_o with θ_o (the twist angle at the pile head); and, replace P_o with M_o (the torsional moment at the pile head).

- c. In Equation A16, replace EA with GJ ; replace $w(z)$ with $O(z)$; and, replace P_o with M_o .
- d. In Equation A18, replace EA with GJ ; and, define K_f such that $G_s(z) = K_f z^n$ for G_s varying with depth.

(Note: Scott (1981) indicates that the torsional resistance to twist at the pile tip may be included as was done for tip reaction for the axially loaded pile. However, in most situations the tip resistance against twist will be negligible.)

5 Pile Head Stiffness Matrix

Three-Dimensional System

Figure 40 illustrates the coordinate system, forces, and displacements at the pile head which must be considered in a three-dimensional analysis. The x- and y-axes are the principal axes of the pile cross section and the z-axis is the longitudinal axis of the pile. Forces and displacements are assumed to have positive senses in the positive coordinate directions (“right-hand rule” for moments and rotations).

For a linearly elastic system, the forces and displacements are related by

$$\begin{Bmatrix} F_x \\ F_y \\ F_z \\ M_x \\ M_y \\ M_z \end{Bmatrix} = \begin{bmatrix} b_{11} & 0 & 0 & 0 & b_{15} & 0 \\ & b_{22} & 0 & b_{24} & 0 & 0 \\ & & b_{33} & 0 & 0 & 0 \\ & & & b_{44} & 0 & 0 \\ \text{Symmetric} & & & & b_{55} & 0 \\ & & & & & b_{66} \end{bmatrix} \begin{Bmatrix} u \\ v \\ w \\ \phi \\ \rho \\ \theta \end{Bmatrix} \quad (118)$$

The b coefficient matrix array is the pile head stiffness matrix and the individual elements b_{ij} are obtained from Equations A21, 107, and 108.

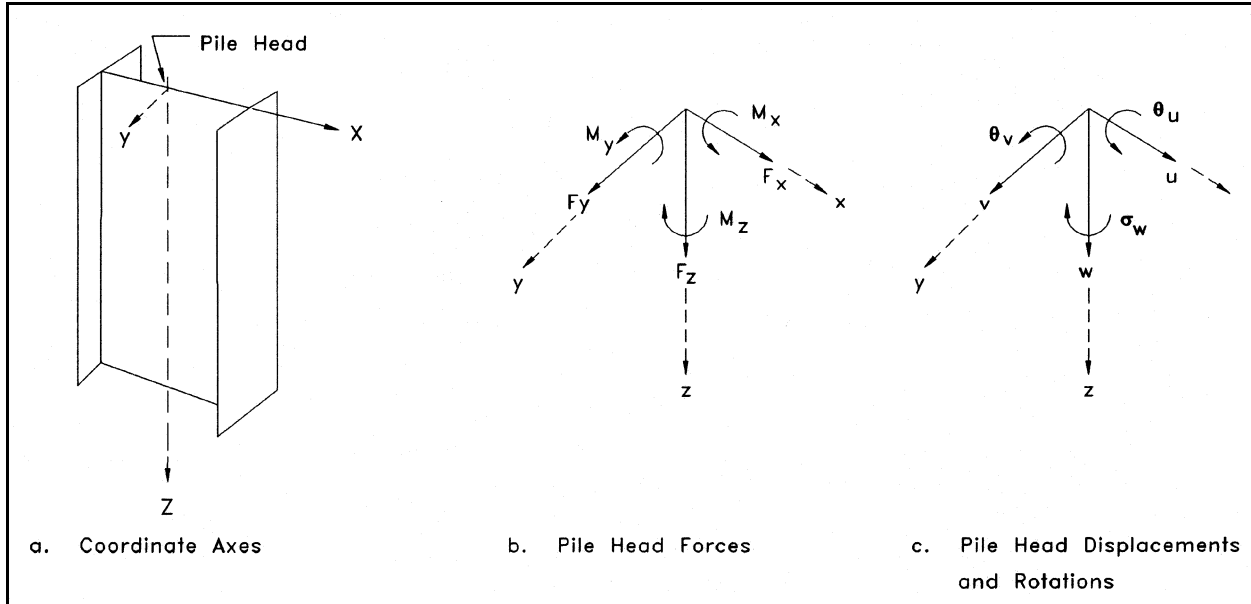


Figure 40. Notation for pile head effects

$$b_{11} = \frac{EI_y}{T_{xz}} \left(\frac{1}{A_{uo} - \frac{B_{uo}}{B_{so}} A_{so}} \right) \quad (119)$$

$$b_{15} = \frac{EI_y}{T_{xz}} \left(\frac{1}{A_{so} - \frac{B_{so}}{B_{uo}} A_{uo}} \right) \quad (120)$$

$$b_{33} = \frac{EA}{T_z a_o} \quad (121)$$

$$b_{66} = \frac{GJ}{T_z a_o} \quad (122)$$

where

E = modulus of elasticity of pile material

I_y = moment of inertia of pile cross section about y-axis

T_{xz} = length parameter for lateral loading in the x - z plane

Equation 98 coefficients A_{uo} , A_{so} , B_{uo} , and B_{so} are obtained from Figures B25 through B28 with $Z_{max} = L/T_{xz}$; terms appearing in Equation 122 are defined in Chapter 2; and, terms in Equation 123 are defined in Chapter 4. The remaining elements of the pile head stiffness matrix, b_{22} , b_{24} , b_{55} , and b_{44} , are evaluated for bending in the y - z plane.

Pile Head Fixity

If the pile head is attached to the supported structure so that the displacements of the pile head and the point of attachment on the structure undergo identical displacements, the stiffness matrix as shown in Equation 118 may be included as a part of the overall system stiffness without alteration. In most installations, the pile head and the supported structure will experience the same translational displacements (u, v, w). However, the method of connection may permit relative rotation between the structure and the pile. To illustrate the effect of relative rotation of the pile and structure, the two-dimensional system shown in Figure 38 is used. The relationship between the head forces and displacements is

$$u_o = \frac{V_o T^3}{EI} A_{uo} + \frac{M_o T^2}{EI} B_{uo} \quad (123)$$

$$\rho_o = \frac{V_o T^2}{EI} A_{so} + \frac{M_o T}{EI} B_{so} \quad (124)$$

The attendant inverse relationship, considering only the terms associated with lateral loading and the notation of Equation 119,

$$\begin{Bmatrix} v_o \\ M_o \end{Bmatrix} = \begin{bmatrix} b_{11} & b_{15} \\ b_{51} & b_{55} \end{bmatrix} \begin{Bmatrix} u_o \\ \rho_o \end{Bmatrix} \quad (125)$$

Pinned-Head Pile

If the pile-to-structure connection is such that no moment is transmitted through the connection, then M_o will be zero. For a unit lateral translation, $u_o = 1$, Equations 123, 124, and 125 yield

$$1 = \frac{V_o T^3}{EI} A_{vo} \quad (126)$$

or

$$b'_{11} = \frac{EI}{T^3} \frac{1}{A_{uo}} \quad (127)$$

and, the resulting rotation of the pile head,

$$\rho'_o = \frac{1}{T} \frac{A_{so}}{A_{uo}} \quad (128)$$

with $b'_{15} = b_{51} = b_{55} = 0$. (The prime superscript denotes the pinned head condition.)

Partial Fixity at Pile Head

Frequently the pile-structure connection permits a limited relative rotation before moment resistance at the pile head is developed. To simulate the partial fixity, it is assumed that moment resistance develops at a reduced rate proportional to the degree of fixity f ($0 \leq f \leq 1$). To evaluate the stiffness elements b_{11} and b_{51} for partial fixity, a unit value of u_o is imposed at the pile head and the rotation is allowed to increase to $(1 - f) \rho'_o$. Similarly, to evaluate b_{15} and b_{55} , $u_o = 0$ and $\rho_o = f \rho'_o$ are imposed. The resulting stiffness elements are

$$b''_{11} = \frac{EI}{T^3} \frac{1}{A_{uo}} \left(1 + \frac{f}{\frac{A_{uo}}{A_{so}} \frac{B_{so}}{B_{uo}} - 1} \right) \quad (129)$$

$$b''_{51} = b''_{15} = \frac{EI}{T^2} \frac{f}{B_{uo} - \frac{A_{uo}}{A_{so}} B_{uo}} \quad (130)$$

$$b''_{55} = \frac{EI}{T} \frac{f}{B_{so} - \frac{A_{so}}{A_{uo}} B_{uo}} \quad (131)$$

Free-Standing Pile Segment

A portion of the pile may extend above the ground surface as illustrated in Figure 41 for bending in the x - z plane. Although the free-standing segment may be considered as a part of the structure supported by the pile, it may be advantageous to combine the free-standing and embedded segments to express the relationship between forces and displacements at the pile head, point o in Figure 41, and eliminate consideration of the effects at the ground surface.

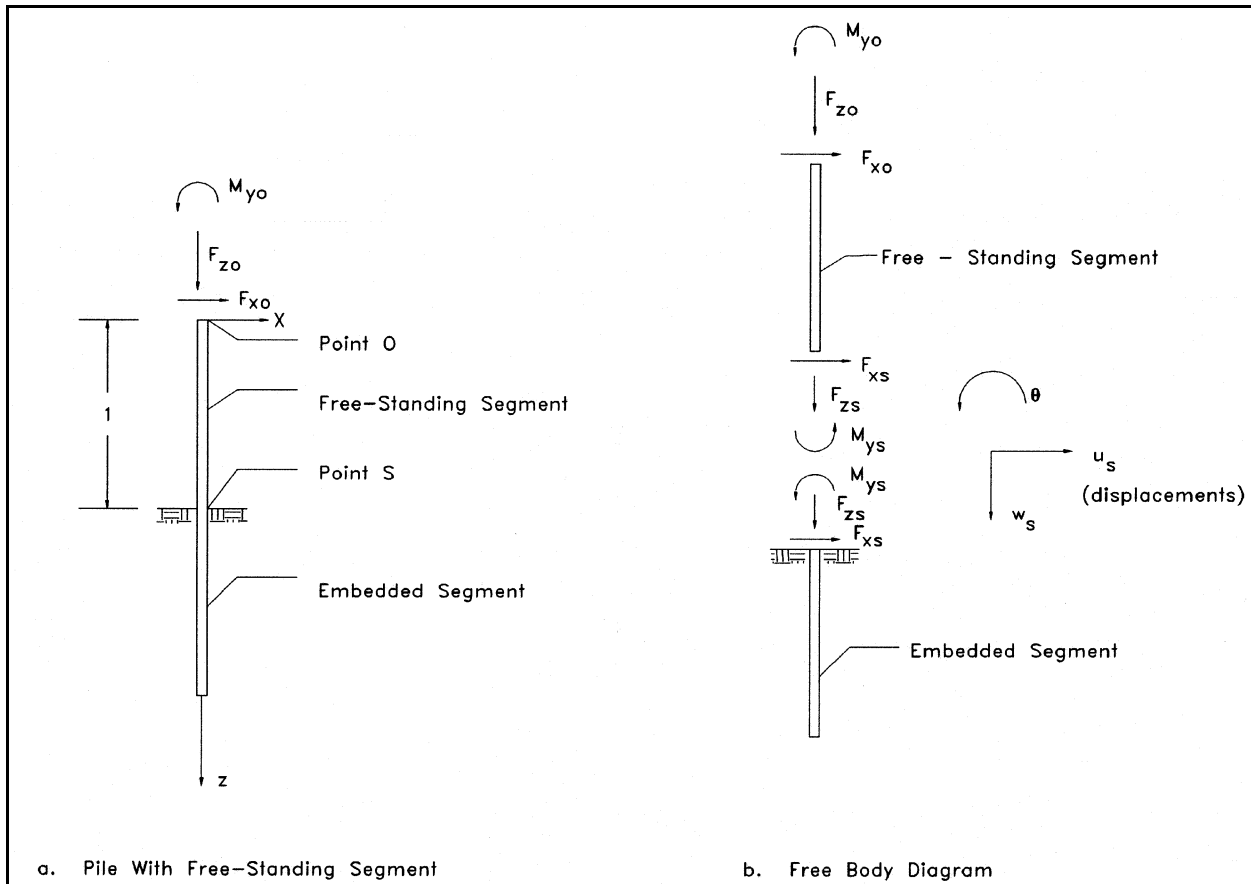


Figure 41. Linearly elastic pile/soil system with free-standing segment

The free-standing segment is not subjected to the effects of surrounding soil; hence, the relationship between end forces and end displacements for the free-standing portion is required. Using conventional beam-column element theory for the two-dimensional system in Figure 41, the free-standing segment's STIFFNESS matrix can be written as:

$$\begin{Bmatrix} F_{xo} \\ M_{yo} \\ F_{zo} \\ F_{xs} \\ M_{ys} \\ F_{zs} \end{Bmatrix} = \frac{E}{l} \begin{bmatrix} \frac{I_y(3+9f)}{l^2} & \frac{6I_y f}{l} & 0 & -\frac{I_y(3+9f)}{l^2} & \frac{3I_y(1+f)}{l} & 0 \\ & 4I_y f & 0 & \frac{6I_y f}{l} & 2I_y f & 0 \\ & & A & 0 & 0 & -A \\ & & & \frac{I_y(3+9f)}{l^2} & -\frac{3I_y(1+f)}{l} & 0 \\ & \text{Symmetric} & & & \frac{I_y(3+f)}{l} & 0 \\ & & & & & A \end{bmatrix} \begin{Bmatrix} u_o \\ \rho_o \\ w_o \\ u_s \\ \rho_s \\ w_s \end{Bmatrix} \quad (132)$$

where E , A , I_y , and l are the modulus of elasticity, cross-sectional area, moment of inertia and length, respectively, of the free-standing segment, and f is the degree of fixity between the pile head and structure at point o . For convenience, the matrices in Equation 132 are partitioned as indicated by the dashed lines and this equation may be written symbolically as

$$\begin{Bmatrix} \tilde{F}_o \\ \tilde{F}_s \end{Bmatrix} = \begin{bmatrix} \tilde{b}_{oo} & \tilde{b}_{os} \\ \tilde{b}_{so} & \tilde{b}_{ss} \end{bmatrix} \begin{Bmatrix} \tilde{U}_o \\ \tilde{U}_s \end{Bmatrix} \quad (133)$$

Similarly, the relationship between forces and displacements at point s (Figure 41) may be written as (see Equation 118)

$$\begin{Bmatrix} F_{xs} \\ M_{ys} \\ F_{zs} \end{Bmatrix} = \begin{bmatrix} b_{11} & b_{15} & 0 \\ b_{51} & b_{55} & 0 \\ 0 & 0 & b_{33} \end{bmatrix} \begin{Bmatrix} u_s \\ \rho_s \\ w_s \end{Bmatrix} \quad (134)$$

or

$$\tilde{F}_s = \tilde{b}_s \tilde{U}_s \quad (135)$$

Because there are no external forces at point s , Equations 133 and 135 may be combined to obtain

$$\tilde{F}_o = \tilde{b}_{oo}\tilde{U}_o + \tilde{b}_{os}\tilde{U}_s \quad (136)$$

$$\tilde{F}_s = \mathbf{0} = \tilde{b}_{so}\tilde{U}_o + (\tilde{b}_{ss} + \tilde{b}_s)\tilde{U}_s \quad (137)$$

From Equation 137

$$\tilde{U}_s = -(\tilde{b}_{ss} + \tilde{b}_s)^{-1} \tilde{b}_{so}\tilde{U}_o \quad (138)$$

And substitution of Equation 138 into Equation 136 yields

$$\tilde{F}_o = \left[\tilde{b}_{oo} - \tilde{b}_{os}(\tilde{b}_{ss} + \tilde{b}_s)^{-1} \tilde{b}_{so} \right] \tilde{U}_o = [\tilde{B}] \tilde{U}_o \quad (139)$$

where

$$[\tilde{B}] = \begin{bmatrix} b''''_{11} & b''''_{15} & 0 \\ b''''_{51} & b''''_{55} & 0 \\ 0 & 0 & b''''_{33} \end{bmatrix} \quad (140)$$

is the pile head stiffness matrix for bending in the xz -plane. A similar operation is required for bending in the yz -plane. The torsion stiffness coefficient is given by

$$b''''_{66} = \left(\frac{1}{b_{66}} + \frac{1}{GJ} \right)^{-1} \quad (141)$$

where b_{66} is the torsional coefficient for the embedded segment from Chapter 4, and G and J are shear modulus and torsional area moment of inertia, respectively, for the free-standing segment.

Alternatives for Evaluating Pile Head Stiffnesses

The most reliable means of evaluating the pile stiffness is from field tests of prototype piles. Although the coefficients relating lateral head loads and

displacements may be evaluated from lateral load tests, such tests are not routinely performed.

For complex soil conditions and/or nonprismatic piles which are not readily approximated by one of the procedures for linearly elastic systems discussed previously, the pile head stiffness matrix may be obtained with the aid of computer programs such as CBEAMC, CAXPILE, or COM624.

6 Analysis of Pile Groups

Although isolated single piles may be encountered in some applications, it is more common that a structure foundation will consist of several closely spaced piles (many building codes require a minimum of three piles in a group). The structure/pile/soil system is highly indeterminate and nonlinear. Historically, design methods have been based on numerous simplifying assumptions that render the analytical effort tractable for hand computations. The advent of the computer has allowed solutions to be obtained in which many of the simplifications of the classical design methods are no longer necessary. Synopses of some of the classical methods and more complete descriptions of the computer-based techniques are presented below.

Classical Methods for Pile Group Analysis

All of the classical methods assume that the pile cap (or super-structure) is rigid and that all loads are resisted only by axial forces in the piles. These methods attempt to allocate the superstructure loads to individual piles through the equations of static equilibrium. No direct attempt is made to determine the deformations of the system.

Moment-of-Inertia (Simplified Elastic Center) Method

A complete description of the Elastic Center method is given by Andersen (1956). For the simplified procedure presented here, it is assumed, in addition to a rigid cap, that only vertical loads are applied to the cap, that all piles are vertical, that all piles have the same axial stiffness (EA/L), and that the magnitudes of the axial loads in the piles vary linearly with distance from the centroid of the pile group. The axial load at the head of the i^{th} pile is given by

$$P_{o,i} = \frac{V}{n} \pm \frac{M_y x_i}{I_x} \pm \frac{M_x y_i}{I_y} \quad (142)$$

where

V = resultant vertical load on the cap

n = number of piles in the group

I_x, I_y = moments of inertia about x - and y -axes, respectively, through the centroid of the piles which are treated as point (unit) areas

M_x, M_y = moments of the vertical loads on the cap about the x - and y -axes, respectively

Culmann's Method

The method attributed to Culmann (see Terzaghi (1943)) requires three nonparallel subgroups of piles in the foundation. The piles within each subgroup are assumed to be parallel and are assumed to have the same head load. Each subgroup is replaced by a single pile at the centroid of the subgroup. A graphical procedure is used to resolve the superstructure load applied to the rigid cap to each subgroup.

“Analytical” Method

Teng (1962) describes a simplified procedure for including the effects of horizontal loads as well as battered piles. The vertical component of the axial force in each pile due to the resultant vertical load and moments of the superstructure on the rigid cap is calculated according to the moment of inertia method. The total axial pile load and its horizontal component may be calculated from the vertical component. Teng suggests that an adequate design has been attained if the applied horizontal foundation load does not exceed the sum of the horizontal components of axial pile forces by more than 1,000 lb/pile.

Stiffness Analysis of Pile Foundations

The classical methods described in the previous paragraphs essentially neglect the capability of the piles to resist lateral loads and do not provide a means of evaluating the stresses induced in the pile by bending and shear at the pile head. The classical methods may underestimate the strength of the foundation or may lead to an unconservative design depending on the manner in which the pile head is attached to the structure. Hrennikoff (1950) and Saul (1968) developed a direct stiffness approach to the analysis of two- and three-dimensional pile groups in which the interaction of the piles with the surrounding soil as well as compatibility of pile head and pile cap displacements is included. In this procedure, the relationship between the pile head forces and the displacements of the point of attachment to the rigid pile cap is assumed to be linear.

The two coordinate systems necessary for the direct stiffness analysis are shown in Figures 42 and 43 along with the forces and displacements on the pile cap and pile head. Relationships between the global and local axes are shown in Figure 44.

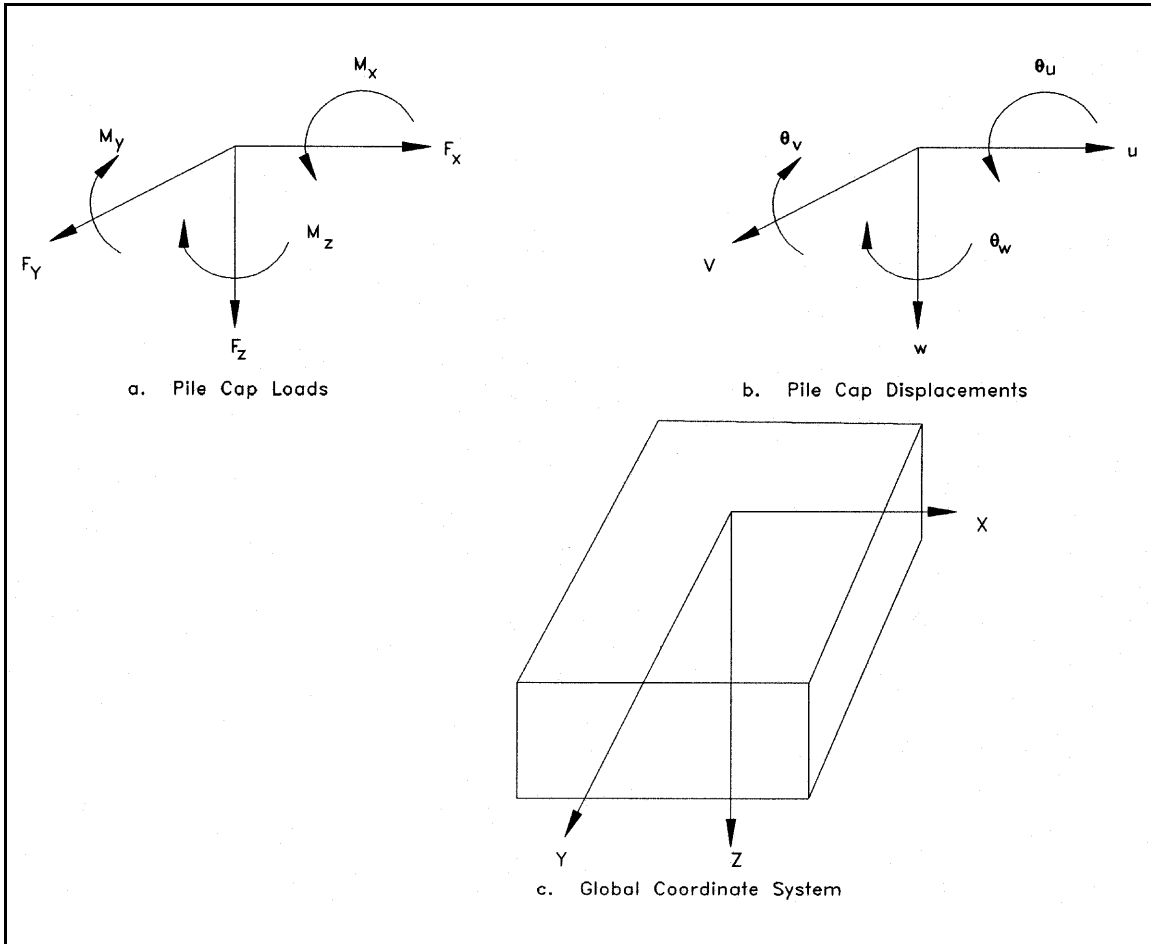


Figure 42. Pile cap loads, displacements, and coordinates

The pile head displacements in the local coordinate system for a pile are expressed in terms of the pile cap displacements by the transformation

$$\{u\}_i = [A]_i [G]_i \{U\} \quad (143)$$

where $\{u\}_i = \{u_i \ v_i \ w_i \ \phi_i \ \rho_i \ \theta_i\}^T$ = pile head displacements in the local coordinate system for the i^{th} pile; $[A]_i$, $[G]_i$ = geometric transformation matrices given by (see Figure 44 for definitions of symbols)

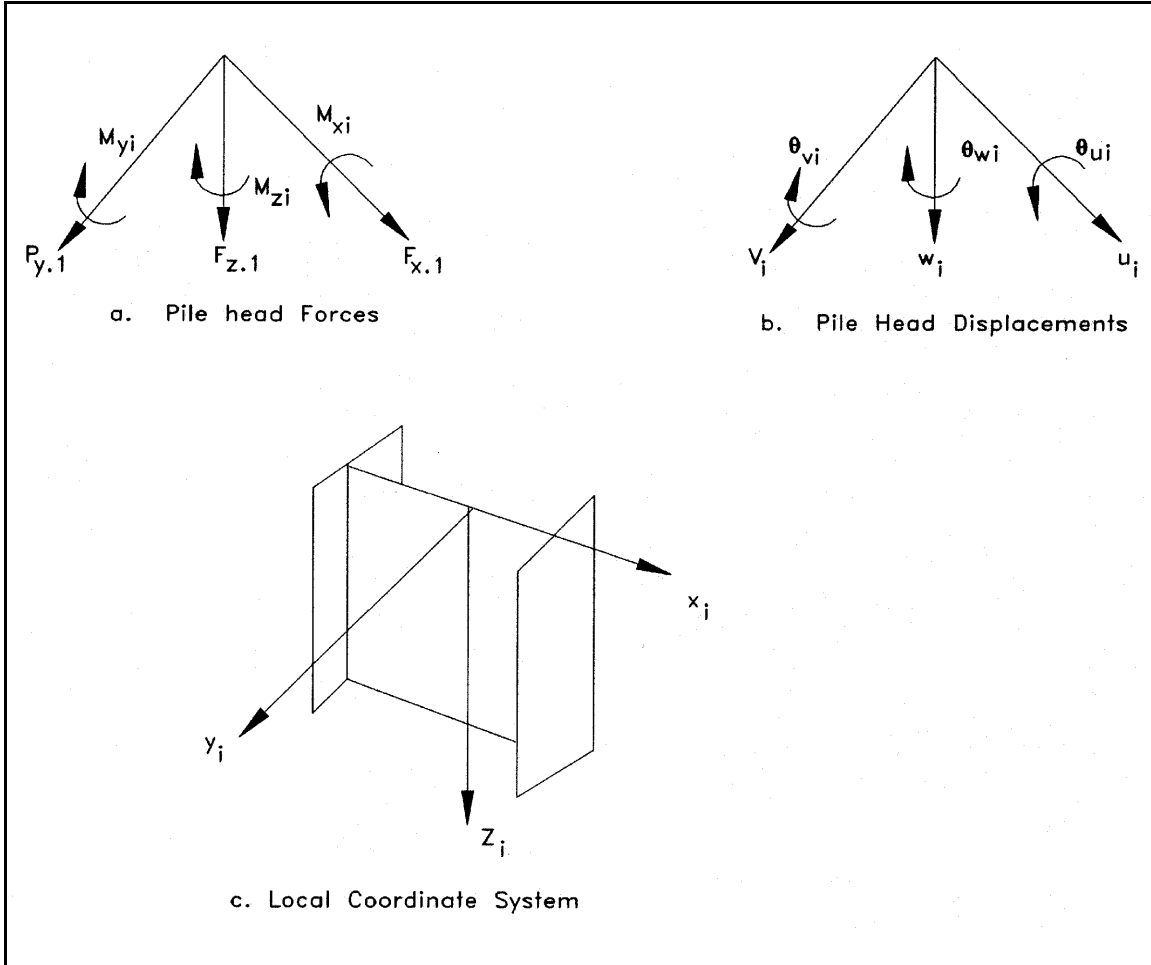


Figure 43. Head forces, displacements, and coordinates for i_{TH} pile

$$[A]_i = \begin{bmatrix}
 (\cos \beta_i \cos \alpha_i) & (\cos \beta_i \sin \alpha_i) & -\sin \beta_i & 0 & 0 & 0 \\
 -\sin \alpha_i & \cos \alpha_i & 0 & 0 & 0 & 0 \\
 (\sin \beta_i \cos \alpha_i) & (\sin \beta_i \sin \alpha_i) & \cos \beta_i & 0 & 0 & 0 \\
 0 & 0 & 0 & (\cos \beta_i \cos \alpha_i) & (\cos \alpha_i \sin \alpha_i) & -\sin \beta_i \\
 0 & 0 & 0 & -\sin \alpha_i & \cos \alpha_i & 0 \\
 0 & 0 & 0 & (\sin \beta_i \cos \alpha_i) & (\sin \beta_i \sin \alpha_i) & \cos \beta_i
 \end{bmatrix} \quad (144)$$

