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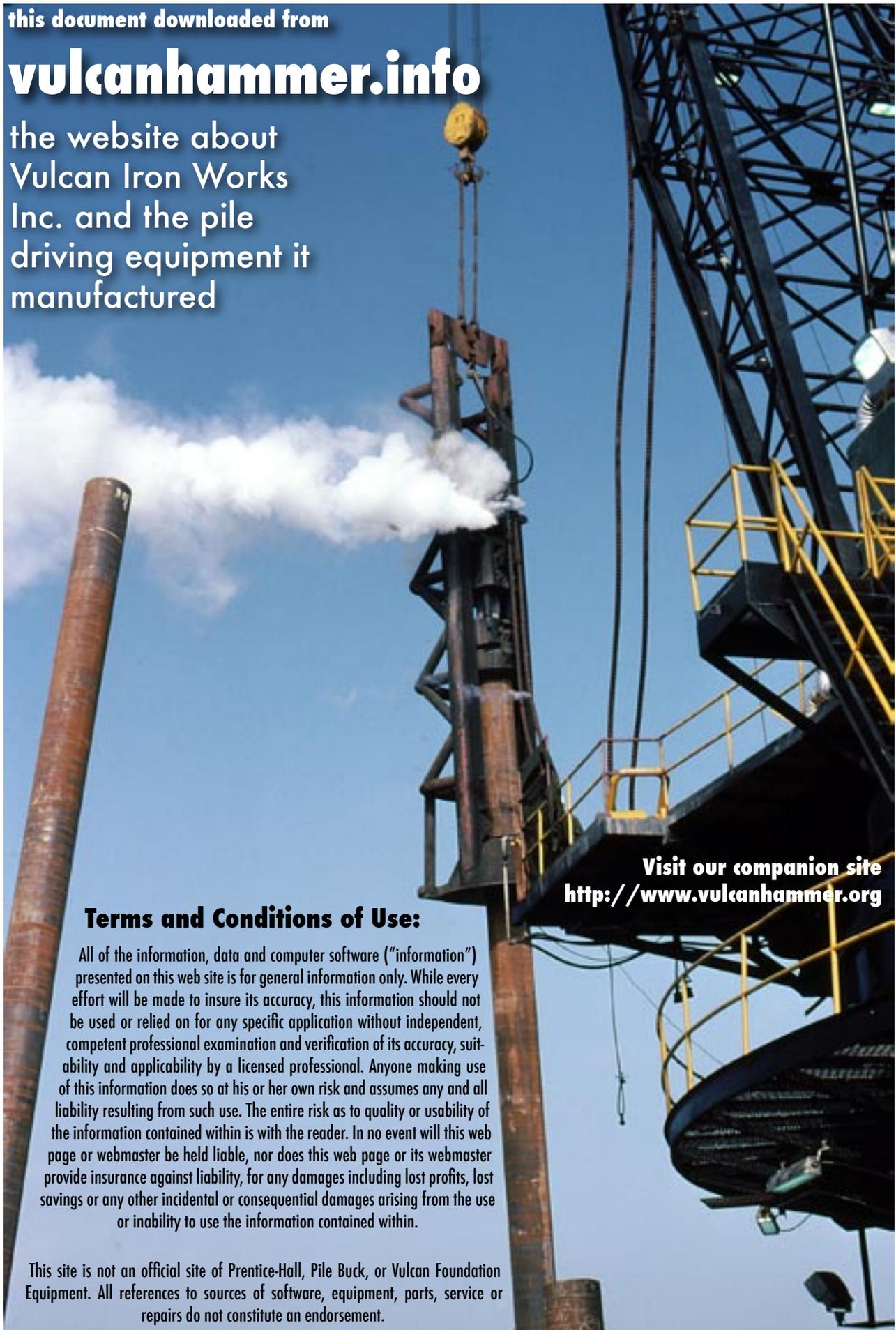
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# United States Patent [19]

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[54] **SEA WATER PILE HAMMER**

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[51] **Int. Cl.<sup>6</sup>** ..... **E02D 7/10; E02D 7/28**