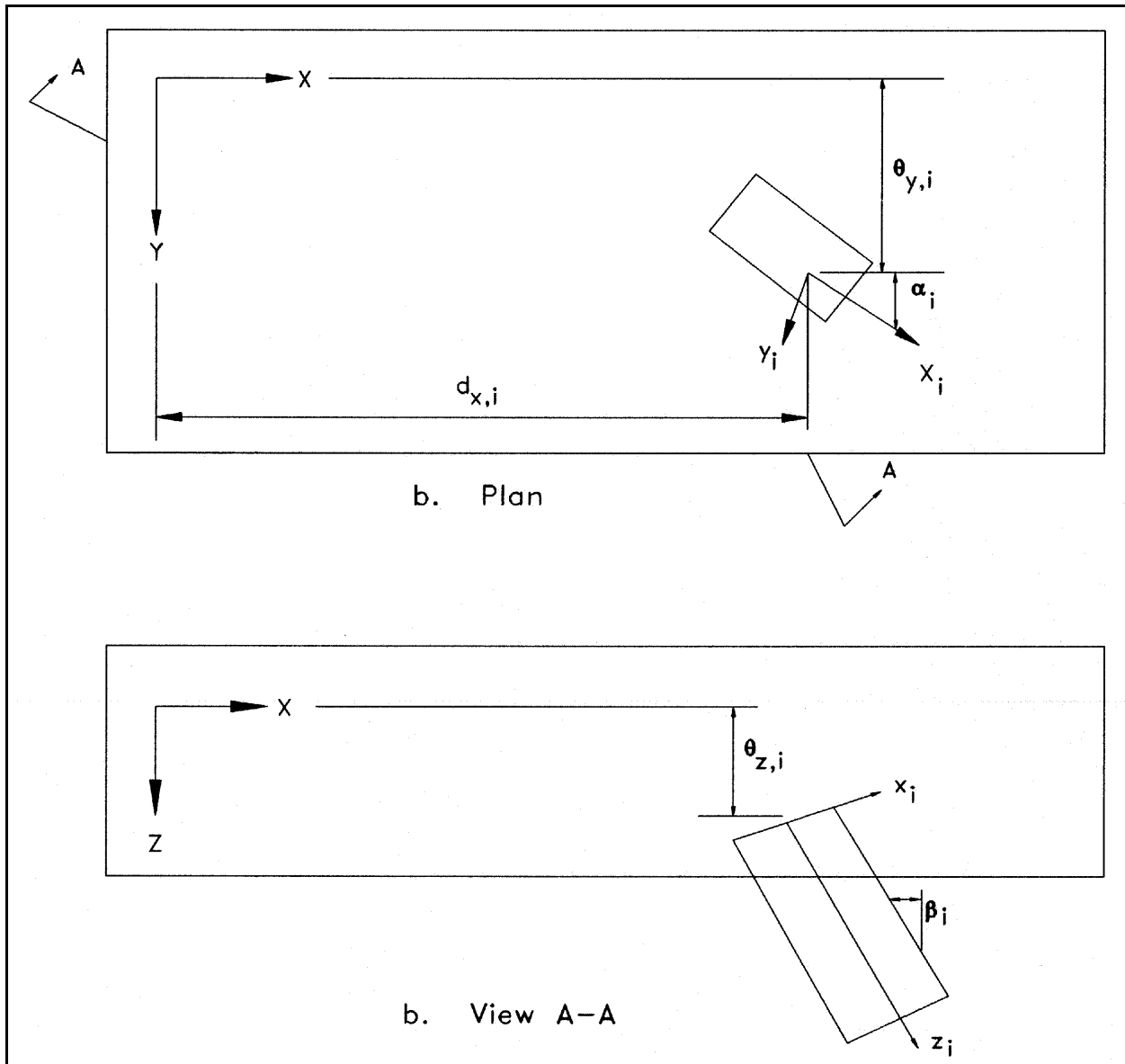


Figure 44. Relationship between global and local coordinates

$$[G]_i = \begin{bmatrix} 1 & 0 & 0 & d_{z,i} & -d_{y,i} & \\ 0 & 1 & 0 & -d_{z,i} & 0 & d_{x,i} \\ 0 & 0 & 1 & d_{y,i} & -d_{x,i} & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix} \quad (145)$$

and $\{U\} = \{U_G V_G W_G \phi_G \rho_G \theta_G\}^T =$ pile cap displacements in the global coordinate directions.

The relationship between pile cap forces and pile cap displacements is given by

$$\{F\} = \left\{ \sum_{i=1}^n [G]_i^T [A]_i^T [b]_i [A]_i [G]_i \right\} \{U\} \quad (146)$$

where $\{F\} = \{F_x F_y F_z M_x M_y M_z\}^T =$ superstructure loads on pile cap in global coordinate directions; $n =$ number of piles in the group; and, $[b]_i =$ pile head stiffness matrix for the local coordinate system described in Chapter 5.

$$(C)_i = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & -u_3 & u_2 & 1 & 0 & 0 \\ u_3 & 0 & -u_1 & 0 & 1 & 0 \\ -u_2 & u_1 & 0 & 0 & 0 & 1 \end{pmatrix} \quad (147)$$

After Equation 146 has been solved for the pile cap displacements, the head displacements and head forces in the local coordinate system for each pile are obtained from Equations 143 and 118, respectively. This method of analysis has been incorporated into the CASE computer program CPGA (Hartman et al. 1984).

The pile-soil-pile interaction (PSPI) method is identical to Saul's method in its treatment of geometric and structural analysis aspects of the pile group problem. However, its treatment of soil reactions against piles is more comprehensive and rigorous. The method was first formalized by O'Neill, Ghazzaly and Ha (1977) for the analysis of pile clusters in offshore drilling platforms. The PSPI algorithm PILGP2R automates the process of computing pile-head stiffness constants $b_{11} - b_{66}$ and b_{15} , b_{24} , and b_{42} by first developing nonlinear relationships between axial pile-head load and axial displacement, pile-head torque and twist, lateral pile-head load and displacement with zero rotation, pile-head moment and rotation with zero displacement, and the cross-coupling relationship between rotation and lateral load and between displacement and moment. Sets of lateral relationships are developed for each of two orthogonal directions to accommodate nonisotropic piles, such as H-piles. Nonlinear subroutines similar to those described in Chapters 2 and 3 are used to develop the axial and lateral relationships, respectively. Hence, the user inputs become unit load transfer curves. Torsional stiffness of individual piles is generally of minor significance in large groups of piles. For that reason special computations of torsional stiffnesses are not made, and the torsional stiffness is assumed to be equal to a constant value of $(GJ)_{pile}/2L$ throughout the computations. The piles remain linearly elastic.

Similarly,

$$(U')_i = (c)_i^T (\Delta) \quad (148)$$

where (Δ) is the vector of global deflections at the origin. By using this transformation, each pile stiffness is moved to the origin of the pile cap. By using Equations 93, 94, and 95, a single-pile force-deflection relationship can be expressed as

$$(q)_i = (c)_i (a)_i (a)_i^T (c)_i^T (\Delta) \quad (149)$$

$$(Q) = \sum_{i=1}^n (q)_i \quad (150)$$

where

(Q) = resultant external loads applied at origin of pile foundation

n = total number of piles in the foundation

This leads to the expression

$$(Q) = \sum_{i=1}^n (c)_i (a)_i (b)_i (a)_i^T (c)_i^T (\Delta) \quad (151)$$

An iterative solution is used to determine the deformation vector for the rigid pile cap. Initial b-factors are taken as the initial tangents to the various relationships described in the previous paragraph. The three-dimensional load vector is then applied, the cap deformation vector is computed, and the pile-head deformation vectors are computed. From these deformations pile-head reactions are computed from the present b-values. A check is then made of the compatibility of the reactions and deformations at each pile head using the predetermined nonlinear relationships. If compatibility in the reaction and deformation values is noted, new b-values are computed as secants to the axial and lateral pile head load-deformation relationships at the computed values of deformation, and the process is repeated as necessary until tolerance between the computed deformations and deformations on the predetermined relationships at the computed value of pile-head reaction is achieved at every pile.

Since individual, predetermined nonlinear relationships are used to represent the relationships between the various lateral deformation modes in two orthogonal directions, the solution that is thus obtained involves, in effect, superposition of nonlinear functions, which is not theoretically correct, and which may produce errors of practical magnitude as the pile-head behavior becomes highly nonlinear. However, where nonlinearity is relatively small, as would typically occur in the services load range, the errors are not significant.

Axial and lateral behavior algorithm used

Pile-soil-pile interaction is then included as indicated in Figure 45. Once the pile-head deformation is known from the preceding solution, the axial and lateral behavior algorithms are used to compute the soil reaction (axial or lateral) at every node along every pile. (In practice, only selected nodes need to be used at this stage of the calculations.) Lateral reactions are computed in two local orthogonal directions. The lumped reactions against the soil on any generic Pile J at generic Node j are then transformed into a vector of orthogonal reactions in the local coordinate system (X, Y, Z) shown in Figure 45. The additional displacements in the local X, Y, Z directions produced by these reactions on any other pile 1 in the system, denoted d_{ace} ($k = X, Y, \text{ or } Z$) in Figure 45, are then computed by using Mindlin's equations for displacements in the interior of a semi-infinite halfspace. If a rigid layer (e.g., rock) exists, the deflections computed using halfspace theory are corrected as indicated on Figure 45.

$$\begin{aligned}
 d_{Z11}^{Jj} = & \frac{Q_{Zj}}{16\pi G(1-\nu)} \frac{3-4\nu}{R_1} + \left[\frac{8(1-\nu)^2 - (3-4\nu)}{R_2} + \frac{(Z-C)^2}{R_1^3} \right. \\
 & \left. + \frac{(3-4\nu)(Z+C)^2 - 2CZ}{R_2^3} + \frac{6CZ(Z+C)^2}{R_2^5} \right] \\
 & + \frac{Q_{Xj}(X_j^i) + Q_{Yj}(Y_j^i)}{16\pi G(1-\nu)} \left[\frac{Z-C}{R_1^3} + \frac{(3-4\nu)(Z-C)}{R_2^3} \right. \\
 & \left. - \frac{6CZ(Z+C)}{R_2^5} + \frac{4(1-\nu)(1-2\nu)}{R_2(R_2+Z+C)} \right]
 \end{aligned} \tag{152}$$

$$\begin{aligned}
 d_{X11}^{Jj} = & \frac{Q_{Xj}}{16\pi G(1-\nu)} \left\{ \frac{3-4\nu}{R_1} + \frac{1}{R_2} + \frac{(X_j^i)^2}{R_1^3} + \frac{(3-4\nu)(X_j^i)^2}{R_2^3} \right. \\
 & \left. + \frac{2CZ}{R_2^3} \left[1 - \frac{3(X_j^i)^2}{R_2^2} \right] \right\} + \frac{Q_{Xj}(X_j^i)(X_j^i)}{16\pi G(1-\nu)} \left[\frac{1}{R_1^3} \right. \\
 & \left. + \frac{(3-4\nu)}{R_2^3} - \frac{6CZ}{R_2^5} - \frac{4(1-\nu)(1-2\nu)}{R_2(R_2+Z+C)^2} \right]
 \end{aligned} \tag{153}$$

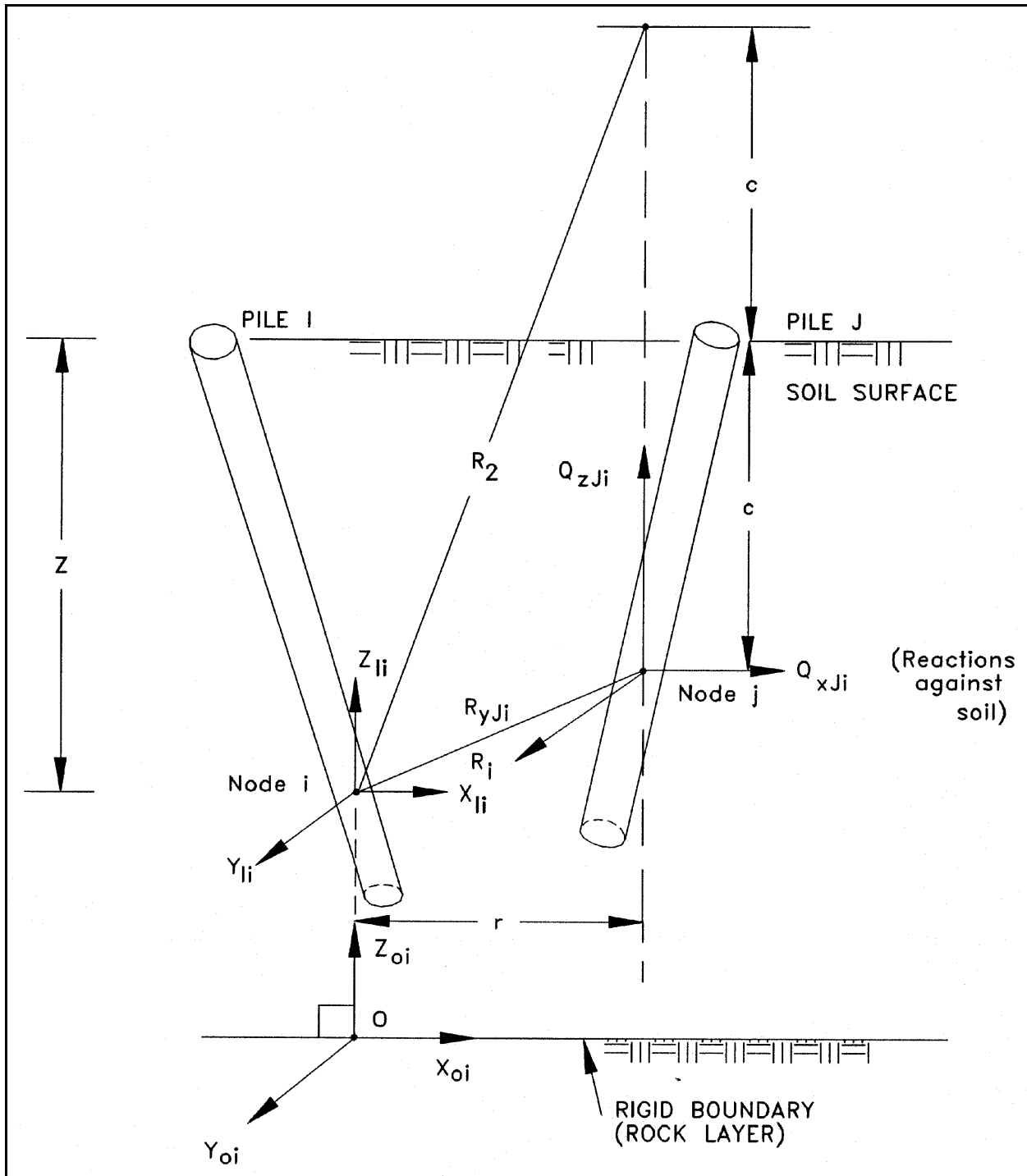


Figure 45. Geometric definitions for computation of added displacement

$$d_{Y_{II}}^{Jj} = \frac{Q_{Xj}}{16\pi G(1 - \nu)} \left\{ \frac{3 - 4\nu}{R_1} + \frac{1}{R_2} + \frac{(Y_j^i)^2}{R_1^3} + \frac{(3 - 4\nu)(Y_j^i)^2}{R_2^3} \right. \\ \left. + \frac{2CZ}{R_2^3} \left[1 - \frac{3(Y_j^i)^2}{R_2^2} \right] \right\} + \frac{Q_{Xj}(X_j^i)(X_j^i)}{16\pi G(1 - \nu)} \left[\frac{1}{R_1^3} \right. \\ \left. + \frac{(3 - 4\nu)}{R_2^3} - \frac{6CZ}{R_2^5} - \frac{4(1 - \nu)(1 - 2\nu)}{R_2(R_2 + Z + C)^2} \right]$$

It is therefore necessary for the analyst to prescribe values of Young's modulus and Poisson's ratio for the soil, which can vary linearly from the soil surface to the top of the rigid surface, and depth to the rigid surface. As with the elastic methods for axial response calculations, these moduli should generally conform to values obtained at low magnitudes of strain (O'Neill 1983).

The additional displacements at Node i, Pile I, due to reactions at all nodes on all piles other than Pile I, are then calculated and summed, and the resulting added deformations at Node i, Pile I due to PSPI are transformed back into the normal pile coordinate system. These displacements are then compared with the displacements computed initially, without considering PSPI. Adjustments are made to the unit load transfer curves ($f-w$, $Q-w$ $p-u$ in two orthogonal directions) to force the unit load transfer curves to pass through the soil displacement value defined by the sum of the initial displacement δ and the additional displacement δ' in the appropriate direction at the value of soil reaction computed initially. Specifically, the entire curve is "stretched" by multiplying all displacement values on the original curve input by the analyst by $(\delta' + \delta)/\delta$. This process is illustrated in Figure 46. It is evident that in geometrically complex groups every unit load transfer curve on every pile will be modified in a different manner. It is also evident that this procedure does not reduce the maximum unit load transfer that can occur at any node in either the axial or lateral direction; thus, it does not reduce the "capacity efficiency" of the group.

The solution for pile-cap deformations is then repeated using the modified unit load transfer curves, which produce, in general, different b matrices for each pile in the system during this pass through the solution. The regeneration of the load-deformation relationships for this second pass for every pile in the system is the source of the high computational effort required for this method compared with Saul's method and which makes it generally impractical for the design office. Once the new, compatible pile head loads and deformations have been determined, the cap deformation vector is defined, and the axial and lateral algorithms are entered with pile-head deformations as boundary conditions to compute moments, shears and axial thrusts along the piles, if desired. If greater accuracy is desired, the correction process can be repeated; however, one set of

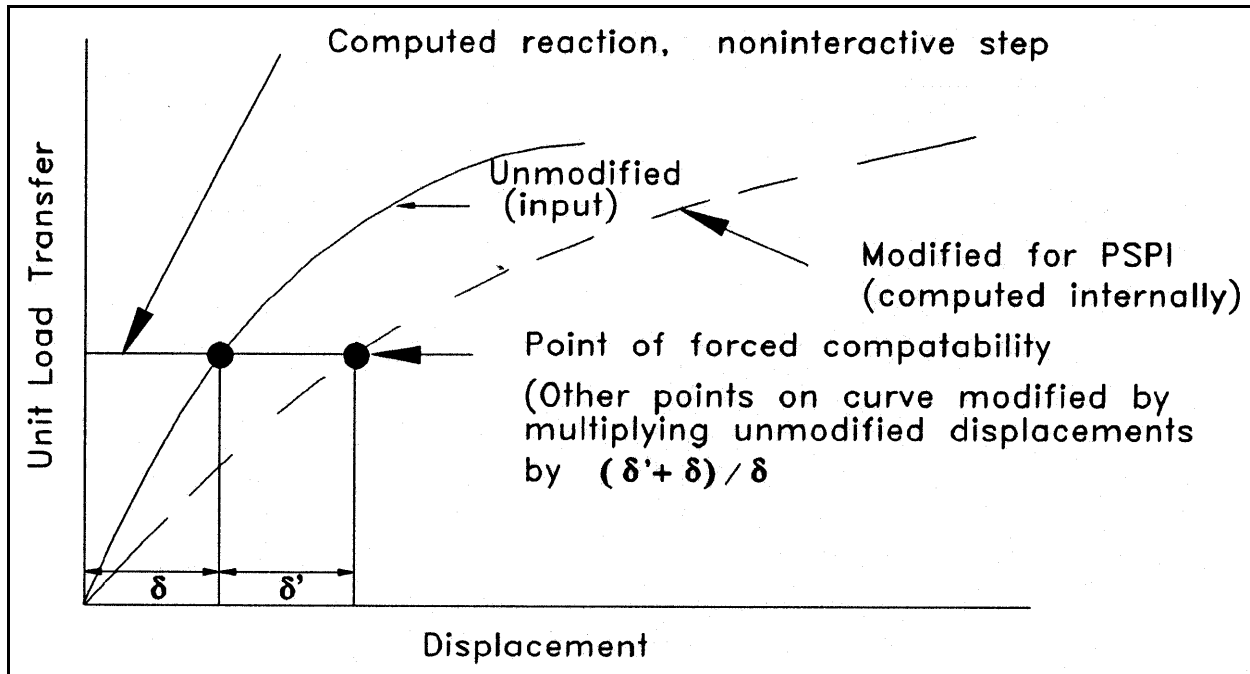


Figure 46. Modification of unit load transfer relationship for group effects at Node i, Pile I

corrections of the unit-load transfer curves appears appropriate for most problems.

Flexible pile cap analysis

The pile analysis methods described above assume that the pile cap, or structure base slab, is rigid in comparison to the stiffness of the piles. For many structures, such as U-frame lock monoliths, this is not a valid assumption, and the flexibility of the base slab should be considered. Currently there are no special-purpose programs to perform this type analysis, so the use of large general-purpose programs like SAP or STRUDL that can represent a flexible pile-cap foundation and piles must be used. The pile element used in the rigid base method has been added to several versions of the SAP and STRUDL programs. Flexible base analyses have already been performed for pile-founded structures designed by the Corps of Engineers. A more detailed report on flexible base analysis will be furnished at some future date.

Nonlinear analysis

One of the assumptions made in the rigid base analysis method is that a pile can be represented by a set of linear stiffnesses. The actual behavior of the pile-soil system may be highly nonlinear. Some existing programs are capable of nonlinear analysis of a structure that is supported by only a few piles. One such

program which may be able to economically analyze a large number of piles under a foundation using a nonlinear model is PILGP2R. However, for large structures supported by as many as 200 piles, nonlinear analysis is not currently practical. The results of the two types of analyses are very close. In O'Neil and Tsao (1984) it was found that, while nonlinearity was an insignificant effect, a rational procedure must be applied to adjusting the subgrade reaction to be able to account for PSPI in typical Corps' structures.

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Appendix A

Linear Approximations for Load Deformation of Axial Piles

Linear Elastic Analyses

For a linearly elastic representation of the pile-soil system, the governing differential equation is

$$EA \frac{d^2w}{dz^2} - E_z(z)w = 0 \quad (A1)$$

where $E_z(z)$ is the stiffness of the axial load-transfer mechanism. A typical $f-w$ curve is shown in Figure A1. At any displacement w the nonlinear $f-w$ curve may be replaced by a linear secant $k_f(z)$. The total stiffness of the load-transfer mechanism appearing in Equation A1 is given by

$$E_z(z) = 2 Rk_f(z) \quad (A2)$$

Soil Stiffness Constant with Depth

Even though Equation A1 is representative of a linearly elastic system, a closed-form solution is possible only if the side friction stiffness is constant with depth. While this condition is not encountered in most soil-pile systems, the solution for constant stiffness serves to indicate characteristics of the system behavior.