[52] **U.S. Cl.** ..... **173/132; 173/115; 173/128; 173/DIG. 1**

[58] **Field of Search** ..... **173/19, 31, 32, 173/81, 89, 115, 128, 132, 141, 211, DIG. 1, 210**

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[57] **ABSTRACT**

A pile hammer for driving down hollow piles from an upper end thereof includes a hollow pile cap adapted to rest and support the hammer on a upper end of the pile being driven. The cap has an anvil surface for receiving blows from a ram which is slidably disposed on a hollow tubular base extending downwardly from the pile cap and having a lower end portion extending into the hollow pile being driven below the level of the pile cap. The ram is slidable on an upper portion of the hollow tubular base and has an annular lower end face adapted to strike the anvil surface of the pile cap when the ram is released to drop from an elevated position above the pile cap. A ram lift system is provided in an upper portion of the hollow tubular base for lifting the ram to an elevated position a selected predetermined height above the pile for release to drop downwardly and strike a driving blow against the anvil surface on the pile cap. The pile hammer is supported completely on the pile being driven and other means of support are not required. Sea water may be used as the operating fluid of the pile hammer and the hammer is operable above or below the water or on dry land. The pile hammer includes a remotely controllable, fluid control system for operating the pile hammer in an automatic or manual mode and the pile hammer does not require a waterproof enclosure.

**24 Claims, 5 Drawing Sheets**

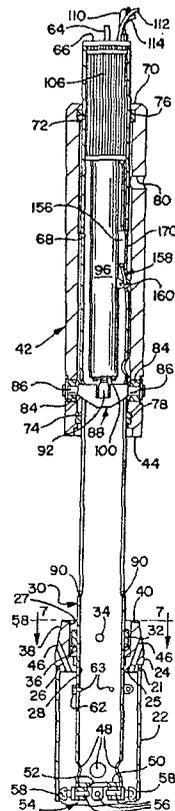


FIG. 5

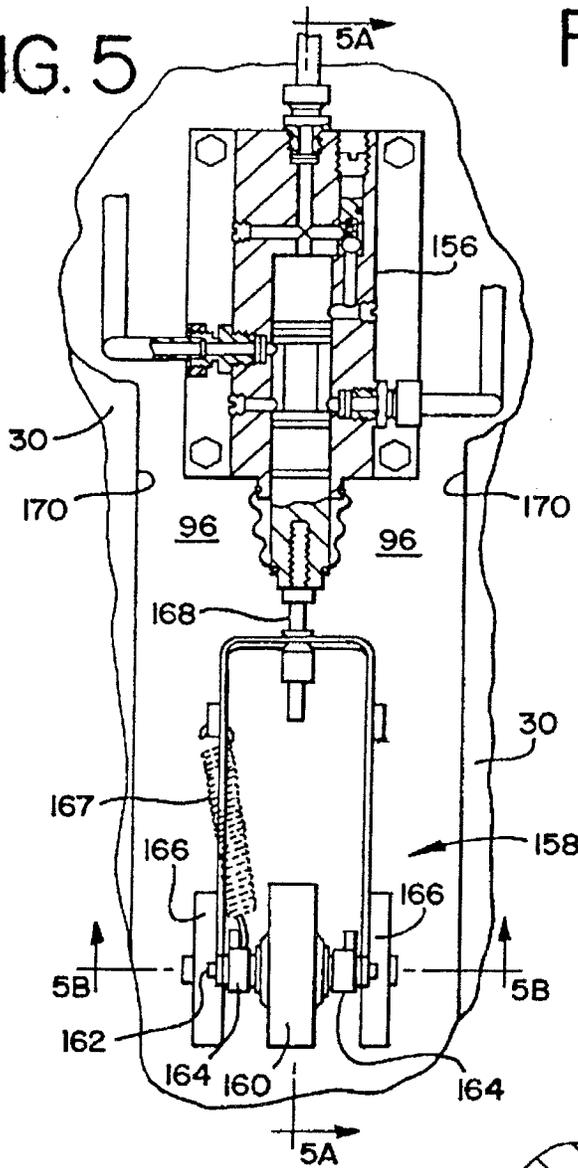


FIG. 5A

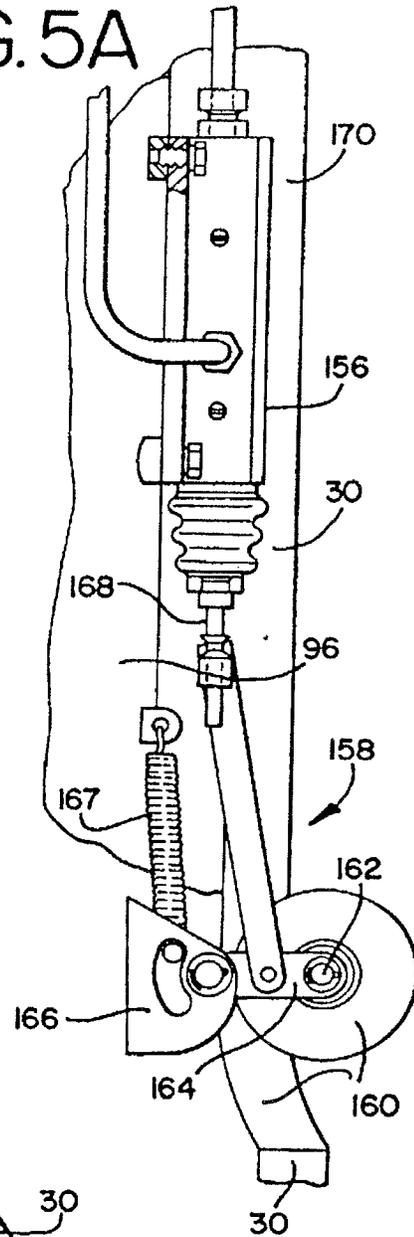


FIG. 5B

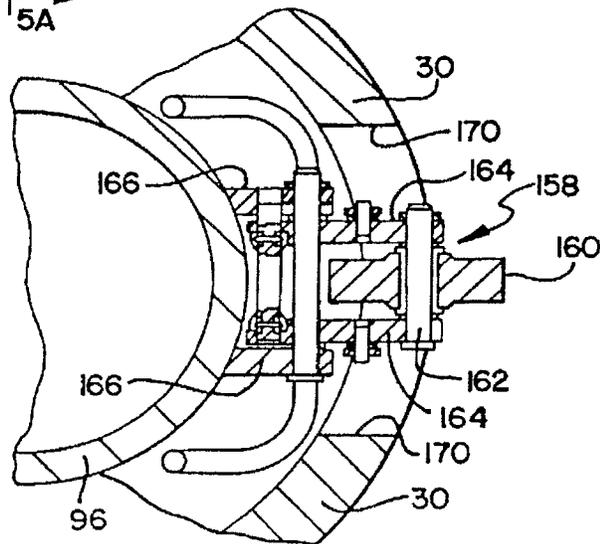


FIG. 9

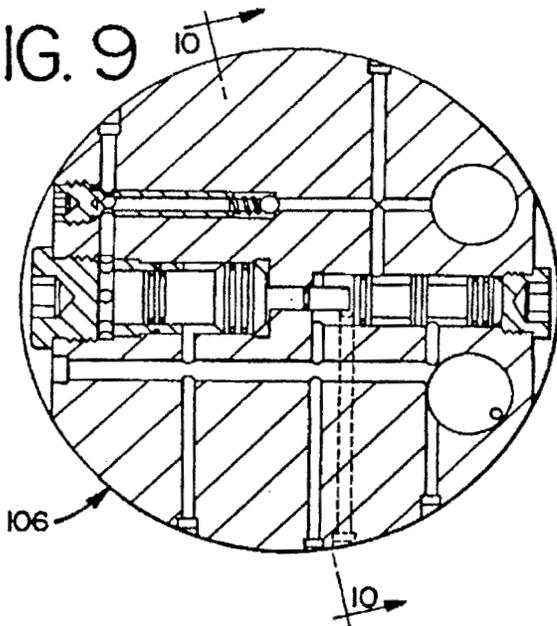


FIG. 10

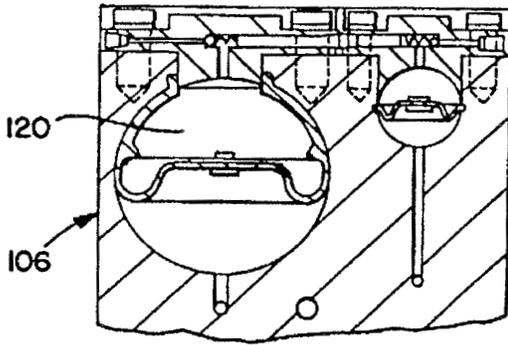


FIG. 13

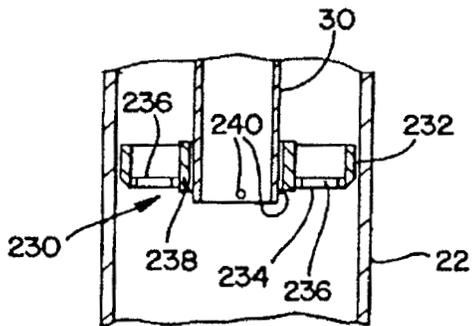
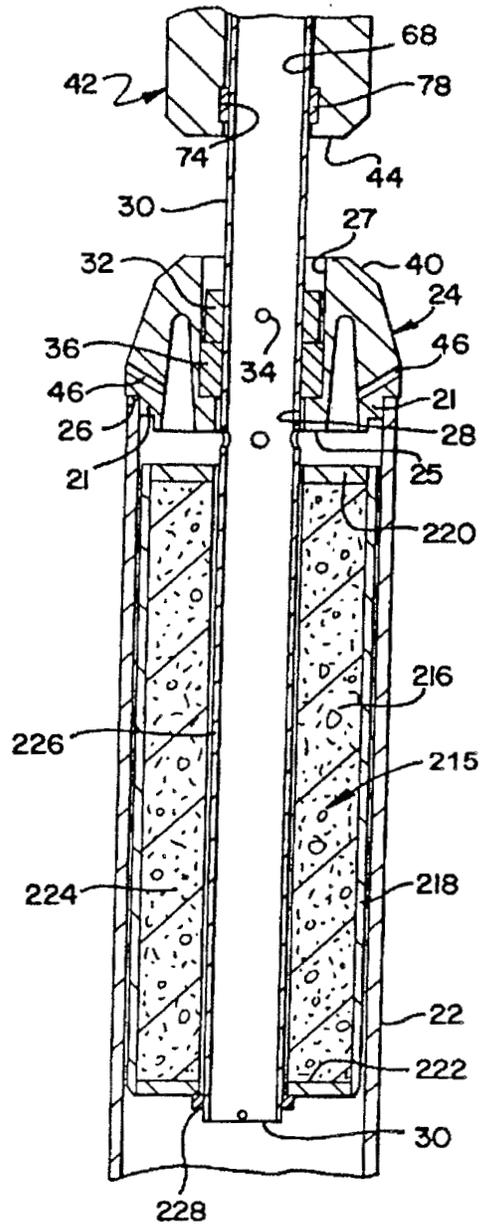


FIG. 12



## SEA WATER PILE HAMMER

## BACKGROUND—FIELD OF INVENTION

The present invention relates to a new and improved sea water pile hammer which is designed to use water as a hydraulic fluid and which is operable both above and below the surface of the water or on dry land and which does not require a waterproof casing.

## BACKGROUND—DESCRIPTION OF PRIOR ART

The primary purpose of pile driving equipment is to drive piles into the earth and so to support structures and prevent them from undesired movement. These include structures which are partially or entirely under the surface of the water, and whose pile may or may not be partially or entirely under the surface of the water. In these cases piles may be driven either from above the water or under its surface.