For E_z constant with depth, the solution of Equation A1 may be written as

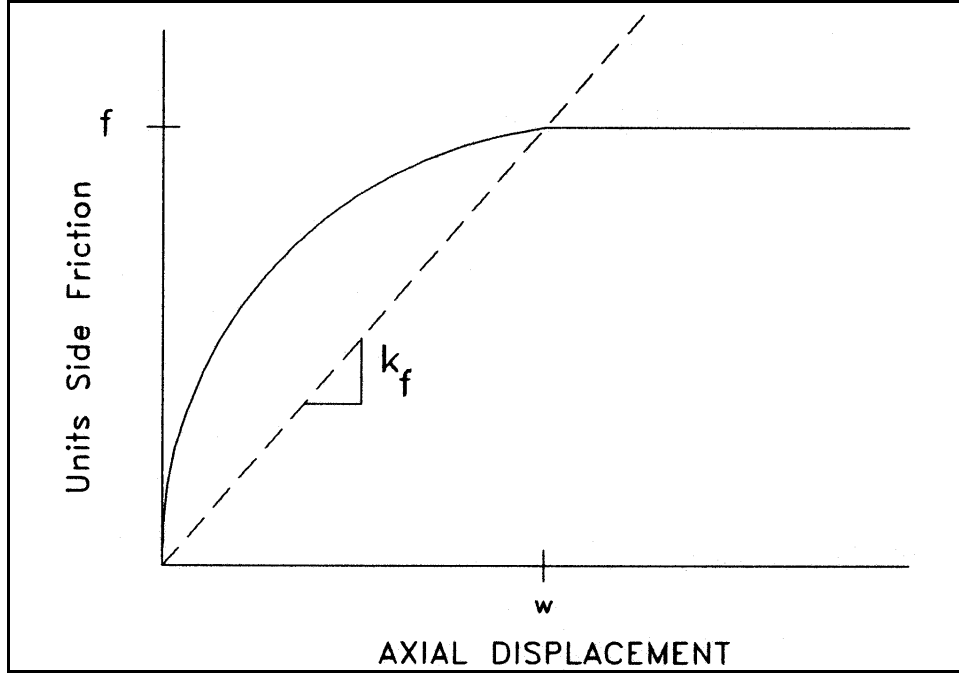


Figure A1. Typical f - w curve

$$w = \frac{P_o T_z}{EA} \left(CI \cos h \frac{z}{T_z} - \sin h \frac{z}{T_z} \right) \quad (A3)$$

where

P_o = axial compressive force at pile head

$T_z = EA/E$

CI = constant to be determined from conditions at the pile tip ($z=L$)

At the pile tip, three alternative conditions are presented:

a. Tip reaction equals zero: At $z = L$, $Q = 0$, hence

$$CI = \frac{\cos h L/T_z}{\sin h L/T_z} = \frac{\cos h Z_{max}}{\sin h Z_{max}} \quad (A4)$$

b. Tip displacement equals zero: At $z = L$, $w = 0$, hence

$$CI = \frac{\sin h Z_{max}}{\cos h Z_{max}} \quad (A5)$$

c. Tip elastically restrained: At $z = L$, $Q = K_t w_t$, hence

$$C1 = \frac{\cos h Z_{max} + r \sin h Z_{max}}{\sin h Z_{max} + r \cos h Z_{max}} \quad (A6)$$

where

$$r = K_t / E_z T_z$$

K_t = stiffness of elastic resistance at pile tip

$$Z_{max} = L / T_z$$

Pile Head Axial Stiffness

Of particular interest is the relationship between the pile head force P_o and axial displacement w_o . For convenience, this is defined by

$$a_o = \frac{EA}{T_z} \frac{w_o}{P_o} \quad (A7)$$

where

a. Pile tip free

$$a_o = \frac{\cos h Z_{max}}{\sin h Z_{max}} \quad (A8)$$

b. Pile tip fixed

$$a_o = \frac{\sin h Z_{max}}{\cos h Z_{max}} \quad (A9)$$

c. Pile tip elastically restrained

$$a_o = \frac{\cos h Z_{max} + \sin h Z_{max}}{\sin h Z_{max} + r \cos h Z_{max}} \quad (A10)$$

a_o is plotted for various values of Z_{max} in Figure A2. It is observed that for values of Z_{max} greater than 2, conditions at the tip have a negligible effect on the pile head force-displacement relationship. As will be discussed later, the pile head axial force-displacement relationship forms a part of the elastic pile head stiffness matrix used in the analysis of pile groups. The axial pile head stiffness coefficient is given by

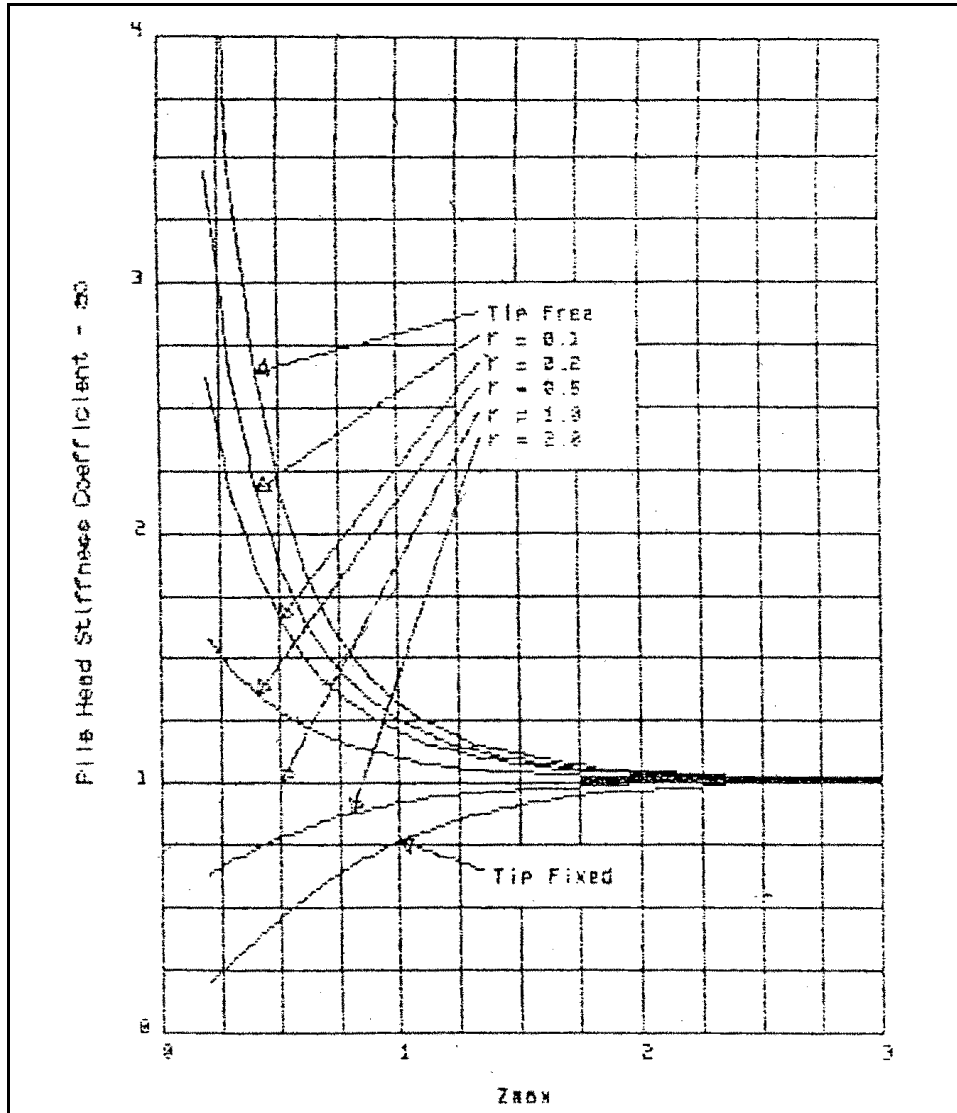


Figure A2. Axial stiffness coefficient for constant soil stiffness

$$\frac{P_o}{w_o} = \frac{EA}{T_z} \frac{1}{a_o} \quad (A11)$$

Nondimensional Analysis for Variable Soil Stiffness

As discussed earlier, the stiffness of the side friction displacement relationship increases with depth. For axial head loads in the working load range (e.g., one-half of the ultimate load), it has been found that the equivalent elastic

side friction increases approximately linearly with depth for normally consolidated clays and as the square root of the depth in homogeneous sands. In general, these variations may be expressed as

$$E_z(z) = K_o + K_f z^n \quad (A12)$$

where

K_o = elastic stiffness of the side friction effect at the ground surface

K_f = elastic stiffness coefficient of the side friction effect in units of force per unit length of pile per unit deflection

$n = 1$ for a linear variation with depth

$n = 1/2$ for variation as the square root of depth

Because the stiffness of the side friction effect is a function of the strength of the soil, K_o will be zero for sands. Some adhesion of clay soil may occur at the ground surface and K for clays may not be zero. However, it is likely that installation effects will minimize adhesion near the ground surface and a conservative estimate is obtained for $K_o = 0$. For the general variation with $K_o = 0$, the governing differential equation is

$$EA \frac{d^2w}{dz^2} - K_f z^n w = 0 \quad (A13)$$

Closed form solutions of Equation A13 do not exist. However, nondimensional solutions may be obtained with relatively simple numerical techniques as described below.

Following the procedures described by Matlock and Reese (1962), the following nondimensional parameters are defined.

$$Z = \frac{z}{T_z} \quad (A14)$$

$$Z_{max} = \frac{L}{T_z} \quad (A15)$$

$$\alpha(Z) = \frac{EA w(z)}{P_o T_z} \quad (A16)$$

$$r = \frac{K_f}{K_f(T_z)^{n+1}} \quad (A17)$$

$$T_z^{(n+20)} = \frac{EA}{K_f} \quad (\text{A18})$$

Substitution of the nondimensional parameters into the governing differential equation yields

$$\frac{d^2 a(Z)}{dZ^2} - Z^n a(Z) = 0 \quad (\text{A19})$$

Equation A19 may be solved for $a(Z)$ by any numerical technique (e.g., finite differences). From the solution of Equation A19, the relationship between pile head force and head displacement is obtained as $a(Z=0)$, whence

$$a_o = \frac{EA w_o}{P_o T_z} \quad (\text{A20})$$

and the pile head axial stiffness is

$$\frac{P_o}{w_o} = \frac{EA}{T_z} \frac{1}{a_o} \quad (\text{A21})$$

Values of the stiffness parameter are plotted in Figure A3 for a linear variation of side friction stiffness with depth and in Figure 25 for side friction stiffness varying as the square root of depth. These figures indicate that the tip reaction stiffness has negligible effect for values of Z_{max} greater than 2.

Evaluation of Side Friction Stiffness for Piles in Sand

Method ESSF1

Mosher (1984) suggested a secant stiffness computed using an axial displacement of 0.1 in. from his expression for the f - w curve. The resulting estimate of elastic stiffness for side friction is

$$E_z = \frac{k_f f_{max} C}{144(f_{max} + 0.1k_f)} \quad (\text{A22})$$

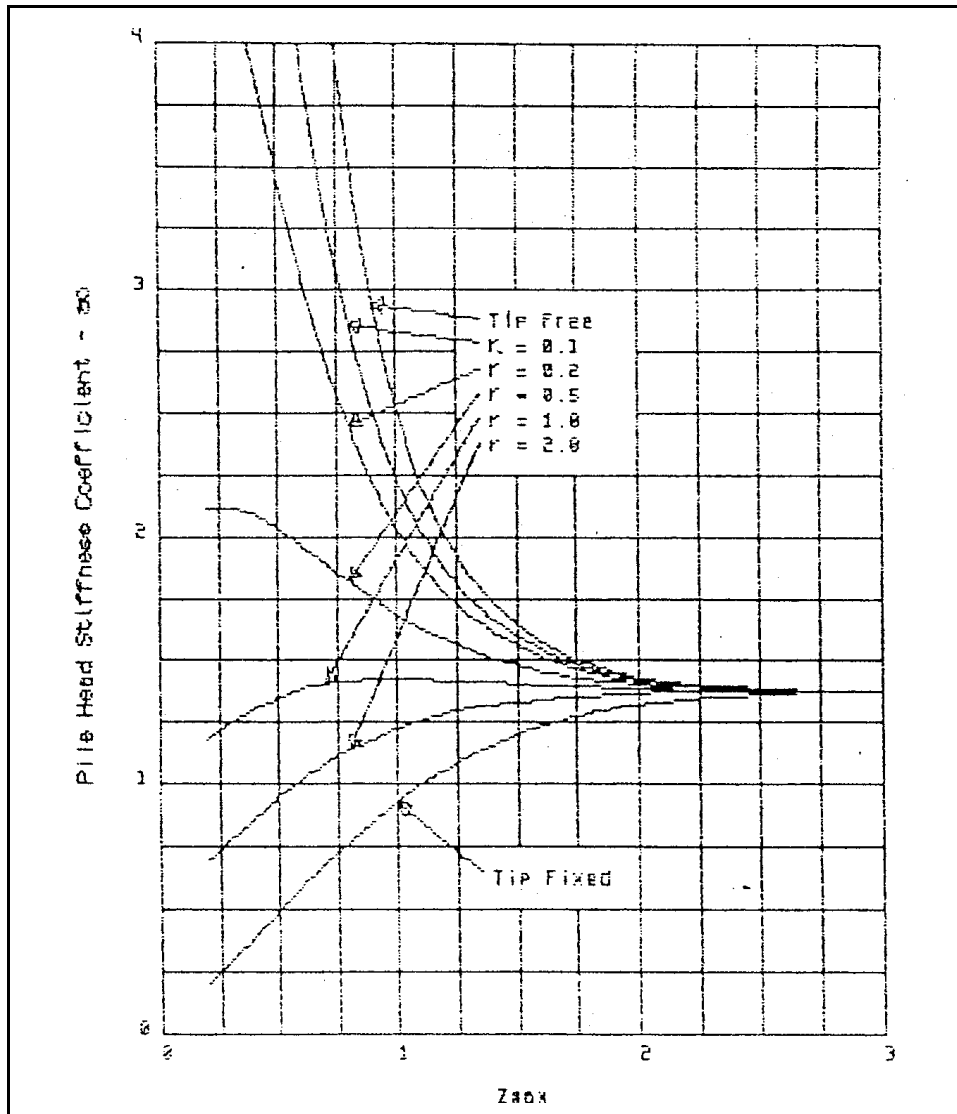


Figure A3. Axial stiffness coefficient for soil stiffness varying linearly with depth where

k_f = initial slope of the $f-w$ curve given in Table 1 in psf

f_{max} = ultimate side friction given in Figure 4 converted to units of psf

$C = 2$

R = circumference of the pile

The resulting units of E_z are in psi.

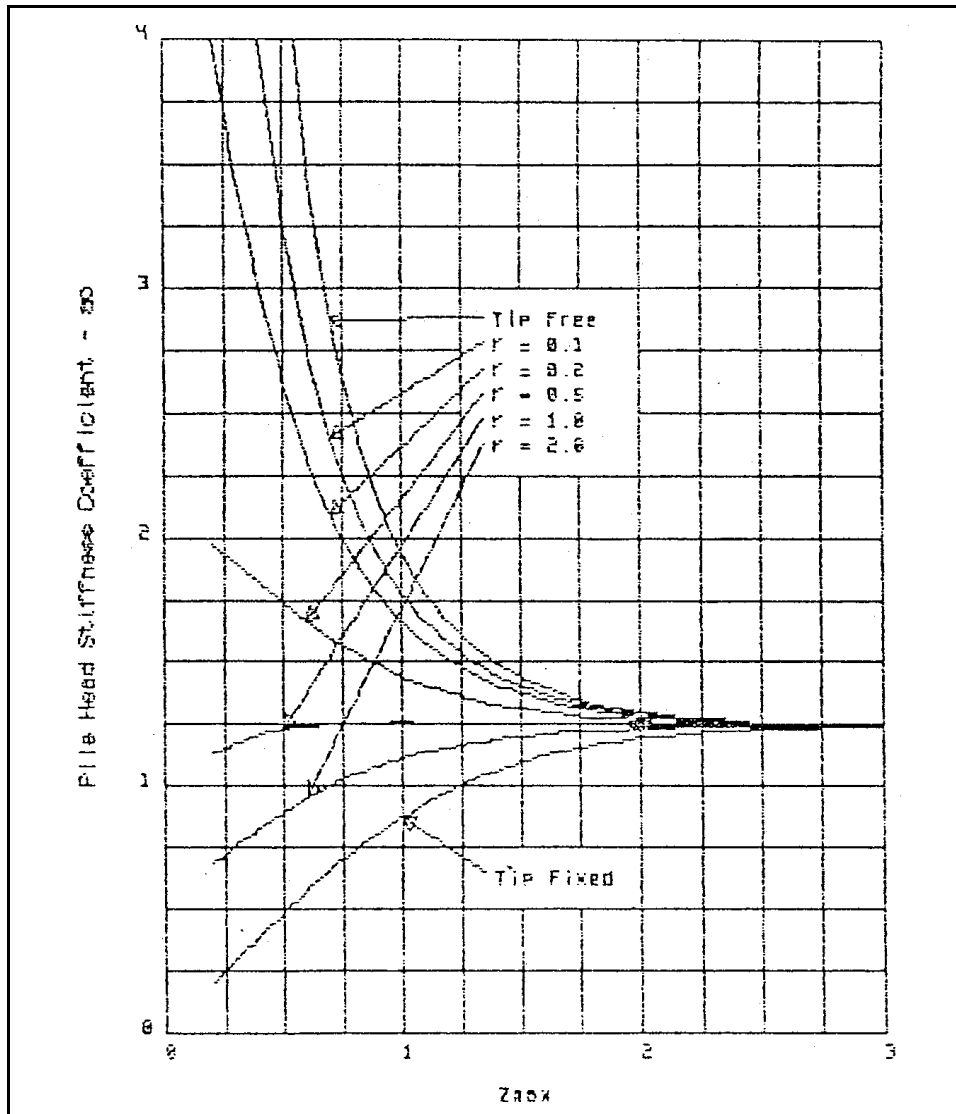


Figure A4. Axial stiffness coefficient for soil stiffness varying as square root of depth

The expression for E_z in Equation A22 includes an implicit variation with depth embodied in the curves for f_{max} as a function of relative depth (see Figure 4 in the main text). An examination of these curves suggests that the variation of E_z approximates a curve proportional to the square root of depth. To utilize the side friction stiffness for this procedure, the actual variation of E_z could be fitted to a curve which varies as the square root of depth (e.g. by least squares fit).

Method ESSF2

The procedure of Kraft, Ray, and Cagawa (1981) for $f-w$ curves for sand may be used to approximate elastic conditions through the use of the initial slope of the $f-w$ curve. From Equation 6 in the main text, the initial slope of the $f-w$ curve yields:

- a. For a homogeneous medium, a constant side friction stiffness equal to

$$E_z(z) = \frac{G_f C}{R \ln \frac{2L(1-\nu)}{R}} \quad (\text{A23})$$

- b. For a medium in which shear modulus varies from zero at the ground surface to G_f at the pile tip, a linearly varying side friction stiffness equal to

$$E_z(z) = \frac{G_f C}{R \ln \frac{2L(1-\nu)}{R}} \frac{z}{L} \quad (\text{A24})$$

- c. For a soil affected by pile installation, the shear modulus G or G_f appearing in Equations A23 and A24 should be replaced by an effective modulus as given in Equation 10 or 11 in the main text.

Evaluation of Side Friction Stiffness for Piles in Clay

Method ECSF1

Kraft, Ray, and Kagawa (1981) suggest that the same procedures used for sand may be used for piles in clay with the shear moduli appearing in Equations A23 and A24 being modified to account for magnitude and time of loading, as shown in Table A1.

Method ECSF2

Heydinger (1984) suggests using a secant to the $f-w$ curve evaluated at a relative displacement $w/2R = 0.005$. From Equation 22 in the main text,

Table A1 Adjustment in G for Various Loading Conditions (Adjustment factor = G (operational)/G (in situ))	
Condition	Adjustment Factor
Immediately After Driving	
Small load	0.85
Large load (> working load)	0.54
After Setup	
Small load	1.04
Large load ($f = 0.4s_u$)	0.96
Large load ($f = s_u$)	0.73

$$E_z = \frac{E_f C/2R}{1 + \left(0.005 \frac{E_f}{f_{max}}\right)^{m^{1/m}}} \quad (A25)$$

where E_f and m are given by Equations 23 and 24 in the main text, respectively. The variation of E_z along the pile depends on the distribution of soil modulus of elasticity used in the evaluation of E_f from Equation 23.

Method ECSF2

The elasto-plastic representation of side friction due to Aschenbrener and Olson (1984) yields

$$E_z = \frac{s_u C}{0.1(\text{in.})} \quad (A26)$$

where for consistent units s_u should be expressed in psi and C in inches producing E_z in psi.

Evaluation of Tip Reaction Stiffness

General

As shown previously, the tip reaction only has a significant effect on the pile head stiffness coefficient for piles having Z_{max} less than 2. If the value of Z_{max} resulting from any of the assessments of side friction described above is less than 2, the tip reaction stiffness may be omitted.

In the discussions for evaluating the tip reaction stiffness that follow, stiffness is proportional to the effective area at the tip A_t bearing on the soil. For closed end or solid piles the effective tip area may reasonably be taken as the cross section area of the pile. For H-piles or open-ended pipe piles the tip area may be as little as the area of material in the cross section to an area equal to that bounded by the exterior of the section (see Figure 5 in the main text). When the radius of the tip reaction area is required to evaluate tip stiffness, an effective radius is obtained from

$$R_t = \sqrt{A_t/\pi} \quad (\text{A27})$$

The tip reaction stiffness may be obtained from any of the procedures described previously for developing q - w curves by evaluating a secant stiffness for a tip displacement representative of working load conditions. Typically in the Corps of Engineers, failure at the tip is considered to occur at a tip displacement of 0.25 in. Unless stated otherwise, working load conditions are assumed to occur at one-tenth of the displacement corresponding to failure (i.e., 0.025 in.).

Evaluation of Tip Reaction Stiffness for Piles in Sand

Method EST1

The theory of elasticity solution for a rigid punch has been used by Kraft, Ray, and Kagawa (1981) (see also Randolph and Wroth 1978) to estimate the tip reaction stiffness as

$$K_t = \frac{4R_t G}{I_t(1 - \nu)} \quad (\text{A28})$$

where the shear modulus G should be taken as an average in situ value between $6R_t$ above the pile tip to $6R_t$ below the tip. The factor I_t in Equation A28 is an influence factor ranging from 0.5 to 0.78.

Method EST2

Mosher (1984) and Vijayvergiya (1977) express the tip reaction q - w curve as a power function (see pages 24-26). Mosher recommends for working load approximations a secant tip reaction stiffness corresponding to a tip displacement of 0.025 in. The corresponding tip stiffnesses are:

$$a. \quad \text{For loose sand: } K_t = 12.6 A_t q_{max} \quad (\text{A29})$$

$$b. \quad \text{For medium sand: } K_t = 18.6 A_t q_{max} \quad (\text{A30})$$

$$c. \text{ For dense sand: } K_t = 22.5 A_t q_{max} \quad (\text{A31})$$

where q_{max} is the ultimate unit tip reaction from Figure 17. For consistent units in Equations A29 through A31, q_{max} must be in pounds per square inch, and A_t must be in square inches, which yields K_t in pounds per inch.

Method EST3

A secant stiffness obtained from the work of Briaud and Tucker (1984), which considers the effects of residual stresses due to installation for a tip displacement 0.025 in., is

$$K_t = \frac{k_q q_{max} A_t}{q_{max} + 0.025 k_q} \quad (\text{A32})$$

and

$$k_q = 467.1 N^{0.0065} \quad (\text{A33})$$

where N is the average uncorrected standard penetration count in blows per foot from a distance of $8R_t$ above the pile tip to $8R_t$ below the tip. The units of k_q in Equation A33 are tsf/in. The required units of other terms in Equation A32 are q_{max} in tons per square foot and A_t in square feet, which yields K_t in tons per inch.

Evaluation of Tip Reaction Stiffness for Piles in Clay

Method ECT1

The bilinear tip reaction curve used by Aschenbrener and Olson (1984) produces

$$K_t = \frac{9s_u A_t}{0.02R_t} \quad (\text{A34})$$

where s_u is the average undrained shear strength of the clay from $6R_t$ above the pile tip to $6R_t$ below the tip.

Method ECT2

The tip stiffness developed by Kraft, Ray, and Kagawa (1981) described on page A11 may be used for piles in clay.

Method ECT3

Skempton (1951) observed the similarity of the load-displacement behavior of a plate load test and the laboratory stress-strain curve for soft clays. It was concluded that a linear approximation of the load displacement relationship up to half of the ultimate load could be related to the strain at 50 percent of the unconfined compression strength indicated by the laboratory stress-strain curve. The observation has been used to obtain an estimate of the pile tip reaction stiffness as

$$K_t = \frac{q_u A_t}{5 \epsilon_{50} R_t} \quad (\text{A35})$$

where

q_u = unconfined compression strength of the clay at the pile tip

A_t = effective tip area

ϵ_{50} = strain at 50 percent of ultimate strength from a laboratory stress-strain curve

R_t = effective radius of the tip area

Typical values of ϵ_{50} are 0.02 for a very soft clay, 0.01 for a soft clay, and 0.005 for a stiff clay.

Appendix B

Nondimensional Coefficients for Laterally Loaded Piles

Basic Equations

$$E_z = kz^n$$

$$T^{n+4} = \frac{EI}{k}$$

$$EI \frac{d^4 u(z)}{dz^4} + kz^n u(z) = 0$$

$$Z = \frac{z}{T}$$

$$Z_{\max} = \frac{L}{T}$$

$$u(Z) = \frac{V_o T^3}{EI} A_u(Z) + \frac{M_o T^2}{EI} B_u(Z)$$

$$\frac{du}{dz} = \frac{V_o T^2}{EI} A_s(Z) + \frac{M_o T}{EI} B_s(Z)$$

$$M(Z) = V_o T A_m(Z) + M_o B_m(Z)$$

Table B1
Nondimensional Coefficients for Laterally Loaded Pile for Soil Modulus Constant with
Depth (Head Shear $V_o = 1$, Head Moment $M_o = 0$)

Z	$Z_{max} = 2$			$Z_{max} = 3$			$Z_{max} = 4$		
	A_u	A_s	A_m	A_u	A_s	A_m	A_u	A_s	A_m
0.00	2.118	-1.741	0.000	1.597	-1.116	0.000	1.474	-1.032	0.000
0.10	1.944	-1.736	0.092	1.486	-1.111	0.094	1.371	-1.027	0.095
0.20	1.771	-1.723	0.164	1.375	-1.097	0.174	1.248	-1.009	0.192
0.30	1.600	-1.704	0.219	1.266	-1.076	0.240	1.168	-0.992	0.247
0.40	1.430	-1.680	0.257	1.160	-1.050	0.293	1.051	-0.958	0.315
0.50	1.264	-1.653	0.282	1.057	-1.018	0.335	0.976	-0.931	0.351
0.60	1.100	-1.624	0.294	0.956	-0.983	0.366	0.867	-0.886	0.395
0.70	0.939	-1.594	0.294	0.860	-0.945	0.388	0.797	-0.854	0.417
0.80	0.781	-1.565	0.286	0.767	-0.906	0.401	0.698	-0.802	0.441
0.90	0.626	-1.537	0.269	0.679	-0.865	0.406	0.635	-0.767	0.451
1.00	0.474	-1.512	0.246	0.594	-0.825	0.405	0.546	-0.712	0.458
1.10	0.324	-1.488	0.219	0.514	-0.784	0.397	0.491	-0.675	0.459
1.20	0.176	-1.468	0.188	0.437	-0.745	0.385	0.413	-0.620	0.454
1.30	0.030	-1.451	0.156	0.365	-0.708	0.368	0.365	-0.584	0.447
1.40	-0.114	-1.437	0.123	0.296	-0.672	0.347	0.298	-0.532	0.433
1.50	-0.258	-1.426	0.091	0.230	-0.638	0.324	0.257	-0.497	0.421
1.60	-0.400	-1.418	0.062	0.168	-0.607	0.298	0.200	-0.448	0.400
1.70	-0.541	-1.413	0.037	0.109	-0.579	0.270	0.165	-0.417	0.385
1.80	-0.683	-1.411	0.017	0.052	-0.553	0.241	0.118	-0.372	0.359
1.90	-0.824	-1.410	0.005	-0.002	-0.531	0.212	0.089	-0.344	0.341
2.00	-0.965	-1.410	0.000	-0.054	-0.511	0.183	0.051	-0.305	0.314
2.10				-0.104	-0.494	0.154	0.027	-0.280	0.295
2.20				-0.153	-0.480	0.127	-0.004	-0.247	0.266
2.30				-0.200	-0.469	0.101	-0.023	-0.226	0.247
2.40				-0.247	-0.460	0.077	-0.049	-0.198	0.218
2.50				-0.292	-0.453	0.055	-0.064	-0.182	0.200
2.60				-0.337	-0.449	0.037	-0.084	-0.159	0.173
2.70				-0.382	-0.446	0.021	-0.097	-0.146	0.155

(Continued)

Table B1 (Concluded)									
Z	Z_{max} = 2			Z_{max} = 3			Z_{max} = 4		
	A_u	A_s	A_m	A_u	A_s	A_m	A_u	A_s	A_m
2.80				-0.426	-0.444	0.010	-0.113	-0.129	0.130
2.90				-0.471	-0.444	0.003	-0.123	-0.119	0.115
3.00				-0.515	-0.443	0.000	-0.136	-0.107	0.093
3.10							-0.145	-0.100	0.079
3.20							-0.156	-0.091	0.060
3.30							-0.163	-0.087	0.049
3.40							-0.173	-0.082	0.034
3.50							-0.180	-0.080	0.026
3.60							-0.189	-0.077	0.015
3.70							-0.195	-0.076	0.010
3.80							-0.205	-0.076	0.004
3.90							-0.211	-0.075	0.001
4.00							-0.218	-0.075	0.000

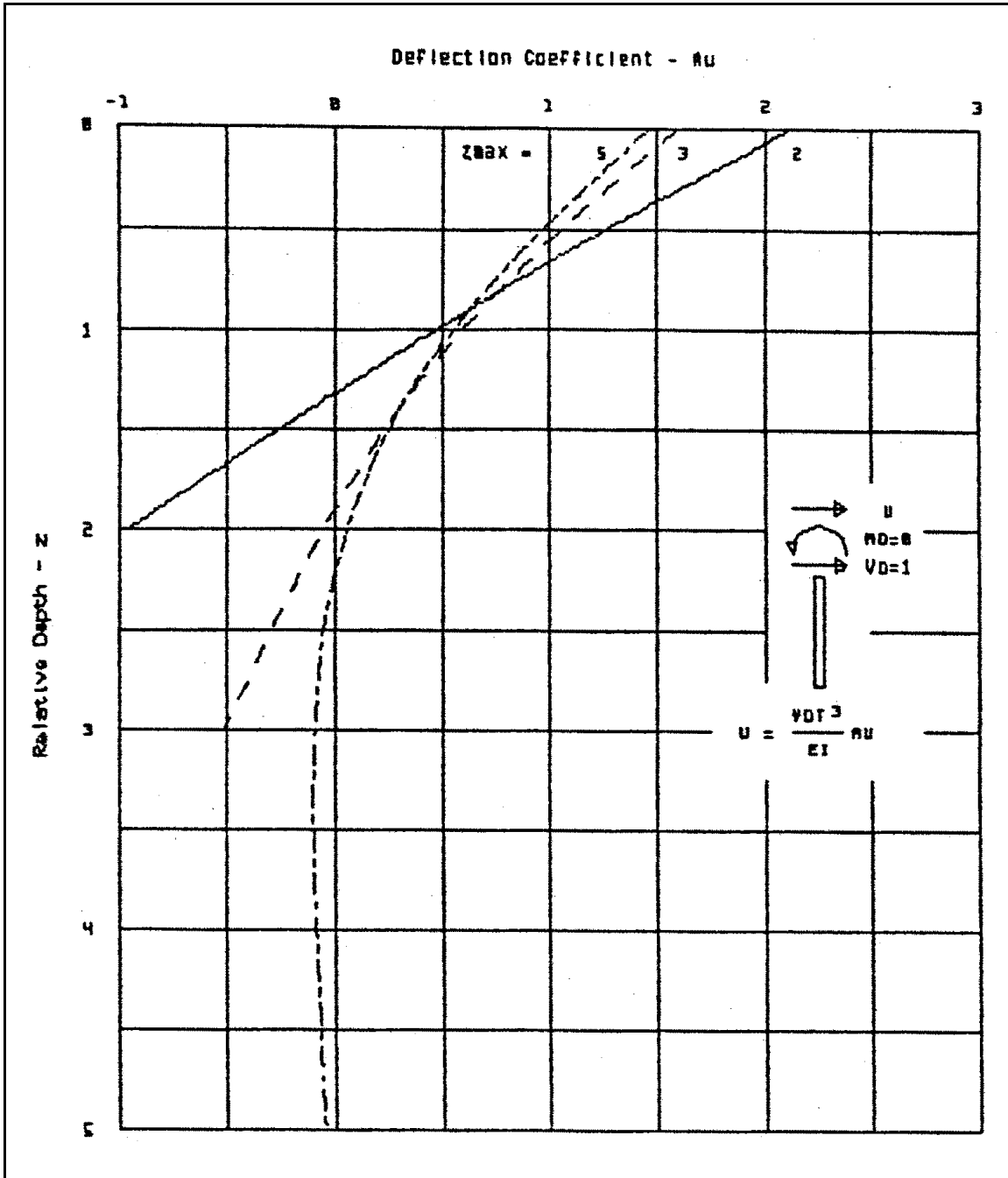


Figure B1. Deflection coefficient for unit head shear for soil stiffness constant with depth

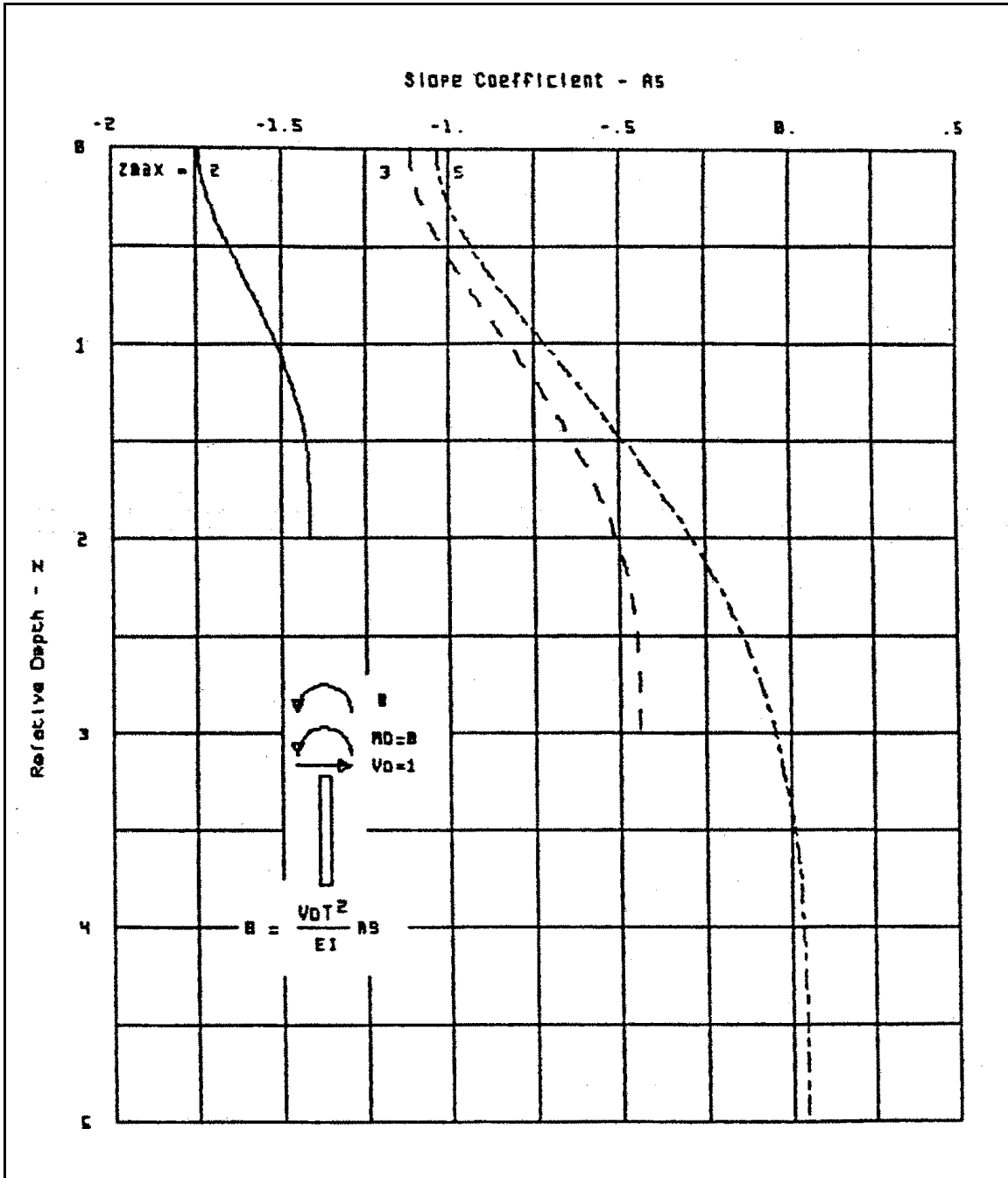


Figure B2. Slope coefficient for unit head shear for soil stiffness constant with depth

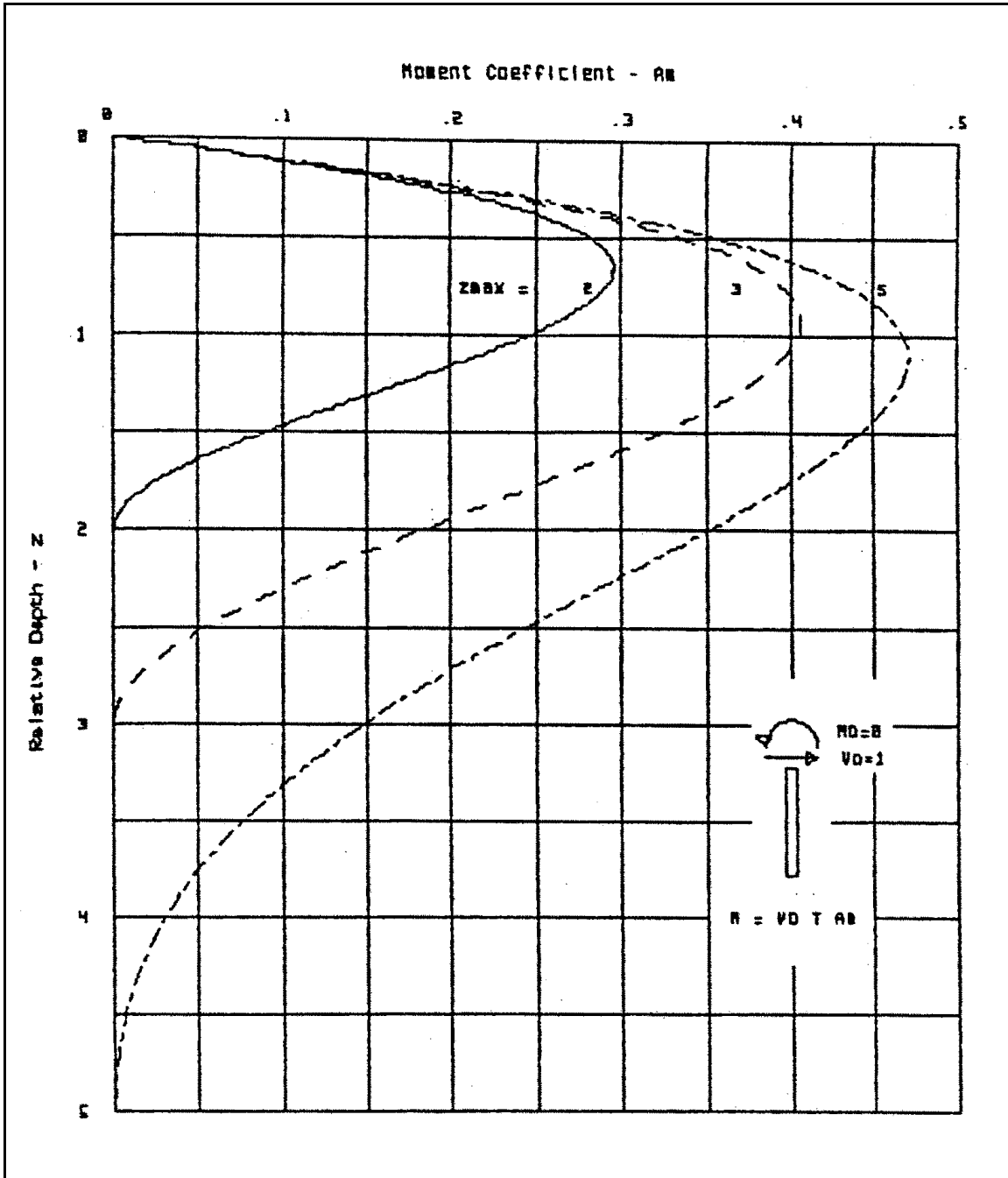


Figure B3. Bending moment coefficient for unit head shear for soil stiffness constant with depth

Table B2
Nondimensional Coefficients for Laterally Loaded Pile for Soil Modulus Constant with
Depth (Head Shear $V_o = 0$, Head Moment $M_o = 1$)

Z	$Z_{max} = 2$			$Z_{max} = 3$			$Z_{max} = 4$		
	B_u	B_s	B_m	B_u	B_s	B_m	B_u	B_s	B_m
0.00	-1.741	2.261	-1.000	-1.116	1.500	-1.000	-1.032	1.441	-1.000
0.10	-1.519	2.161	-0.993	-0.971	1.400	-0.996	-0.893	1.341	-0.997
0.20	-1.308	2.063	-0.972	-0.836	1.301	-0.983	-0.739	1.222	-0.982
0.30	-1.107	1.967	-0.937	-0.710	1.204	-0.961	-0.645	1.144	-0.966
0.40	-0.915	1.876	-0.891	-0.595	1.109	-0.932	-0.514	1.030	-0.934
0.50	-0.731	1.789	-0.836	-0.489	1.017	-0.897	-0.435	0.956	-0.909
0.60	-0.557	1.709	-0.773	-0.391	0.930	-0.858	-0.327	0.850	-0.865
0.70	-0.389	1.635	-0.705	-0.303	0.846	-0.814	-0.261	0.782	-0.834
0.80	-0.229	1.568	-0.633	-0.222	0.767	-0.767	-0.173	0.685	-0.784
0.90	-0.076	1.508	-0.559	-0.149	0.693	-0.719	-0.121	0.623	-0.749
1.00	0.072	1.456	-0.484	-0.083	0.623	-0.668	-0.052	0.537	-0.695
1.10	0.216	1.412	-0.410	-0.024	0.559	-0.617	-0.011	0.483	-0.658
1.20	0.355	1.374	-0.338	0.029	0.500	-0.565	0.042	0.407	-0.604
1.30	0.491	1.344	-0.269	0.076	0.446	-0.514	0.073	0.360	-0.568
1.40	0.624	1.320	-0.205	0.118	0.397	-0.464	0.112	0.295	-0.515
1.50	0.755	1.303	-0.148	0.156	0.353	-0.415	0.134	0.255	-0.480
1.60	0.885	1.290	-0.098	0.189	0.314	-0.367	0.162	0.201	-0.430
1.70	1.013	1.283	-0.057	0.218	0.280	-0.321	0.176	0.168	-0.397
1.80	1.141	1.279	-0.026	0.245	0.250	-0.277	0.194	0.123	-0.351
1.90	1.269	1.277	-0.007	0.269	0.224	-0.236	0.202	0.096	-0.322
2.00	1.397	1.277	0.000	0.290	0.202	-0.198	0.212	0.060	-0.280
2.10				0.309	0.184	-0.162	0.216	0.038	-0.254
2.20				0.327	0.170	-0.130	0.218	0.010	-0.218
2.30				0.343	0.158	-0.100	0.219	-0.006	-0.196
2.40				0.359	0.150	-0.075	0.216	-0.028	-0.164
2.50				0.373	0.143	-0.052	0.214	-0.040	-0.145
2.60				0.387	0.139	-0.034	0.208	-0.056	-0.119
2.70				0.401	0.136	-0.019	0.203	-0.065	-0.104

(Continued)

Table B2 (Concluded)									
Z	Z_{max} = 2			Z_{max} = 3			Z_{max} = 4		
	B_u	B_s	B_m	B_u	B_s	B_m	B_u	B_s	B_m
2.80				0.415	0.135	-0.009	0.195	-0.076	-0.083
2.90				0.428	0.134	-0.002	0.188	-0.082	-0.070
3.00				0.442	0.134	0.000	0.178	-0.090	-0.054
3.10							0.170	-0.094	-0.044
3.20							0.159	-0.098	-0.032
3.30							0.151	-0.101	-0.025
3.40							0.139	-0.103	-0.017
3.50							0.130	-0.104	-0.012
3.60							0.118	-0.105	-0.007
3.70							0.109	-0.106	-0.004
3.80							0.097	-0.106	-0.001
3.90							0.088	-0.106	-0.000
4.00							0.078	-0.106	0.000

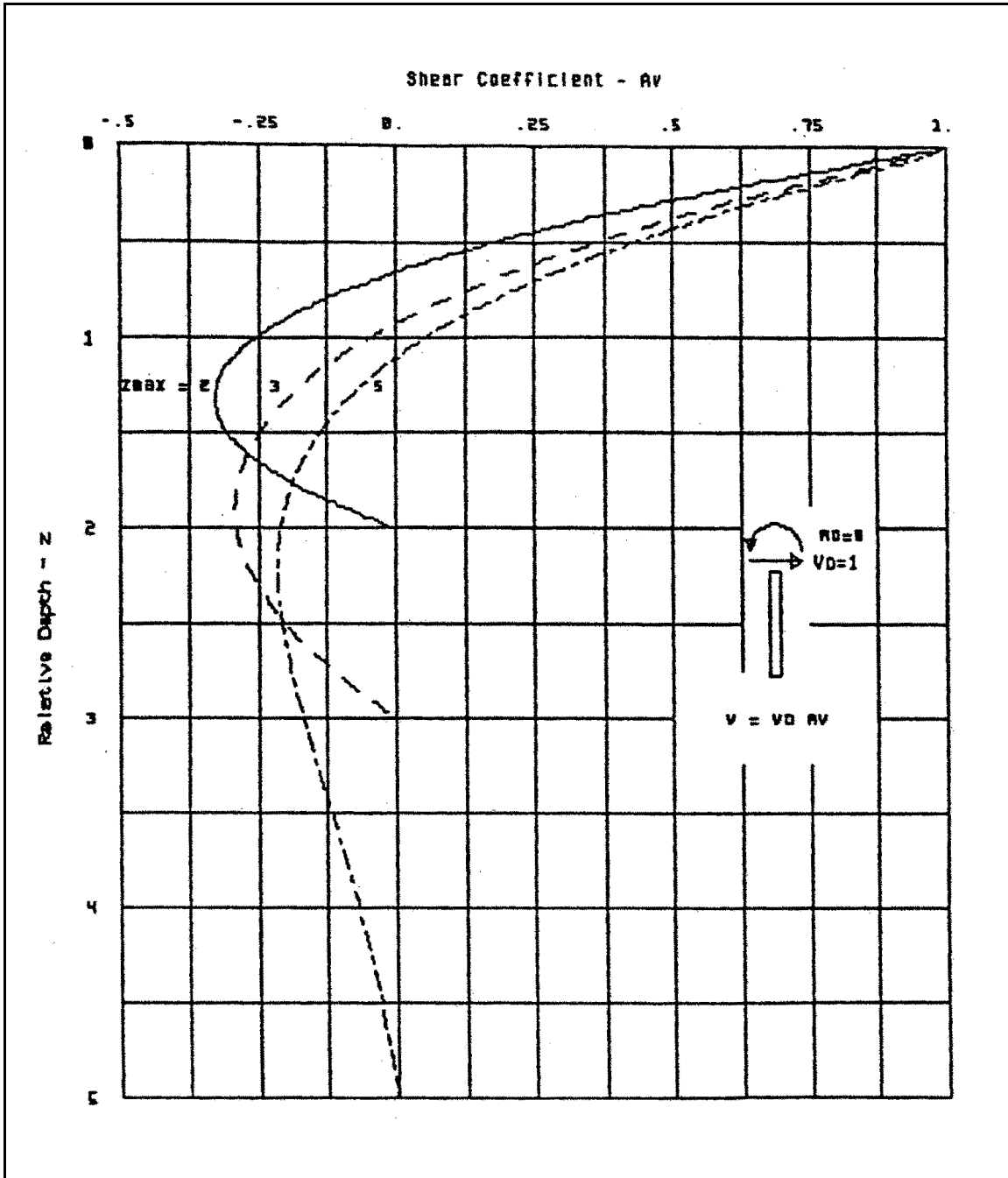


Figure B4. Shear coefficient for unit head shear for soil stiffness constant with depth

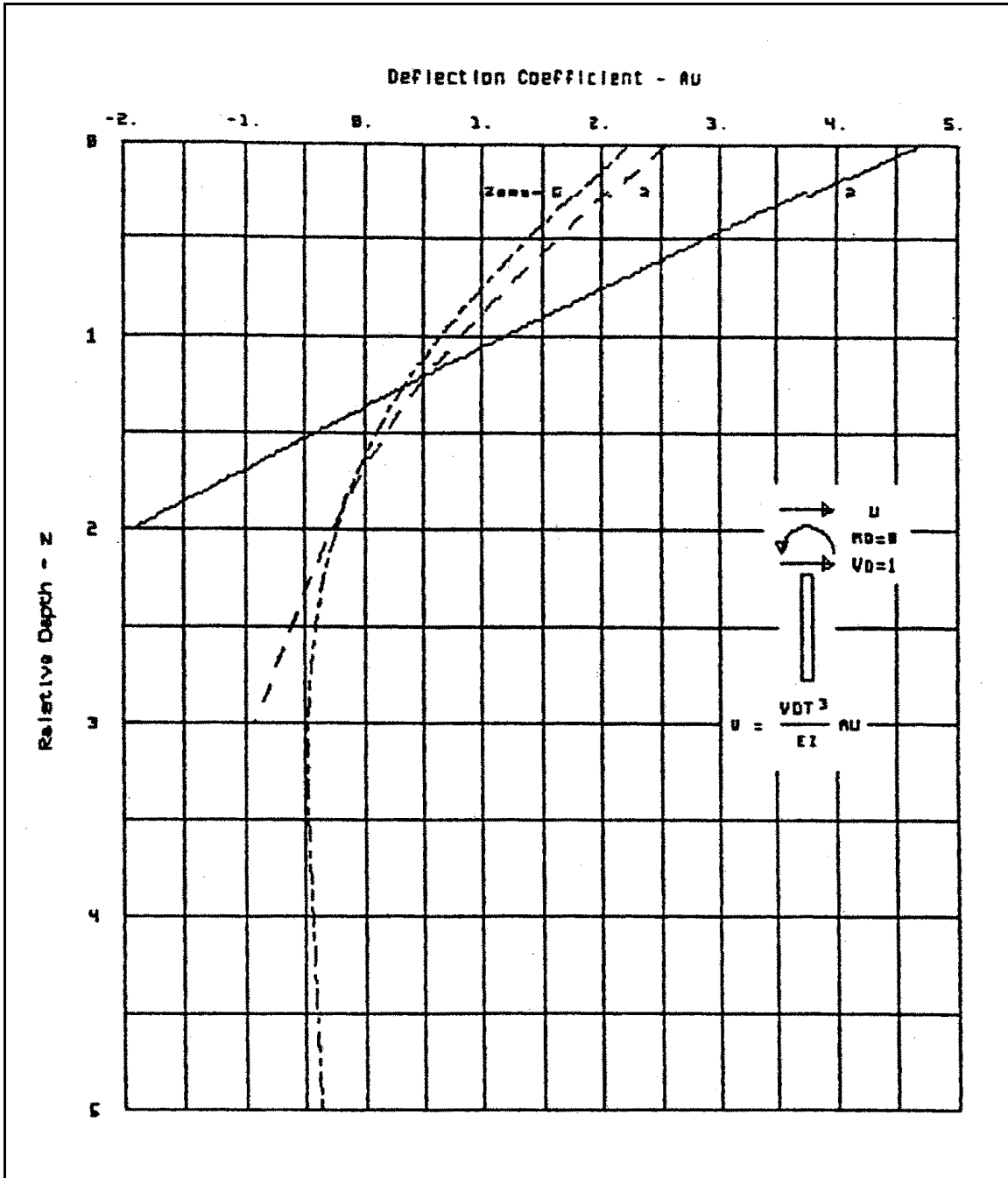


Figure B5. Deflection coefficient for unit head shear for soil stiffness varying linearly with depth

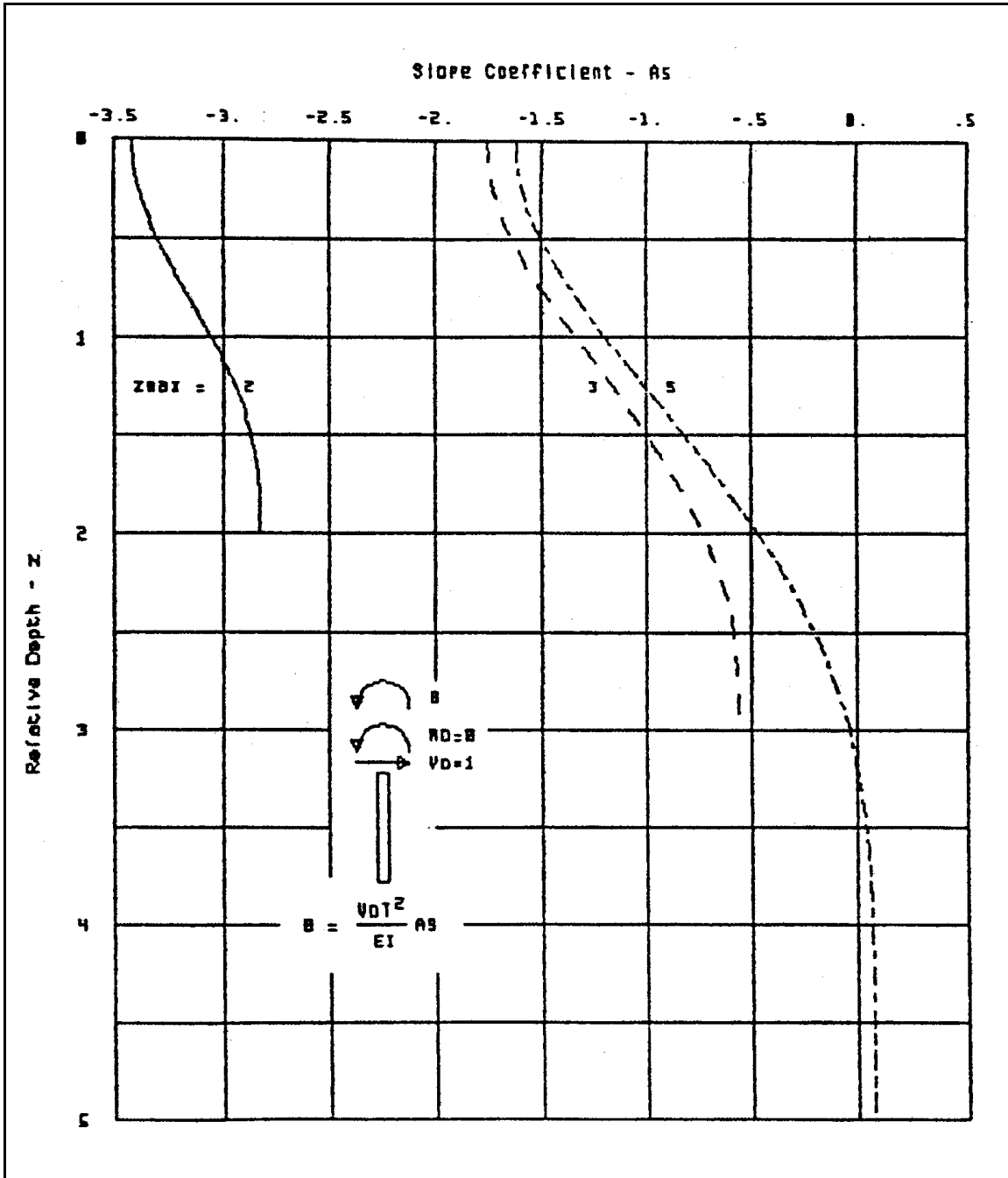


Figure B6. Slope coefficient for unit head shear for soil stiffness varying linearly with depth

Table B3
Nondimensional Coefficients for Laterally Loaded Pile for Soil Modulus Varying
Linearly with Depth (Head Shear $V_o = 1$, Head Moment $M_o = 0$)