Concerning hammers which are designed to drive piles under the surface of the water, the prior art has many examples of hammers which require that the casing surrounding the impacting ram be capable of preventing the ingress of water into the mechanism and so to impede the downward velocity of the ram. This can be accomplished in a variety of ways, including sealing the case from water ingress, use of a compressed air source to force any water inside of the case out, and other means.

The weakness with all of these methods is that they require special measures to prevent the ingress of water into the case, whether this be to prevent damage to the interior parts or to prevent excessive drag on the ram during its motion, and they require that these measures be reasonably free of failure, lest the hammer be rendered inoperable by the ingress of water.

## OBJECTS AND ADVANTAGES

Accordingly, several objects and advantages of our invention are

to provide a new and improved sea water pile hammer and more particularly to provide a new and improved sea water pile hammer which can operate both above and below the surface of the water without requiring a waterproof casing in either case;

to provide a new and improved sea water pile hammer of the character described which is completely supported by a pile cap which rests on and is supported by the pile being driven;

to provide a new and improved sea water pile hammer of the character described in which a central tubular base extends downwardly inside of a pile being driven for guidance and limiting both the angle and the offset between the longitudinal axis of the pile cap and the longitudinal axis of the hollow piling;

to provide a new and improved sea water pile hammer of the character described which has a new and unique pile cap provided with radial slots for reducing energy loss during a driving blow;

to provide a new and improved sea water pile hammer of the character described which has a minimal width dimension relative to the length and incurs minimal water disturbance when the ram or hammer is dropped onto an anvil surface of a pile cap to drive a pile;

to provide a new and improved sea water pile hammer of the character described which has a remotely controllable

adjustable setting of ram rise before release to obtain a downward driving hammer stroke of a desired force;

to provide a new and improved sea water pile hammer of the character described utilizing sea or fresh water as a hydraulic fluid for lifting the ram and which is capable of both manual and automatic operation controlled from a location remote from the pile hammer. Still further objects and advantages will become apparent from a consideration of the ensuing description and accompanying drawings.

## BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a longitudinal cross-sectional view of a new and improved sea water pile hammer constructed in accordance with the features of the present invention and illustrating a ram of the hammer in a lower position resting on an anvil surface of a hollow pile cap.

FIG. 2 is a view similar to FIG. 1, but illustrating the ram in an elevated position ready to be dropped to strike a driving blow.

FIG. 3 is an upper end or top view of the pile hammer looking downwardly in the direction of arrows 3—3 of FIG. 1.

FIG. 4 is a transverse cross-sectional view of the pile hammer taken substantially along lines 4—4 of FIG. 1.

FIG. 5 is an enlarge fragmentary side elevational view of a portion of the pile hammer looking in the direction of arrows 5—5 of FIG. 1.

FIG. 5a is a cross-sectional view taken substantially along lines of 5A—5A of FIG. 5.

FIG. 5b is a fragmentary cross-sectional view taken substantially along lines 5B—5B of FIG. 5.

FIG. 6 is a transverse cross-sectional view taken substantially along lines 6—6 of FIG. 1.

FIG. 7 is a transverse cross-sectional view taken substantially along lines 7—7 of FIG. 2.

FIG. 8 is a fragmentary longitudinal cross-sectional view taken substantially along lines 8—8 of FIG. 1.

FIG. 9 is a transverse cross-sectional view taken substantially along lines 9—9 of FIG. 8.

FIG. 10 is a cross-sectional view taken substantially along lines 10—10 of FIG. 9.

FIG. 11 is a schematic diagram of a hydraulic control system of the pile hammer constructed in accordance with the features of the present invention.

FIG. 12 is a longitudinal cross-sectional view of another embodiment of a lower end guidance and alignment system for the sea water pile hammer constructed in accordance with the present invention.

FIG. 13 is a transverse cross-sectional view of yet another embodiment of a lower end guidance and alignment system for the sea water pile hammer constructed in accordance with the present invention.

## PREFERRED EMBODIMENT—DESCRIPTION

Referring now more particularly to the drawings and FIGS. 1—11, therein is illustrated one embodiment of a new and improved sea water pile hammer constructed in accordance with the features of the present invention and referred to generally by the reference numeral 20. The pile hammer 20 is designed and adapted to operate both above and below water and on dry land and utilizes either sea or fresh water as an operating fluid. The unique design of the pile hammer 20 eliminates the need for a sealed enclosure and the pile

is resting on the annular, upper end face or anvil surface 40 of the annular pile cap 24. The central bore 68 is formed with an upper annular groove 72 and a lower annular groove 74 in order to accommodate the upper resilient shock ring 76 and the lower resilient shock ring 78, both of which are formed of low friction material and engage the outer surface of the elongated, upstanding, hollow tubular base 30 to provide shock relief and low sliding friction between the hollow, heavy, generally cylindrically shaped ram 42 and the elongated, upstanding, hollow tubular base 30 on both upward lift stroke and downward driving strokes.

Adjacent an upper end portion, the body of the hollow, heavy, generally cylindrically shaped ram 42 is provided with one or more wall ports 80 to communicate between the inside and outside of the ram for equalizing the pressure during a pile driving operation. Adjacent a lower end portion of the hollow, heavy, generally cylindrically shaped ram 42 is formed a pair of diametrically opposed, radially oriented bores 82 for containing a pair of annular, resilient, shock element bearings 84 (FIG. 6) mounted on opposite, axle ends 86 of a transverse lift yoke 88. End portions of the transverse lift yoke 88, inwardly of the opposite, axle ends 86 are slidably disposed in longitudinally extending diametrically opposite guide slots 90 that are formed in the elongated, upstanding, hollow tubular base 30 above the annular pile cap 24. A central portion of the body of the transverse lift yoke 88 is connected to a clevis 92 on the lower end of a piston rod 94 (FIGS. 1 and 6) of a fluid operated lift cylinder 96 mounted inside an upper portion of the elongated, upstanding, hollow tubular base 30 by means of a removable cross pin 98 (FIG. 6.) The piston rod 94 extends upwardly into the fluid operated lift cylinder 96 through a central bore in an annular lower end wall 100 of the cylinder and is joined to a piston 102 that is fluid controlled to move between the annular lower end wall 100 and an upper end wall 104. The upper end wall 104 of the fluid operated lift cylinder 96 is secured to the lower end of the hydraulic base element 106 of generally cylindrical shape, mounted in the upper end of the elongated, upstanding, hollow tubular base 30 just below the top plate 66 of the pile hammer 20.

In accordance with the present invention, the pile hammer 20 is provided with a control system illustrated schematically in FIG. 11 for remote operative control of the hammer using sea water or other fluid as an operative fluid medium. The control system includes a fluid supply indicated as a whole by the power pack 108 which can be positioned at a convenient location such as a derrick barge several meters away from the hollow piling 22 being driven, or on land from a conventional pile driving rig. The power pack 108 is interconnected to the pile hammer 20 by means of large diameter, flexible, pressure line 110, regulating control line 112 and small bore flexible line 114, all of which lines pass through openings in the top plate 66 and are connected to the crank end hydraulic accumulator 116, head end accumulator 118, and control accumulator 120. These are contained in the hydraulic base element 106 in the upper end of the elongated, upstanding, hollow tubular base 30 above the fluid operated lift cylinder 96.

The power pack 108 is effective to start initial operation and to cease operation of the elongated, upstanding, hollow tubular base 30 beginning when the hollow, heavy, generally cylindrically shaped ram 42 is in an initial rest or lower position (FIG. 1) through one or more operating cycles, either in a manual or an automatic operating mode. The amount of impact energy from each downward driving or power stroke of the hollow, heavy, generally cylindrically

shaped ram 42 depends upon the level of which the hollow, heavy, generally cylindrically shaped ram 42 is lifted to (FIG. 2) before it is released to drop down toward the annular pile cap 24 to exert a driving blow on the hollow piling 22.