Z	$Z_{max} = 2$			$Z_{max} = 3$			$Z_{max} = 4$		
	A_u	A_s	A_m	A_u	A_s	A_m	A_u	A_s	A_m
0.00	4.738	-3.418	0.000	2.727	-1.758	0.000	2.442	-1.622	0.000
0.10	4.396	-3.413	0.099	2.552	-1.753	0.100	2.280	-1.616	0.100
0.20	4.055	-3.399	0.194	2.377	-1.738	0.197	2.087	-1.597	0.216
0.30	3.717	-3.375	0.281	2.204	-1.714	0.289	1.960	-1.577	0.290
0.40	3.381	-3.343	0.357	2.034	-1.680	0.375	1.773	-1.536	0.394
0.50	3.048	-3.304	0.419	1.868	-1.639	0.452	1.651	-1.502	0.458
0.60	2.720	-3.259	0.466	1.707	-1.590	0.521	1.474	-1.442	0.543
0.70	2.396	-3.211	0.497	1.551	-1.535	0.579	1.361	-1.396	0.592
0.80	2.078	-3.161	0.511	1.400	-1.475	0.626	1.198	-1.321	0.655
0.90	1.764	-3.109	0.509	1.256	-1.410	0.662	1.094	-1.268	0.689
1.00	1.456	-3.059	0.490	1.118	-1.343	0.687	0.947	-1.182	0.729
1.10	1.152	-3.012	0.458	0.987	-1.273	0.701	0.855	-1.123	0.747
1.20	0.853	-2.968	0.412	0.863	-1.203	0.703	0.725	-1.032	0.764
1.30	0.559	-2.930	0.357	0.747	-1.133	0.696	0.645	-0.971	0.768
1.40	0.267	-2.897	0.294	0.637	-1.064	0.679	0.534	-0.879	0.764
1.50	-0.021	-2.871	0.227	0.534	-0.998	0.653	0.466	-0.818	0.755
1.60	-0.307	-2.852	0.161	0.437	-0.934	0.618	0.374	-0.729	0.733
1.70	-0.592	-2.839	0.100	0.347	-0.874	0.577	0.318	-0.671	0.714
1.80	-0.875	-2.831	0.049	0.262	-0.819	0.530	0.242	-0.587	0.679
1.90	-1.158	-2.828	0.013	0.183	-0.768	0.479	0.197	-0.534	0.652
2.00	-1.441	-2.828	0.000	0.108	-0.723	0.423	0.138	-0.459	0.607
2.10				0.038	-0.684	0.366	0.103	-0.411	0.574
2.20				-0.029	-0.650	0.308	0.058	-0.346	0.523
2.30				-0.092	-0.622	0.250	0.032	-0.305	0.488
2.40				-0.153	-0.600	0.195	-0.002	-0.250	0.435
2.50				-0.212	-0.583	0.143	-0.020	-0.216	0.399
2.60				-0.270	-0.571	0.097	-0.043	-0.172	0.346
2.70				-0.327	-0.563	0.057	-0.056	-0.145	0.312

(Continued)

Table B3 (Concluded)									
Z	Z_{max} = 2			Z_{max} = 3			Z_{max} = 4		
	A_u	A_s	A_m	A_u	A_s	A_m	A_u	A_s	A_m
2.80				-0.383	-0.559	0.027	-0.071	-0.111	0.262
2.90				-0.439	-0.558	0.007	-0.079	-0.091	0.231
3.00				-0.494	-0.557	0.000	-0.089	-0.066	0.186
3.10							-0.093	-0.052	0.159
3.20							-0.099	-0.036	0.121
3.30							-0.101	-0.027	0.098
3.40							-0.104	-0.017	0.069
3.50							-0.105	-0.012	0.051
3.60							-0.106	-0.007	0.030
3.70							-0.106	-0.005	0.019
3.80							-0.107	-0.004	0.007
3.90							-0.107	-0.003	0.002
4.00							-0.108	-0.003	0.000

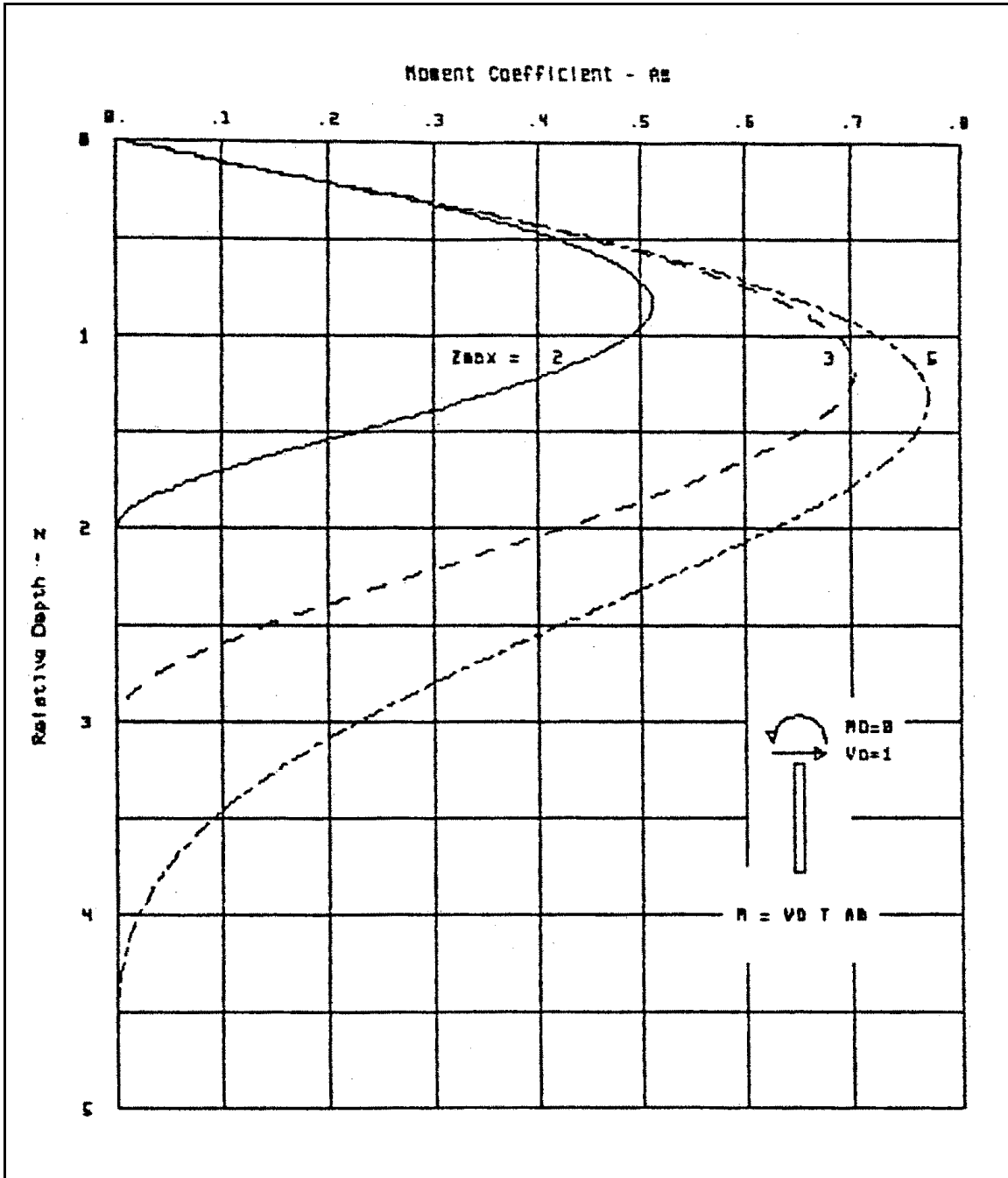


Figure B7. Bending moment coefficient for unit head shear for soil stiffness varying linearly with depth

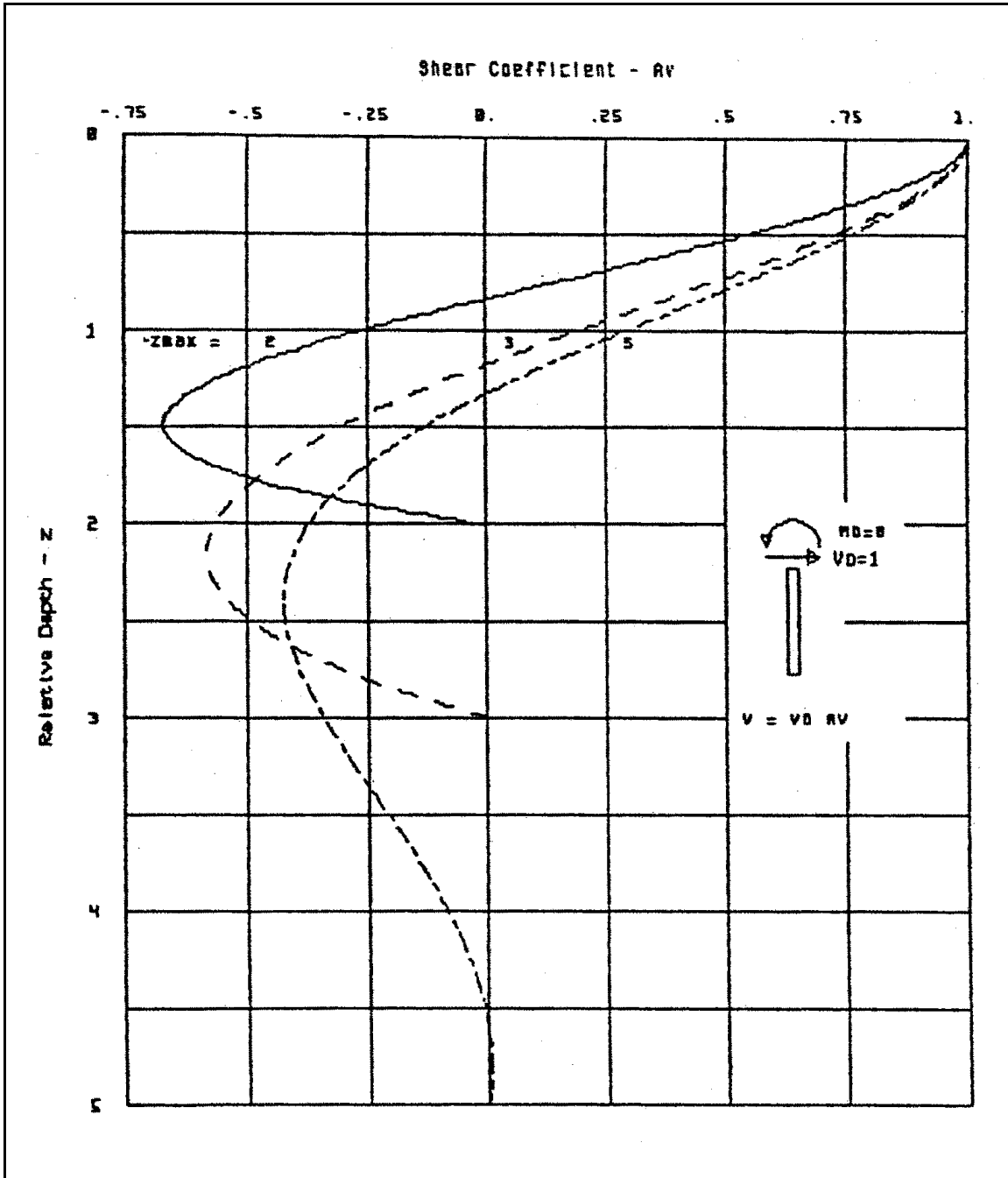


Figure B8. Shear coefficient for unit head shear for soil stiffness varying linearly with depth

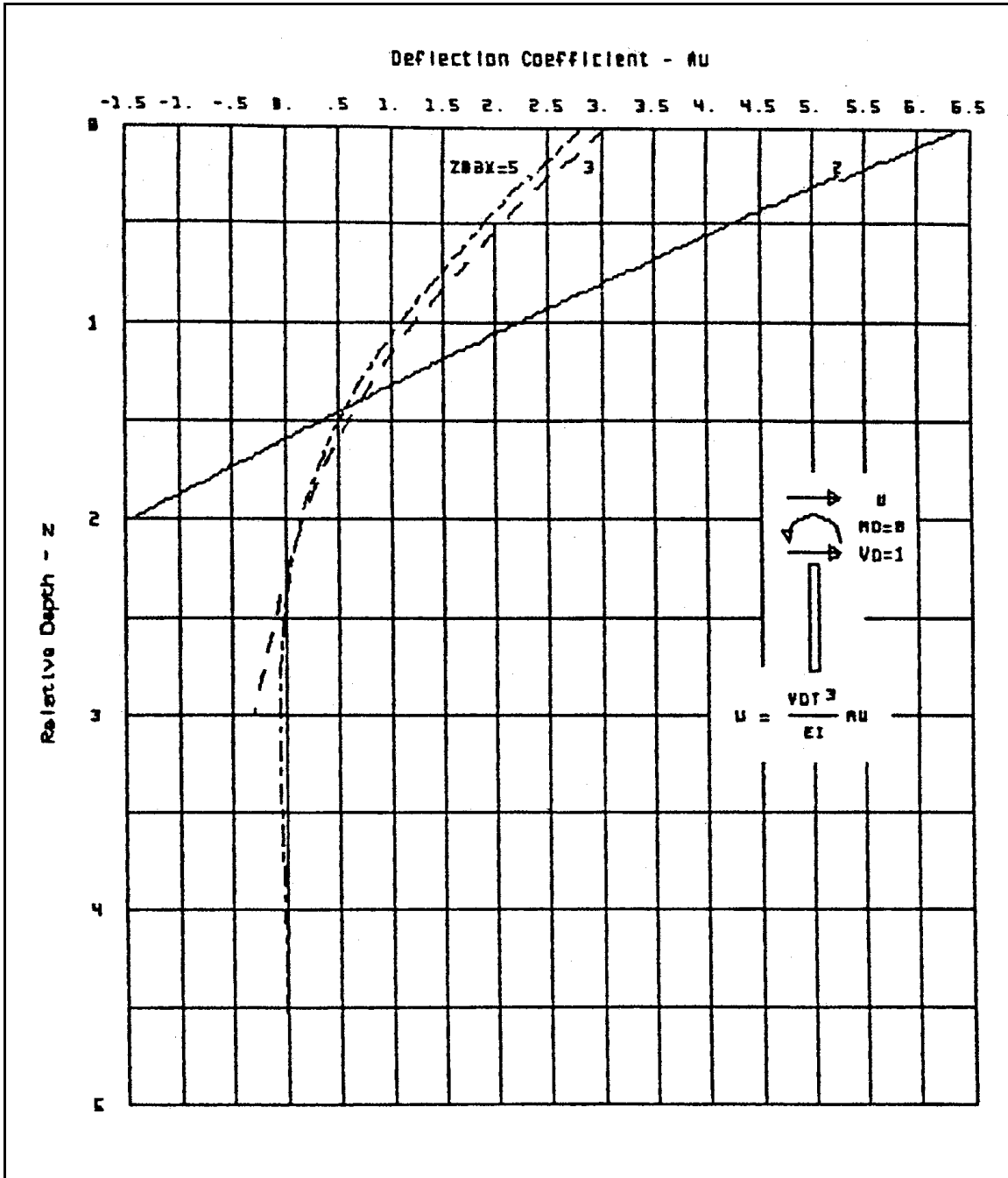


Figure B9. Deflection coefficient for unit head shear for soil stiffness varying linearly with depth

Table B4
Nondimensional Coefficients for Laterally Loaded Pile for Soil Modulus Varying
Linearly with Depth (Head Shear $V_o = 0$, Head Moment $M_o = 1$)

Z	$Z_{max} = 2$			$Z_{max} = 3$			$Z_{max} = 4$		
	B_u	B_s	B_m	B_u	B_s	B_m	B_u	B_s	B_m
0.00	-3.418	3.213	-1.000	-1.758	1.819	-1.000	-1.622	1.751	-1.000
0.10	-3.102	3.113	-0.999	-1.581	1.719	-1.000	-1.452	1.651	-1.000
0.20	-2.796	3.013	-0.996	-1.414	1.619	-0.998	-1.261	1.531	-0.997
0.30	-2.499	2.914	-0.987	-1.257	1.519	-0.993	-1.141	1.452	-0.994
0.40	-2.213	2.816	-0.970	-1.110	1.420	-0.985	-0.974	1.333	-0.984
0.50	-1.936	2.720	-0.945	-0.973	1.322	-0.972	-0.871	1.254	-0.975
0.60	-1.668	2.628	-0.910	-0.846	1.226	-0.955	-0.727	1.139	-0.955
0.70	-1.410	2.539	-0.865	-0.728	1.132	-0.932	-0.639	1.063	-0.938
0.80	-1.161	2.455	-0.810	-0.619	1.040	-0.904	-0.518	0.952	-0.908
0.90	-0.919	2.377	-0.746	-0.520	0.951	-0.871	-0.445	0.880	-0.884
1.00	-0.685	2.306	-0.674	-0.429	0.866	-0.834	-0.346	0.777	-0.844
1.10	-0.458	2.243	-0.594	-0.347	0.784	-0.792	-0.286	0.710	-0.814
1.20	-0.236	2.187	-0.510	-0.272	0.707	-0.747	-0.207	0.615	-0.766
1.30	-0.020	2.141	-0.423	-0.205	0.635	-0.698	-0.160	0.555	-0.732
1.40	0.192	2.103	-0.336	-0.145	0.568	-0.647	-0.099	0.471	-0.678
1.50	0.401	2.073	-0.252	-0.091	0.506	-0.593	-0.063	0.418	-0.641
1.60	0.607	2.052	-0.173	-0.044	0.449	-0.538	-0.017	0.345	-0.584
1.70	0.812	2.038	-0.105	-0.001	0.398	-0.483	0.008	0.299	-0.546
1.80	1.015	2.031	-0.050	0.036	0.353	-0.427	0.040	0.237	-0.490
1.90	1.218	2.028	-0.013	0.070	0.313	-0.373	0.058	0.199	-0.452
2.00	1.421	2.027	0.000	0.099	0.278	-0.319	0.079	0.148	-0.398
2.10				0.125	0.249	-0.267	0.089	0.118	-0.363
2.20				0.149	0.225	-0.219	0.101	0.078	-0.312
2.30				0.170	0.205	-0.173	0.106	0.054	-0.280
2.40				0.190	0.190	-0.131	0.111	0.023	-0.236
2.50				0.209	0.179	-0.094	0.112	0.005	-0.208
2.60				0.226	0.171	-0.062	0.111	-0.017	-0.170
2.70				0.243	0.166	-0.036	0.109	-0.030	-0.146

(Continued)

Table B4 (Concluded)									
Z	Z_{max} = 2			Z_{max} = 3			Z_{max} = 4		
	B_u	B_s	B_m	B_u	B_s	B_m	B_u	B_s	B_m
2.80				0.259	0.163	-0.017	0.105	-0.046	-0.115
2.90				0.276	0.162	-0.004	0.101	-0.054	-0.097
3.00				0.292	0.162	0.000	0.093	-0.064	-0.072
3.10							0.088	-0.069	-0.059
3.20							0.079	-0.075	-0.041
3.30							0.073	-0.078	-0.031
3.40							0.064	-0.081	-0.020
3.50							0.057	-0.083	-0.014
3.60							0.047	-0.084	-0.007
3.70							0.040	-0.084	-0.004
3.80							0.030	-0.085	-0.001
3.90							0.023	-0.085	-0.000
4.00							0.015	-0.085	-0.000

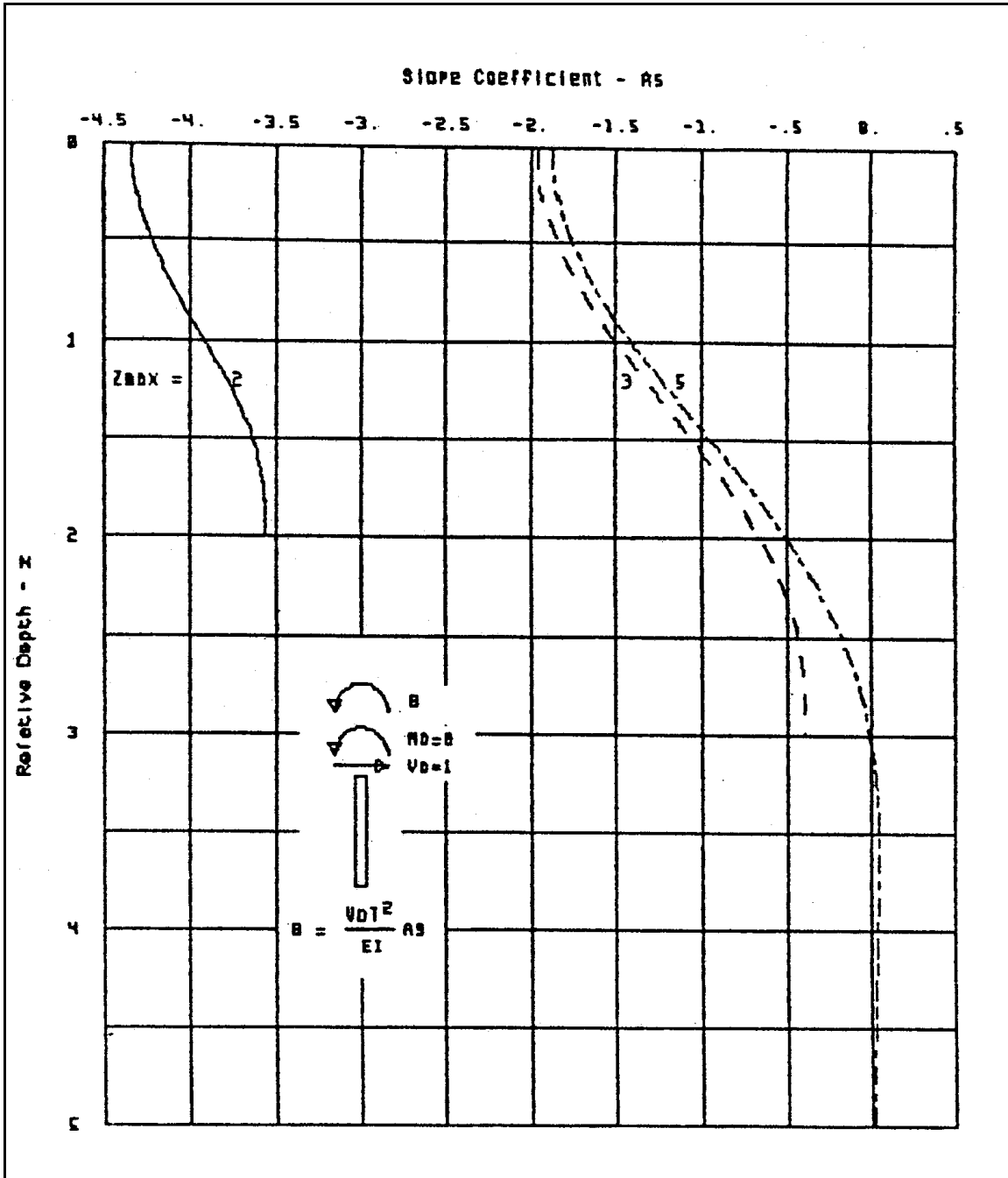


Figure B10. Slope coefficient for unit head shear for soil stiffness varying parabolically with depth

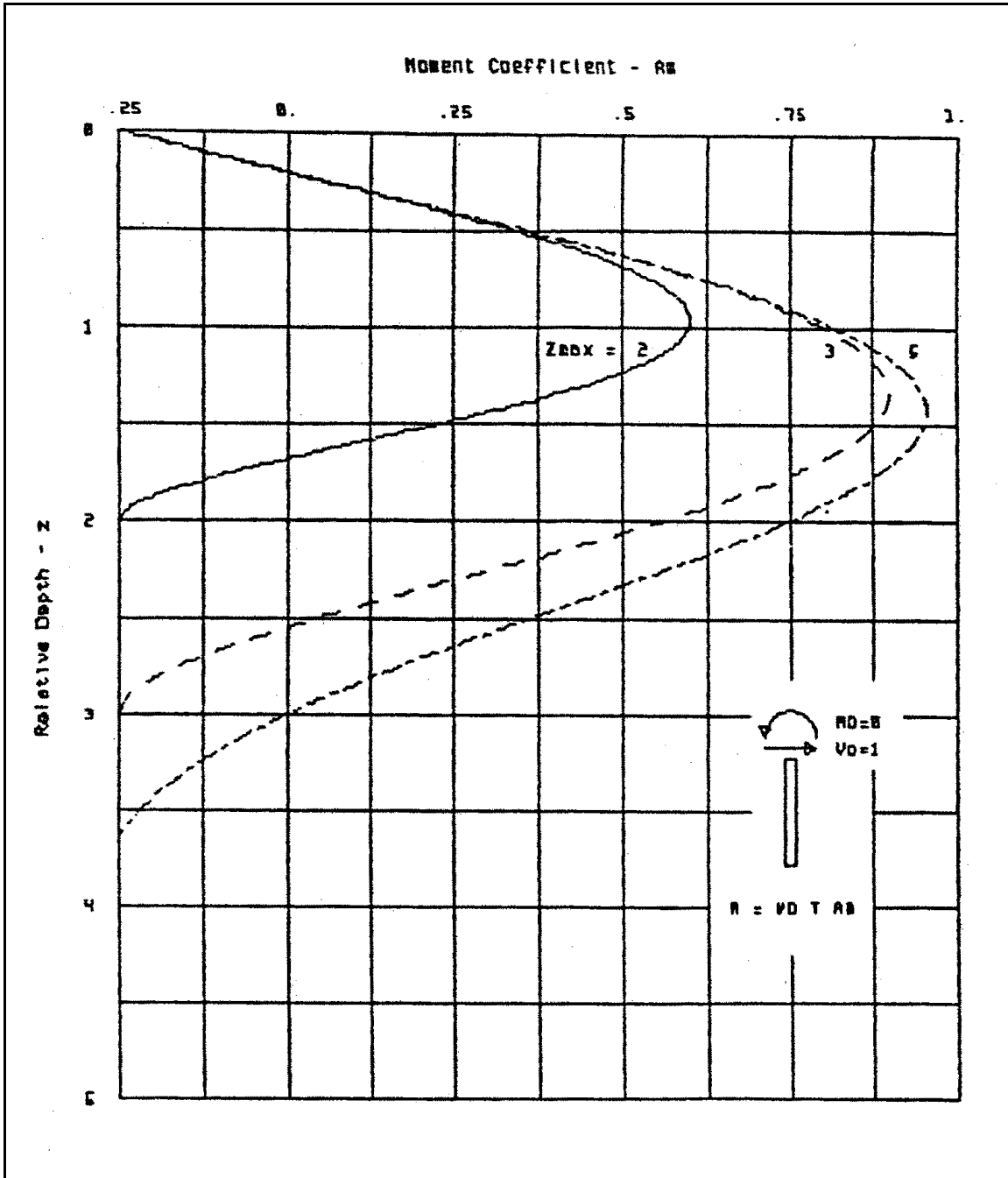


Figure B11. Bending moment coefficient for unit head shear for soil stiffness varying parabolically with depth

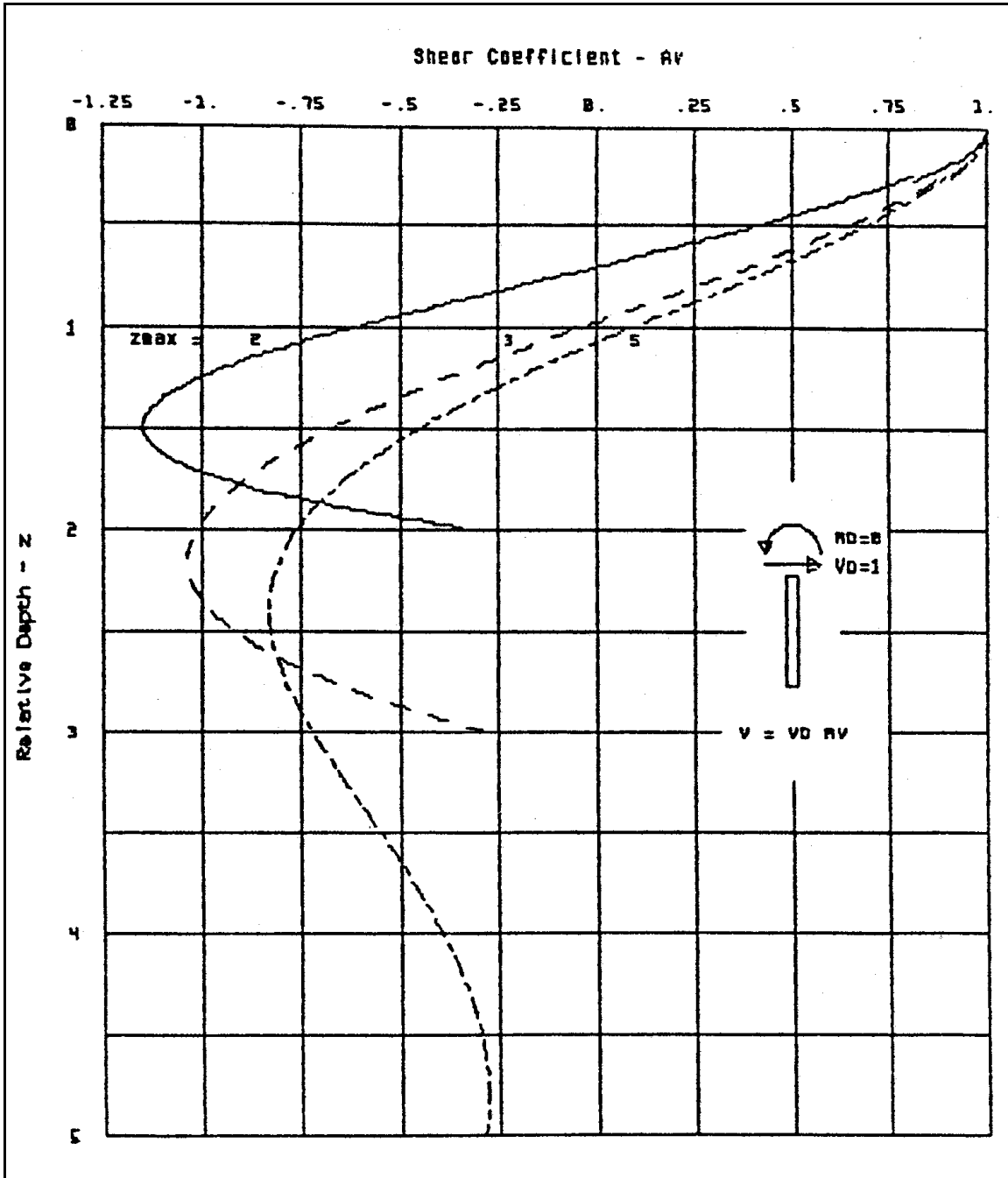


Figure B12. Shear coefficient for unit head shear for soil stiffness varying parabolically with depth

Table B5
Nondimensional Coefficients for Laterally Loaded Pile for Soil Modulus Varying
Parabolically with Depth (Head Shear $V_o = 1$, Head Moment $M_o = 0$)

Z	$Z_{max} = 2$			$Z_{max} = 3$			$Z_{max} = 4$		
	A_u	A_s	A_m	A_u	A_s	A_m	A_u	A_s	A_m
0.00	6.418	-4.348	0.000	3.039	-1.970	0.000	2.820	-1.884	0.000
0.10	5.983	-4.343	0.100	2.842	-1.965	0.100	2.631	-1.879	0.100
0.20	5.550	-4.328	0.199	2.647	-1.950	0.200	2.407	-1.859	0.219
0.30	5.118	-4.303	0.296	2.453	-1.925	0.298	2.259	-1.839	0.298
0.40	4.689	-4.269	0.389	2.262	-1.890	0.395	2.041	-1.796	0.414
0.50	4.265	-4.225	0.473	2.075	-1.846	0.487	1.898	-1.760	0.488
0.60	3.845	-4.174	0.548	1.893	-1.793	0.575	1.691	-1.695	0.594
0.70	3.430	-4.116	0.608	1.717	-1.732	0.655	1.557	-1.645	0.659
0.80	3.022	-4.053	0.651	1.547	-1.662	0.728	1.365	-1.560	0.748
0.90	2.619	-3.987	0.676	1.384	-1.586	0.790	1.243	-1.498	0.800
1.00	2.224	-3.919	0.679	1.230	-1.505	0.841	1.069	-1.398	0.865
1.10	1.836	-3.852	0.660	1.083	-1.418	0.880	0.960	-1.328	0.900
1.20	1.454	-3.788	0.619	0.946	-1.329	0.906	0.807	-1.217	0.938
1.30	1.078	-3.729	0.557	0.818	-1.238	0.918	0.712	-1.141	0.955
1.40	0.708	-3.677	0.477	0.699	-1.146	0.917	0.582	-1.026	0.964
1.50	0.342	-3.634	0.383	0.588	-1.055	0.902	0.503	-0.949	0.961
1.60	-0.019	-3.601	0.282	0.488	-0.966	0.873	0.396	-0.835	0.943
1.70	-0.378	-3.578	0.181	0.395	-0.881	0.832	0.333	-0.760	0.923
1.80	-0.735	-3.564	0.091	0.311	-0.800	0.780	0.248	-0.652	0.881
1.90	-1.091	-3.559	0.026	0.235	-0.725	0.718	0.199	-0.582	0.847
2.00	-1.447	-3.558	0.000	0.166	-0.657	0.647	0.135	-0.484	0.786
2.10				0.103	-0.596	0.570	0.099	-0.423	0.742
2.20				0.047	-0.543	0.488	0.053	-0.338	0.670
2.30				-0.005	-0.498	0.404	0.028	-0.287	0.619
2.40				-0.053	-0.462	0.320	-0.002	-0.217	0.542
2.50				-0.098	-0.434	0.239	-0.018	-0.176	0.491
2.60				-0.140	-0.414	0.164	-0.036	-0.121	0.416
2.70				-0.181	-0.401	0.099	-0.044	-0.090	0.367

(Continued)

Table B5 (Concluded)									
Z	Z_{max} = 2			Z_{max} = 3			Z_{max} = 4		
	A_u	A_s	A_m	A_u	A_s	A_m	A_u	A_s	A_m
2.80				-0.221	-0.394	0.047	-0.052	-0.050	0.298
2.90				-0.260	-0.391	0.013	-0.055	-0.028	0.256
3.00				-0.299	-0.390	0.000	-0.057	-0.001	0.198
3.10							-0.057	0.013	0.163
3.20							-0.054	0.030	0.117
3.30							-0.051	0.038	0.091
3.40							-0.046	0.047	0.059
3.50							-0.042	0.051	0.042
3.60							-0.036	0.055	0.023
3.70							-0.031	0.057	0.013
3.80							-0.024	0.058	0.004
3.90							-0.020	0.058	0.001
4.00							-0.014	0.058	0.000

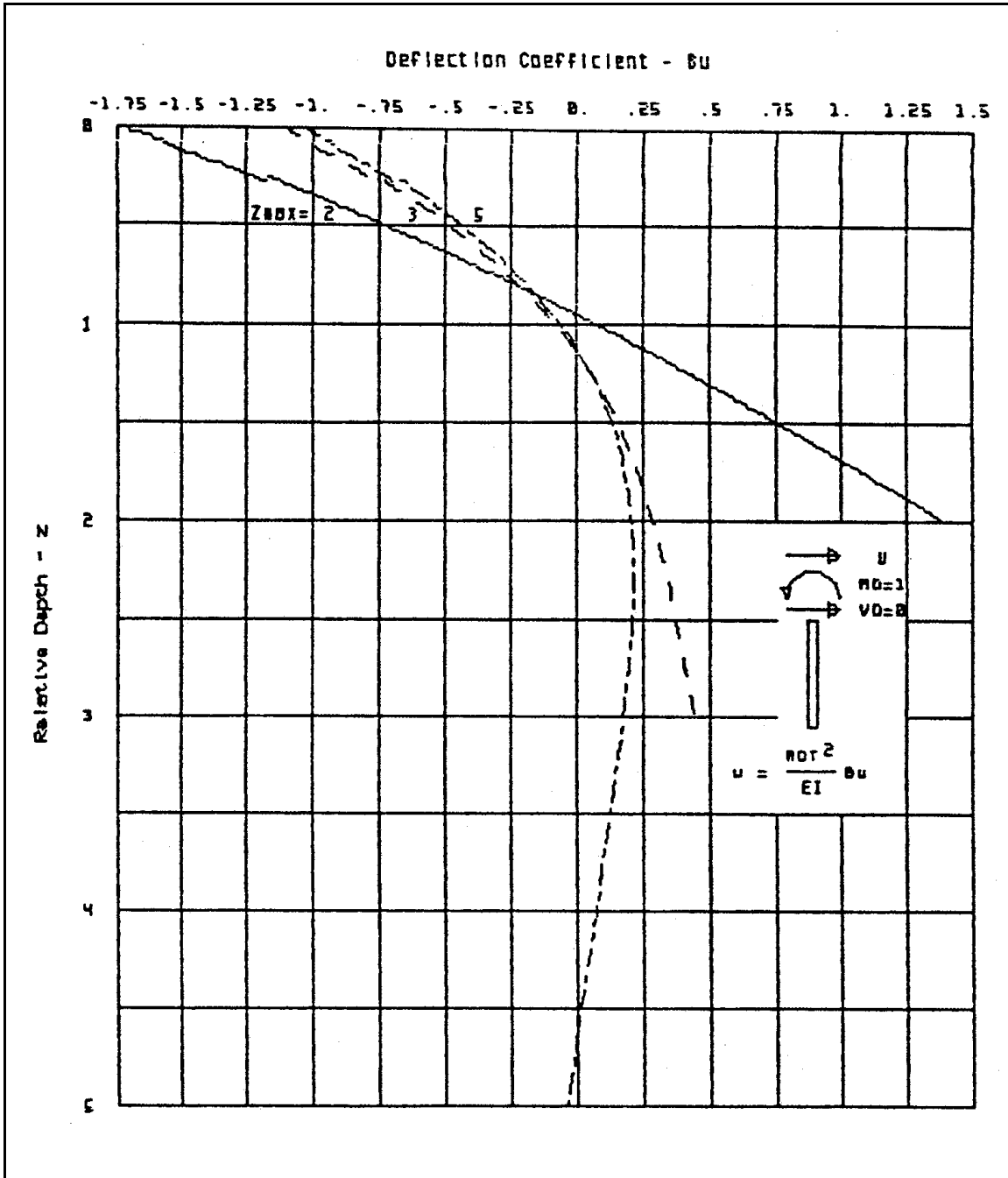


Figure B13. Deflection coefficient for unit head moment for soil stiffness constant with depth

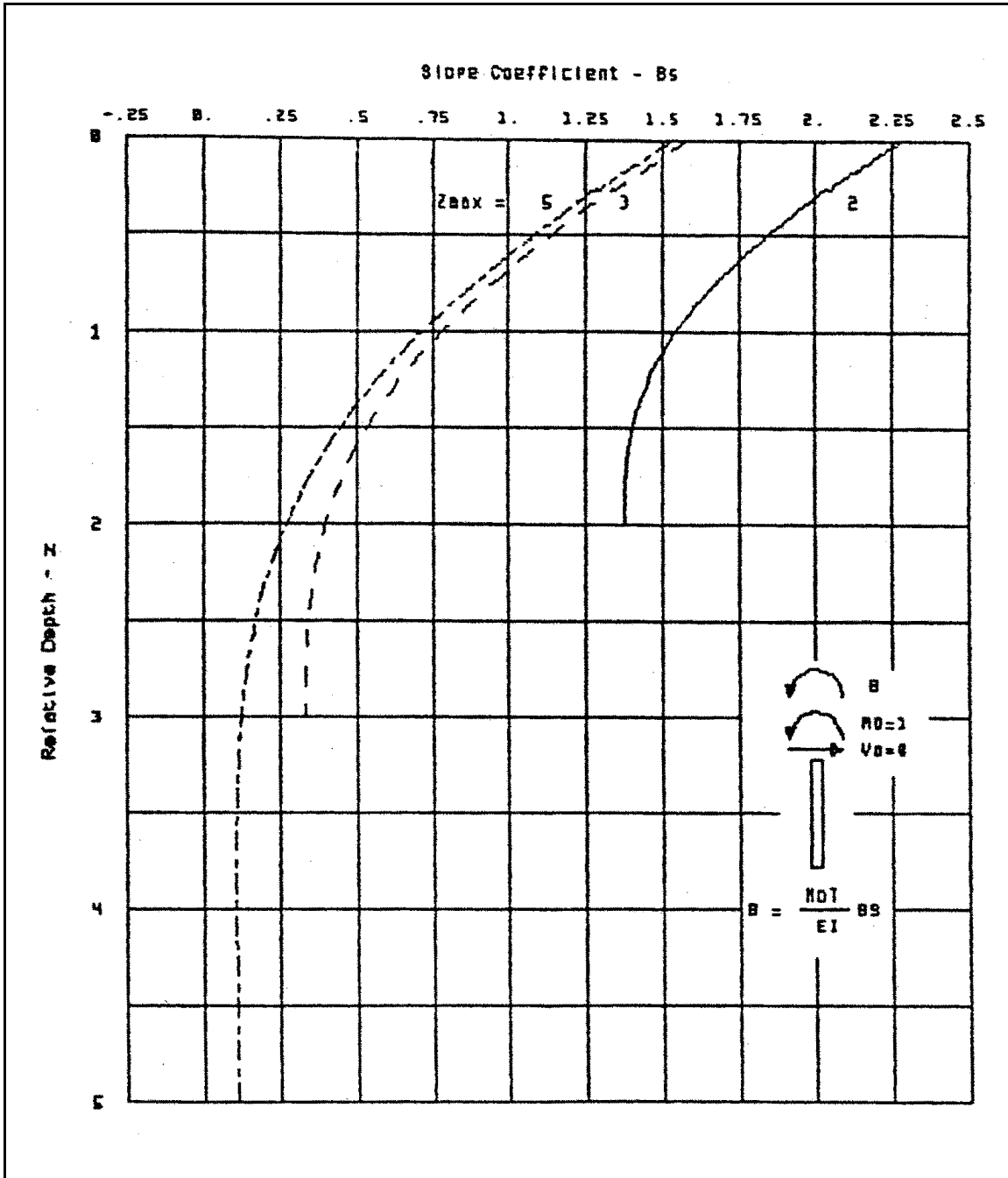


Figure B14. Slope coefficient for unit head moment for soil stiffness constant with depth

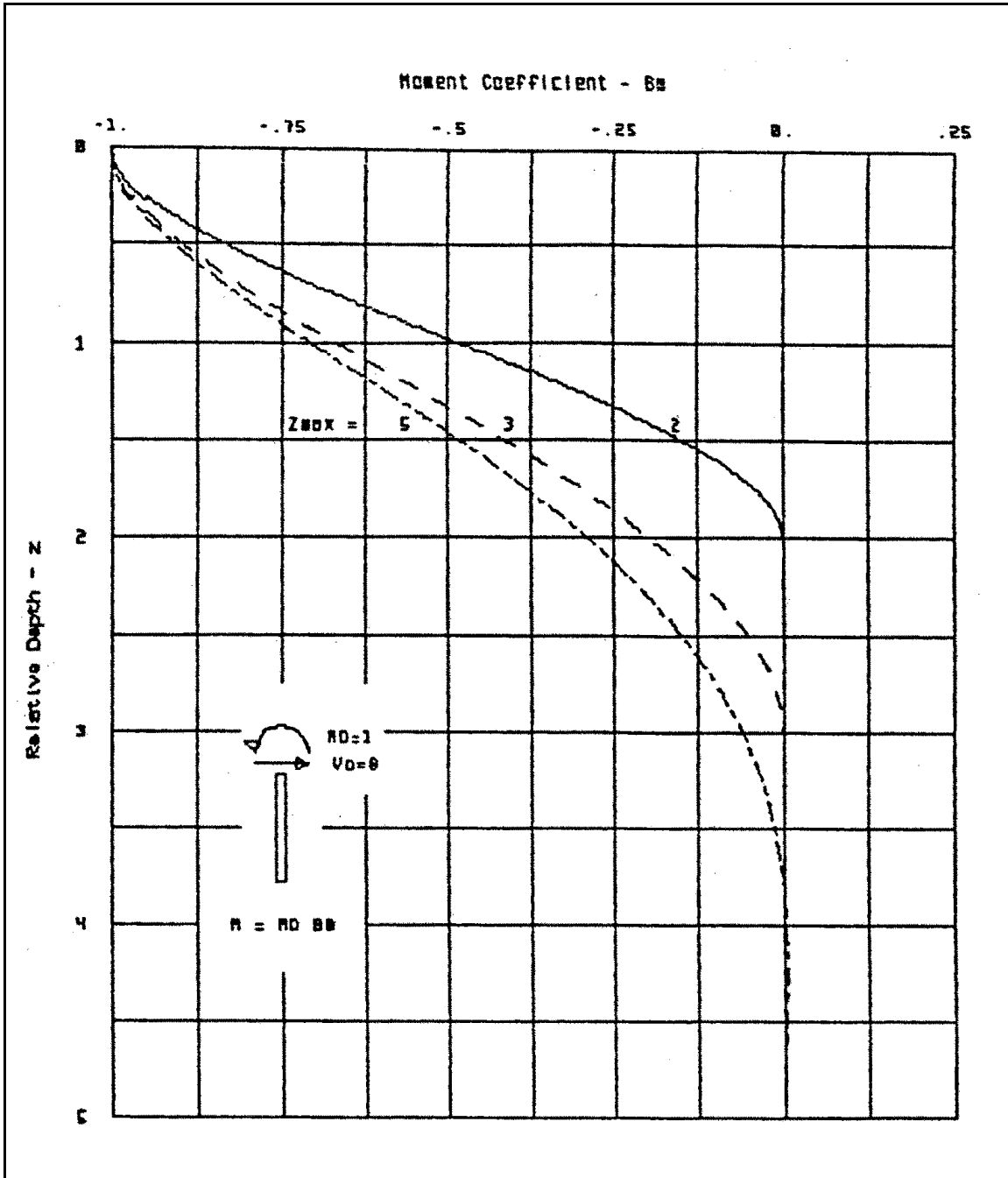


Figure B15. Bending moment coefficient for unit head moment for soil stiffness constant with depth

Table B6
Nondimensional Coefficients for Laterally Loaded Pile for Soil Modulus Varying
Parabolically with Depth (Head Shear $V_o = 0$, Head Moment $M_o = 1$)

Z	$Z_{max} = 2$			$Z_{max} = 3$			$Z_{max} = 4$		
	B_u	B_s	B_m	B_u	B_s	B_m	B_u	B_s	B_m
0.00	-4.348	3.624	-1.000	-1.970	1.925	-1.000	-1.884	1.888	-1.000
0.10	-3.990	3.524	-1.000	-1.783	1.825	-1.000	-1.700	1.788	-1.000
0.20	-3.643	3.424	-0.999	-1.605	1.725	-1.000	-1.493	1.668	-1.000
0.30	-3.306	3.324	-0.998	-1.438	1.625	-0.999	-1.362	1.589	-0.999
0.40	-2.978	3.224	-0.993	-1.280	1.525	-0.997	-1.179	1.469	-0.996
0.50	-2.661	3.125	-0.983	-1.133	1.425	-0.992	-1.065	1.389	-0.993
0.60	-2.353	3.028	-0.966	-0.995	1.326	-0.985	-0.905	1.271	-0.984
0.70	-2.055	2.932	-0.942	-0.867	1.228	-0.975	-0.807	1.192	-0.976
0.80	-1.767	2.840	-0.907	-0.749	1.132	-0.960	0.670	1.076	-0.959
0.90	-1.487	2.751	-0.860	-0.641	1.037	-0.940	-0.587	1.000	-0.944
1.00	-1.216	2.668	-0.802	-0.542	0.944	-0.915	-0.474	0.888	-0.916
1.10	-0.953	2.591	-0.732	-0.452	0.854	-0.885	-0.406	0.816	-0.893
1.20	-0.698	2.522	-0.650	-0.371	0.767	-0.850	-0.315	0.711	-0.853
1.30	-0.449	2.462	-0.559	-0.299	0.684	-0.808	-0.260	0.644	-0.822
1.40	-0.205	2.411	-0.460	-0.234	0.605	-0.762	-0.189	0.548	-0.771
1.50	0.034	2.370	-0.356	-0.177	0.532	-0.712	-0.147	0.488	-0.734
1.60	0.269	2.339	-0.254	-0.128	0.463	-0.657	-0.094	0.404	-0.675
1.70	0.502	2.319	-0.159	-0.085	0.400	-0.599	-0.064	0.351	-0.633
1.80	0.733	2.307	-0.078	-0.047	0.343	-0.539	-0.026	0.279	-0.569
1.90	0.964	2.302	-0.022	-0.016	0.293	-0.477	-0.006	0.235	-0.525
2.00	1.194	2.302	0.000	0.011	0.248	-0.415	0.019	0.176	-0.459
2.10				0.034	0.210	-0.353	0.032	0.141	-0.416
2.20				0.053	0.177	-0.292	0.046	0.095	-0.353
2.30				0.070	0.151	-0.235	0.052	0.069	-0.312
2.40				0.084	0.130	-0.180	0.058	0.035	-0.255
2.50				0.096	0.115	-0.131	0.060	0.016	-0.219
2.60				0.107	0.104	-0.088	0.061	-0.008	-0.171
2.70				0.117	0.097	-0.052	0.060	-0.020	-0.142

(Continued)

Table B6 (Concluded)									
Z	Z_{max} = 2			Z_{max} = 3			Z_{max} = 4		
	B_v	B_s	B_m	B_v	B_s	B	B	B_s	B_m
2.80				0.126	0.093	-0.024	0.056	-0.035	-0.103
2.90				0.136	0.092	-0.006	0.053	-0.042	-0.081
3.00				0.145	0.092	0.000	0.048	-0.050	-0.053
3.10							0.043	-0.054	-0.038
3.20							0.037	-0.057	-0.021
3.30							0.032	-0.059	-0.012
3.40							0.025	-0.060	-0.003
3.50							0.020	-0.060	0.000
3.60							0.013	-0.060	0.002
3.70							0.008	-0.059	0.003
3.80							0.001	-0.059	0.002
3.90							-0.004	-0.059	0.001
4.00							-0.009	-0.059	0.000

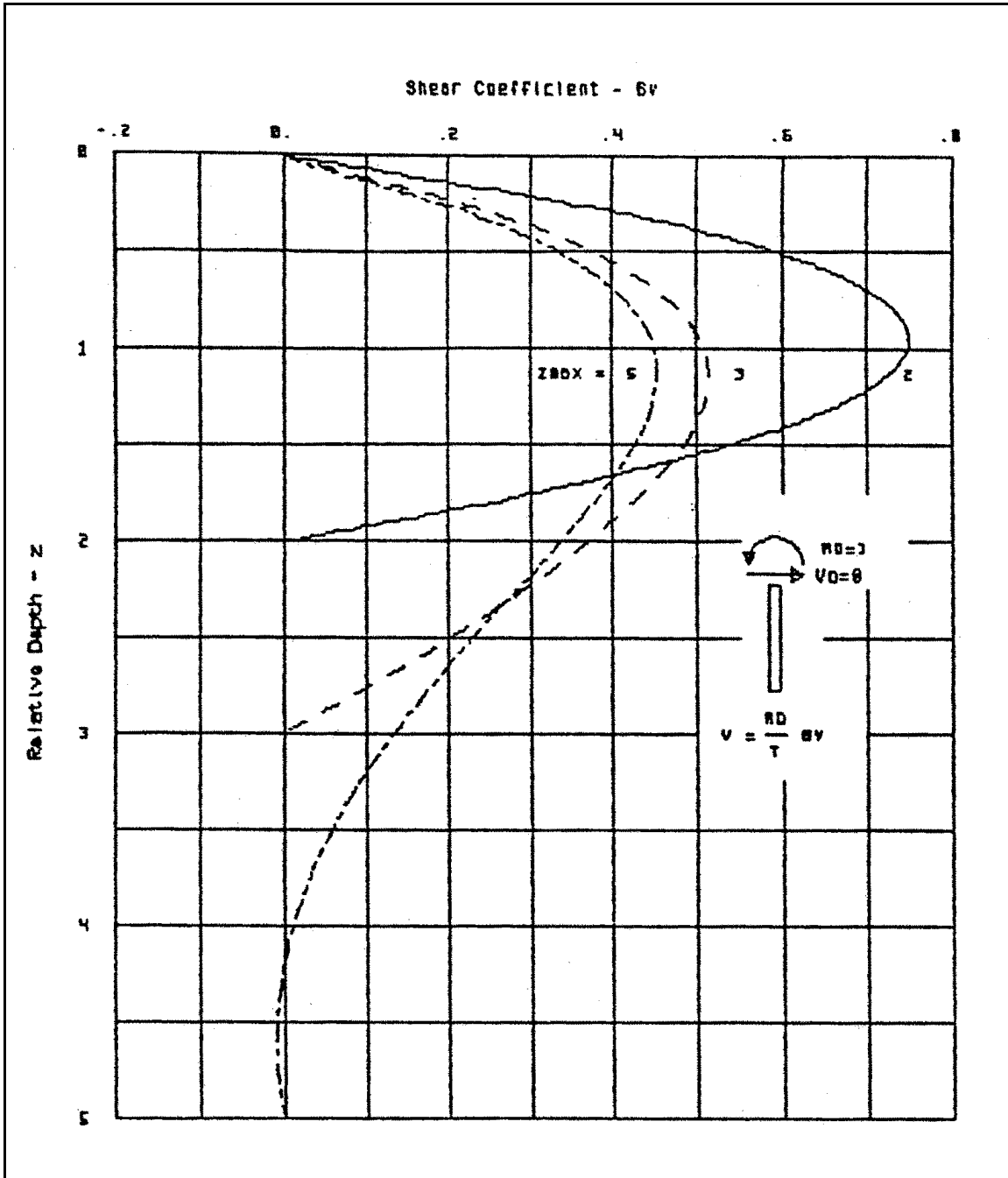


Figure B16. Shear coefficient for unit head moment for soil stiffness constant with depth