The power pack 108 includes a fluid supply reservoir 122 (FIG. 11) which supplies fluid through a check valve 124 and filter 126 to an inlet side of hydraulic pump 128. High pressure fluid from an outlet side of the pump is fed through a filter check valve 130 and pump filter 132 to a high pressure manifold 134 connected to the large diameter, flexible, pressure line 110. Pressure output from the hydraulic pump 128 is adjustable via an adjustable relief valve 136 and manual dump valve 138 is also provided for returning the output fluid from the hydraulic pump 128 to the fluid supply reservoir 122.

A main pressure gauge 140 is provided so that an operator can ascertain the output pressure available from the hydraulic pump 128 into the high pressure manifold 134 and adjust the adjustable relief valve 136 to increase or decrease the pressure as desired. A depressurizing manual dump valve 142 is provided for depressurizing the high pressure manifold 134. A manual, two-way control valve 144 is provided for operation of the pile hammer 20 in an automatic mode and when the valve is in the position shown (FIG. 11.) pressurized fluid is directed into a manually adjustable pressure reducing valve 146 which is connected to supply control fluid at a selected reduced pressure to the regulating control line 112. A control line pressure gauge 148 is provided to monitor the hydraulic pressure of the fluid supplied to the regulating control line 112.

A manual operation valve 150 is provided for initiating operation of the pile hammer 20 and continuing operation in the manual mode. When the manual operation valve 150 is in the position shown in FIG. 11, output from the manual operation valve 150 is directed through a pressure relief valve 152 into the small bore flexible line 114.

Pressurized fluid from the small bore flexible line 114 is directed via a passage or line 154 in the hydraulic base element 106 to a mechanically controlled valve 156 (FIGS. 5, 5A and 11) mounted on the fluid operated lift cylinder 96 and activated in response to the position of the hollow, heavy, generally cylindrically shaped ram 42 relative to the elongated, upstanding, hollow tubular base 30 or annular pile cap 24. The mechanically controlled valve 156 is actuated by a mechanism 158 (FIGS. 5, 5A and 5B) which senses the position of the hollow, heavy, generally cylindrically shaped ram 42 relative to the elongated, upstanding, hollow tubular base 30 by means of a cam follower roll 160 mounted on an axle 162. The axle 162 is supported at opposite ends on pivot arms 164 which are pivotally mounted at their inner ends on a pair of spaced apart brackets 166 secured to the fluid operated lift cylinder 96 as best shown in FIG. 5B. The pivot arms 164 are biased in a clockwise direction by spring 167 (FIG. 5A) to move the cam follower roll 160 to an outward position and in this position a stem 168 of the mechanically controlled valve 156 is pulled outwardly as shown in FIG. 5. An elongated slot 170 is formed in the elongated, upstanding, hollow tubular base 30 to accommodate the mechanism 158 and permit the cam follower roll 160 to extend outwardly thereof (FIG. 5B.) until engaged by the inside surface of the hollow, heavy,

comparator valve 178 of the main pilot valve 196 provide a pressure comparance or measurement of the pressure difference between the fluid in the head end accumulator 118 and the control accumulator 120. When the pressure difference becomes zero, the upper pusher 194 moves the main comparator valve 196 down and forces fluid out into the line 174 via the mechanically controlled valve 156 to the sump S.

While the main pilot valve 196 is switching position, the main operating valve 180 is also activated so that working fluid drainage through an outlet to the sump S is stopped and the piston end of the fluid operated lift cylinder 96 then becomes connected with the rod end. This results in a stoppage of the upward movement of the hollow, heavy, generally cylindrically shaped ram 42, and after the ram stops moving upwardly, it drops down in a pile driving stroke under its own weight, boosted by additional effort from the fluid operated lift cylinder 96 due to a difference in cross-sectional areas of the piston rod 94 and the small diameter inner control cylinder 188.

After a downward blow of the hollow, heavy, generally cylindrically shaped ram 42 upon the annular, upper end face or anvil surface 40 of the annular pile cap 24, the mechanically controlled valve 156 is returned to occupy a right hand position (FIG. 11) and transmits high pressure fluid to the pusher 175 causing the main pilot valve 196 and the main operating valve 180 to switch position. The operating cycle is then automatically repeated. Stoppage of the pile hammer 20 is accomplished by moving the manual operation valve 1/50 into an upper position. The height of the hollow, heavy, generally cylindrically shaped ram 42 when dropped determines the impact energy value obtained in a downward, pile driving stroke and the value may be adjusted during hammer operation by a simple adjustment of the pressure value output from the manually adjustable pressure reducing valve 146, which acts as a setter in determining the height of a lifting upward stroke of the hollow, heavy, generally cylindrically shaped ram 42 by the fluid operated lift cylinder 96.

#### CONCLUSIONS AND SCOPE

Obviously, many modifications and variations of the present invention are possible in light of the above teachings. Thus, it is to be understood that, within the scope of the appended claims, the invention may be practiced otherwise than as specifically described above.

What is claimed is:

1. A pile hammer for driving a hollow pile having a longitudinal axis by applying repeated axially directed driving blows to an upper end thereof, said pile hammer comprising:

an annular pile cap adapted to rest on the upper end of the pile and having an upper annular anvil surface in vertical alignment with the upper end of the pile;

said pile cap having a central axial bore extending entirely through said pile cap;

a base having an annular intermediate portion supported upon the pile cap and having a lower end portion extending downwardly from said intermediate portion through said central axial bore into said hollow pile below said cap;

said base including a hollow tubular upper portion extending upward from said intermediate portion;

an axially elongated hollow ram encircling and slidably mounted on said hollow tubular upper portion for movement between upper and lower positions and having a lower end hammer face adapted to strike said anvil surface when said ram is in said lower position; and

lift means mounted within said hollow tubular upper portion of said base and within said ram when said ram is in said upper position for lifting said ram to said upper position, and means for releasing said ram and permitting said ram to drop downwardly to said lower position to strike a driving blow with said hammer face against said anvil surface.

2. The pile hammer of claim 1, including:

guide means adjacent said lower end portion of said base engageable with the pile for limiting axial and radial misalignment between said base and the pile.

3. The pile hammer of claim 2, wherein:

said guide means includes a plurality of elements extending radially outwards from said lower end portion of said base having outer ends adapted for stopping engagement against an inside surface of the pile to limit said axial and radial misalignment.

4. The pile hammer of claim 2, wherein:

said guide means includes an elongated member mounted on said lower end portion of said base having a cylindrical guide surface facing the inside surface of the pile.

5. The pile hammer of claim 1, wherein:

said lift means includes a fluid cylinder means mounted inside said hollow tubular upper portion of said base for lifting said ram to said upper position.

6. The pile hammer of claim 5, wherein:

said lift means includes accumulator means mounted inside said hollow tubular upper portion of said base for supplying pressurized fluid to said fluid cylinder means for lifting said ram.

7. The pile hammer of claim 6, wherein:

said lift means includes a source of fluid pressure remote from said accumulator means for supplying pressurized fluid to said accumulator means.

8. The pile hammer of claim 5, wherein:

said fluid cylinder means includes piston rod means extending axially downwardly inside said upper portion of said base.

9. The pile hammer of claim 8, wherein:

said hollow tubular upper portion of said base is formed with elongated axially extending slots on opposite sides; and including

yoke means connected to a lower end of said piston rod means extending outwardly through said slots for engaging said ram to lift said ram when said piston rod is moved upwardly into said cylinder means.

10. The pile hammer of claim 9, including:

shock absorbers interconnected between said yoke means and said ram for reducing shock forces on said piston rod means and cylinder means as said ram strikes said anvil surface on a driving blow.

11. The pile hammer of claim 1, wherein:

said lower end portion of said base includes radially outwardly extending lift means engageable with said pile cap for lifting said pile cap in response to lifting of said base upward from the pile.

12. A submersible sea water pile hammer for driving a submerged hollow pile having a longitudinal axis by applying repeated axially directed driving blows to an upper end thereof, said pile hammer comprising:

pile cap means having a lower end portion adapted to engage the upper end of the hollow pile for supporting the pile hammer on the pile;

an elongated hollow base extending downwardly and upwardly through said pile cap means and supported by said pile cap means;