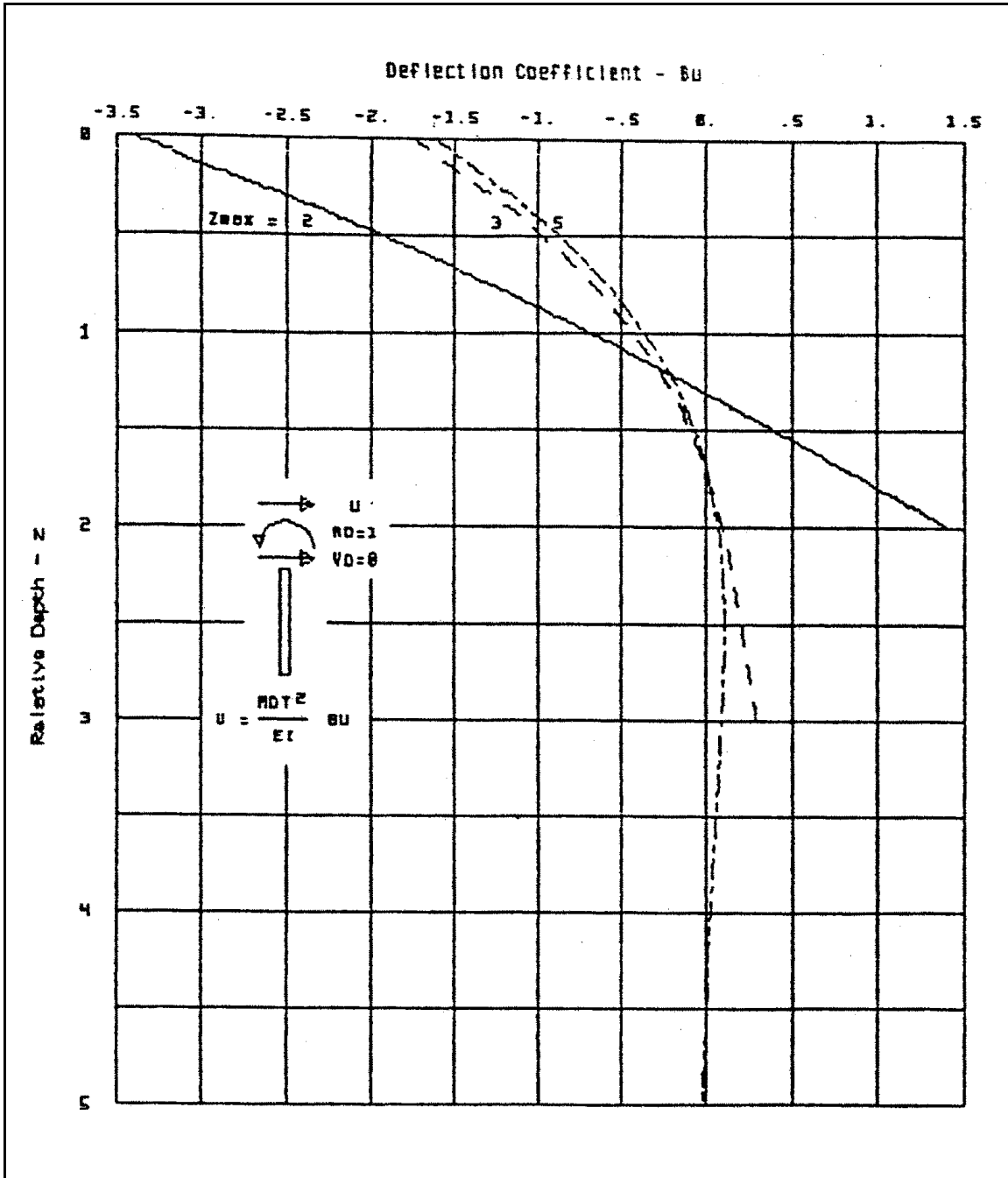


Figure B17. Deflection coefficient for unit head moment for soil stiffness constant with depth

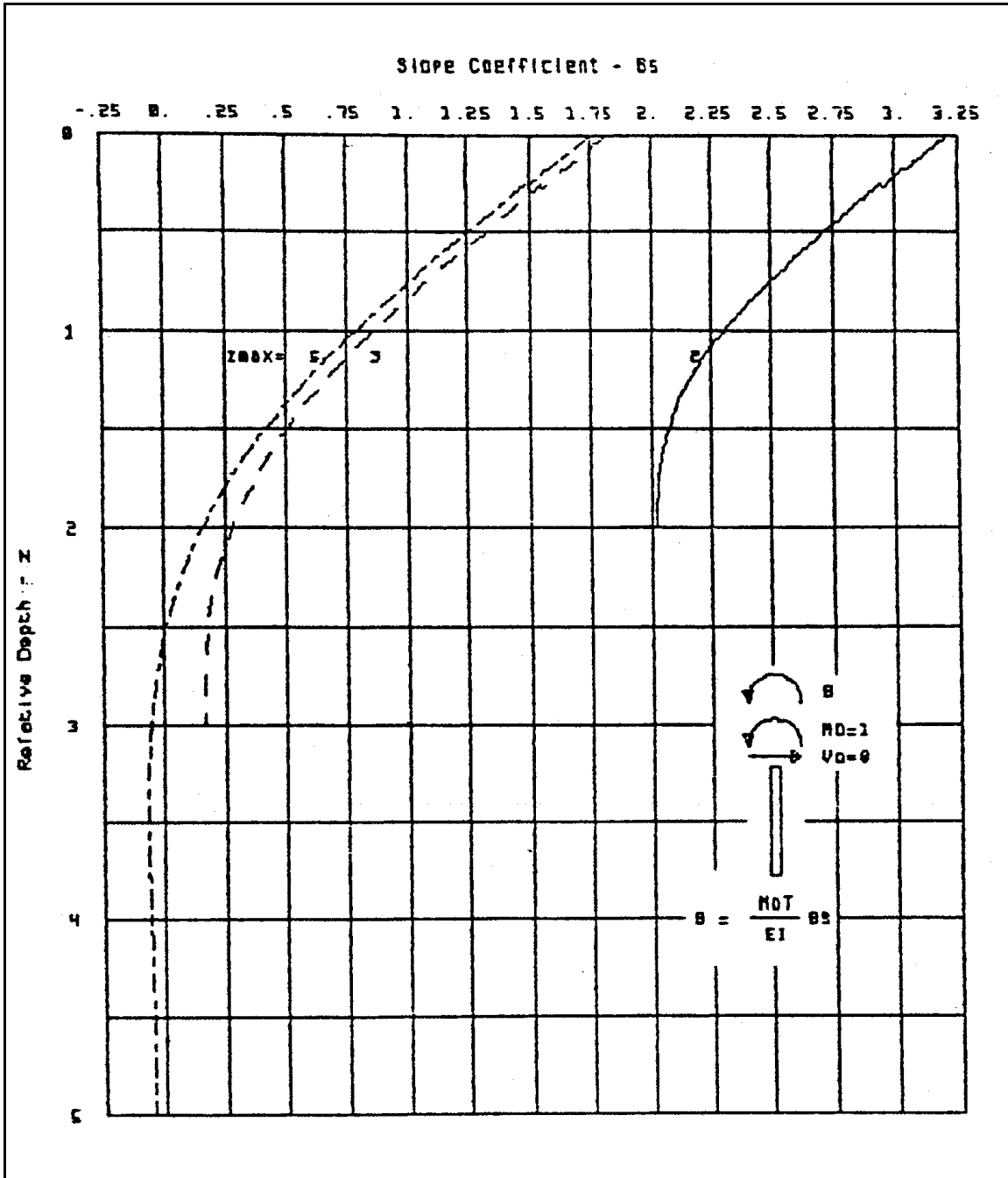


Figure B18. Slope coefficient for unit head moment for soil stiffness constant with depth

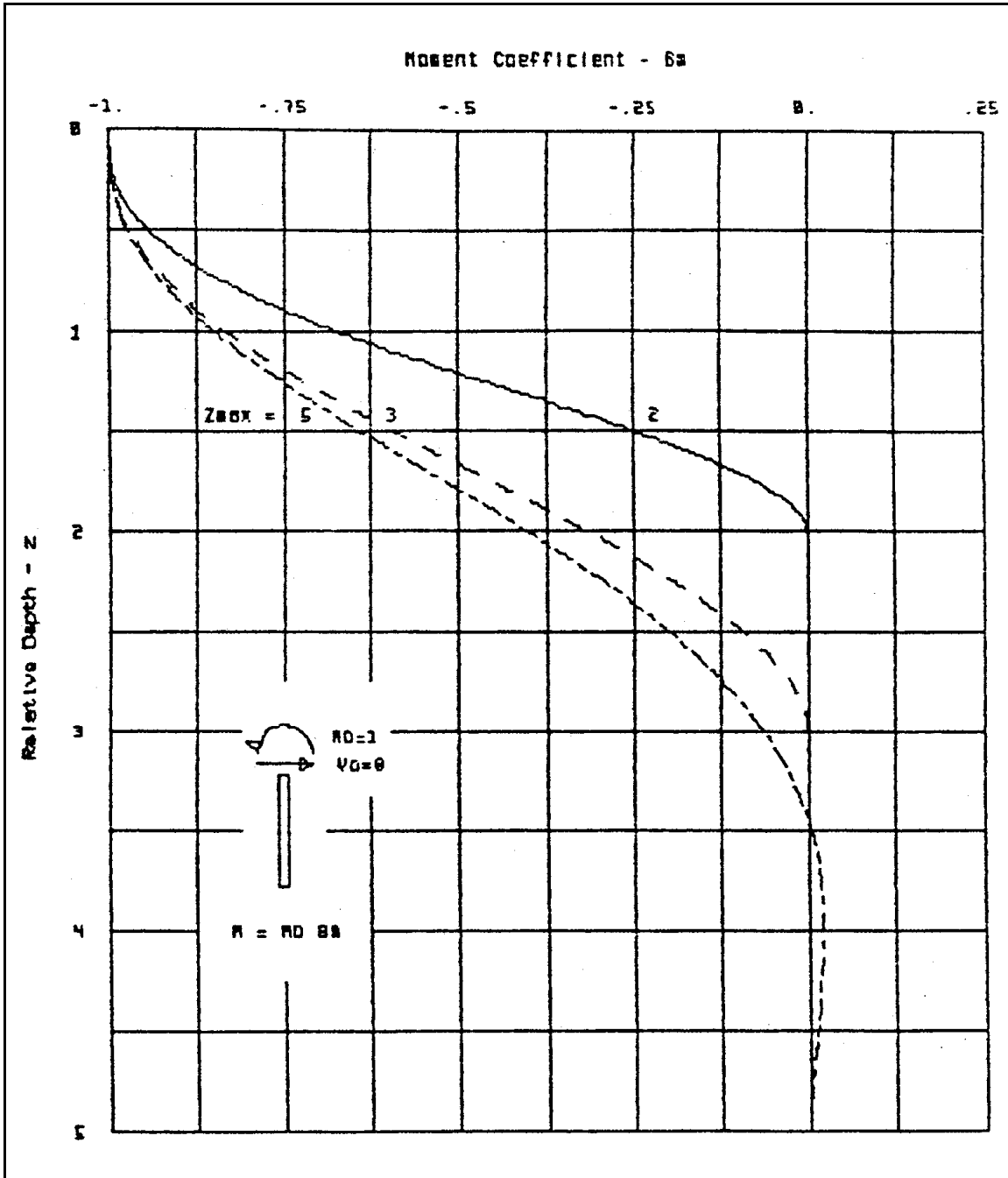


Figure B19. Bending moment coefficient for unit head moment for soil stiffness varying linearly with depth

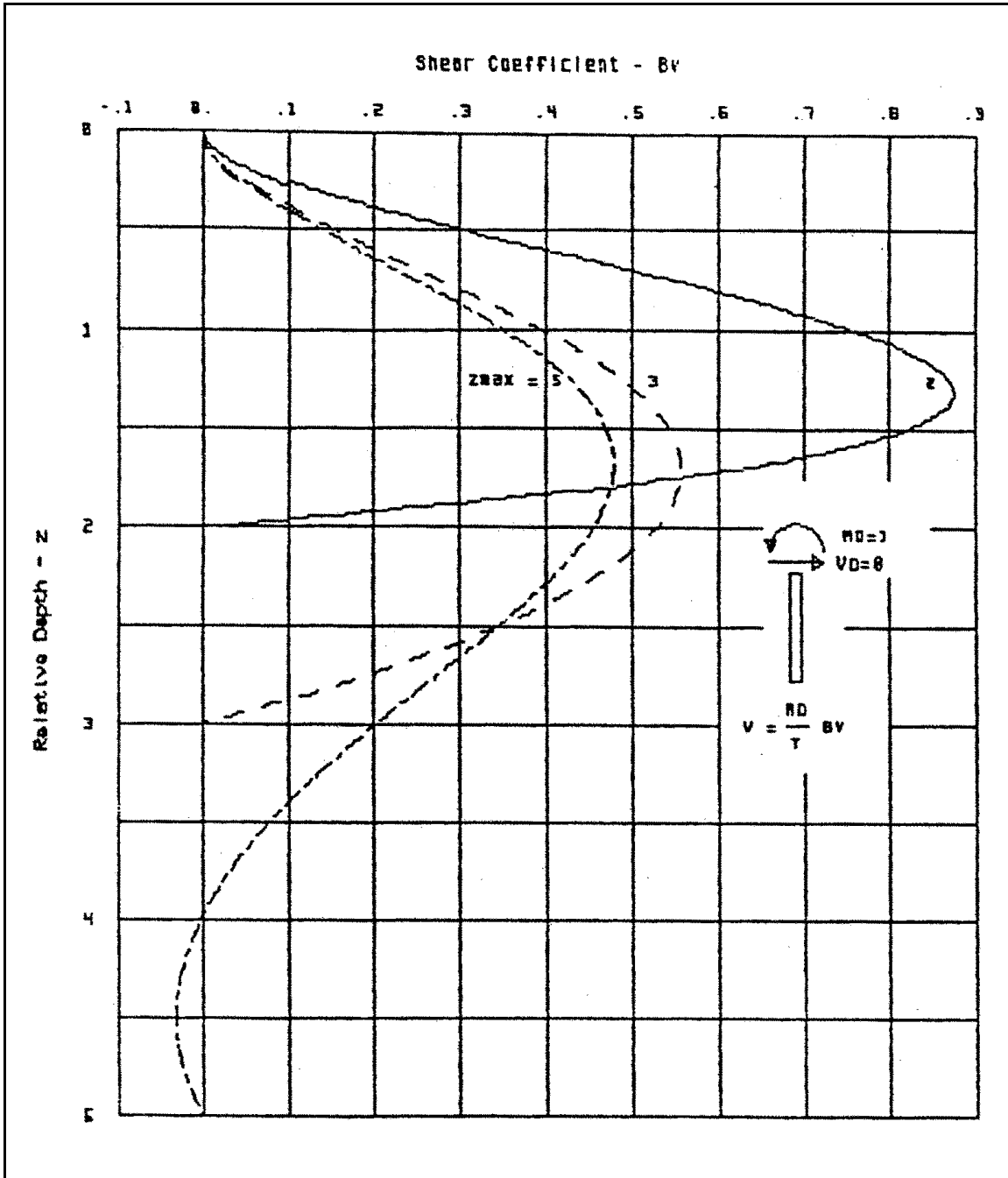


Figure B20. Shear coefficient for unit head moment for soil stiffness varying linearly with depth

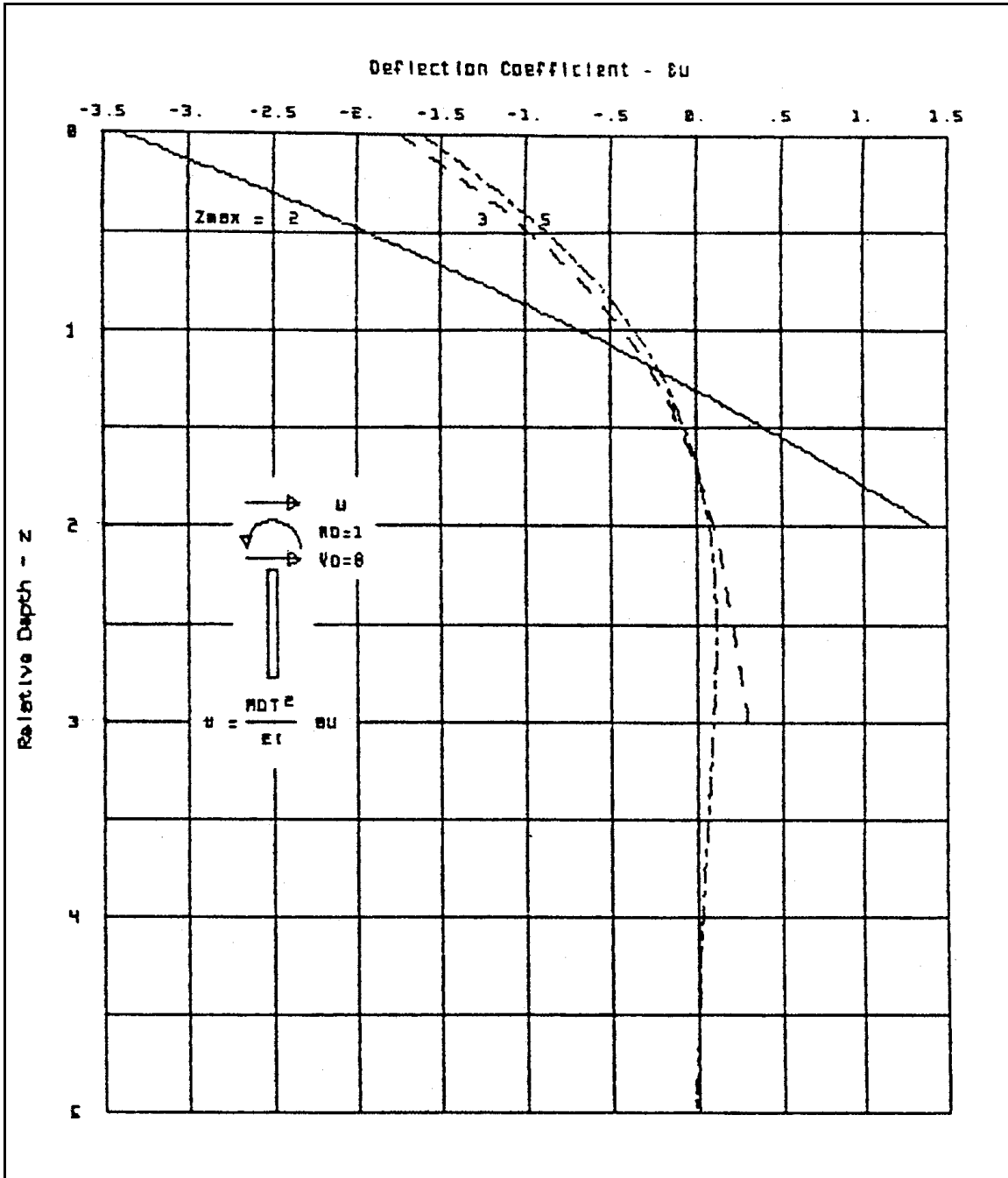


Figure B21. Deflection coefficient for unit head moment for soil stiffness varying parabolically with depth

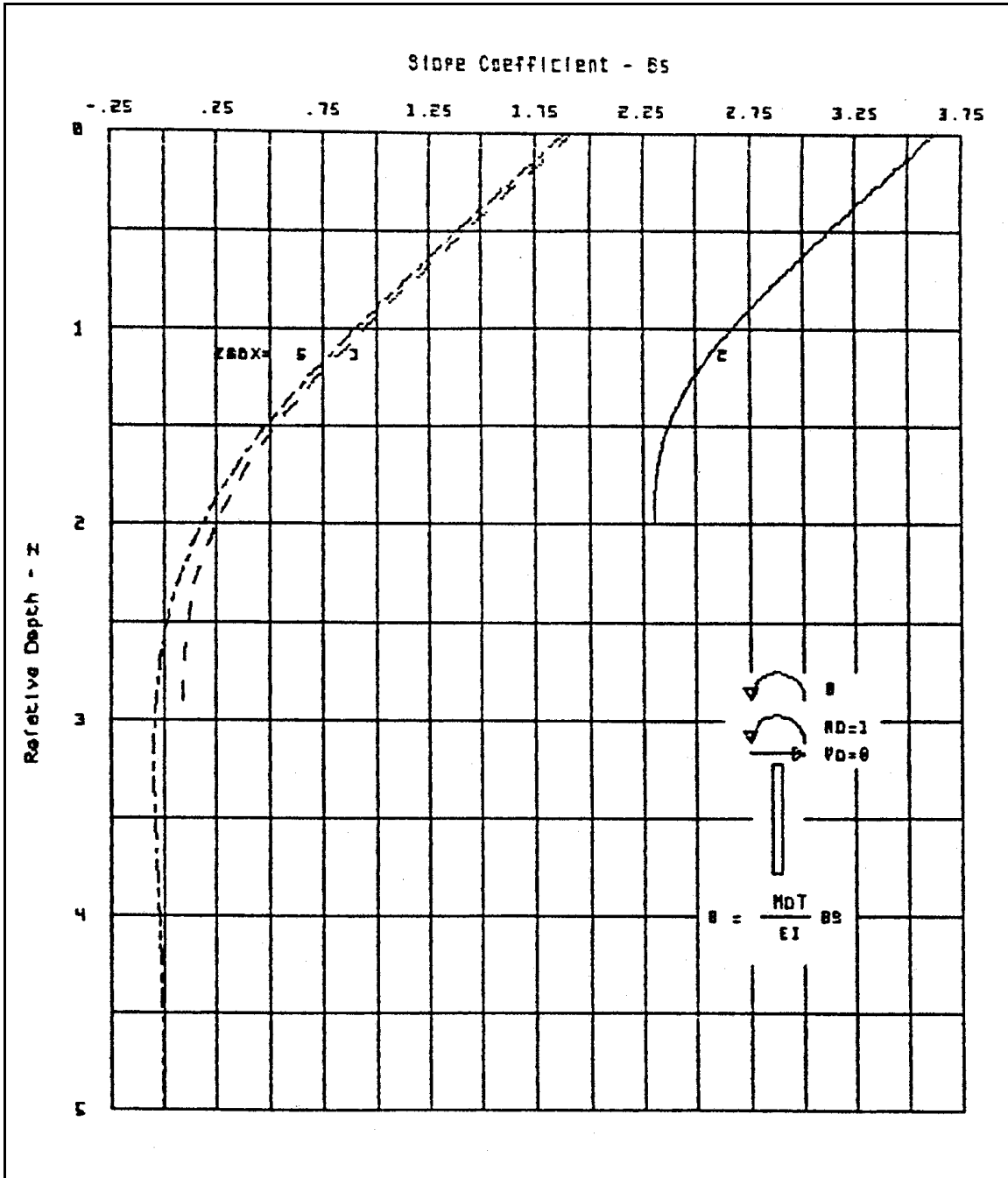


Figure B22. Slope coefficient for unit head moment for soil stiffness varying parabolically with depth

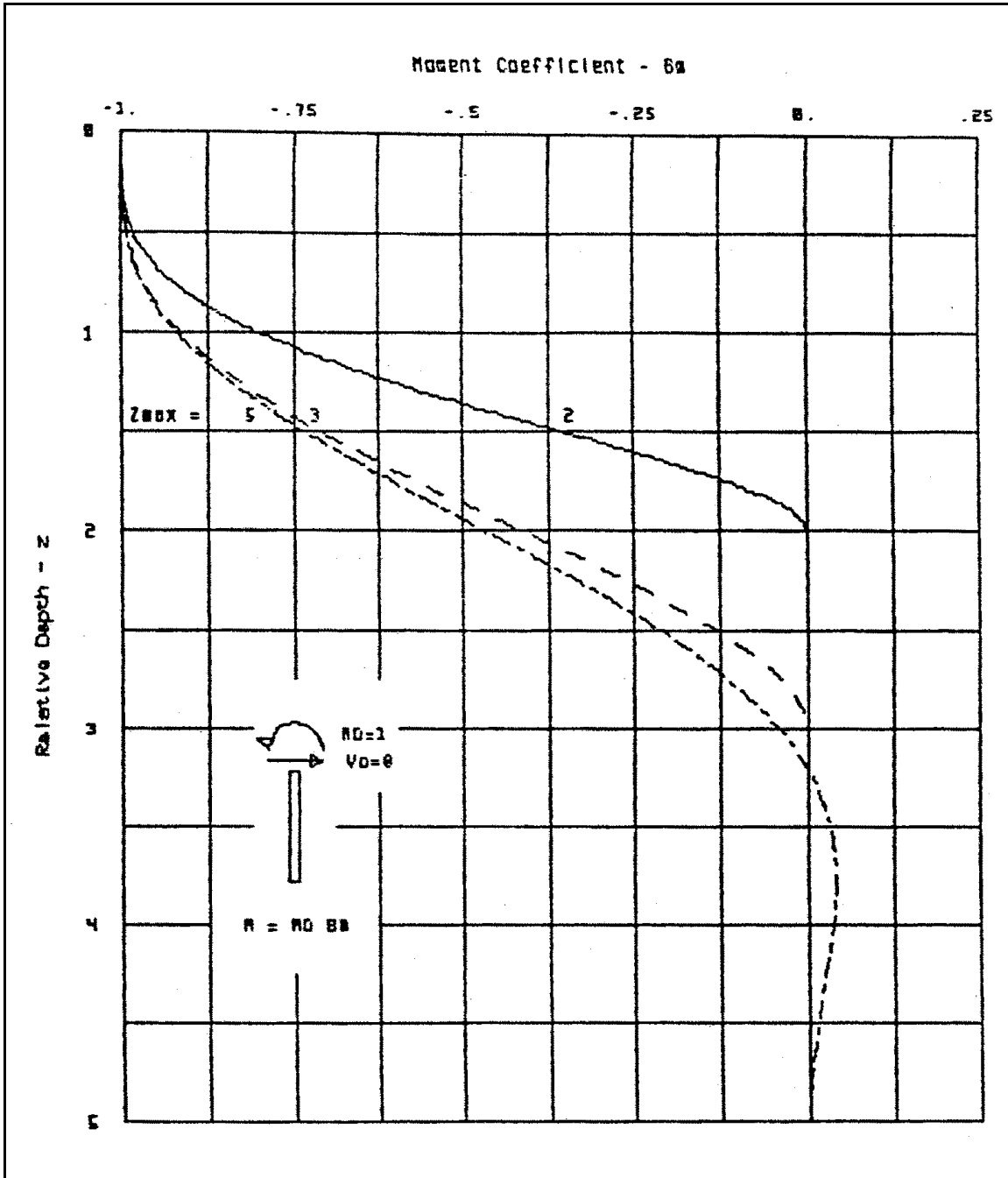


Figure B23. Bending moment coefficient for unit head moment for soil stiffness varying parabolically with depth

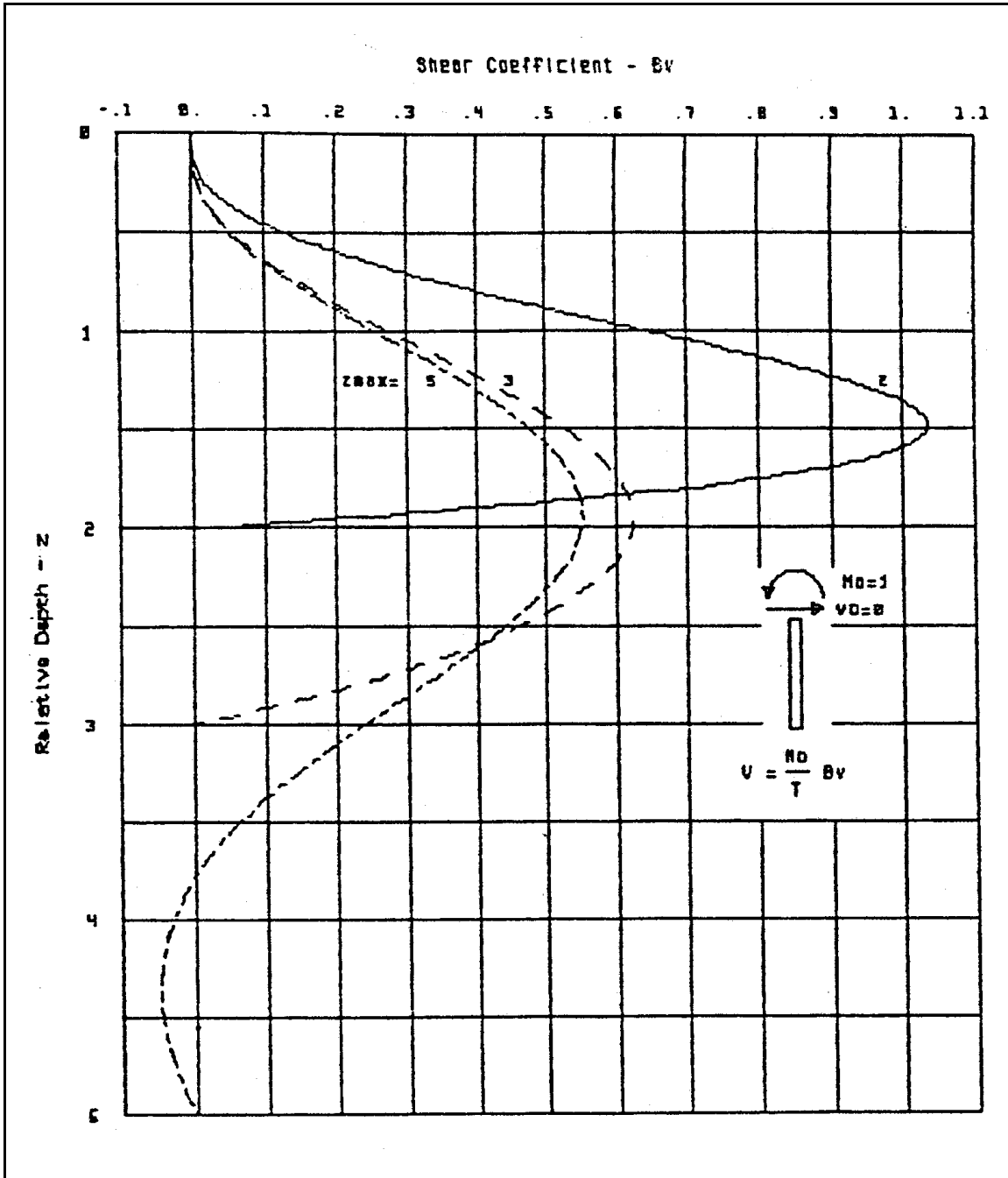


Figure B24. Shear coefficient for unit head moment for soil stiffness varying parabolically with depth

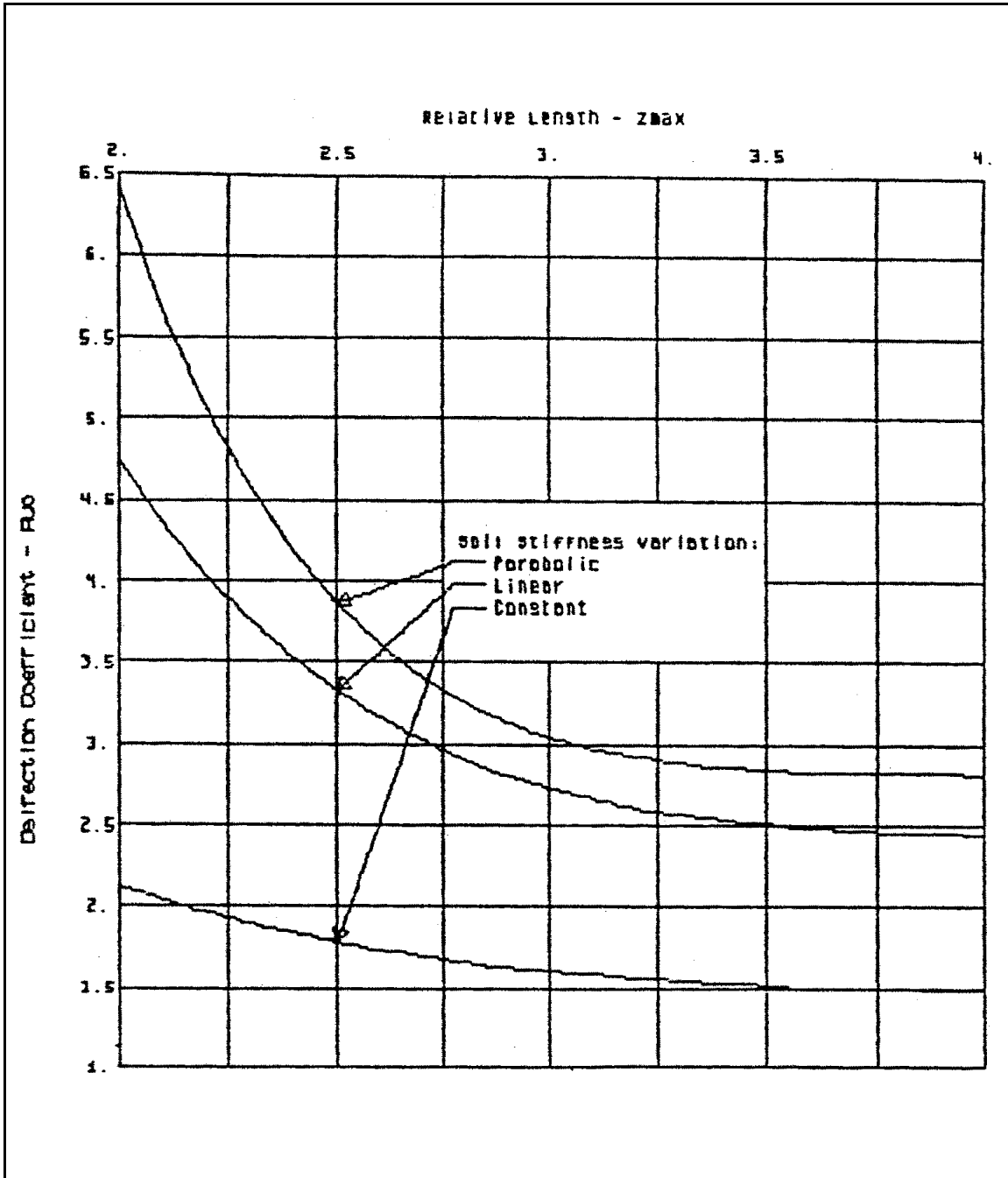


Figure B25. Pile head deflection coefficients for unit head shear

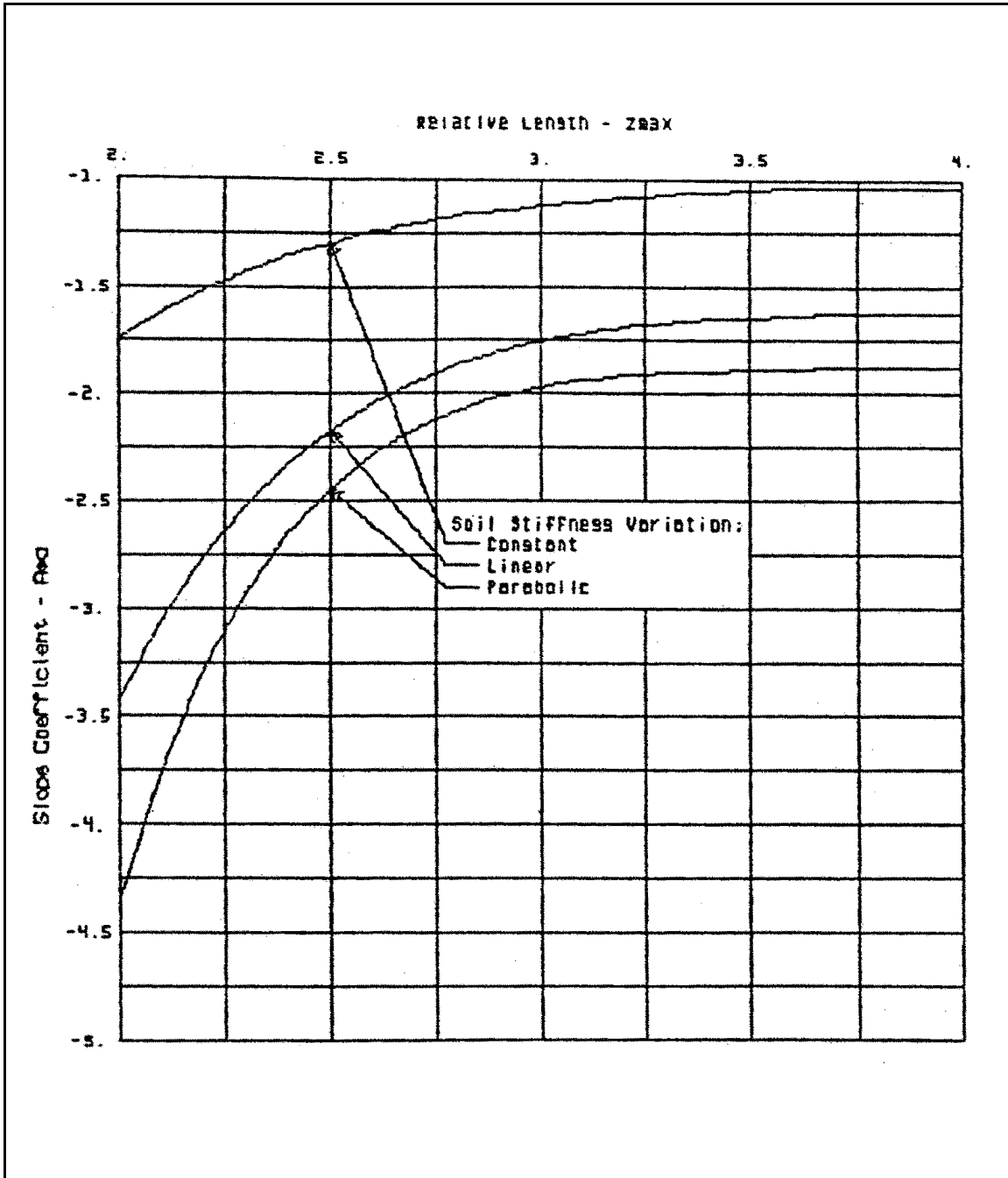


Figure B26. Pile head slope coefficients for unit head shear

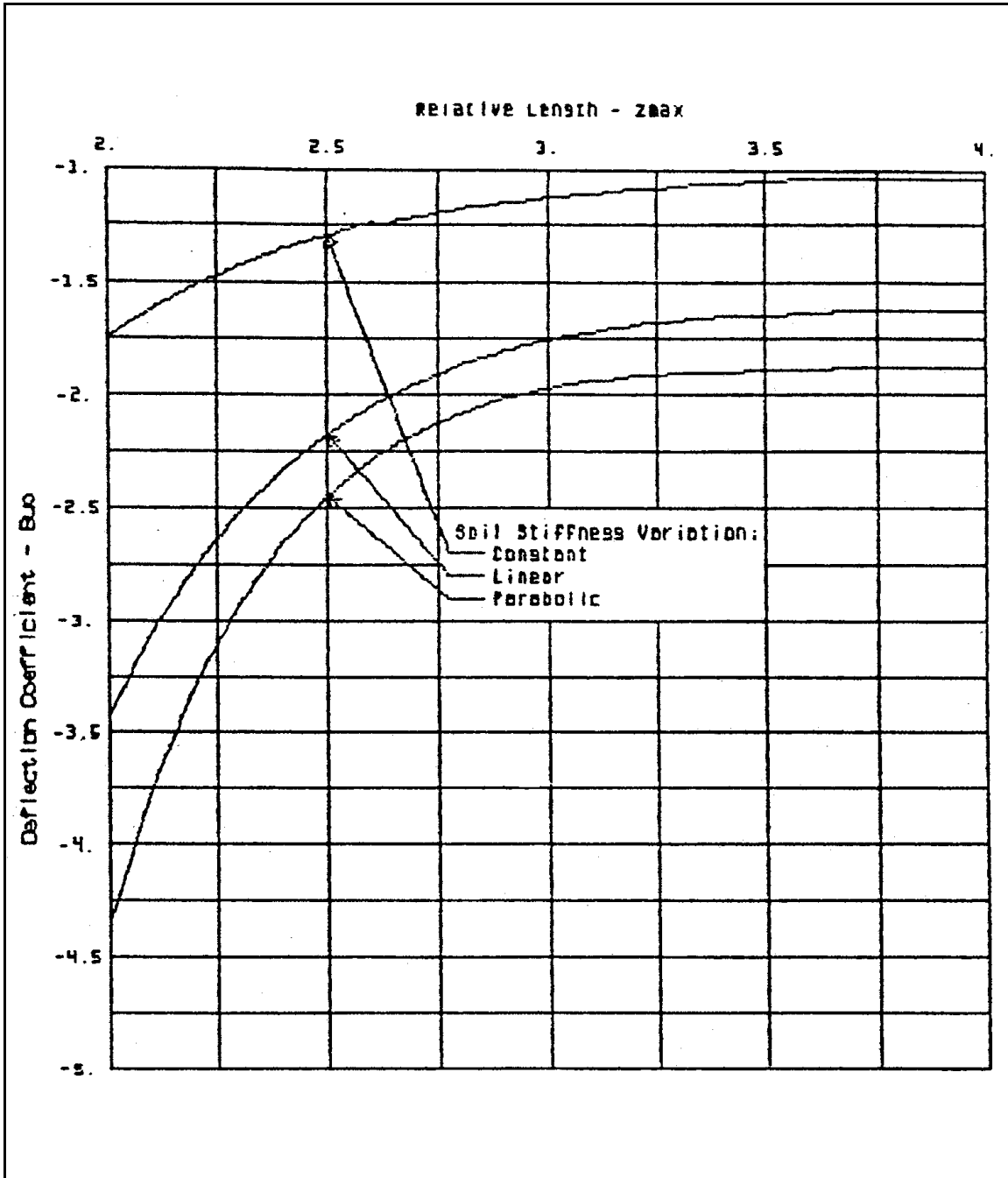


Figure B27. Pile head deflection coefficients for unit head moment

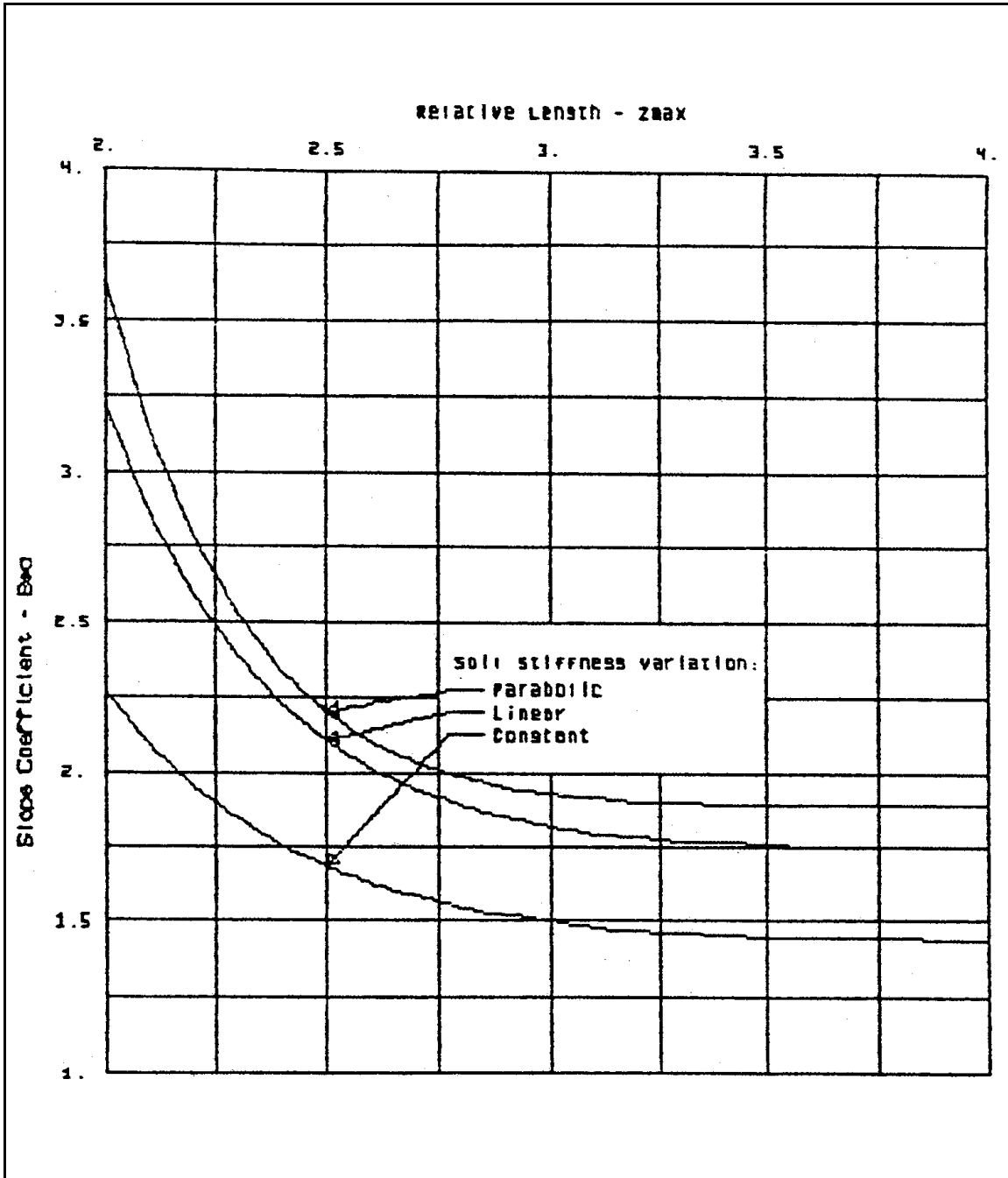


Figure B28. Pile head slope coefficients for unit head moment

REPORTS PUBLISHED UNDER THE COMPUTER-AIDED STRUCTURAL ENGINEERING (CASE) PROJECT

	Title	Date
Technical Report K-78-1	List of Computer Programs for Computer-Aided Structural Engineering	Feb 1978
Instruction Report 0-79-2	User's Guide: Computer Program with Interactive Graphics for Analysis of Plane Frame Structures (CFRAME)	Mar 1979
Technical Report K-80-1	Survey of Bridge-Oriented Design Software	Jan 1980
Technical Report K-80-2	Evaluation of Computer Programs for the Design/Analysis of Highway and Railway Bridges	Jan 1980
Instruction Report K-80-1	User's Guide: Computer Program for Design/Review of Curvi-linear Conduits/Culverts (CURCON)	Feb 1980
Instruction Report K-80-3	A Three-Dimensional Finite Element Data Edit Program	Mar 1980
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Instruction Report K-80-6	Basic User's Guide: Computer Program for Design and Analysis of Inverted-T Retaining Walls and Floodwalls (TWDA)	Dec 1980
Instruction Report K-80-7	User's Reference Manual: Computer Program for Design and Analysis of Inverted-T Retaining Walls and Floodwalls (TWDA)	Dec 1980
Technical Report K-80-4	Documentation of Finite Element Analyses Report 1: Longview Outlet Works Conduit Report 2: Anchored Wall Monolith, Bay Springs Lock	Dec 1980 Dec 1980
Technical Report K-80-5	Basic Pile Group Behavior	Dec 1980
Instruction Report K-81-2	User's Guide: Computer Program for Design and Analysis of Sheet Pile Walls by Classical Methods (CSHTWAL) Report 1: Computational Processes Report 2: Interactive Graphics Options	Feb 1981 Mar 1981
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Instruction Report K-81-4	User's Guide: Computer Program for Design and Analysis of Cast-in-Place Tunnel Linings (NEWTUN)	Mar 1981
Instruction Report K-81-6	User's Guide: Computer Program for Optimum Nonlinear Dynamic Design of Reinforced Concrete Slabs Under Blast Loading (CBARCS)	Mar 1981
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Technical Report K-81-2	Theoretical Basis for CTABS80: A Computer Program for Three-Dimensional Analysis of Building Systems	Sep 1981

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Instruction Report K-82-7	User's Guide: Computer Program for Bearing Capacity Analysis of Shallow Foundations (CBEAR)	Jun 1982
Instruction Report K-83-1	User's Guide: Computer Program with Interactive Graphics for Analysis of Plane Frame Structures (CFRAME)	Jan 1983
Instruction Report K-83-2	User's Guide: Computer Program for Generation of Engineering Geometry (SKETCH)	Jun 1983
Instruction Report K-83-5	User's Guide: Computer Program to Calculate Shear, Moment, and Thrust (CSMT) from Stress Results of a Two-Dimensional Finite Element Analysis	Jul 1983
Technical Report K-83-1	Basic Pile Group Behavior	Sep 1983
Technical Report K-83-3	Reference Manual: Computer Graphics Program for Generation of Engineering Geometry (SKETCH)	Sep 1983
Technical Report K-83-4	Case Study of Six Major General-Purpose Finite Element Programs	Oct 1983
Instruction Report K-84-2	User's Guide: Computer Program for Optimum Dynamic Design of Nonlinear Metal Plates Under Blast Loading (CSDOOR)	Jan 1984
Instruction Report K-84-7	User's Guide: Computer Program for Determining Induced Stresses and Consolidation Settlements (CSETT)	Aug 1984
Instruction Report K-84-8	Seepage Analysis of Confined Flow Problems by the Method of Fragments (CFRAG)	Sep 1984
Instruction Report K-84-11	User's Guide for Computer Program CGFAG, Concrete General Flexure Analysis with Graphics	Sep 1984
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Technical Report ATC-86-5	Decision Logic Table Formulation of ACI 318-77, Building Code Requirements for Reinforced Concrete for Automated Constraint Processing, Volumes I and 11	Jun 1986
Technical Report ITL-87-2	A Case Committee Study of Finite Element Analysis of Concrete Flat Slabs	Jan 1987
Instruction Report ITL-87-2 (Revised)	User's Guide for Concrete Strength Investigation and Design (CASTR) in Accordance with ACI 318-89	Mar 1992
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	Report 2: General Loads Module	Sep 1989
	Report 6: Free-Body Module	Sep 1989
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Technical Report ITL-87-4	Finite Element Studies of a Horizontally Framed Miter Gate	Aug 1987
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Instruction Report ITL-87-5	Sliding Stability of Concrete Structures (CSLIDE)	Oct 1987
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Technical Report ITL-88-2	User's Guide: Pile Group Graphics Display (CPGG) Postprocessor to CPGA Program	Apr 1988
Instruction Report ITL-88-2	User's Guide for Design and Investigation of Horizontally Framed Miter Gates (CMITER)	Jun 1988
Instruction Report ITL-88-4	User's Guide for Revised Computer Program to Calculate Shear, Moment, and Thrust (CSMT)	Sep 1988
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Technical Report ITL-89-6	The Response-Spectrum Dynamic Analysis of Gravity Dams Using the Finite Element Method; Phase 11	Aug 1989
Contract Report ITL-89-1	State of the Art on Expert Systems Applications in Design, Construction, and Maintenance of Structures	Sep 1989
Instruction Report ITL-90-1	User's Guide: Computer Program for Design and Analysis of Sheet Pile Walls by Classical Methods (CWALSHT)	Feb 1990
Instruction Report ITL-90-2	User's Guide: Pile Group-Concrete Pile Analysis Program (CPGC) Preprocessor to CPGA Program	Jun 1990
Instruction Report ITL-90-3	Investigation and Design of U-Frame Structures Using Program CUFRCB Volume A: Program Criteria and Documentation Volume B: User's Guide for Basins Volume C: User's Guide for Channels	May 1990 May 1990 May 1990
Instruction Report ITL-90-6	User's Guide: Computer Program for Two-Dimensional Analysis of U-Frame or W-Frame Structures (CWFRAM)	Sep 1990
Technical Report ITL-91-3	Application of Finite Element, Grid Generation, and Scientific Visualization Techniques to 2-D and 3-D Seepage and Groundwater Modeling	Sep 1990
Instruction Report ITL-91-1	User's Guide: Computer Program for Design and Analysis of Sheet-Pile Walls by Classical Methods (CWALSHT) Including Rowe's Moment Reduction	Oct 1991
Technical Report ITL-92-2	Finite Element Modeling of Welded Thick Plates for Bonneville Navigation Lock	May 1992
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Instruction Report ITL-92-3	Concept Design Example, Computer-Aided Structural Modeling (CASM) Report 1: Scheme A Report 2: Scheme B Report 3: Scheme C	Jun 1992 Jun 1992 Jun 1992
Instruction Report ITL-92-4	User's Guide: Computer-Aided Structural Modeling (CASM) – Version 3.00	Apr 1992
Instruction Report ITL-92-5	Tutorial Guide: Computer-Aided Structural Modeling (CASM) - Version 3.00	Apr 1992

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Instruction Report GL-87-1	User's Guide: UTEXAS3 Slope-Stability Package; Volume IV, User's Manual	Nov 1992
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Technical Report ITL-93-2	Steel Structures for Civil Works, General Considerations for Design and Rehabilitation	Aug 1993
Technical Report ITL-93-3	Soil-Structure Interaction Study of Red River Lock and Dam No. 1 Subjected to Sediment Loading	Sep 1993
Instruction Report ITL-93-3	User's Manual-ADAP, Graphics-Based Dam Analysis Program	Aug 1993
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Technical Report ITL-94-2	User's Guide for the Incremental Construction, Soil-Structure Interaction Program SOILSTRUCT with Far-Field Boundary Elements	Mar 1994
Instruction Report ITL-94-1	Tutorial Guide: Computer-Aided Structural Modeling (CASM); Version 5.00	Apr 1994
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Technical Report ITL-94-4	Dynamics of Intake Towers and Other MDOF Structures Under Earthquake Loads: A Computer-Aided Approach	Jul 1994
Technical Report ITL-94-5	Procedure for Static Analysis of Gravity Dams Including Foundation Effects Using the Finite Element Method - Phase 1 B	Jul 1994

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Instruction Report ITL-94-5	User's Guide: Computer Program for Winkler Soil-Structure Interaction Analysis of Sheet-Pile Walls (CWALSSI)	Nov 1994
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Instruction Report ITL-96-1	User's Guide: Computer Program for Two-Dimensional Dynamic Analysis of U-Frame or W-Frame Structures (CDWFRM)	Jun 1996
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ERDC/ITL TR-00-1	Evaluation and Comparison of Stability Analysis and Uplift Criteria for Concrete Gravity Dams by Three Federal Agencies	Jan 2000
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